





KLINSMANN AGYEI

MSc Robotics and AI, passionate about developing intelligent systems that can effectively recognize their environment, make informed decisions and operate seamlessly in the physical world. Currently seeking PhD positions in Robotics and Artificial Intelligence.



 klinsmannjurgenagyei@gmail.com  +7 952 668 3326, +233 20 498 0856  WR-0036-0003  <https://klins101.github.io>
 <https://github.com/Klins101>

Education

2022-2024	MSc Robotics and Artificial Intelligence ITMO University
2015-2019	BSc Mechanical Engineering University of Energy and Natural Resources

Work History

May - August 2023

Robotics Engineer, Intern

Void Robotics, USA-Remote.

- Contributed to building an Operating system for autonomous transportation of robot using ROS2, Arduino and a GPS based navigation system.
- Enhanced the Real-Time Kinematic (RTK) GPS library by transitioning from version 2 to version 3, while also revising and adapting existing code syntaxes to align with the requirements of version 3. Subsequently, thorough testing of the upgraded library was conducted on a remote system utilizing secure shell (SSH) protocol.
- Utilized GitHub Actions to orchestrate the building of ROS2 within Ubuntu 22.04 Docker image. This encompassed constructing the project workspace and executing comprehensive tests to validate the robot simulation subsequent to each code push to a designated branch within the GitHub repository.
- Integrated the ROS 2 Nav2 framework along with the Spatio-Temporal Voxel Layer(STVL) to depict the environment using the vortex grid format. Since STVL was not available for ROS humble.

2022

Open-Source Software Developer

Deep Ivy, Unify AI

- Reformatted old Python Machine Learning functions to comply with the Python array API standards on the deep ivy framework.
- Created issues and sent pull requests after finding and fixing issues on the open-source ivy machine learning framework on GitHub.

2020 - 2022

Software Engineer - Data Science

AmaliTech GmbH, Takoradi-Ghana.

- Developed an LSTM and CNN combination model in addition to OpenCV's classical Computer Vision framework to extract part of the video when riders are speeding and the part where they encounter a curve from a video.
- Developed an object detection model with Yolov5, and PyTorch to detect objects on the driveway such as cars, bicycles, humans, and so on.
- Used Labelme image annotation to label or annotate road lanes and objects in images to be used for the object detection algorithm
- Responsible for scrapping app reviews from popular apps and performing a sentiment analysis on them using transfer learning from hugging face transformer library.
- Implemented Python's Google Play scraper to get user reviews from various apps from google play store and saved the data into a CSV file using python's pandas library.
- Prepared a custom dataset for face detection with Detectron2 using the Labelme annotation tool.

ONLINE COURSES

Udemy

Convolutional Neural Network with python - **Intermediate**
Deep Learning: Learn with TensorFlow and python - **Intermediate**
Image Processing with Python - **Intermediate**
Internet of Things - **Beginner**

COEX

Aerial Robotics - **Beginner**

WorldQuant University

MSc Financial Engineering
Applied Data Science - **Advanced**

France Université Numérique

Machine Learning in Python with scikit-learn - **Advanced**.

Codecademy

Data Scientist Career Path Certification - **Intermediate**
Data Analytics Career Path Certification- **Intermediate**
Design Databases with PostgreSQL- **Intermediate**
Analyze Data with SQL - **Intermediate**
Build Machine Learning Model with Python - **Intermediate**
Build Deep Learning Model with TensorFlow - **Intermediate**
Master Statistics with Python - **Intermediate**
Visualize Data with Python - **Intermediate**
Analyze Natural Language Processing with Python - **Intermediate**

Udacity

AWS Machine Learning Foundation - **Beginner**

Skill Set

Programming Languages: Python: Advanced, C++: Intermediate, MATLAB: Intermediate

Frameworks and Libraries: PyTorch, TensorFlow, sci-kit learn, OpenCV(python & C++) ,
Pandas, Matplotlib, Ivy, Seaborn, Jax, NumPy, SciPy, SymPy.

Utils: Bash, Git, Docker, make (catkin, colcon)

Communication: ROS 1 and ROS 2

CAD and Simulators: Unity, SolidWorks, Gazebo, Simscape Multibody, Coppeliasim, PyBullet

Operating System: Linux, Windows.

Languages: English: Native, French: Beginner, Russian: Beginner.

Awards and Scholarships

Newmont Ghana Scholarship, for needy but brilliant students, 2015-2019

Russian Government Scholarship, 2022-2024

Winner of Open Doors Russian Competition for Engineering and Technology

Citation of Honor for my remarkable initiative in initiating the formation of the robotics and design club, providing a platform for students to explore their passion for Robotics, CAD and engineering, MESA-UENR, 2018

Citation of Honor for insightful, dedicative attitude, skills and instrumental role in the parliamentary council and reinvention of the UENR SRC, 2018

Leadership and Extra Curriculum Activities

2017/2018

President

Mechanical Engineering Students' Association, UENR

2017-2018

Coordinator

West African Institute of Mining, Metallurgy and Petroleum, UENR

2017-2018

Member

Ghana Institute of Engineers, Student Chapter

2014/2015

Member

National Science and Maths Quiz Team, Labone Senior High School

2014-2015

Member

National Robotics Competition Team, Labone Senior High School

Research

Study of Control algorithms for robotic systems based on reinforcement Learning

Klinsmann Agyei, Alexey Vedyakov

ITMO University, 2023

New Horizon, Quantitative behavioral models

Klinsmann Agyei, Alberto Buccellato, Greg Ciresi

WorldQuant University, 2022

Design and Fabrication of an electric power amplifier

Klinsmann Agyei, Peter Tokor Sobuur, Christopher Morimaha, Nana Agyemang Derkyi

University of Energy and Natural Resources, 2019