

```
#include "Haeldningssensorblok.h"
```

```
uint32 getLevel( void )
{
    uint32 VatterVal = 0;

    ADC_DelSig_1_IsEndConversion(ADC_DelSig_1_WAIT_FOR_RESULT);/* Wait for ADC
conversion to be completed */
/* get value from Accelerometer */
VatterVal = ADC_DelSig_1_GetResult32();
return VatterVal;
}
```