

Clustering, Mixture Models, and the EM Algorithm

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Agenda

- ▶ Clustering
- ▶ Two Component Mixture Model
- ▶ Latent Variable
- ▶ EM Algorithm

What will you learn in this lecture

- ▶ Clustering
- ▶ Importance of mixture models
- ▶ Simple illustrations of mixture models
- ▶ We will learn about the two component mixture model (and extension)
- ▶ Will learn about latent variables
- ▶ Two component mixture model (and extension)
- ▶ EM algorithm

Clustering

Clustering is an **unsupervised method** that divides up data into groups (clusters), so that points in any one group are more “similar” to each other than to points outside the group

Clustering methods (that we have covered)

- ▶ Fuzzy clustering (such as deterministic entity resolution or blocking)
- ▶ Overlapping clustering (such as locality sensitive hashing)
- ▶ Fellegi Sunter method (technically a mixture model, stay tuned)

Clustering methods (that we have not covered)

- ▶ Mixture models, such as Gaussian (GMMs)
- ▶ K-means
- ▶ K-medoids
- ▶ Hierarchical clustering
- ▶ Among many others

Application areas

- ▶ Clustering temperatures to identify weather patterns, grouping individuals based on height and weight similarities.
- ▶ Clustering customers based on satisfaction levels (ordinal) or grouping individuals based on gender (categorical).
- ▶ Clustering stock price movements to identify similar trends, grouping temperature readings based on seasonal patterns.
- ▶ Clustering GPS coordinates to identify spatial patterns, grouping locations on a map based on features.

Application areas

- ▶ Clustering users in a social network or data based based on their connections (edge structure), grouping academic papers based on citation patterns.
- ▶ Clustering articles based on topics, grouping emails by subject matter.
- ▶ Clustering photographs by content, grouping medical images based on visual features.
- ▶ Clustering music tracks by genre, grouping speech recordings by language.
- ▶ Clustering surveillance footage to identify similar activities, grouping video clips by visual similarities.

Importance

- ▶ First proposed by Karl Pearson (1984) and analyzed on crab data.
- ▶ Applications: “agriculture, astronomy, bioinformatics, biology, economics, engineering, genetics, imaging, marketing, medicine, neuroscience, psychiatry, and psychology, among many other fields in the biological, physical, and social sciences”. McLachlan et. al (2019).
- ▶ One of the methods in machine learning is **topic modeling**, which identifies “topics” in collections of documents/webpages.
- ▶ Topic modeling relies on mixtures models.

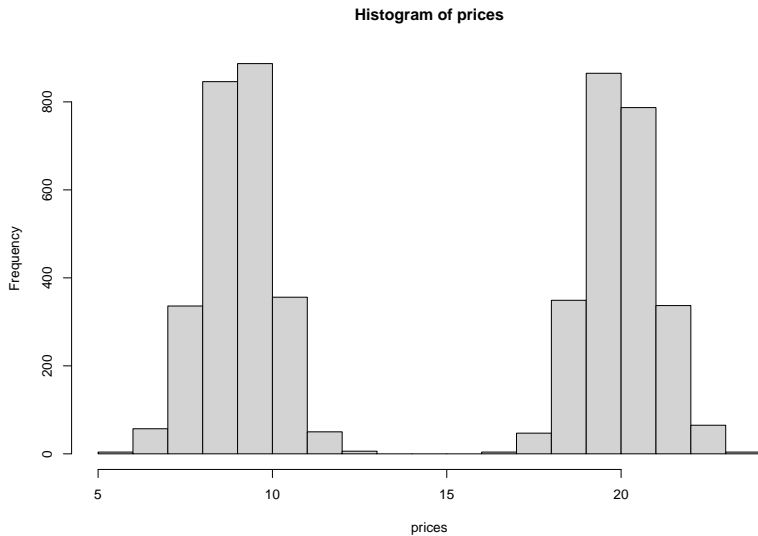
Motivation

- ▶ Suppose we want to simulate the price of a randomly chosen book.
- ▶ Paperbacks are often cheaper than hardbacks, so let's model them separately.
- ▶ Model the price of a book as a mixture model.
- ▶ There will be two components (or clusters) in our model – one for paperbacks and one for hardbacks.

Model

- ▶ Paperback distribution: $N(9, 1)$
- ▶ Hardback distribution: $N(20, 2)$
- ▶ Assume that there's a 50% chance of choosing a paperback and 50% of choosing hardback.

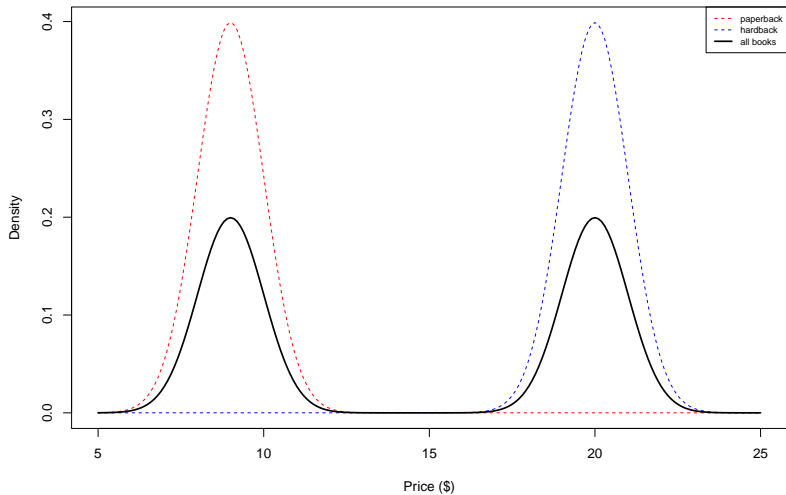
Motivation



Motivation

- ▶ Are the prices of books unimodal or bimodal?
- ▶ Suppose you would want to predict the price of a book. Would its distribution be Normal or something else based on the the histogram.

Motivation



Motivation

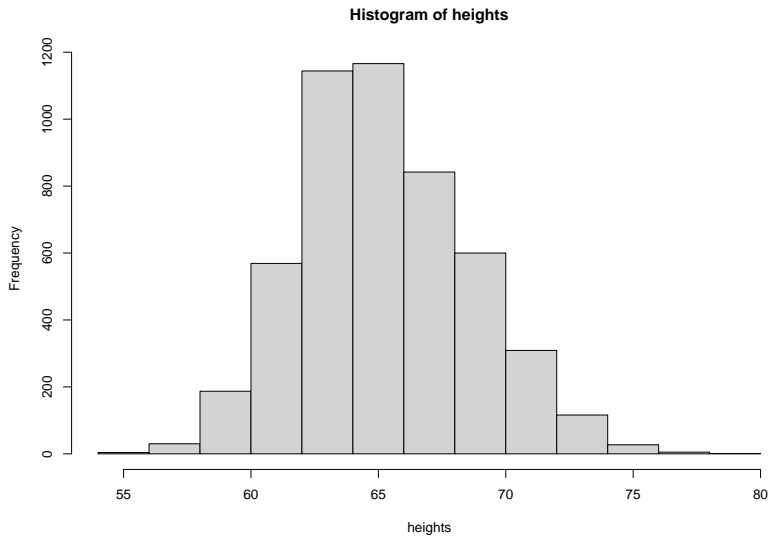
Now assume our data are the heights of students at University X.

Assume the height of a randomly chosen male is normally distributed with a mean equal to 5'9 and a standard deviation of 2.5 inches.

Assume the height of a randomly chosen female is $N(5'4, 2.5)$.

Assume that 75% of the population is female and 25% is male.

Motivation

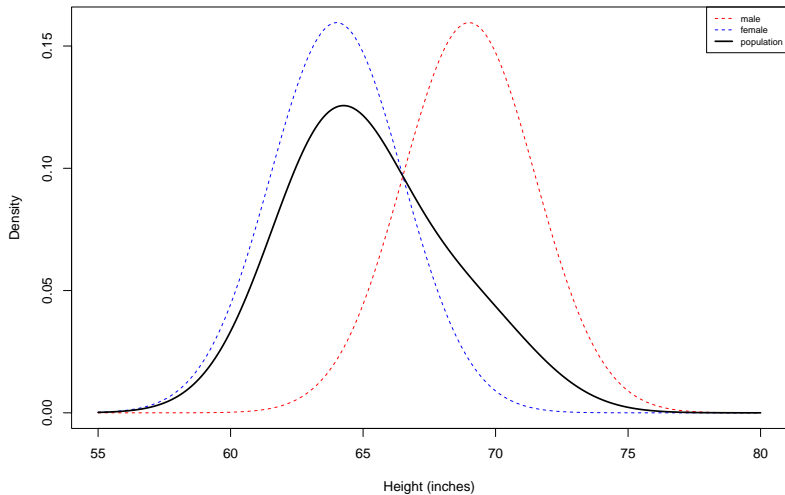


Motivation

The histogram is now unimodal.

Are heights normally distributed (assuming this model)? Let's investigate!

Motivation



Motivation

The Gaussian mixture model is unimodal because there is so much overlap between the two densities.

In this example, observe that the population density is not symmetric, and therefore not normally distributed.

Goal

The goal of this module is to introduce **mixture models**, which are commonly used in applications in classical and modern machine learning.

We will do this using a **latent variable**.

Background

A **latent variable** is the true version of the state of a random variable that is unknown and not directly observed.¹

¹We will not delve into the properties of latent variables in this course.

Mixture models can be viewed as probabilistic clustering

- ▶ Mixture models put similar data points into “clusters”.
- ▶ This is appealing as we can potentially compare different probabilistic clustering methods by how well they predict (under cross-validation). We will not explore this in this particular lecture.
- ▶ This contrasts other methods such as k-means and hierarchical clustering as they produce clusters (and not predictions), so it's difficult to test if they are correct/incorrect.²

²Explore looking at these on your own and see if you can determine their limitations practically, compared to other machine learning models.

Two-component mixture model

Assume that both mixture components have the same precision, $\lambda = 1/\sigma^2$, which is fixed and known.

Let π be the mixture proportion for the first component.

Then the two-component Normal mixture model is:

$$X_1, \dots, X_n \mid \mu, \pi \sim F(\mu, \pi) \quad (1)$$

where $F(\mu, \pi)$ is the distribution with p.d.f.

$$f(x \mid \mu, \pi) = (1 - \pi)\mathcal{N}(x \mid \mu_0, \lambda^{-1}) + \pi\mathcal{N}(x \mid \mu_1, \lambda^{-1}).$$

Likelihood

The likelihood is

$$\begin{aligned} p(x_{1:n} | \mu, \pi) &= \prod_{i=1}^n f(x_i | \mu, \pi) \\ &= \prod_{i=1}^n \left[(1 - \pi) \mathcal{N}(x_i | \mu_0, \lambda^{-1}) + \pi \mathcal{N}(x_i | \mu_1, \lambda^{-1}) \right]. \end{aligned}$$

Likelihood

What do you notice about the likelihood function?

$$\begin{aligned} p(x_{1:n} | \mu, \pi) &= \prod_{i=1}^n f(x_i | \mu, \pi) \\ &= \prod_{i=1}^n \left[(1 - \pi) \mathcal{N}(x_i | \mu_0, \lambda^{-1}) + \pi \mathcal{N}(x_i | \mu_1, \lambda^{-1}) \right]. \end{aligned}$$

Likelihood

The **likelihood** is very complicated function of μ and π .

This makes working with it directly to find the MLE (or other estimates) difficult.

Thus, we will rewrite the likelihood using **latent variables**.

Latent allocation variables to the rescue!

Define an equivalent model that includes latent “allocation” variables Z_1, \dots, Z_n .

These indicate which mixture component each data point comes from—that is, Z_i indicates whether subject i is from component 1 or 2.

$$X_i \mid \mu, Z \sim \mathcal{N}(\mu_{Z_i}, \lambda^{-1}) \text{ independently for } i = 1, \dots, n. \quad (2)$$

$$Z_1, \dots, Z_n \mid \mu, \pi \stackrel{iid}{\sim} \text{Bernoulli}(\pi) \quad (3)$$

How can we check that the latent allocation model is equivalent to our original model? (Exercise to complete outside of class).

Extension to k -components

Assume we observe X_1, \dots, X_n and that each X_i is sampled from one of K **mixture components**.

Associated with each random variable X_i is a latent variable (or label) $Z_i \in \{1, \dots, K\}$ which indicates which component X_i came from.

Notation

Let π_k be called **mixture proportions** or **mixture weights**, which represent the probability that X_i belongs to the k -th mixture component.

The mixture proportions are non-negative and they sum to one, $\sum_{k=1}^K \pi_k = 1$.

We call $P(X_i | Z_i = k)$ the **mixture component**, and it represents the distribution of X_i assuming it came from component k .

Law of Total Probability

From the law of total probability, it follows that

$$P(X_i = x) = \sum_{k=1}^K P(X_i = x | Z_i = k) \underbrace{P(Z_i = k)}_{\pi_k} \quad (4)$$

$$= \sum_{k=1}^K P(X_i = x | Z_i = k) \pi_k \quad (5)$$

$$= \sum_{k=1}^K \pi_k P(X_i = x | Z_i = k) \quad (6)$$

Mixture Models

For discrete random variables these mixture components can be any probability mass function $p(\cdot | Z_k)$.

For continuous random variables they can be any probability density function $f(\cdot | Z_k)$.

The corresponding pmf and pdf for the mixture model are:

$$p(x) = \sum_{k=1}^K \pi_k p(x | Z_k)$$

$$f_x(x) = \sum_{k=1}^K \pi_k f_{x|Z_k}(x | Z_k)$$

Likelihood

The likelihood of observing independent samples X_1, \dots, X_n with mixture proportion vector $\pi = (\pi_1, \pi_2, \dots, \pi_K)$ is therefore:

$$L(X_1, \dots, X_n \mid \pi) = \prod_{i=1}^n P(X_i \mid \pi) = \prod_{i=1}^n \sum_{k=1}^K P(X_i \mid Z_i = k) \pi_k$$

Estimation

Now assume we are in the Gaussian mixture model setting where the k -th component is $N(\mu_k, \sigma^2)$ and the mixture proportions are π_k .

How can we estimate $\{\mu_k, \sigma^2, \pi_k\}$ from the observed data X_1, \dots, X_n ?

Solution: EM Algorithm.

Why? The MLE is not possible to find in closed form. Think about why this is the case.

Conditional and marginal distributions

Recall that the conditional distribution $X_i|Z_i = k \sim N(\mu_k, \sigma_k^2)$, where $\pi_k = P(Z_i = k)$.

The marginal distribution of X_i is:

$$P(X_i = x) = \sum_{k=1}^K P(Z_i = k)P(X_i = x|Z_i = k) \quad (7)$$

$$= \sum_{k=1}^K \pi_k N(x \mid \mu_k, \sigma_k^2) \quad (8)$$

Note: $\sigma_k^2 = \sigma^2$ moving forward.

Joint distribution

The joint probability of observations X_1, \dots, X_n is

$$P(X_1 = x_1, \dots, X_n = x_n) = \prod_{i=1}^n \sum_{k=1}^K \pi_k N(x_i \mid \mu_k, \sigma_k^2)$$

Exercise

Show that

$$\log P(X_1, \dots, X_n \mid \mu_1, \dots, \mu_K) \quad (9)$$

$$= \log \prod_{i=1}^n P(x_i \mid \mu_1, \dots, \mu_K) \quad (10)$$

$$= \sum_{i=1}^n \log \left[\sum_{k=1}^K P(x_i \mid \pi_k, \mu_1, \dots, \mu_K) \pi_k \right] \quad (11)$$

Background

Recall that

$$\frac{\partial \log f(x)}{\partial dx} = \frac{1}{f(x)} \frac{\partial f(x)}{\partial dx}.$$

Exercise

Show that

$$\frac{\partial \log P(X_1, \dots, X_n \mid \mu_1, \dots, \mu_K)}{\partial \mu_k} \quad (12)$$

$$= \sum_{i=1}^n P(\pi_k \mid x_i, \mu_1, \dots, \mu_K) \frac{(x_i - \mu_k)}{\sigma} \quad (13)$$

This implies that

$$\mu_k = \frac{\sum_{i=1}^n P(\pi_k \mid x_i, \mu_1, \dots, \mu_K) x_i}{\sum_{i=1}^n P(\pi_k \mid x_i, \mu_1, \dots, \mu_K)},$$

which is a non-linear equation of the μ_k 's.

Intuition of EM

$$\mu_k = \frac{\sum_{i=1}^n P(\pi_k \mid x_i, \mu_1, \dots, \mu_K) x_i}{\sum_{i=1}^n P(\pi_k \mid x_i, \mu_1, \dots, \mu_K)},$$

- ▶ E-step: If for each x_i we knew that for each π_k the prob. that μ_k was in component π_k is $P(\pi_k \mid x_i, \mu_1, \dots, \mu_K)$. Then we could compute μ_k .
- ▶ M-step: If we knew each μ_k , then we could compute $P(\pi_k \mid x_i, \mu_1, \dots, \mu_K)$ for each μ_k and x_i

EM Algorithm

Initialize all the unknown parameters. On iteration t , let the estimates be $\lambda^{(t)} = \{\mu_1^{(t)}, \dots, \mu_k^{(t)}\}$

1. E-Step:

$$P(\pi_k \mid x_i, \lambda^{(t)}) = \frac{P(\pi_k \mid x_i, \lambda^{(t)})x_i}{P(\pi_k \mid x_i, \lambda^{(t)})} \quad (14)$$

2. M-Step:

$$\mu_k^{(t+1)} = \frac{\sum_{i=1}^n P(\pi_k \mid x_i, \lambda^{(t)})x_i}{\sum_{i=1}^n P(\pi_k \mid x_i, \lambda^{(t)})} \quad (15)$$

Exercise

Assume our mixture components are fully specified Gaussian distributions with $K = 2$ components:

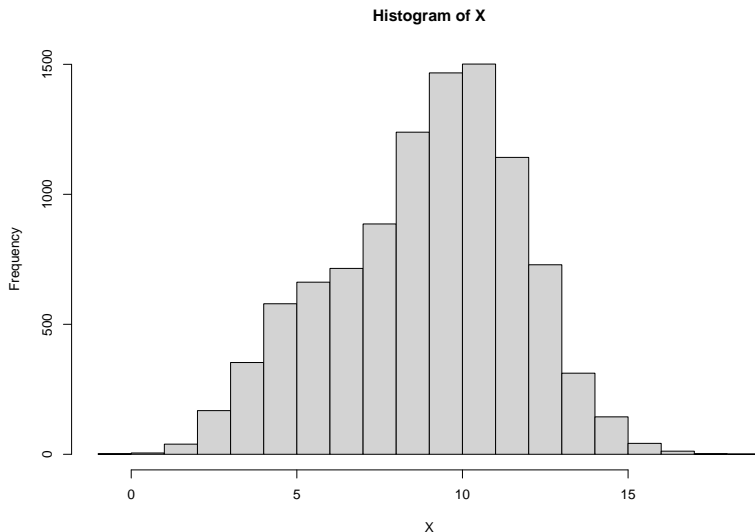
$$X_i \mid Z_i = 0 \sim N(5, 1.5) \quad (16)$$

$$X_i \mid Z_i = 1 \sim N(10, 2) \quad (17)$$

Let the true mixture proportions be $P(Z_i = 0) = 0.25$ and $P(Z_i = 1) = 0.75$, respectively.

Exercise

1. Simulate data from the mixture model on the previous slide, which should produce the following histogram.



Exercise

Compute the likelihood $P(X_i|Z_i = 0)$ and $P(X_i|Z_i = 1)$ and store these in a matrix L .

Exercise

Implement the E and M step in a function called `emIteration`. Then evaluate the EM and verify that your estimates are 0.29 and 0.71, respectively.

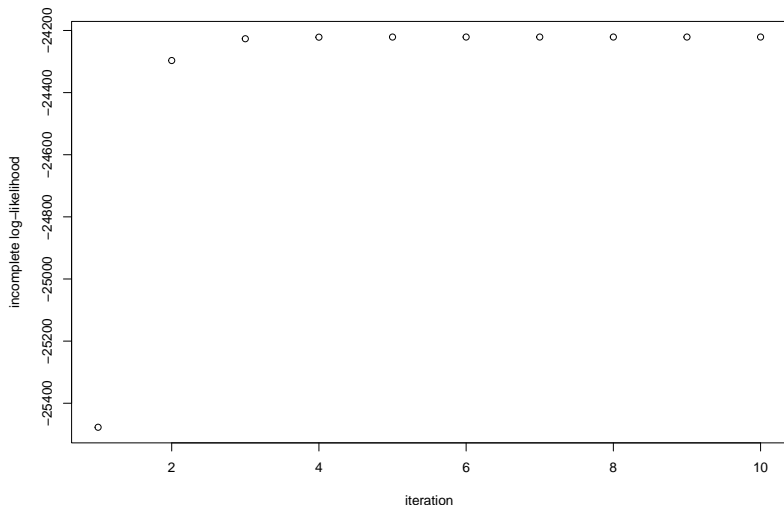
Plot the incomplete log-likelihood versus the iteration. What do you observe regarding its behavior.

Perform EM

```
#perform EM  
ee <- mixture.EM(w.init=c(0.5,0.5), L)  
print(paste("Estimate = (", round(ee[[1]][1],2), ",",  
           round(ee[[1]][2],2), ")", sep=""))
```

```
## [1] "Estimate = (0.22,0.78)"
```

Plot



The log-likelihood is strictly increasing, meaning that we have reached a local maxima.

R packages for mixture models

- ▶ The `mclust` package (<http://www.stat.washington.edu/mclust/>) is standard for Gaussian mixtures.
- ▶ The `mixtools` considers classic parametric densities, mixtures of regressions, and some non-parametric mixtures.