

Linear Independence and Bases

1 Linear Independence

Definition 1.1. Let V be a vector space over a field F and $S \subseteq V$. We say that S is linearly dependent if there exist distinct vectors $v_1, \dots, v_n \in S$ and scalars $a_1, \dots, a_n \in F$, not all zero, such that

$$a_1v_1 + \dots + a_nv_n = 0.$$

If no such relation exists, then S is linearly independent.

Remark 1.2. 1. \emptyset is linearly independent.

2. If $0 \in S$, then S is linearly dependent.

3. S is linearly independent iff

$$a_1v_1 + \dots + a_nv_n = 0 \Rightarrow a_1 = \dots = a_n = 0.$$

Examples

Example 1.3. Let $S = \{v\}$. Then S is linearly independent if and only if $v \neq 0$.

Example 1.4. Let $S = \{v, w\}$. Then S is linearly independent if and only if neither vector is a scalar multiple of the other.

Example 1.5. In F^n , the standard vectors e_1, \dots, e_n form a linearly independent set.

Example 1.6. In $F[x]$, the set $\{x^n : n \in \mathbb{N}\}$ is linearly independent.

Example 1.7. In the vector space of continuous functions $f : \mathbb{R} \rightarrow \mathbb{R}$, the set

$$\{e^x, \sin x, \cos x\}$$

is linearly independent.

Proof. Suppose

$$ae^x + b \sin x + c \cos x = 0 \quad \text{for all } x \in \mathbb{R}.$$

If $a \neq 0$, then e^x is unbounded while $\sin x$ and $\cos x$ are bounded, a contradiction. Hence $a = 0$. Thus $b \sin x + c \cos x = 0$ for all x . Plugging in $x = 0$ gives $c = 0$, and plugging in $x = \frac{\pi}{2}$ gives $b = 0$. Therefore $a = b = c = 0$, and the set is linearly independent. \square

2 Maximal Linearly Independent Sets

Definition 2.1. A linearly independent set $S \subseteq V$ is called maximal linearly independent if for every $v \notin S$, the set $S \cup \{v\}$ is linearly dependent.

Example 2.2. In F^n , the set $\{e_1, \dots, e_n\}$ is a maximal linearly independent set.

3 Bases

Theorem 3.1 (Characterization of Bases). Let V be a vector space over F and $S \subseteq V$. The following are equivalent:

1. S is a minimal spanning set of V .
2. S is a maximal linearly independent set.
3. Every vector $v \in V$ can be written uniquely as

$$v = a_1v_1 + \cdots + a_nv_n, \quad v_i \in S.$$

Definition 3.2. A basis of V is a set $S \subseteq V$ satisfying the equivalent conditions above.