

## **Vorlesung/Übung Robotik**

- [https://github.com/TUBAF-IfI-LiaScript/VL\\_SoftwareprojektRobotik](https://github.com/TUBAF-IfI-LiaScript/VL_SoftwareprojektRobotik)

### **Husky - Simulation:**

- <https://www.clearpathrobotics.com/assets/guides/kinetic/husky/SimulatingHusky.html>

### **Sonstiges:**

- <https://github.com/ComputerScienceLecturesTUBAF/RobotikProjekt-SoSe21/wiki>

### **Sensoren:**

#### **Lidar-Sensor:**

- <https://www.sick.com/de/en/detection-and-ranging-solutions/2d-lidar-sensors/tim5xx/tim551-2050001/p/p343045>
- ROS: [https://github.com/SICKAG/sick\\_scan](https://github.com/SICKAG/sick_scan)
- ROS2: [https://github.com/SICKAG/sick\\_scan2](https://github.com/SICKAG/sick_scan2)

#### **GNSS:**

- HOLDER -