sensor.cpp 1

```
#include "sensor.h"

//Konstruktor
sensor::sensor(){}
sensor::sensor(rs232 *com)
{
    m_pComSensor = com;
}

//
int sensor::getLevel()
{
    m_pComSensor->send(REQ_HAELDNING);
    m_pComSensor->readAck(STATUS_HAELDNING);
    return m_pComSensor->readValue();
}
```