

Vorlesung/Übung Robotik

- https://github.com/TUBAF-IfI-LiaScript/VL_SoftwareprojektRobotik

Husky - Simulation:

- <https://www.clearpathrobotics.com/assets/guides/kinetic/husky/SimulatingHusky.html>

Sonstiges:

- <https://github.com/ComputerScienceLecturesTUBAF/RobotikProjekt-SoSe21/wiki>

Sensoren:

Lidar-Sensor:

- <https://www.sick.com/de/en/detection-and-ranging-solutions/2d-lidar-sensors/tim5xx/tim551-2050001/p/p343045>
- ROS: https://github.com/SICKAG/sick_scan
- ROS2: https://github.com/SICKAG/sick_scan2

GNSS:

- HOLDER -