

Appendix HW#5.

Problem 3. Given θ , the random variable X has a binomial distribution with $n = 3$ and probability of success θ . If the prior density of θ is

$$p(\theta) = \begin{cases} k & \text{if } \frac{1}{2} < \theta < 1 \\ 0 & \text{otherwise} \end{cases}$$

what is the Bayes estimate of θ for an absolute error loss if $X = 1$.

Solution. We know that prior distribution of θ is the uniform distribution over the interval $\left(\frac{1}{2}, 1\right)$. Therefore, we have

$$p(\theta) = \begin{cases} 2, & \text{if } \theta \in \left[\frac{1}{2}, 1\right] \\ 0, & \text{otherwise} \end{cases}$$

X has a binomial distribution with $n = 3$ and probability of success θ . Therefore, likelihood function has the following form:

$$f(X = 1/\theta) = \begin{cases} \binom{3}{1} \theta^1 (1 - \theta)^2, & \text{if } \theta \in \left[\frac{1}{2}, 1\right] \\ 0, & \text{otherwise} \end{cases}$$

Let us calculate joint density function:

$$f(X = 1, \theta) = f(X = 1/\theta) \cdot p(\theta) = \begin{cases} 6 \theta^1 (1 - \theta)^2, & \text{if } \theta \in \left[\frac{1}{2}, 1\right] \\ 0, & \text{otherwise} \end{cases}$$

Calculate marginal density function. By definition, we have

$$f(X = 1) = \int_{-\infty}^{+\infty} f(X = 1, \theta) d\theta = \int_{1/2}^1 f(X = 1, \theta) d\theta = 6 \int_{1/2}^1 \theta (1 - \theta)^2 d\theta = \frac{5}{32}$$

Posterior density function has the form:

$$p(\theta|X = 1) = \frac{f(X = 1|\theta) \cdot p(\theta)}{f(X = 1)} = \begin{cases} \frac{6 \cdot 32}{5} \cdot \theta (1 - \theta)^2 & \text{if } \theta \in \left[\frac{1}{2}, 1\right] \\ 0, & \text{otherwise} \end{cases}$$

Bayes estimator for θ for absolute error loss function is the posterior median, that is

$$\int_{1/2}^{\hat{\theta}} p(\theta|X=1) d\theta = \frac{1}{2}$$

or

$$\frac{6 \cdot 32}{5} \cdot \int_{1/2}^{\hat{\theta}} (\theta - 2\theta^2 + \theta^3) d\theta = \frac{1}{2}.$$

We obtain the following equation

$$96 \hat{\theta}^4 - 256 \hat{\theta}^3 + 192 \hat{\theta}^2 - 27 = 0$$

Thus we obtain

$$\hat{\theta} \approx 0.62065 \quad \text{and} \quad -0.31$$

and thus

$$\hat{\theta} = 0.62065.$$

Let $f(x_1, x_2, \dots, x_m)$ be a joint density function of the component of m -dimensional random vector. We consider the problem of constructing a set of m -dimensional vectors corresponding to a probability distribution with a density function f , that is, constructing a sample with a given distribution. We denote by B the set of points $x \in \mathbf{R}^m$ such that $f(x_1, x_2, \dots, x_m) > 0$ for $(x_1, \dots, x_m) \in B$ and $f(x_1, x_2, \dots, x_m) = 0$ if $(x_1, x_2, \dots, x_m) \notin B$.

Consider a sequence of m -dimensional random vectors $X_0, X_1, \dots, X_n, \dots$ that make up the Markov chain. For this Markov chain and for the Borel set $A \subset \mathbf{R}^m$, we denote by $P^{(n)}((x_1, x_2, \dots, x_m), A)$ the transition probability from state (x_1, x_2, \dots, x_m) to the set A in exactly n steps (the condition that the set A is Borel is imposed so that it can be integrated over this set).

If for any Borel set $A \subset \mathbf{R}^m$ for any or almost any (x_1, x_2, \dots, x_m) we have

$$P^{(n)}(x, A) \rightarrow \int_A f(y_1, y_2, \dots, y_m) dy_1 dy_2 \dots dy_m, \quad \text{for} \quad n \rightarrow +\infty \quad (36.1)$$

then realized the Markov chain, we can get a set of m -dimensional vectors (sample), corresponding to the probability distribution with the density function f . Of course, to satisfy condition (36.1), the Markov chain $X_0, X_1, \dots, X_n, \dots$ must somehow be constructed using the function f . MCMC are used when working not only with continuous but also with discrete multidimensional distributions.

§36.1. METROPOLIS ALGORITHM.

The Markov chain $X_0, X_1, \dots, X_n, \dots$ is sought among those, for which the transition probabilities in one step for any $(x_1, x_2, \dots, x_m) \in B$ and for any Borel set $A \subset \mathbf{R}^m$ have the form:

$$P^{(1)}((x_1, x_2, \dots, x_m), A) = g(x_1, x_2, \dots, x_m) \cdot I_A(x_1, x_2, \dots, x_m) + \int_A h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) dy_1 dy_2 \dots dy_m. \quad (36.2)$$

Here $I_A(x_1, x_2, \dots, x_m)$ is the indicator of a set A , that is $I_A(x_1, x_2, \dots, x_m) = 1$, if $(x_1, x_2, \dots, x_m) \in A$, and $I_A(x_1, x_2, \dots, x_m) = 0$, if $(x_1, x_2, \dots, x_m) \notin A$. It is obvious that

$$g(x_1, x_2, \dots, x_m) = 1 - \int_{\mathbf{R}^m} h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) dy_1 dy_2 \dots dy_m, \quad (36.3)$$

since

$$P^{(1)}((x_1, x_2, \dots, x_m), \mathbf{R}^m) = 1.$$

Function $h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m))$ is satisfied the following reversibility condition:

$$\begin{aligned} f(x_1, x_2, \dots, x_m) \cdot h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = \\ = f(y_1, y_2, \dots, y_m) \cdot h((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) \end{aligned} \quad (36.4)$$

for any $(x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m) \in \mathbf{R}^m$.

Let's prove that from reversibility condition (36.4) follows the invariance condition:

$$\int_A f(y_1, y_2, \dots, y_m) dy_1 dy_2 \dots dy_m = \int_{\mathbf{R}^m} P^{(1)}(x_1, x_2, \dots, x_m, A) f(x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m \quad (36.5)$$

for any Borel set $A \subset \mathbf{R}^m$.

Really, using (36.4) and (36.3) we get:

$$\begin{aligned} & \int_{\mathbf{R}^m} P^{(1)}(x_1, x_2, \dots, x_m, A) f(x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m = \\ & = \int_{\mathbf{R}^m} f(x_1, x_2, \dots, x_m) g(x_1, x_2, \dots, x_m) I_A(x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m + \\ & + \int_{\mathbf{R}^m} \int_A f(x_1, x_2, \dots, x_m) h(x_1, x_2, \dots, x_m, y_1, y_2, \dots, y_m) dy_1 dy_2 \dots dy_m dx_1 dx_2 \dots dx_m = \end{aligned}$$

$$\begin{aligned}
&= \int_A f(x_1, x_2, \dots, x_m) g(x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m + \\
&+ \int_{R^m} \int_A f(y_1, y_2, \dots, y_m) h(y_1, y_2, \dots, y_m, x_1, x_2, \dots, x_m) dy_1 dy_2 \dots dy_m dx_1 dx_2 \dots dx_m = \\
&= \int_A f(x_1, x_2, \dots, x_m) g(x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m + \\
&+ \int_A \int_{R^m} f(y_1, y_2, \dots, y_m) h(y_1, y_2, \dots, y_m, x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m dy_1 dy_2 \dots dy_m = \\
&= \int_A f(x_1, x_2, \dots, x_m) g(x_1, x_2, \dots, x_m) dx_1 dx_2 \dots dx_m + \\
&+ \int_A f(y_1, y_2, \dots, y_m) (1 - g(y_1, y_2, \dots, y_m)) dy_1 dy_2 \dots dy_m = \int_A f(y_1, y_2, \dots, y_m) dy_1 dy_2 \dots dy_m
\end{aligned}$$

that is (36.5).

It is interesting that the invariance condition (36.5) is the basic for validity of (36.1). In Metropolis algorithm very important is nonnegative function

$$c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)),$$

which we choose such that

$$\int_{R^m} c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) dy_1 dy_2 \dots dy_m = 1 \quad (36.6)$$

for any $(x_1, x_2, \dots, x_m) \in R^m$.

Next we denote

$$\begin{aligned}
&\alpha((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = \\
&\begin{cases} \min \left(1, \frac{f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m))}{f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m))} \right) & \text{if } f(x_1, \dots, x_m) c((x_1, \dots, x_m), (y_1, \dots, y_m)) > 0 \\ 1, & \text{if } f(x_1, \dots, x_m) c((x_1, \dots, x_m), (y_1, \dots, y_m)) = 0. \end{cases}
\end{aligned}$$

We note that if $(x_1, x_2, \dots, x_m) \in B$, $(y_1, y_2, \dots, y_m) \notin B$ and $c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) > 0$, then $\alpha((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = 0$.

Let us prove that the function

$$h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) \alpha((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m))$$

satisfy to reversibility condition (36.4).

We choose the points (x_1, x_2, \dots, x_m) and (y_1, y_2, \dots, y_m) .

Assume that $f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = 0$. In this case the left-hand side of (36.4) equal to zero. But if $f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = 0$ then and the right-hand side of (36.4) equal to zero.

If $f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) > 0$, then $\alpha((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = 0$ and therefore the right-hand side of (36.4) is equal to zero. Therefore, if

$$f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = 0,$$

then condition (36.4) is fulfilled.

Now let $f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) > 0$. If

$$f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) < f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)),$$

then

$$\alpha((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = 1,$$

therefore we have

$$\alpha((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = \frac{f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m))}{f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m))}.$$

Thus we have

$$\begin{aligned} f(x_1, x_2, \dots, x_m) h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) &= f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = \\ &= f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) \cdot \alpha((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = \\ &= f(y_1, y_2, \dots, y_m) h((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)), \end{aligned}$$

and condition (36.4) is fulfilled.

If

$$f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) \geq f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)),$$

then

$$\alpha((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = 1,$$

therefore we have

$$\alpha((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = \frac{f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m))}{f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m))}.$$

Thus we have

$$\begin{aligned} & f(x_1, x_2, \dots, x_m) h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = \\ &= f(x_1, x_2, \dots, x_m) c((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) \alpha((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m)) = \\ &= f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = \\ &= f(y_1, y_2, \dots, y_m) c((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) \alpha((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)) = \\ &= f(y_1, y_2, \dots, y_m) h((y_1, y_2, \dots, y_m), (x_1, x_2, \dots, x_m)), \end{aligned}$$

and condition (36.4) is fulfilled. Therefore, $h((x_1, x_2, \dots, x_m), (y_1, y_2, \dots, y_m))$ defined by (36.7) satisfies the reversibility condition (36.4).

Note, that function $g(x_1, x_2, \dots, x_m)$ is constructed by formula (36.7) and takes on only the values between zero and one.