

	u	v	w
ρ	$a \sin(\phi) \cos(\theta)$	$b \sin(\phi) \sin(\theta)$	$c \cos(\phi)$
θ	$-a \sin(\phi) \sin(\theta)$	$b \cos(\phi) \cos(\theta)$	0
ϕ	$a \cos(\phi) \cos(\theta)$	$b \cos(\phi) \sin(\theta)$	$-c \sin(\phi)$

equation of ellipsoid = $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$

equation in u, v, w space = $u^2 + v^2 + w^2 = 1$

where $u = \frac{x}{a}$ $v = \frac{y}{b}$ $w = \frac{z}{c}$

Jacobian transformation

Turn equation into spherical coordinates

u	v
$\rho \sin \phi \cos \theta = \frac{x}{a}$	$\rho \sin \phi \sin \theta = \frac{y}{b}$
w	
$\rho \cos(\phi) = \frac{z}{c}$	

Determinant

$$\int_{\phi_1}^{\phi_2} \int_{\theta_1}^{\theta_2} \int_0^1$$

$|Jacobian| d\rho d\theta d\phi = \text{Volume} \Rightarrow$ Definite integral

★ User specifies values for $a, b, c, \phi_1, \phi_2, \theta_1, \theta_2$ ★

$$\text{Volume} = -\frac{1}{3} [abc (\cos(\phi_2) - \cos(\phi_1))] [\theta_2 - \theta_1]$$

```
clear
clear all
clc

syms phi theta p a b c phiStart phiEnd thetaStart thetaEnd

x = (p*sin(phi)*cos(theta))*a
y = (p*sin(phi)*sin(theta))*b
z = (p*cos(phi))*c

jacobian = [diff(x, p) diff(x, theta) diff(x, phi); diff(y, p) ...
            diff(y, theta) diff(y, phi); diff(z, p) diff(z, theta) diff(z, phi);]

% absolute value of the determinant (does not work with absolute value)
determ = -1 * det(jacobian)

% limits always from 0 to 1 for p
inner = int(determ, p, 0, 1);

% user specified limits phi
middle = int(inner, phi, phiStart, phiEnd);

% user specified limits theta
outer = int(middle, theta, thetaStart, thetaEnd)
```

```
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clear all
clc

syms phi theta p a b c phiStart phiEnd thetaStart thetaEnd

u = (p*sin(phi)*cos(theta))*a
v = (p*sin(phi)*sin(theta))*b
w = (p*cos(phi))*c

jacobian = [diff(u, p) diff(u, theta) diff(u, phi); diff(v, p) ...
            diff(v, theta) diff(v, phi); diff(w, p) diff(w, theta) diff(w, phi);]

% absolute value of the determinant (does not work with absolute value)
determ = -1 * det(jacobian)

% limits always from 0 to 1 for p
inner = int(determ, p, 0, 1);

% user specified limits phi
middle = int(inner, phi, phiStart, phiEnd);

% user specified limits theta
outer = int(middle, theta, thetaStart, thetaEnd)
```