

Beregning af 0-punkter

$$R_{out} := 8.4 \, \Omega \quad D := 0.447 \quad N_{ps} := 1 \quad L_p := 57.7 \, \mu H \quad f_s := 100 \, kHz$$

$$R_{ESR} := \left((15 \, \Omega \cdot 10^{-3})^{-1} \cdot 4 \right)^{-1} = 3.75 \, \Omega \cdot 10^{-3} \quad C_{out} := 56 \, \mu F \cdot 4 = 224 \, \mu F$$

$$f_{RHPZ} := \frac{R_{out} \cdot (1-D)^2 \cdot N_{ps}^2}{2 \pi \cdot L_p \cdot D} = 15.851 \, kHz \quad \omega_{RHPZ} := 2 \pi \cdot f_{RHPZ}$$

$$f_{ESRz} := \frac{1}{2 \pi \cdot R_{ESR} \cdot C_{out}} = 189.47 \, kHz \quad \omega_{ESRz} := 2 \pi \cdot f_{ESRz}$$

$$f_{BW} := \frac{f_{RHPZ}}{3} = 5.284 \, kHz$$

$$V_{inmin} := 26 \, V \quad V_{out} := 21 \, V$$

$$\tau_L := \frac{2 \cdot L_p \cdot f_s}{R_{out} \cdot N_{ps}} = 1.374$$

$$M := \frac{V_{out} \cdot N_{ps}}{V_{inmin}} = 0.808$$

Open-loop gain:

$$A_{CS} := 1.65 \quad R_{CS} := 0.167 \, \Omega$$

$$G_o := \frac{R_{out} \cdot N_{ps}}{R_{CS} \cdot A_{CS}} \cdot \frac{1}{\frac{(1-D)^2}{\tau_L} + (2 \cdot M) + 1} = 10.742 \quad 20 \cdot \log(G_o) = 20.621$$

Beregning af poler

$$f_{p1} := \frac{\frac{(1-D)^3}{\tau_L} + 1 + D}{2 \pi \cdot R_{out} \cdot C_{out}} = 132.807 \, Hz \quad \omega_{p1} := 2 \pi \cdot f_{p1}$$

$$f_{p2} := \frac{f_s}{2} = 50 \, kHz \quad \omega_{p2} := 2 \pi \cdot f_{p2}$$

$$s := 0$$

$$H_0 := G_o \cdot \frac{\left(1 + \frac{s}{\omega_{ESRz}}\right) \cdot \left(1 - \frac{s}{\omega_{RHPZ}}\right)}{1 + \frac{s}{\omega_{p1}}} \cdot \frac{1}{1 + \frac{s}{\omega_{p2}} + \frac{s^2}{\omega_{p2}^2}} \rightarrow 10.741599241902968$$

Beregning af kompenseringsnetværk

$$R_{FB1} := 18.7 \text{ } k\Omega \quad R_{FB2} := 2.55 \text{ } k\Omega \quad A_{ol_{db}} := -5.4 \quad A_{ol} := 10^{\frac{A_{ol_{db}}}{20}} = 0.537$$

$$R_{par} := \left(R_{FB1}^{-1} + R_{FB2}^{-1}\right)^{-1} = 2.244 \text{ } k\Omega$$

$$R_{comp} := A_{ol} = \frac{R_{comp}}{R_{par}} \cdot \frac{R_{FB2}}{R_{FB1} + R_{FB2}} \xrightarrow{\text{solve}, R_{comp}} 10.042494592123724929 \cdot k\Omega$$

$$f_{zero} := 300 \text{ } Hz \quad R_{comp} := 10 \text{ } k\Omega$$

$$C_{comp} := \frac{1}{2 \cdot \pi \cdot R_{comp} \cdot C_{comp}} = f_{zero} \xrightarrow{\text{solve}, C_{comp}} \frac{1}{6000 \cdot \pi \cdot Hz \cdot k\Omega}$$

$$C_{comp} = 53.052 \text{ } nF \quad C_{comp} := 50 \text{ } nF$$

$$f_{zero} := \frac{1}{2 \cdot \pi \cdot R_{comp} \cdot C_{comp}} = 318.31 \text{ } Hz$$

Optimering af reguleringsloop. ønsket gain aflæses på bode plot i db.

$$A_{ol_{db}} := 8.5 \quad A_{ol} := 10^{\frac{A_{ol_{db}}}{20}} = 2.661$$

$$R_{comp} := \frac{R_{comp1}}{R_{par}} \cdot \frac{R_{FB2}}{R_{FB1} + R_{FB2}} = A_{ol} \xrightarrow{\text{solve}, R_{comp1}} 49.75555861823774139 \cdot k\Omega$$

$$f_{zero} := 132.8 \text{ } Hz$$

$$C_{comp} := \frac{1}{2 \cdot \pi \cdot R_{comp} \cdot C_{comp1}} = f_{zero} \xrightarrow{\text{solve}, C_{comp1}} \frac{0.000024086874513293678733}{Hz \cdot k\Omega}$$

$$C_{comp} = 24.087 \text{ } nF$$