# Opencv seminar

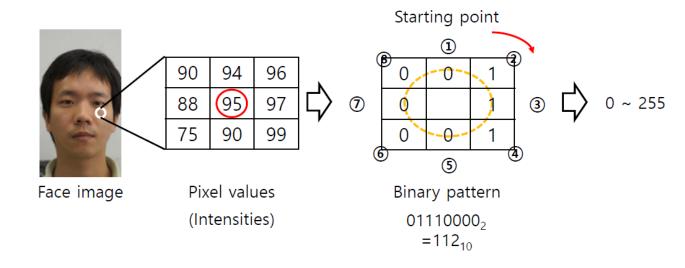
4. Face Identification

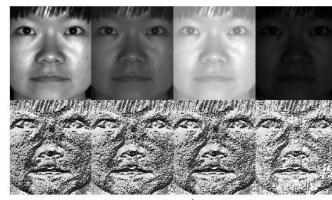
2018.02.05

### **LBP**

- Local binary pattern
- LBP works robust to the illumination change!

$$f_{\text{LBP}}(x,y) = \sum_{1 \le i \le n} 2^{i-1} \text{LBP}^{i}(x,y) \text{ where } \text{LBP}^{i}(x,y) = \begin{cases} 1, & \text{if } I(x,y) > I(x_i,y_i) \\ 0, & \text{otherwise} \end{cases}$$





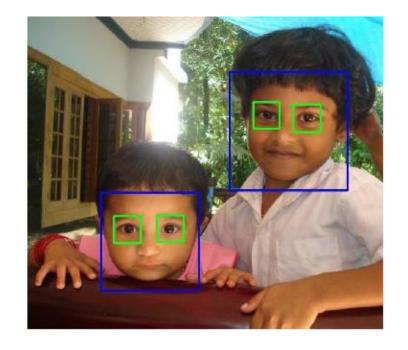
<result>

## Class CascadeClassifier (1/2)

#### Apply the function of eye detection

: Opency also provides the function for eye detection

```
#include<stdio.h>
#include<stdlib.h>
#include<iostream>
#include<opency/cv.h>
#include<opency/highgui.h>
#include<opencv2/opencv.hpp>
#include<opencv2/objdetect/objdetect.hpp>
#include<opencv2/ml/ml.hpp>
using namespace cv;
using namespace cv::ml;
using namespace std;
```



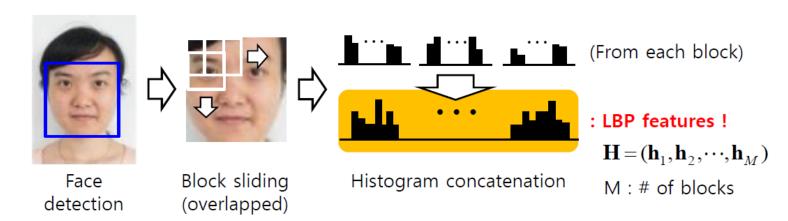
## Class CascadeClassifier (2/2)

```
void main(){
          CascadeClassifiercascade;
          cascade.load("~/OpenCV3.1.0/sources/data/lbpcascades/lbpcascade frontalface.xml");
          Matimg=imread("face1.bmp",1);//imageread(color)
          vector<Rect>faces:
          cascade.detectMultiScale(img,faces,1.1,4,0|CV HAAR SCALE IMAGE,Size(10,10));
          for(y=0;y<faces.size();y++){
                    Pointlb(faces[y].x+faces[y].width,faces[y].y+faces[y].height);
                    Pointtr(faces[y].x,faces[y].y);
                    rectangle(img,lb,tr,Scalar(0,255,0),3,8,0);
          imshow("Face",img);
          waitKey(50000);
```

### Implementation

- Feature extraction
  - To encode such patterns, histogram is employed
    - Since the range of LBP image is also 0~255, conventional histogram-based representation can be adopted!

$$\mathbf{h} = (h_1, h_2, \dots, h_{256}) \quad \text{where} \quad h_k = \frac{N_k}{\sqrt{\sum_{q=1}^{256} N_q^2 + \delta}}, \quad N_k = \sum_{f_{\text{LBP}}(x, y) \in k} 1$$



### Implementation

- Your task
  - 1. Use class CascadeClassifier to find the face in the images
  - 2. Convert gray image to LBP images
  - 3. Construct the 256-bin histogram
  - 4. Compute Euclidean distance between two LBP features (similarity computation)

Similarity : 
$$S(\mathbf{H}^{en}, \mathbf{H}^{ver}) = \frac{1}{256} \sum_{i=1}^{256} ||\mathbf{h}_{i}^{en} - \mathbf{h}_{i}^{ver}||$$
 (en : enroll image, ver : verification image)

To determine whether given two images are same or not, we need to set the threshold value!