

```
u =
a*p*cos(theta)*sin(phi)
b*p*sin(phi)*sin(theta)
c*p*cos(phi)
jacobian =
{ a*cos(theta)*sin(phi), -a*p*sin(phi)*sin(theta), a*p*cos(phi)*cos(theta)]
[ b*sin(phi)*sin(theta), b*p*cos(theta)*sin(phi), b*p*cos(phi)*sin(theta)]
                                                              -c*p*sin(phi)]
                                                 0,
             c*cos(phi),
determ =
a*b*c*p^2*cos(phi)^2*cos(theta)^2*sin(phi) + a*b*c*p^2*cos(phi)^2*sin(phi)*sin(theta)^2 + \checkmark
a*b*c*p^2*cos(theta)^2*sin(phi)^3 + a*b*c*p^2*sin(phi)^3*sin(theta)^2
outer =
-(a*b*c*(cos(phiEnd) - cos(phiStart))*(thetaEnd - thetaStart))/3
>>
```

```
clear
clear all
clc
syms phi theta p a b c phiStart phiEnd thetaStart thetaEnd
u = (p*sin(phi)*cos(theta))*a
v = (p*sin(phi)*sin(theta))*b
w = (p*cos(phi))*c
jacobian = [diff(u, p) diff(u, theta) diff(u, phi); diff(v, p) ...
    diff(v, theta) diff(v, phi); diff(w, p) diff(w, theta) diff(w, phi);]
's absolute value of the determinant (does not work with absolute value)
determ = -1 * det(jacobian)
% limits always from 0 to 1 for p
inner = int(determ, p, 0, 1);
Mauser specified limits phi
middle = int(inner, phi, phiStart, phiEnd);
* user specified limits theta
outer = int(middle, theta, thetaStart, thetaEnd)
```