

模型先计算 loss, 求负 log likelihood, 调用函数 neg_log_likelihood
 在此函数中, 先用 LSTM 获得 emission probability, 调用函数 get_lstm_features
 get_lstm_features 详解

```
def _get_lstm_features(self, sentence):
    self.hidden = self.init_hidden()
    embeds = self.word_embeds(sentence).view(len(sentence), 1, -1)
    lstm_out, self.hidden = self.lstm(embeds, self.hidden)
    lstm_out = lstm_out.view(len(sentence), self.hidden_dim)
    lstm_feats = self.hidden2tag(lstm_out)
    return lstm_feats
```

假设句子长度为 10, word embedding 为 30,
 embeds 为 (10, 1, 30), LSTM 需要输入为 3 维,
 LSTM-out 为 (10, hidden-dim)
 LSTM-facts 为 (10, tags), 此为由 LSTM 获得的特征

LSTM-facts: [] → 每一个 tag 到 word 的 emission probability, 注意与 HMM 不同, 此值为广义范围,
 具体说为 tags 与当前 word 的关系.
 10 × tags
 return feats (10 × tags)
 将 feats 传入 forward-alg 中, 计算所有 exp 的和
 forward-alg 详解

```
def _forward_alg(self, feats):
    # Do the forward algorithm to compute the partition function
    init_alphas = torch.full((1, self.tagset_size), -10000.)
    # START_TAG has all of the score.
    init_alphas[0][self.tag_to_ix[START_TAG]] = 0.

    # Wrap in a variable so that we will get automatic backprop
    forward_var = init_alphas

    # Iterate through the sentence
    for feat in feats:
        alphas_t = [] # The forward tensors at this timestep
        for next_tag in range(self.tagset_size):
            # broadcast the emission score: it is the same regardless of
            # the previous tag
            emit_score = feat[next_tag].view(1, -1)
            trans_score = self.transitions[next_tag].view(1, -1)
            # the ith entry of trans_score is the score of transitioning to
            # next_tag from i
            trans_score = self.transitions[next_tag].view(1, -1)
            # The previous tag var before we do log-sum-exp
            next_tag_var = forward_var + trans_score + emit_score
            # The forward variable for this tag is log-sum-exp of all the
            # scores.
            alphas_t.append(log_sum_exp(next_tag_var).view(1))
        forward_var = torch.cat(alphas_t).view(1, -1)
    terminal_var = forward_var + self.transitions[self.tag_to_ix[STOP_TAG]]
    alpha = log_sum_exp(terminal_var)
    return alpha
```

init_alphas: 初始 tag 概率 [-10000, -10000, 0, -10000 ...]
 设为 -10000, 因为初始只能为 START
 forward → init_alphas 不懂为什么要指向
 for feat in feats: 循环每个单词 [] 1 × tags
 alphas_t = []
 for next_tag in tags: 循环每个 tag, 损积!
 emit_score = feat[某 tag] → [同样数值] 1 × tags
 tag ↔ word ↑ → 这个 tag 和这个 word 的关系
 trans_score = [] 1 × tags
 任意 tags → 这 tag 的概率
 next_tag_var = forward + trans_score + emit_score.
 [-10000 -10000 1 -10000 -10000]
 tags → tag [100 200 3 1 5]
 tag → word [100 100 100 100 100]
 alphas_t = [← log-sum] 1 × tags
 因为 tag → tag 怎么累加, 都要加 emission score.

```
def log_sum_exp(...):
    max_score = vec[0].argmax(vec)
    max_score_broadcast = max_score.view(1, -1).expand(1, vec.size()[1])
    return max_score + \
        torch.log(torch.sum(torch.exp(vec - max_score_broadcast)))
```

插入 log-sum 函数, 讲解一下

先上公式: $P(x, y)$
 $P(y|x) = \frac{P(x, y)}{\sum_i P(x, y)}$ \log
 $\log P(y|x) = \log P(x, y) - \log \sum_i P(x, y)$

VOC中是上面输出结果，第一次 alpha_{-t} 只有
START 权重最高，减去最大值，防止溢出。

$$P(x, y) = \exp(w \cdot \phi(x, y))$$

因为后期我们要用 negative-log-likelihood，故取负号
 $-\log P(y|x) = (\log P(x, y)) - \log P(x)$

把所有可能的 tag 循环完后，我们得到对每个 tag 的输出结果，是 tag 个分母

$$\text{alpha}_{-t} = [\downarrow]_{\text{tag}}$$

到此 tag 的所有可能的 log-sum

跳出循环：forward 更新为 alpha_{-t} ，即保留之前的 path，每个圆实例下

最初的 forward	$[t_1 \quad t_2 \quad \text{START}]$
next-tag-var	$[t_1 \quad t_2 \quad \text{START}]$
alpha_{-t}	$[t_1 \quad t_2 \quad \text{START}] \leftarrow \text{新的forward}$

算下个单词，还是那样，但是 forward 变了

最后，加上 STOP，返回分数

将 feats, tags 传入 `_score_sentence` 中

```
def _score_sentence(self, feats, tags):
    # Gives the score of a provided tag sequence
    score = torch.zeros(1)
    tags = torch.cat([torch.tensor([self.tag_to_ix[START_TAG]], dtype=torch.long), tags])
    for i, feat in enumerate(feats):
        score += self.transitions[tags[i + 1], tags[i]] + feat[tags[i + 1]]
    score += self.transitions[self.tag_to_ix[STOP_TAG], tags[-1]]
    return score
```

训练完成后，我们采用 viterbi 算法解码

```
def _viterbi_decode(self, feats):
    backpointers = []
    # Initialize the viterbi variables in log space
    init_vars = torch.full((1, self.tagset_size), -10000.)
    init_vars[0][self.tag_to_ix[START_TAG]] = 0
    # forward_var at step i holds the viterbi variables for step i-1
    forward_var = init_vars
    for feat in feats:
        bptrs_t = [] # holds the backpointers for this step
        viterbivars_t = [] # holds the viterbi variables for this step
        for next_tag in range(self.tagset_size):
            # next_tag_var[i] holds the viterbi variable for tag i at the
            # previous step, plus the score of transitioning
            # from tag i to next_tag.
            # We don't include the emission scores here because the max
            # does not depend on them (we add them in below)
            next_tag_var = forward_var + self.transitions[next_tag]
            best_tag_id = argmax(next_tag_var)
            bptrs_t.append(best_tag_id)
            viterbivars_t.append(next_tag_var[0][best_tag_id].view(1))
        # Now add in the emission scores, and assign forward_var to the set
        # of viterbi variables we just computed
        forward_var = (torch.cat(viterbivars_t) + feat).view(1, -1)
        bptrs_t.append(bptrs_t[-1].view(1))
    # Transition to STOP_TAG
    terminal_var = forward_var + self.transitions[self.tag_to_ix[STOP_TAG]]
    best_tag_id = argmax(terminal_var)
    path_score = terminal_var[0][best_tag_id]
    path_score.append(bptrs_t[-1])
    # Follow the back pointers to decode the best path.
    best_path = [best_tag_id]
    for bptrs_t in reversed(backpointers):
        best_tag_id = bptrs_t[best_tag_id]
        best_path.append(best_tag_id)
    # Pop off the start tag (we don't want to return that to the caller)
    start = best_path.pop()
    assert start == self.tag_to_ix[START_TAG] # Sanity check
    best_path.reverse()
    return path_score, best_path
```

transition to STOP-TAG

得到最后一个 tag 到 STOP-TAG 的值，求最大，就为最后一个 tag

$[\quad \quad \quad \quad \quad] , [\quad \quad \quad]]$

↓ 到最后一个 tag 的最好端 tag
最后最好端 tag 为 t_3

取出到 t_3 的最好 tag, e.g. t_2

$[\quad \quad \quad \quad \quad]$
 $\text{next-tag-var} = \begin{bmatrix} t_1 & t_2 & t_1 \\ \downarrow & & \\ t_1 & & \end{bmatrix} \text{ transition}$

bptrs-t best-tag-id 哪个 tag 能到此 tag 最大
 viterbivars-t 分数

到 t1 最大
 $\begin{bmatrix} t_1 & t_2 & t_3 \end{bmatrix} \text{ viterbivars-t}$ } forward
 $\begin{bmatrix} t_1 & t_2 & t_3 \end{bmatrix} \text{ feat}$
 $\downarrow t_1$ 到 forward 的 emission
 $\text{backpointers} [\quad]$
 到 t1 最好 tag → 到 t2 最好 tag

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Please talk with me if you have any question or find any problem

