CDU

+ CDUInit(void); void
+ CDUStartUpRoutine(Sensor* sensorarray, unsigned char* alive, unsigned char* Messagebuffer, unsigned char* receivebuffer, Cduflags* CDUFlags); void
+ CDUSend(Sensor* Sens, unsigned char functioncode, unsigned char* Messagebuffer, Cduflags* CDUFlags); void
+ CDUReceive(Sensor* Sens, unsigned char functioncode, unsigned char* receivebuffer, Cduflags* CDUFlags); unsigned char
+ CDUPCCom(void); void
+ InitSensorArray(Sensor* sensorarray); void