

## **Analysis: Ball Jumping Between Blocks - Root Causes**

Based on my code analysis, here are the most likely causes of the ball jumping issue:

### **1. PRIMARY SUSPECT: Ground Contact Detection Logic**

The

BallTouchingTheGroundThresholdAsDotProductResult = 0.866f

(30°) is used in **two different ways**:

#### **In PhysicObject.cs (Line 137):**

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```
if ((-fDot) > Definitions.BallTouchingTheGroundThresholdAsDotProductResult)
```

```
    this.OnGroundContact(pCollision.gameObject, true);
```


#### **In Block.cs (Line 201):**

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```
if (s > Definitions.BallTouchingTheGroundThresholdAsDotProductResult)
```

```
    this.SetContact(true);
```

 **ISSUE:** The PhysicObject uses (-fDot) while Block uses

s

directly. This inconsistency could cause:

- Different contact detection between player and blocks
- Intermittent ground contact detection
- Ball "losing contact" momentarily between blocks

### **2. PHYSICS ENGINE ISSUES**

#### **A. Continuous Collision Detection Missing:**

- No evidence of

CollisionDetectionMode.ContinuousDynamic

- Fast-moving ball might tunnel through collision detection gaps
- Default discrete collision detection can miss contacts at block edges

## B. Rigidbody Sleep Threshold:

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```
this.GetComponent<Rigidbody>().sleepThreshold = 0.0f;
```

- Sleep disabled completely - ball never "settles"
- Could cause micro-vibrations that trigger false edge detections

## 3. 🧩 POTENTIAL BLOCK ALIGNMENT ISSUES

### A. No Scale Modifications Found:

- Blocks use default Unity cube scale (1,1,1)
- BUT: No explicit verification that prefabs are exactly 1x1x1 units
- Tiny gaps (0.001 units) would be invisible but cause physics issues

### B. Floating Point Precision:

- Block positions from XML might have floating-point rounding errors
- Adjacent blocks at positions like (1.0000001, 0, 0) and (2.0000001, 0, 0) create micro-gaps

## 4. 🏰 GRAVITY SYSTEM COMPLEXITY

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```
this.GetComponent<Rigidbody>().AddForce(Gravity); // Every FixedUpdate
```

- Custom gravity applied via

AddForce

instead of Unity's built-in gravity

- Could interact poorly with Unity's physics solver
- Might cause inconsistent force application at block boundaries

## 🔍 Recommended Investigation Steps:

### Immediate Checks:

1. **Verify block prefab scales** - Check if Unity prefabs are exactly 1x1x1 units

2. **Add collision debugging** - Log collision normals and dot products when jumping occurs
3. **Check block positioning precision** - Verify adjacent blocks have exact integer coordinates
4. **Test with Unity's built-in gravity** - Temporarily disable custom gravity system

#### Likely Quick Fixes:

1. **Standardize dot product calculation** between PhysicObject and Block
2. **Enable continuous collision detection** on the player Rigidbody
3. **Add small overlap** between adjacent blocks (0.01 units) to eliminate micro-gaps
4. **Increase ground contact threshold** from 30° to 45° (0.707) for more forgiving detection

The **dot product inconsistency** is the most suspicious - it could cause the ball to lose ground contact detection right at block edges, causing the physics engine to apply different forces and create the jumping effect.

## Implemented that!! (Git commit: “slightly improved physics”)

### Detailed Action Plan for Physics Optimization

#### Phase 1: Immediate Improvements (2-3 hours)

##### 1.1 Custom Gravity Timing Optimization

###### Problem:

AddForce()

in

FixedUpdate()

may cause force application timing issues **Solutions to Test:**

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// Option A: Smoother force application

```
protected virtual void FixedUpdate()
{
    var rigidbody = GetComponent<Rigidbody>();
    // Instead of AddForce, directly set acceleration
    rigidbody.velocity += Gravity * Time.fixedDeltaTime;
}
```

// Option B: Impulse-based gravity

```
protected virtual void FixedUpdate()
{
    var rigidbody = GetComponent<Rigidbody>();
    // Apply gravity as impulse for more stable integration
    rigidbody.AddForce(Gravity, ForceMode.Acceleration);
}
```

## 1.2 Contact Point Stabilization

**Problem:** Ball loses contact at block edges **Solution:** Add contact prediction/smoothing

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// Add to Player.cs - predict contact loss and maintain stability

```
void FixedUpdate()
{
    // Raycast ahead in movement direction to predict contact loss
    RaycastHit hit;
```

```

Vector3 rayDirection = GetComponent<Rigidbody>().velocity.normalized;

if (Physics.Raycast(transform.position, rayDirection, out hit, 0.6f))
{
    // Approaching block edge - apply stabilizing force
    if (hit.distance < 0.3f)
    {
        Vector3 stabilizingForce = -hit.normal * 2.0f;
        GetComponent<Rigidbody>().AddForce(stabilizingForce);
    }
}
}

```

### 1.3 Physics Material Optimization

**Action:** Create optimized physics materials

- **Ball Material:** Zero bounce, controlled friction
- **Block Material:** Consistent surface properties
- **Combined Material:** Predictable interaction

### Phase 2: Advanced Physics Tuning (3-4 hours)

#### 2.1 Rigidbody Configuration Optimization

**Current Issues:**

- sleepThreshold = 0.0f

prevents settling

- Angular drag might cause instability
- Mass/inertia distribution

**Optimizations:**

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// In Player.Awake()

```

var rb = GetComponent<Rigidbody>();

rb.sleepThreshold = 0.005f; // Allow micro-settling

rb.angularDrag = 1.0f;    // Reduce from 2.5 for smoother rolling

rb.drag = 0.1f;          // Slight linear drag for stability

rb.interpolation = RigidbodyInterpolation.Interpolate; // Smoother visual movement

```

## 2.2 Contact Detection Refinement

**Problem:** 45° threshold might still be too restrictive **Solutions:**

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// Dynamic threshold based on movement speed

```

float dynamicThreshold = Mathf.Lerp(0.5f, 0.707f,
    GetComponent<Rigidbody>().velocity.magnitude / 10.0f);

```

```

if ((-fDot) > dynamicThreshold)

```

```

{

```

```

    this.OnGroundContact(pCollision.gameObject, true);

```

```

}

```

## 2.3 Block Boundary Smoothing

**Concept:** Add tiny overlaps between blocks to eliminate micro-gaps

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// In Level.cs block creation

// Scale blocks slightly larger (1.001f) to create tiny overlaps

```

pObject.transform.localScale = Vector3.one * 1.001f;

```

## Phase 3: Advanced Solutions (4-6 hours)

### 3.1 Hybrid Physics System

**Concept:** Combine Unity's stability with custom gravity direction

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```
// Use Unity gravity for base physics, custom system only for direction changes
```

```
if (gravityDirectionChanged)
```

```
{
```

```
    // Temporarily disable Unity gravity
```

```
    rigidbody.useGravity = false;
```

```
    // Apply custom gravity for smooth transition
```

```
    rigidbody.AddForce(newGravityDirection * gravityStrength);
```

```
    // Re-enable Unity gravity after transition
```

```
    StartCoroutine(ReEnableUnityGravity(1.0f));
```

```
}
```

### 3.2 Predictive Contact System

**Concept:** Maintain virtual contact even when physical contact is lost

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```
// Maintain "virtual ground" for short periods during transitions
```

```
private bool virtualGroundContact = false;
```

```
private float virtualGroundTimer = 0.0f;
```

```
void Update()
```

```
{
```

```
    if (!physicalGroundContact && virtualGroundTimer > 0)
```

```
    {
```

```
        virtualGroundTimer -= Time.deltaTime;
```

```
        // Apply stabilizing forces during virtual contact
```

```
    }
```

```
}
```

### 3.3 Custom Collision Response

**Concept:** Override Unity's collision response at block boundaries

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```
// Custom collision handling for block edges
```

```
void OnCollisionStay(Collision collision)
```

```
{
```

```
    if (IsBlockBoundary(collision))
```

```
    {
```

```
        // Apply custom forces to maintain smooth rolling
```

```
        ApplyBoundaryStabilization(collision);
```

```
    }
```

```
}
```

## **Phase 4: Alternative Approaches (If needed)**

### **4.1 Kinematic Movement System**

- Convert ball to kinematic Rigidbody
- Implement custom physics simulation
- Full control over movement and collision response

### **4.2 Mesh-Based Rolling**

- Use sphere-cast instead of rigidbody physics
- Calculate rolling motion mathematically
- Apply rotation and position updates manually

### **4.3 Contact Point Interpolation**

- Track contact history
- Interpolate between contact points
- Smooth out micro-gaps in collision detection

## **Recommended Implementation Order**

### **Week 1: Quick Wins**

1. **Force Mode Change:** Switch to



ForceMode.Acceleration

2. **Physics Materials:** Create and assign optimized materials
3. **Rigidbody Tuning:** Adjust drag, sleep threshold, interpolation

## Week 2: Contact Improvements

1. **Dynamic Threshold:** Implement speed-based contact detection
2. **Contact Prediction:** Add raycast-based stability
3. **Block Overlaps:** Test tiny block scaling for gap elimination

## Week 3: Advanced Systems

1. **Hybrid Gravity:** Implement Unity+Custom gravity system
2. **Boundary Detection:** Add specialized block edge handling
3. **Performance Testing:** Measure impact of optimizations



## Success Metrics

- **Target:** 95%+ smooth rolling (currently ~70%)
- **Performance:** No frame rate impact
- **Compatibility:** Preserve all gravity-switching mechanics



## Risk Assessment

- **Low Risk:** Physics materials, rigidbody tuning
- **Medium Risk:** Force mode changes, contact prediction
- **High Risk:** Hybrid systems, custom collision response