Deep Learning

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Outline

Generative Adversarial Networks

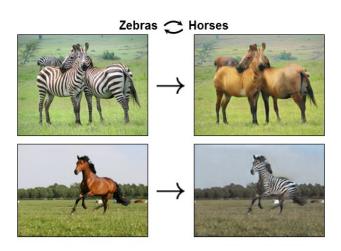
• Image-to-image translation is a class of vision and graphics problems where the goal is to learn the mapping between an input image and an output image using a training set of aligned image pairs.

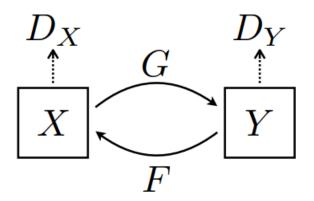
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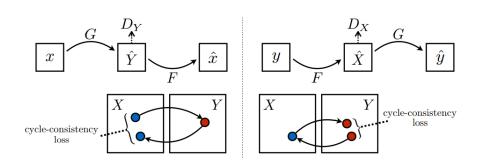
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- However, for many tasks, paired training data will not be available.
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- Our goal is to learn a mapping $G: X \to Y$ such that the distribution of images from G(X) is indistinguishable from the distribution Y.
- We will couple it with an inverse mapping $F: Y \to X$ and introduce a cycle consistency loss to enforce $F(G(X)) \approx X$.







Our loss function will be the following

$$L\left(G,F,D_{X},D_{Y}\right)=L_{GAN}\left(G,D_{Y},X,Y\right)+L_{GAN}\left(F,D_{X},Y,X\right)+\lambda L_{cyc}\left(G,F\right),$$

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$$L_{GAN}\left(G, D_{Y}, X, Y\right)$$

$$= \mathbb{E}_{y \sim p_{data}(y)} \left[\log D_{Y}\left(y\right)\right] + \mathbb{E}_{x \sim p_{data}(x)} \left[\log \left(1 - D_{Y}\left(G\left(x\right)\right)\right)\right]$$

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$$L_{cyc}\left(\textit{G},\textit{F}\right) = \mathbb{E}_{\textit{x} \sim \textit{p}_{\textit{data}}\left(\textit{x}\right)}\left[\|\textit{F}\left(\textit{G}\left(\textit{x}\right)\right) - \textit{x}\|_{1}\right] + \mathbb{E}_{\textit{y} \sim \textit{p}_{\textit{data}}\left(\textit{y}\right)}\left[\|\textit{G}\left(\textit{F}\left(\textit{y}\right)\right) - \textit{y}\|_{1}\right]$$

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$$L_{GAN}(F, D_X, Y, X)$$

$$= \mathbb{E}_{x \sim p_{data}(x)} \left[\log D_X(x) \right] + \mathbb{E}_{y \sim p_{data}(y)} \left[\log \left(1 - D_X(F(y)) \right) \right]$$

$$L_{cyc}(G, F) = \mathbb{E}_{x \sim p_{data}(x)} [\|F(G(x)) - x\|_1] + \mathbb{E}_{y \sim p_{data}(y)} [\|G(F(y)) - y\|_1]$$

We aim to solve

$$G^*, F^* = \arg\min_{G, F} \max_{D_X, D_Y} L(G, F, D_X, D_Y)$$

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• Jensen-Shannon (JS) distance

$$JS(\mathbb{P}_r \| \mathbb{P}_g) = \frac{1}{2} \left(KL(\mathbb{P}_r \| \mathbb{P}_m) + KL(\mathbb{P}_g \| \mathbb{P}_m) \right)$$

where
$$\mathbb{P}_m = rac{\mathbb{P}_r + \mathbb{P}_g}{2}$$
.



• The Earth-Mover (EM) distance or Wasserstein-1

$$W\left(\mathbb{P}_{r},\mathbb{P}_{g}\right)=\inf_{\gamma\in\Pi\left(\mathbb{P}_{r},\mathbb{P}_{g}\right)}\mathbb{E}_{\left(x,y\right)\sim\gamma}\left(\left\|x-y\right\|\right)$$

where $\Pi(\mathbb{P}_r, \mathbb{P}_g)$ denotes the set of all joint distributions $\gamma(x, y)$ whose marginals are respectively \mathbb{P}_r and \mathbb{P}_g .

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$$W(\mathbb{P}_0, \mathbb{P}_{\theta}) = |\theta|$$



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- All distances other than EM are not continuous.
- When $\theta_t \to 0$, the sequence $(\mathbb{P}_{\theta_t})_{t \in \mathbb{N}}$ converges to \mathbb{P}_0 under the EM distance, but does not converge at all under either the JS, KL, reverse KL or TV divergences.
- Only EM distance has informative gradient.

Lipschitz functions

Definition 1

Let X and Y are normed vector spaces. A function $f: X \to Y$ is called

• K-Lipschitz if there exists a real constant K>0 such that, for all x_1 and x_2 in X

$$||f(x_1) - f(x_2)|| \le K||x_1 - x_2||.$$

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Theorem 1

If function $f: \mathbb{R}^n \to \mathbb{R}$ has bounded gradient, then f is a Lipschitz function.

Theorem 1. Let \mathbb{P}_r be a fixed distribution over \mathcal{X} . Let Z be a random variable (e.g Gaussian) over another space \mathcal{Z} . Let $g: \mathcal{Z} \times \mathbb{R}^d \to \mathcal{X}$ be a function, that will be denoted $g_{\theta}(z)$ with z the first coordinate and θ the second. Let \mathbb{P}_{θ} denote the distribution of $g_{\theta}(Z)$. Then,

- 1. If g is continuous in θ , so is $W(\mathbb{P}_r, \mathbb{P}_{\theta})$.
- 2. If g is locally Lipschitz and satisfies regularity assumption 1, then $W(\mathbb{P}_r, \mathbb{P}_{\theta})$ is continuous everywhere, and differentiable almost everywhere.
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Corollary 1. Let g_{θ} be any feedforward neural network⁴ parameterized by θ , and p(z) a prior over z such that $\mathbb{E}_{z \sim p(z)}[\|z\|] < \infty$ (e.g. Gaussian, uniform, etc.). Then assumption 1 is satisfied and therefore $W(\mathbb{P}_r, \mathbb{P}_{\theta})$ is continuous everywhere and differentiable almost everywhere.

Theorem 2. Let \mathbb{P} be a distribution on a compact space \mathcal{X} and $(\mathbb{P}_n)_{n\in\mathbb{N}}$ be a sequence of distributions on \mathcal{X} . Then, considering all limits as $n\to\infty$,

- 1. The following statements are equivalent
 - $\delta(\mathbb{P}_n, \mathbb{P}) \to 0$ with δ the total variation distance.
 - $JS(\mathbb{P}_n, \mathbb{P}) \to 0$ with JS the Jensen-Shannon divergence.
- 2. The following statements are equivalent
 - $W(\mathbb{P}_n, \mathbb{P}) \to 0$.
 - $\mathbb{P}_n \xrightarrow{\mathcal{D}} \mathbb{P}$ where $\xrightarrow{\mathcal{D}}$ represents convergence in distribution for random variables.
- 3. $KL(\mathbb{P}_n||\mathbb{P}) \to 0$ or $KL(\mathbb{P}||\mathbb{P}_n) \to 0$ imply the statements in (1).
- 4. The statements in (1) imply the statements in (2).



Summary 1

Wasserstein (or EM) loss for neural networks is continuous and differentiable almost everywhere. Moreover, Convergence in KL implies convergence in TV and JS which implies convergence in EM.

Training

Kantorovich-Rubinstein duality 2

$$W\left(\mathbb{P}_{r}, \mathbb{P}_{\theta}\right) = \sup_{\|f\|_{L} \leq 1} \left(\mathbb{E}_{x \sim \mathbb{P}_{r}}\left[f\left(x\right)\right] - \mathbb{E}_{x \sim \mathbb{P}_{\theta}}\left[f\left(x\right)\right]\right)$$

where the supremum is over all the 1-Lipschitz functions $f: \mathcal{X} \to \mathbb{R}$.

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Note that if we replace $||f||_L \leq 1$ for $||f||_L \leq K$ (consider K-Lipschitz for some constant K) then we end up with $K \cdot W(\mathbb{P}_r, \mathbb{P}_g)$.

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Therefore, if we have a parameterized family of functions $\{f_w\}_{w\in\mathcal{W}}$ that are all K-Lipschitz for some K, we could consider solving the problem

$$\max_{w \in \mathcal{W}} \left(\mathbb{E}_{x \sim \mathbb{P}_r} \left[f_w \left(x \right) \right] - \mathbb{E}_{z \sim p(z)} \left[f_w \left(g_\theta \left(z \right) \right) \right] \right)$$

for estimating $W(\mathbb{P}_r, \mathbb{P}_{\theta})$.

