

Deep Learning

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December 18, 2019

1 Generative Adversarial Networks

2 Ensemble of Neural Networks

WGANs

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- Jensen-Shannon (JS) distance

$$JS(\mathbb{P}_r \| \mathbb{P}_g) = \frac{1}{2} (KL(\mathbb{P}_r \| \mathbb{P}_m) + KL(\mathbb{P}_g \| \mathbb{P}_m))$$

$$\text{where } \mathbb{P}_m = \frac{\mathbb{P}_r + \mathbb{P}_g}{2}.$$

- The Earth-Mover (EM) distance or Wasserstein-1

$$W(\mathbb{P}_r, \mathbb{P}_g) = \inf_{\gamma \in \Pi(\mathbb{P}_r, \mathbb{P}_g)} \mathbb{E}_{(x,y) \sim \gamma} (\|x - y\|)$$

where $\Pi(\mathbb{P}_r, \mathbb{P}_g)$ denotes the set of all joint distributions $\gamma(x, y)$ whose marginals are respectively \mathbb{P}_r and \mathbb{P}_g .

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- Only EM distance has informative gradient.

Definition 1

Let X and Y be normed vector spaces. A function $f : X \rightarrow Y$ is called

- K -Lipschitz if there exists a real constant $K > 0$ such that, for all x_1 and x_2 in X

$$\|f(x_1) - f(x_2)\| \leq K\|x_1 - x_2\|.$$

- local Lipschitz if for every $x \in X$ there exists a neighbourhood U of x such that f is Lipschitz on U .

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Theorem 1

If function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ has bounded gradient, then f is a Lipschitz function.

Theorem 1. *Let \mathbb{P}_r be a fixed distribution over \mathcal{X} . Let Z be a random variable (e.g Gaussian) over another space \mathcal{Z} . Let $g : \mathcal{Z} \times \mathbb{R}^d \rightarrow \mathcal{X}$ be a function, that will be denoted $g_\theta(z)$ with z the first coordinate and θ the second. Let \mathbb{P}_θ denote the distribution of $g_\theta(Z)$. Then,*

- 1. If g is continuous in θ , so is $W(\mathbb{P}_r, \mathbb{P}_\theta)$.*
- 2. If g is locally Lipschitz and satisfies regularity assumption 1, then $W(\mathbb{P}_r, \mathbb{P}_\theta)$ is continuous everywhere, and differentiable almost everywhere.*
- 3. Statements 1-2 are false for the Jensen-Shannon divergence $JS(\mathbb{P}_r, \mathbb{P}_\theta)$ and all the KLs.*

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Corollary 1. *Let g_θ be any feedforward neural network^A parameterized by θ , and $p(z)$ a prior over z such that $\mathbb{E}_{z \sim p(z)}[\|z\|] < \infty$ (e.g. Gaussian, uniform, etc.). Then assumption 1 is satisfied and therefore $W(\mathbb{P}_r, \mathbb{P}_\theta)$ is continuous everywhere and differentiable almost everywhere.*

Theorem 2. *Let \mathbb{P} be a distribution on a compact space \mathcal{X} and $(\mathbb{P}_n)_{n \in \mathbb{N}}$ be a sequence of distributions on \mathcal{X} . Then, considering all limits as $n \rightarrow \infty$,*

1. *The following statements are equivalent*

- $\delta(\mathbb{P}_n, \mathbb{P}) \rightarrow 0$ with δ the total variation distance.
- $JS(\mathbb{P}_n, \mathbb{P}) \rightarrow 0$ with JS the Jensen-Shannon divergence.

2. *The following statements are equivalent*

- $W(\mathbb{P}_n, \mathbb{P}) \rightarrow 0$.
- $\mathbb{P}_n \xrightarrow{\mathcal{D}} \mathbb{P}$ where $\xrightarrow{\mathcal{D}}$ represents convergence in distribution for random variables.

3. $KL(\mathbb{P}_n \| \mathbb{P}) \rightarrow 0$ or $KL(\mathbb{P} \| \mathbb{P}_n) \rightarrow 0$ imply the statements in (1).

4. *The statements in (1) imply the statements in (2).*

Summary 1

Wasserstein (or EM) loss for neural networks is continuous and differentiable almost everywhere. Moreover, Convergence in KL implies convergence in TV and JS which implies convergence in EM.

Kantorovich-Rubinstein duality 2

$$W(\mathbb{P}_r, \mathbb{P}_\theta) = \sup_{\|f\|_L \leq 1} (\mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)])$$

where the supremum is over all the 1-Lipschitz functions $f : \mathcal{X} \rightarrow \mathbb{R}$.

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Note that if we replace $\|f\|_L \leq 1$ for $\|f\|_L \leq K$ (consider K -Lipschitz for some constant K) then we end up with $K \cdot W(\mathbb{P}_r, \mathbb{P}_g)$.

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Note that if we replace $\|f\|_L \leq 1$ for $\|f\|_L \leq K$ (consider K -Lipschitz for some constant K) then we end up with $K \cdot W(\mathbb{P}_r, \mathbb{P}_g)$.

Therefore, if we have a parameterized family of functions $\{f_w\}_{w \in \mathcal{W}}$ that are all K -Lipschitz for some K , we could consider solving the problem

$$\max_{w \in \mathcal{W}} (\mathbb{E}_{x \sim \mathbb{P}_r} [f_w(x)] - \mathbb{E}_{z \sim p(z)} [f_w(g_\theta(z))])$$

for estimating $W(\mathbb{P}_r, \mathbb{P}_\theta)$.

Theorem 3. *Let \mathbb{P}_r be any distribution. Let \mathbb{P}_θ be the distribution of $g_\theta(Z)$ with Z a random variable with density p and g_θ a function satisfying assumption 1. Then, there is a solution $f : \mathcal{X} \rightarrow \mathbb{R}$ to the problem*

$$\max_{\|f\|_L \leq 1} \mathbb{E}_{x \sim \mathbb{P}_r}[f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta}[f(x)]$$

and we have

$$\nabla_\theta W(\mathbb{P}_r, \mathbb{P}_\theta) = -\mathbb{E}_{z \sim p(z)}[\nabla_\theta f(g_\theta(z))]$$

when both terms are well-defined.

Algorithm 1 WGAN, our proposed algorithm. All experiments in the paper used the default values $\alpha = 0.00005$, $c = 0.01$, $m = 64$, $n_{\text{critic}} = 5$.

Require: : α , the learning rate. c , the clipping parameter. m , the batch size. n_{critic} , the number of iterations of the critic per generator iteration.

Require: : w_0 , initial critic parameters. θ_0 , initial generator's parameters.

```
1: while  $\theta$  has not converged do
2:   for  $t = 0, \dots, n_{\text{critic}}$  do
3:     Sample  $\{x^{(i)}\}_{i=1}^m \sim \mathbb{P}_r$  a batch from the real data.
4:     Sample  $\{z^{(i)}\}_{i=1}^m \sim p(z)$  a batch of prior samples.
5:      $g_w \leftarrow \nabla_w [\frac{1}{m} \sum_{i=1}^m f_w(x^{(i)}) - \frac{1}{m} \sum_{i=1}^m f_w(g_\theta(z^{(i)}))]$ 
6:      $w \leftarrow w + \alpha \cdot \text{RMSPProp}(w, g_w)$ 
7:      $w \leftarrow \text{clip}(w, -c, c)$ 
8:   end for
9:   Sample  $\{z^{(i)}\}_{i=1}^m \sim p(z)$  a batch of prior samples.
10:   $g_\theta \leftarrow -\nabla_\theta \frac{1}{m} \sum_{i=1}^m f_w(g_\theta(z^{(i)}))$ 
11:   $\theta \leftarrow \theta - \alpha \cdot \text{RMSPProp}(\theta, g_\theta)$ 
12: end while
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- we can train the critic till optimality,
- if the clipping parameter is large, then it can take a long time for any weights to reach their limit, thereby making it harder to train the critic till optimality. If the clipping is small, this can easily lead to vanishing gradients when the number of layers is big.

- A meaningful loss metric that correlates with the generator's convergence and sample quality,

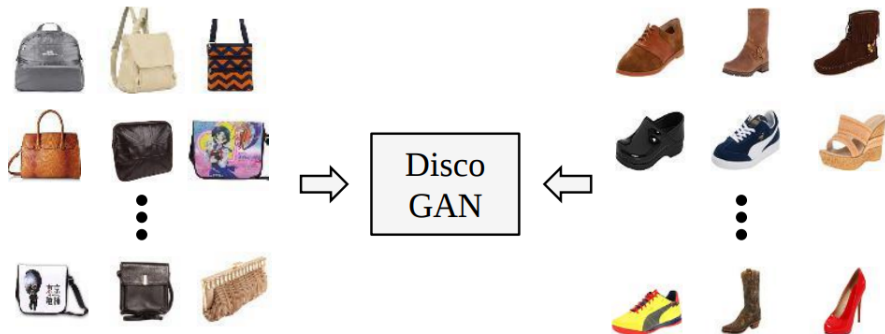
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- slower to converge than KL loss.

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Denote our domains by A and B . Also denote by G_{AB} and G_{BA} our generators and let D_A and D_B are discriminators of domains A and B respectively. Now denote

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$$L_D = L_{D_A} + L_{D_B}.$$

Huber Loss

$$L_{\delta}(y, f(x)) = \begin{cases} \frac{1}{2} (y - f(x))^2, & \text{for } |y - f(x)| \leq \delta \\ \delta |y - f(x)| - \frac{1}{2}\delta^2, & \text{otherwise.} \end{cases}$$

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Ensemble Learning

- ◆ Ensemble learning that combines the decisions of multiple hypotheses is some of the strongest existing machine learning methods.

