```
//
                                                                         //
    Name: Talkthrough for the ADSP-BF533 EZ-KIT Lite
//
//
      ______
//---
//
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//
//
//
   Project Name: BF533 C Talkthrough TDM
//
   Date Modified: 04/03/03
                                                                 //
//
//
                  VisualDSP++4.5
   Software:
                                                                         //
//
//
   Hardware:
                  ADSP-BF533 EZ-KIT Board
//
//
                 Disconnect RSCLK0 and TSCLK0 (Turn SW9 pin 6 OFF)
   Connections:
//
                   Disconnect RFS0 and TFS0 (Turn SW9 pin 5 OFF)
                   Connect an input source (such as a radio) to the Audio
//
                   input jack and an output source (such as headphones) to //
//
                   the Audio output jack
                  This program sets up the SPI port on the ADSP-BF533 to configure the AD1836 codec. The SPI port is disabled
   Purpose:
//
                                                                         //
//
                  after initialization. The data to/from the codec are //
//
                  transfered over SPORTO in TDM mode
                                                                         //
#include "Talkthrough.h"
#include "sysreq.h"
#include "ccblkfn.h"
#include "stats.h"
#include "stdio.h"
//-----//
// Variables
                                                                         //
//
                                                                         //
// Description: The variables iChannelxLeftIn and iChannelxRightIn contain
               the data coming from the codec AD1836. The (processed)
               playback data are written into the variables
//
              iChannelxLeftOut and iChannelxRightOut respectively, which //
              are then sent back to the codec in the SPORTO ISR. //
//
               The values in the array iCodec1836TxReqs can be modified to //
              set up the codec in different configurations according to //
//
             the AD1885 data sheet.
                            -----//
// left input data from ad1836
int iChannel0LeftIn, iChannel1LeftIn;
// right input data from ad1836
int iChannelORightIn, iChannel1RightIn;
// left ouput data for ad1836
int iChannel0LeftOut, iChannel1LeftOut;
// right ouput data for ad1836
int iChannelORightOut, iChannel1RightOut;
// array for registers to configure the ad1836
// names are defined in "Talkthrough.h"
volatile short sCodec1836TxRegs[CODEC_1836_REGS_LENGTH] =
                   DAC_CONTROL_1
                                   0x000,
                   DAC_CONTROL_2
DAC_VOLUME_0
DAC_VOLUME_1
                                    0 \times 0000,
                                    0x3ff,
                                   0x3ff.
                   DAC_VOLUME_2
                                 0x3ff,
                   DAC_VOLUME_3
                                  0x3ff,
                   DAC_VOLUME_4
DAC_VOLUME_5
                                    0x3ff.
                                  | 0x3ff,
                   ADC_CONTROL_1
                                  0x000,
                                 0x180,
0x000
                   ADC_CONTROL_2
                   ADC_CONTROL_3
};
```

```
// SPORTO DMA transmit buffer
volatile int iTxBuffer1[8];
// SPORTO DMA receive buffer
volatile int iRxBuffer1[8];
int yn = 0;
int xn = 0;
int num1 = 0;
int num2 = 0;
int playFlag = 1;
int recFlag = 1;
int doX = 0;
short sound[INPUTLEN] = {
#include "Sig_chirpfinal.hex"
short sound2[INPUTLEN] = {
#include "Sig_ChirpD.hex"
short sinus[INPUTLEN] = {
#include "sinus.hex"
short soundIn[INPUTLEN];
short corr[LAGS] = \{0\};
int lags = LAGS;
int input_l = SAMPLES;
int n_measurements = 0;
int NumberOfMeasurements = 50;
int distance[50] = \{0\};
// Function: main
                                                                          //
                                                                          //
// Description: After calling a few initalization routines, main() just
              waits in a loop forever. The code to process the incoming
//
//
               data can be placed in the function Process_Data() in the
              file "Process_Data.c".
//
//-----//
void main(void)
   sysreg_write(reg_SYSCFG, 0x32); //Initialize System Configuration Register
   Init_EBIU();
Init_Flash();
   Init1836();
   Init_Sport0();
   Init_DMA();
   Init_Interrupts();
   Enable DMA Sport0();
   while(1)
       if(doX){
       crosscorr_fr16(sound,
                    soundIn,
                    input_1,
                    lags,
                    corr);
       distance[n measurements] = calc dist(corr);
       //printf("%d \n",distance[n_measurements]/10);
       n_measurements++;
       if(n_measurements >= NumberOfMeasurements){
           n_measurements = 0;
```