Principles and Applications of Microcontrollers

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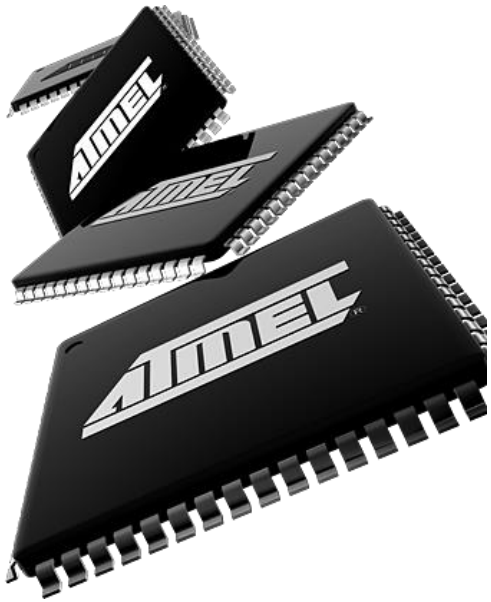
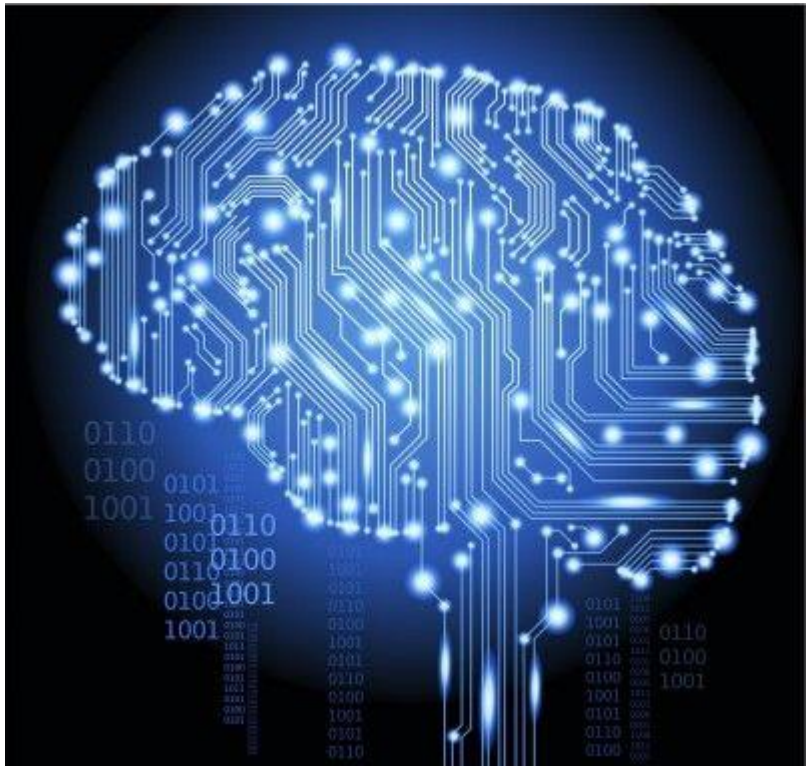
Today:

- AVR assembly language
- Machine code
- Status register



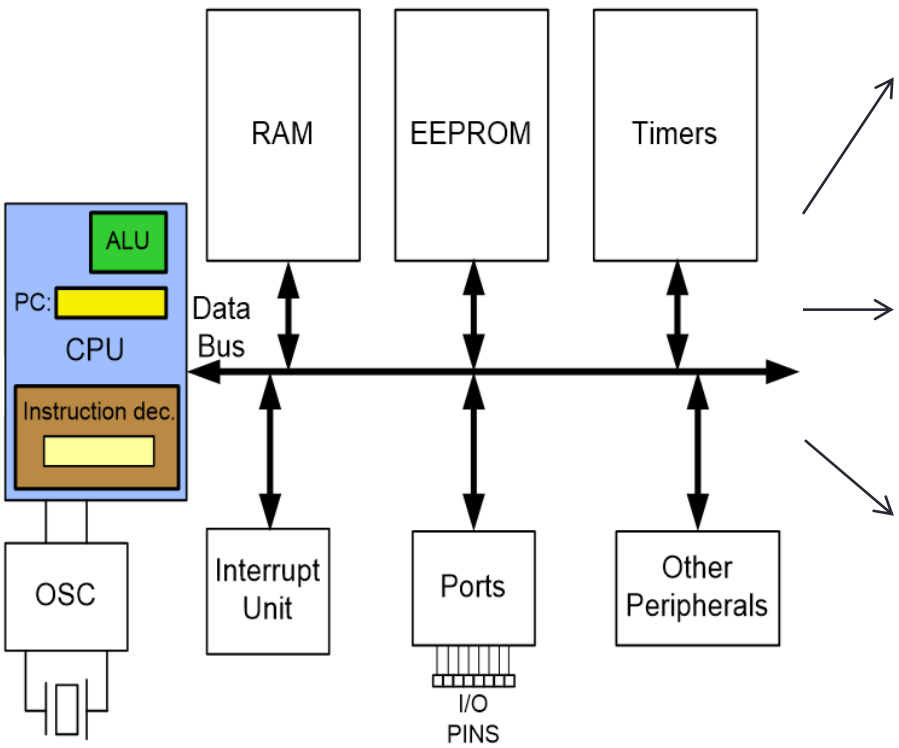
Outline

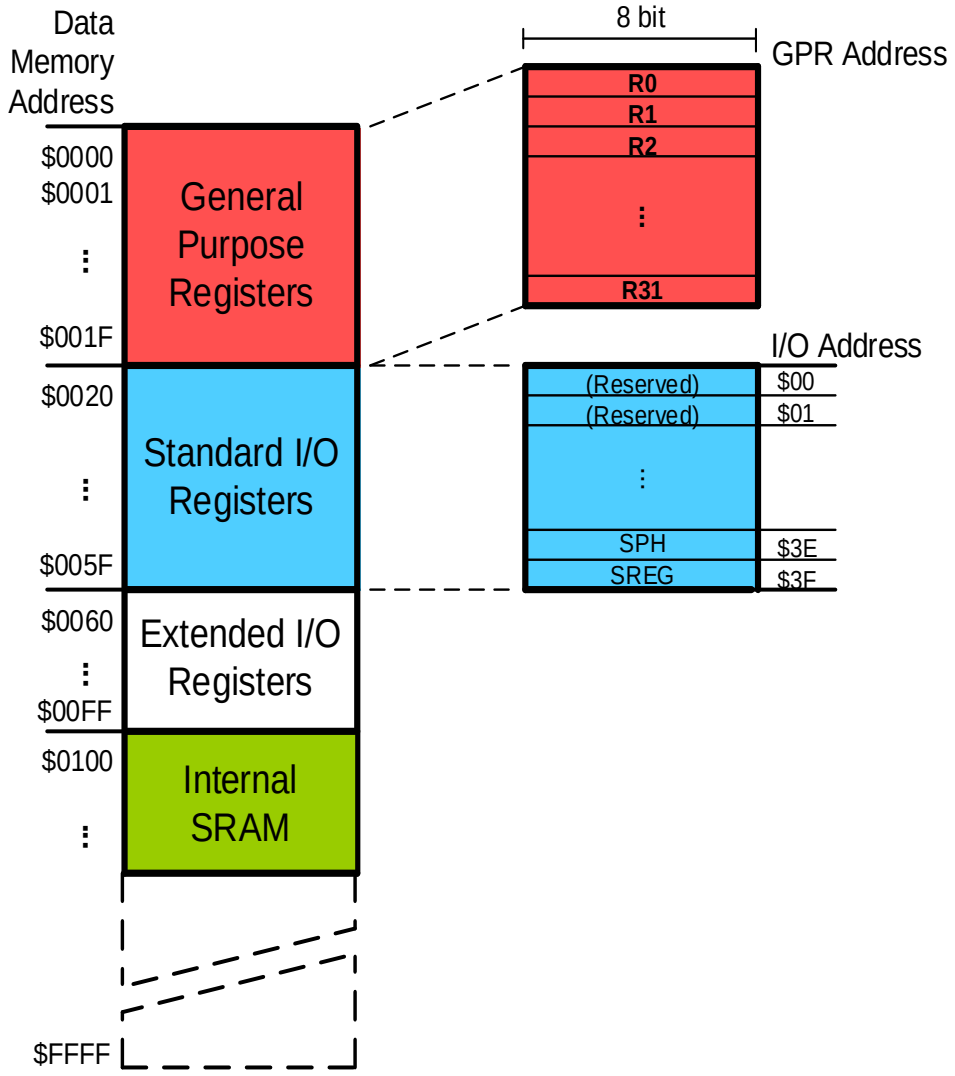
- Accessing data memory
- AVR assembly language
  - Structure of AVR assembly
  - Machine code
- Status register
- Getting started



Data Memory Access

- How to access data memory outside the I/O?





Accessing Data Memory – LDS & STS

- LDS – load data from space
- Syntax: `LDS Rd, k`

  where 0 ≤ d ≤ 31, k between $0000 to $FFFF
- Example:
  - `LDS R1, 0x60 ;R1= [0x60]`
- STS – sto
- Syntax: S
- Example:
  - `STS 0x60, R13 ;[0x60] = R13`

Example: Add contents of location 0x90 to contents of location 0x95 and store the result in location 0x313.

Solution:

```
LDS   R20, 0x90        ;R20 = [0x90]
LDS   R21, 0x95        ;R21 = [0x95]
ADD   R20, R21         ;R20 = R20 + R21
STS   0x313, R20       ;[0x313] = R20
```

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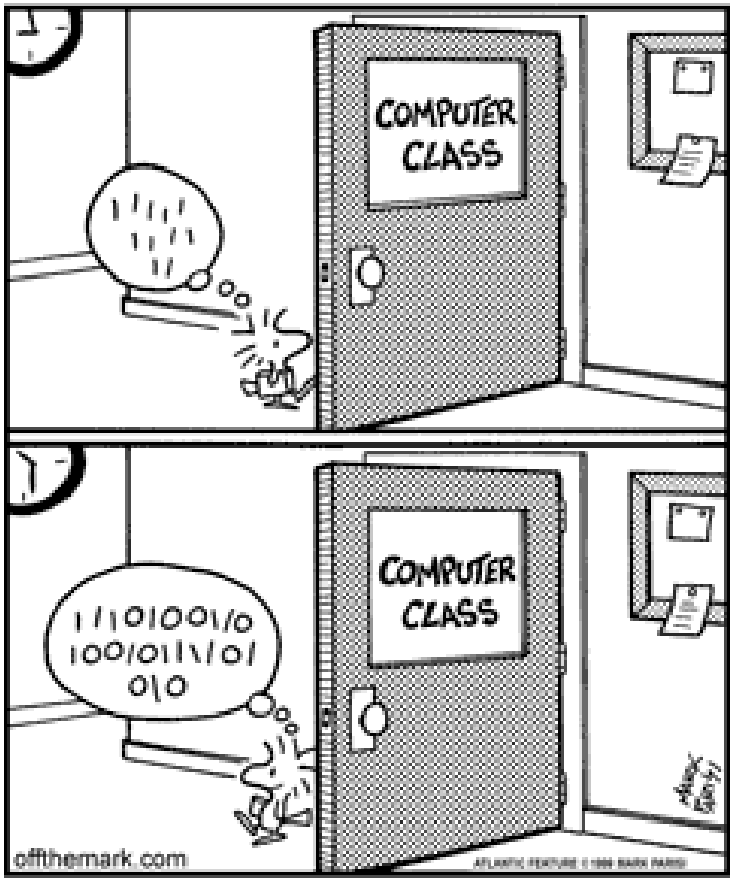
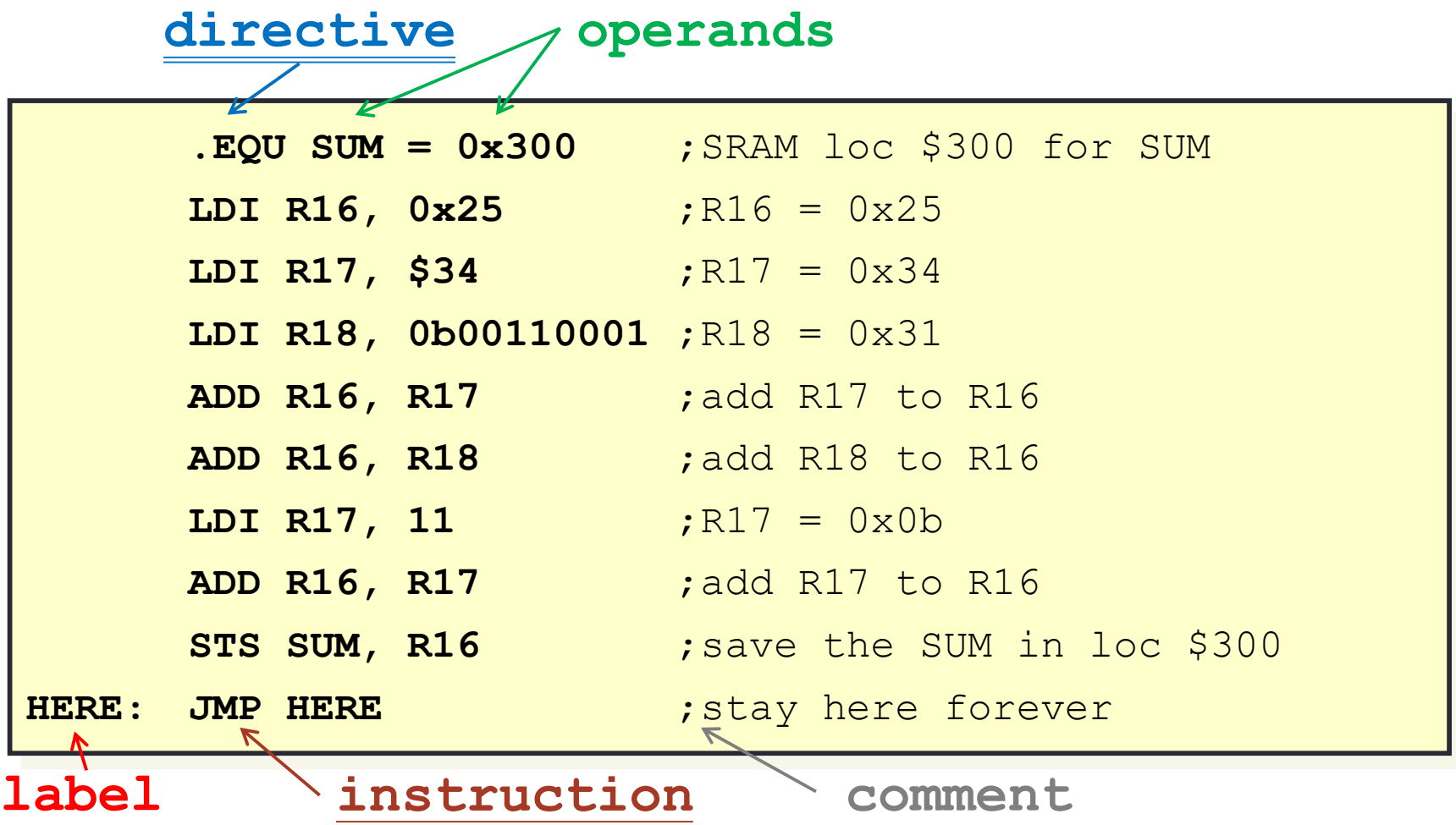


An Example Assembly Program



Assembler Directives – .EQU & .SET

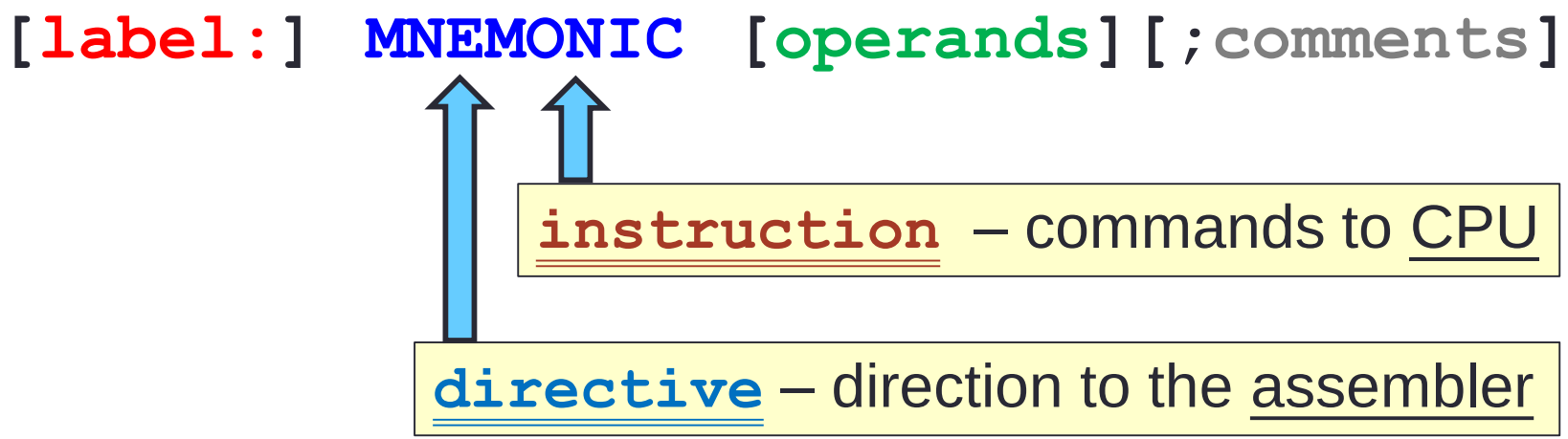
- Syntax: **.EQU *name = value***
- Example:

```
.EQU    COUNT = 0x25
LDI     R21, COUNT          ;R21 = 0x25
LDI     R22, COUNT + 3      ;R22 = 0x28
```

- Syntax: **.SET *name = value***
- Example:

```
.SET    COUNT = 0x25
LDI     R21, COUNT          ;R21 = 0x25
LDI     R22, COUNT + 3      ;R22 = 0x28
.SET    COUNT = 0x19
LDI     R21, COUNT          ;R21 = 0x19
```

Structure of Assembly Language



- **directive** does NOT generate any machine code
- **operands** are data items being manipulated
- For assembly, is it case sensitive?

Frequently Used Instructions

Arithmetic and logic

a+b	ADD
a-b	SUB
a&b	AND
a|b	OR
a++	INC
a--	DEC
-a	NEG
a=0	CLR

Move

reg1=reg2	MOV
reg=17	LDI
reg=mem	LDS
mem=reg	STS
periperal	IN
peripheral	OUT
heap	PUSH
heap	POP

Bit operation and others

a<<1	LSL
a>>1	LSR,
Ø C (not avail. In C)	ROL, ROR
Status bits	SEI, CLI, CLZ...
No op.	NOP

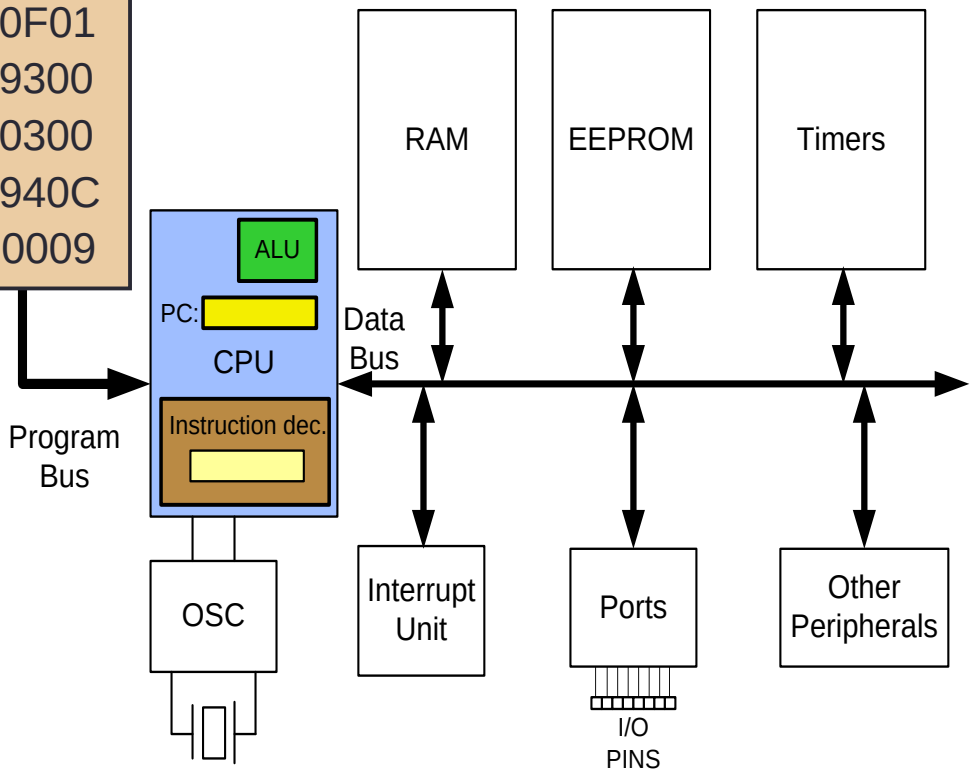
From: AVR 8-bit instruction set

Machine Code

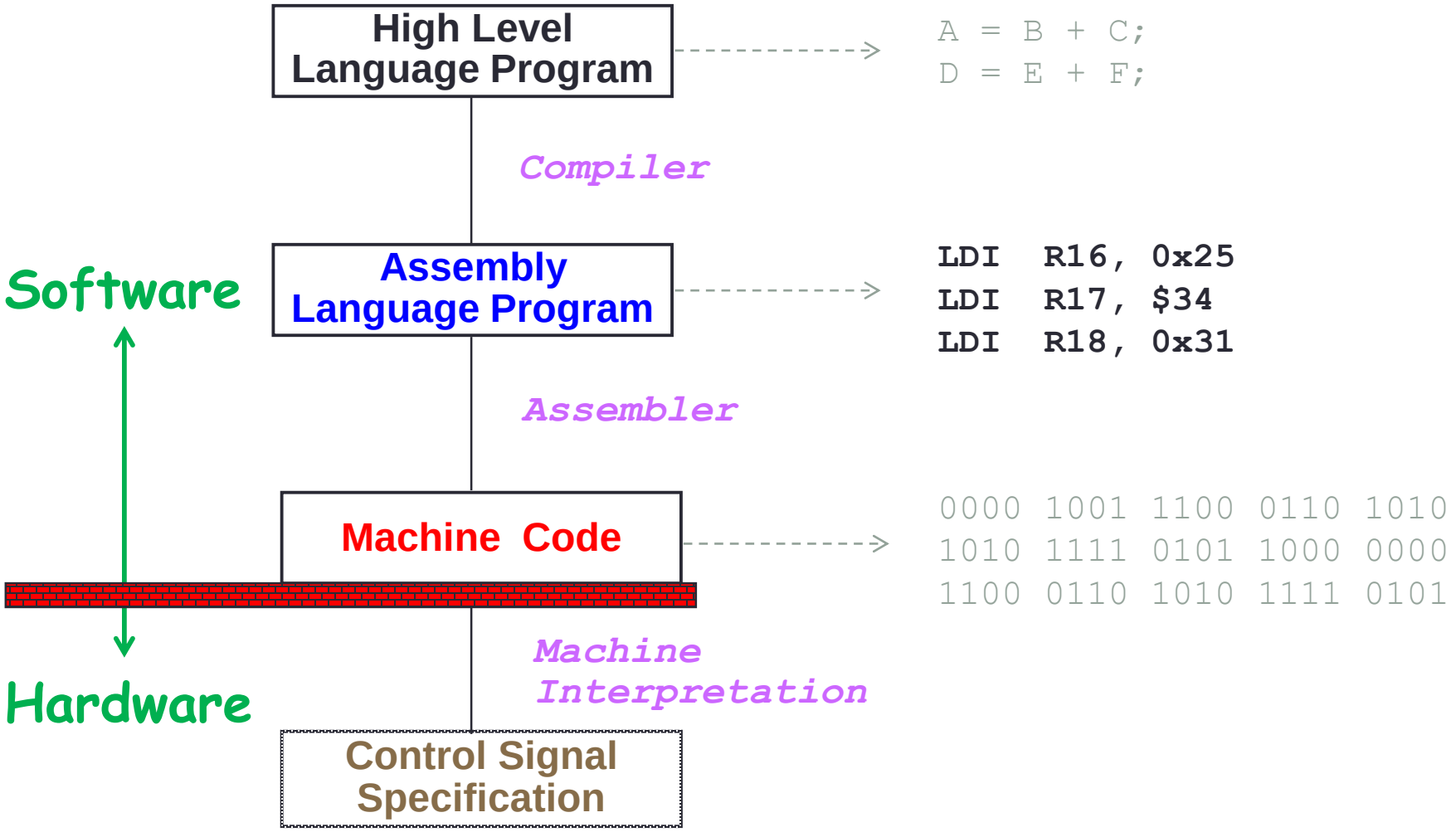
```
      LDI   R16, 0x25
      LDI   R17, $34
      LDI   R18, 0x31
      ADD   R16, R17
      ADD   R16, R18
      LDI   R17, 11
      ADD   R16, R17
      STS   0x300, R16
HERE:JMP  HERE
```

00	E205
01	E314
02	E321
03	0F01
04	0F02
05	E01B
06	0F01
07	9300
08	0300
09	940C
0A	0009

- Assembly code is turned into machine code
- Size of each machine code: 16 or 32 bits

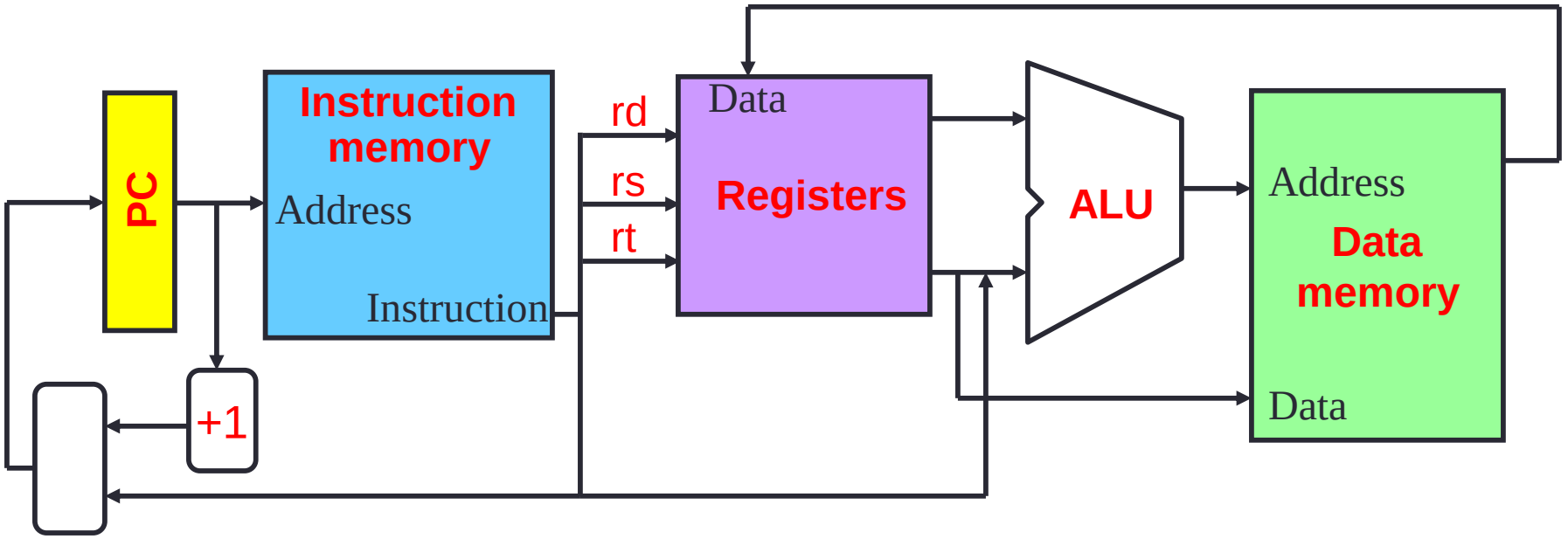


Levels of Computer Language



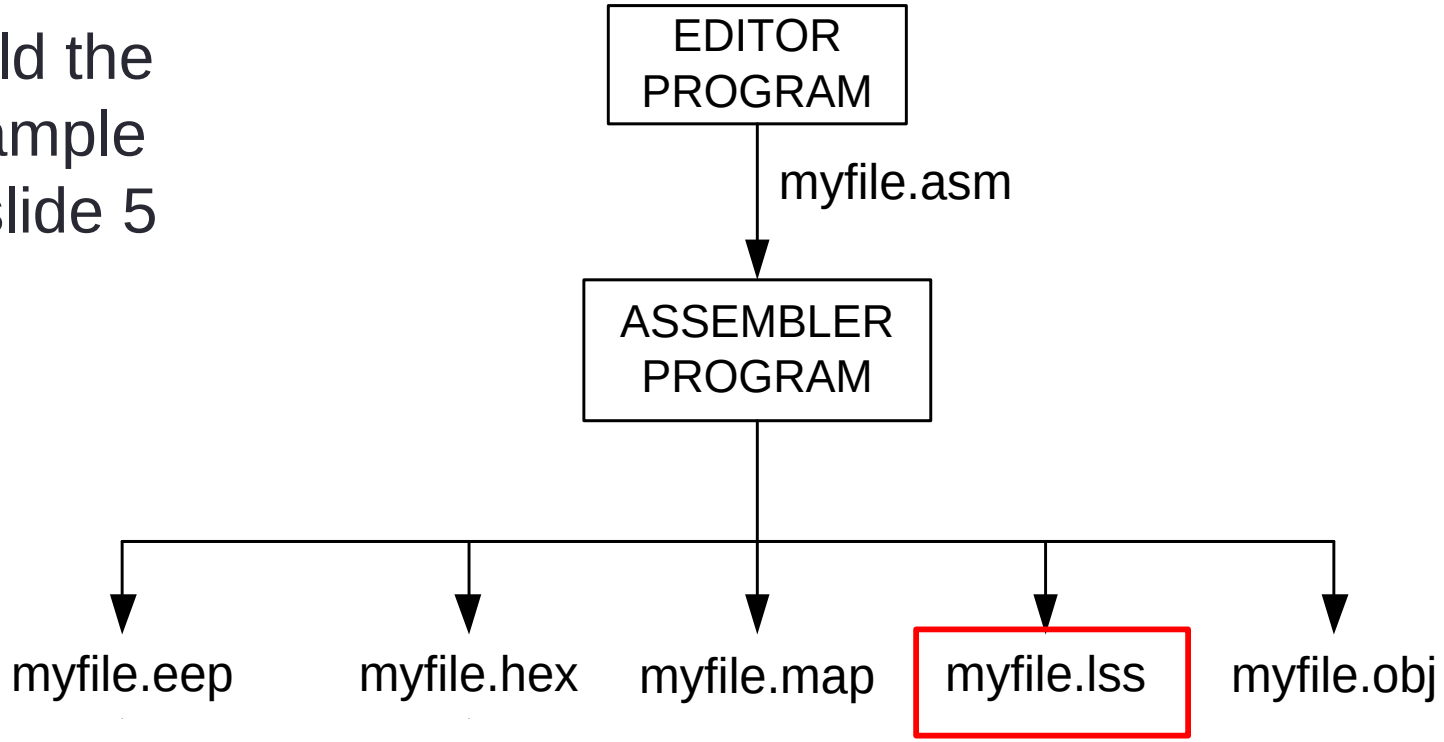
Instruction Set Architecture

- The instructions are actually realized in hardware
- Wires are connected between each components

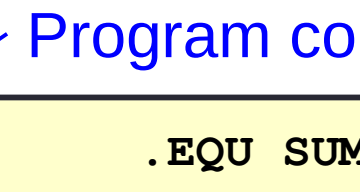


Assembler

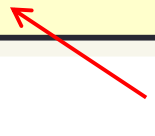
- Build the example in slide 5



Example List (.lss) File




```
                .EQU SUM = 0x300      ;SRAM loc $300 for SUM
00 E205         LDI R16, 0x25         ;R16 = 0x25
01 E314         LDI R17, $34          ;R17 = 0x34
02 E321         LDI R18, 0b00110001   ;R18 = 0x31
03 0F01         ADD R16, R17          ;add R17 to R16
04 0F02         ADD R16, R18          ;add R18 to R16
05 E01B         LDI R17, 11           ;R17 = 0x0b
06 0F01         ADD R16, R17          ;add R17 to R16
07 9300 0300    STS SUM, R16          ;save the SUM in loc $300
09 940C 0009    HERE: JMP HERE        ;stay here forever
```



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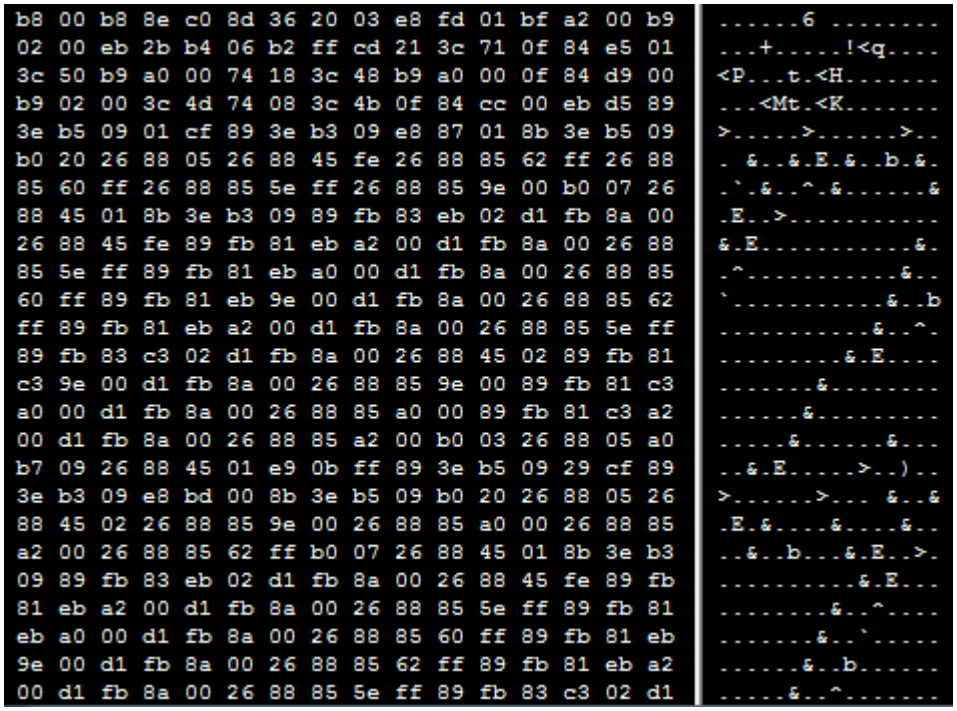


Composition of Machine Codes

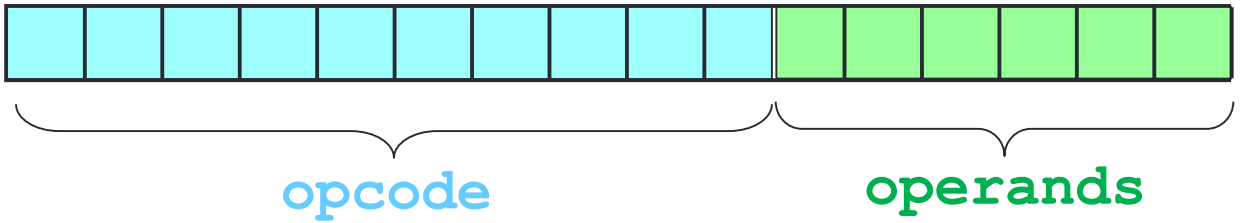
- The assembler generates 16-bit or 32-bit machine codes
- Each machine code consists of 2 fields: opcode and operands

```
instruction   operands
```

Assembly code: `LDI R16, 0x25`

Assembler

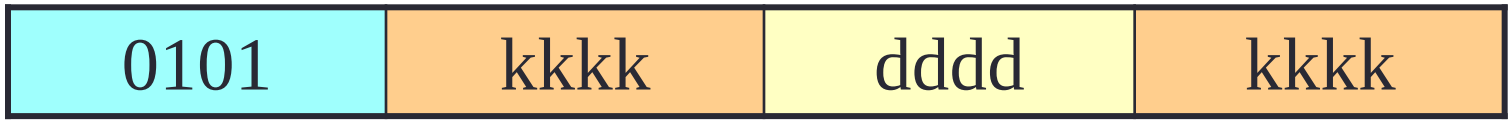
Machine code:



Some AVR Machine Code Examples

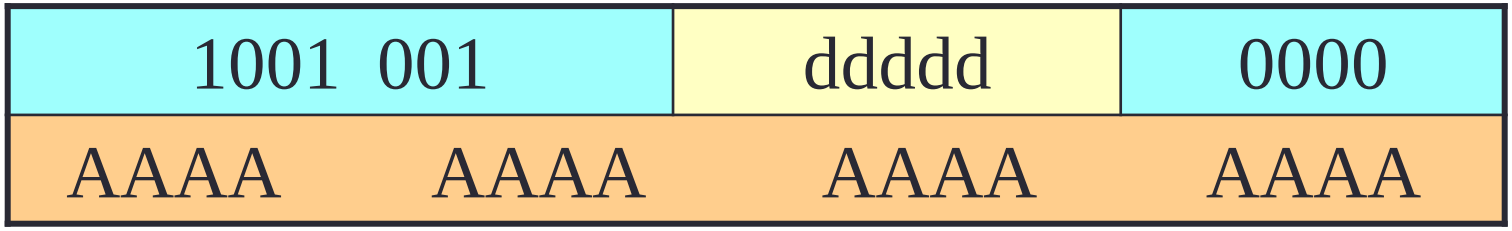
ADD

SUBI



OUT

STS

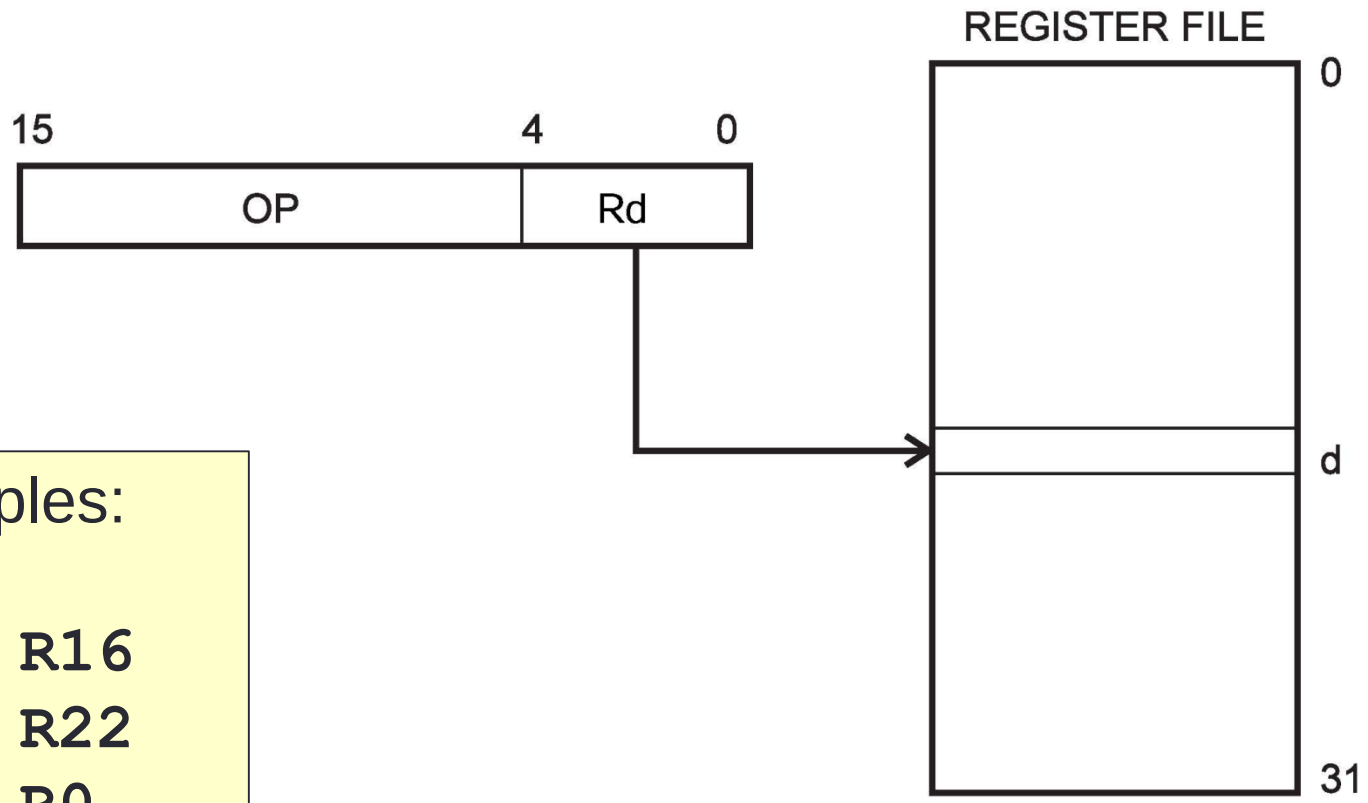


Instruction Types and Addressing Modes

- Instruction type:
  - Data transfer (**`MOV`**)
  - Arithmetic (**`ADD`**, **`SUB`**)
  - Logical
  - Program control (**`BRNE`**, **`BRCC`**)
  - I/O (**`IN`**, **`OUT`**)
- Addressing mode:
  - Register direct
  - I/O direct
  - Data direct
  - Data indirect
  - Relative program addressing

Register Direct – 1 Register

- 16-bit

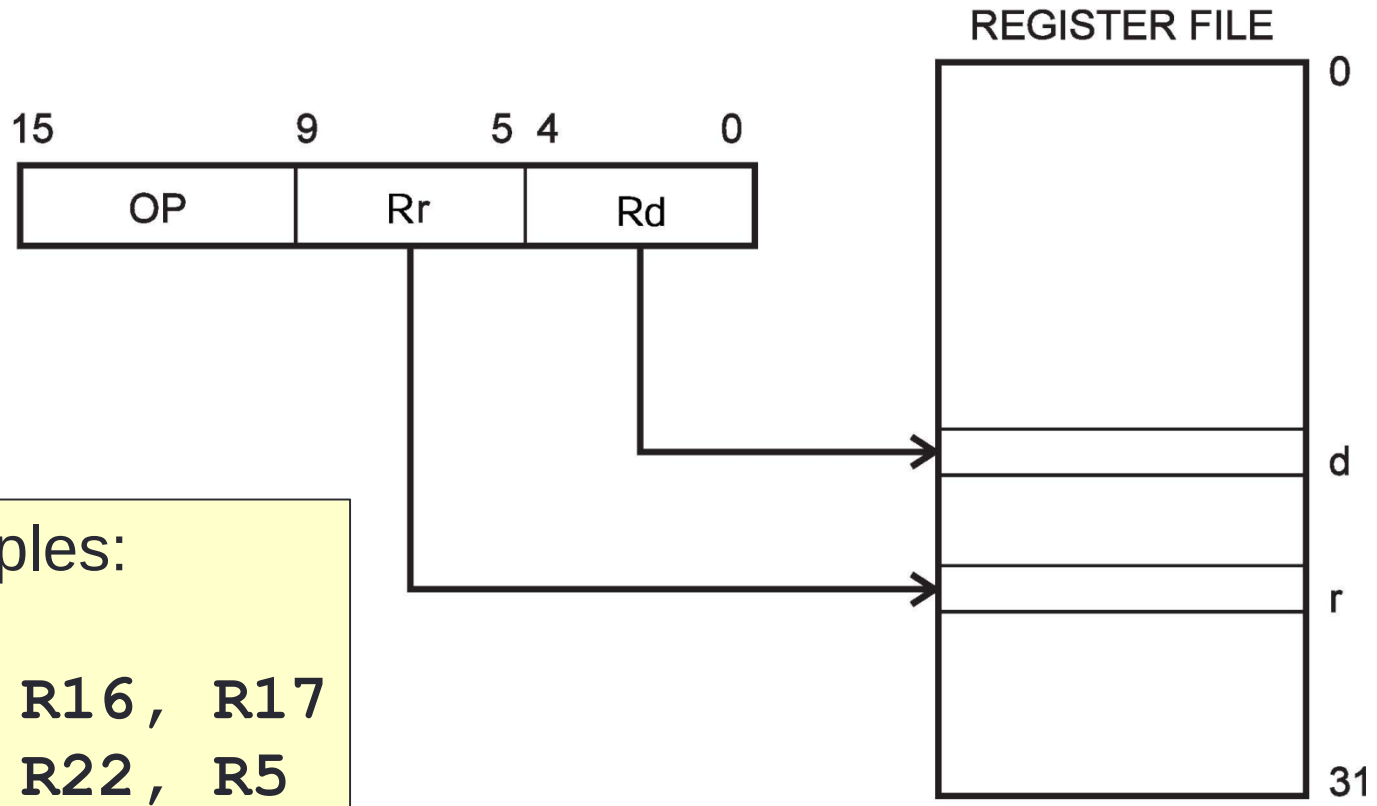


Examples:

```
INC   R16
CLR   R22
EOR   R0
```

Register Direct – 2 Registers

- 16-bit

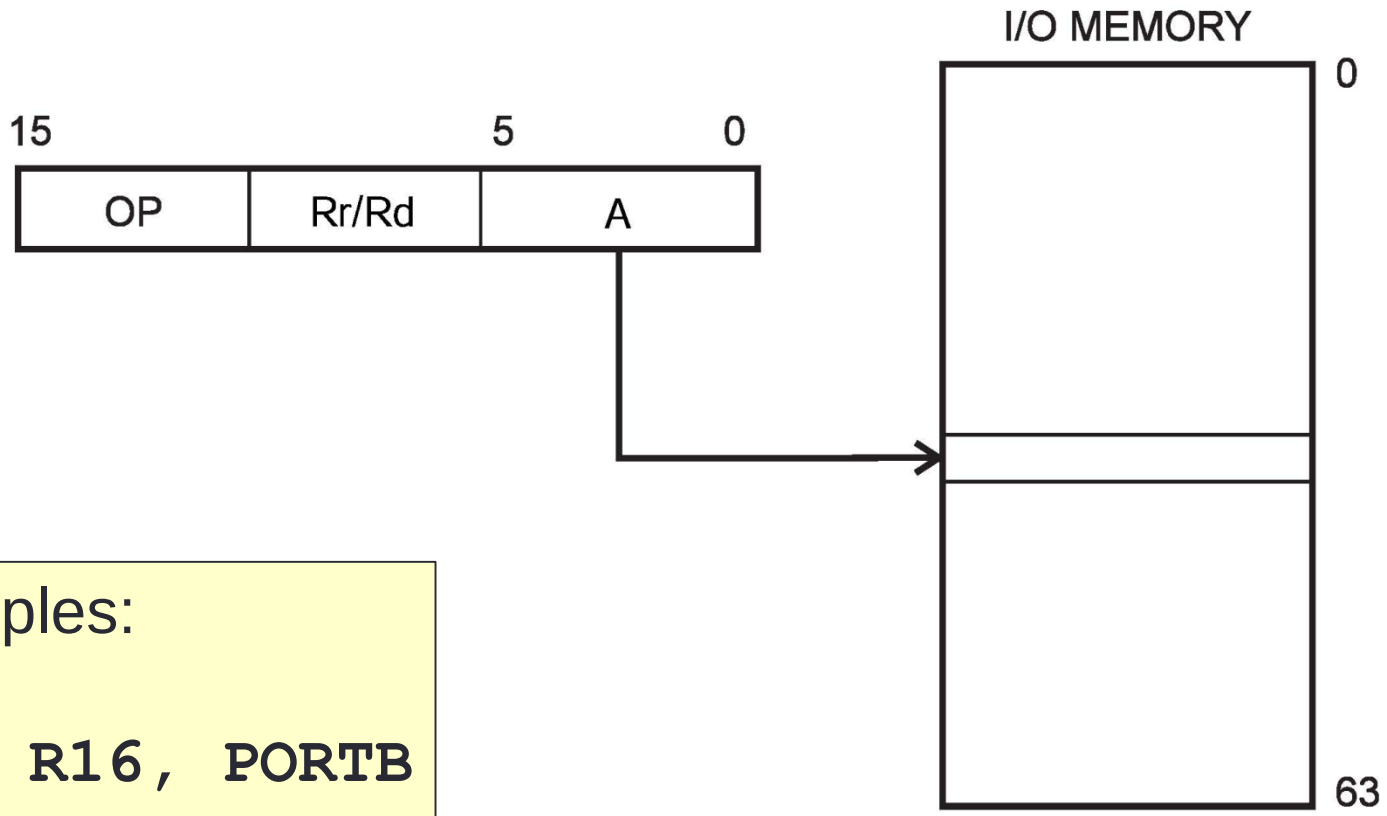


Examples:

```
ADD   R16, R17
CP    R22, R5
MOV   R0, R1
```

I/O Direct

- 16-bit

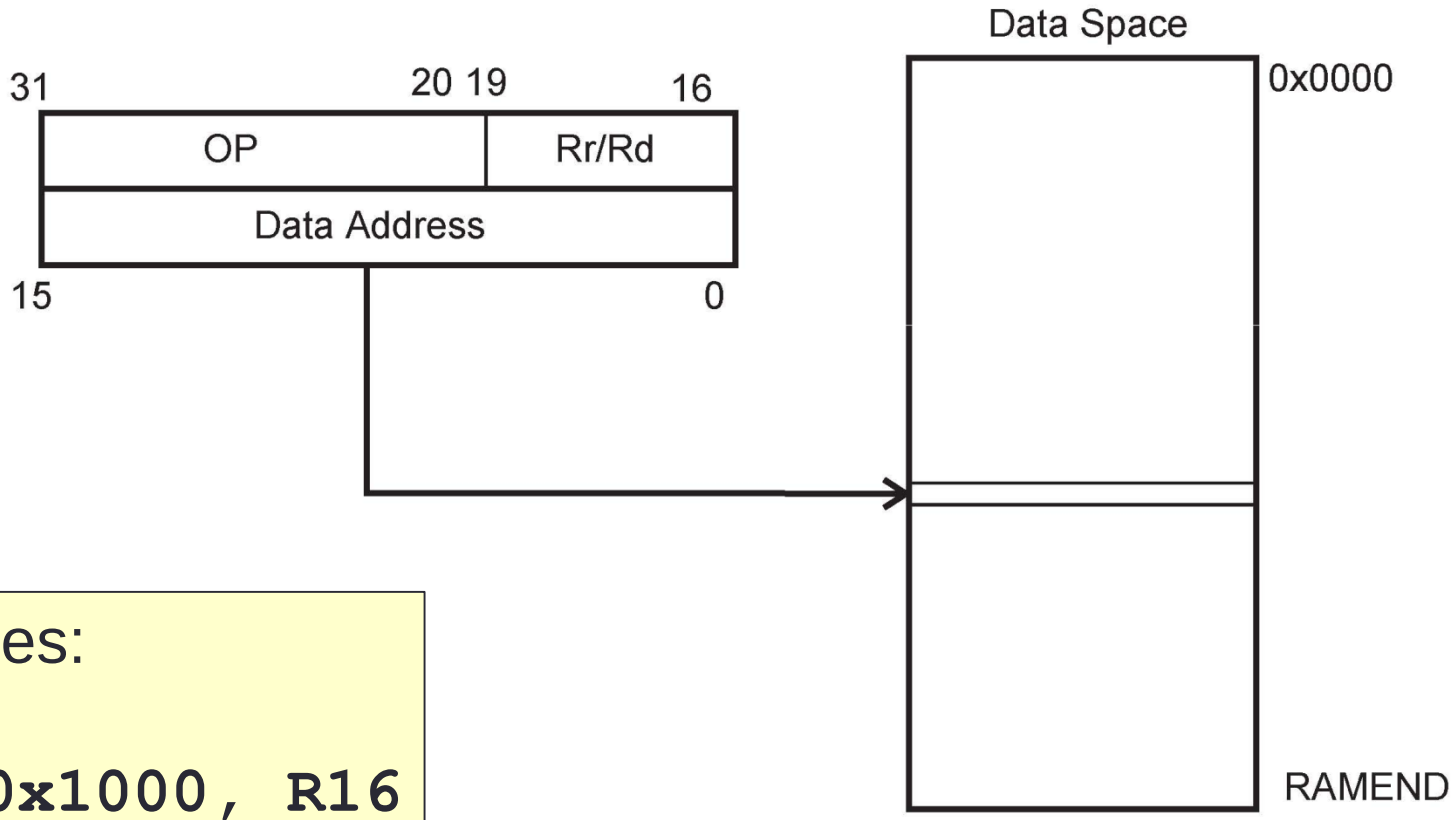


Examples:

```
IN   R16, PORTB
OUT  PORTC, R20
```

Data Direct

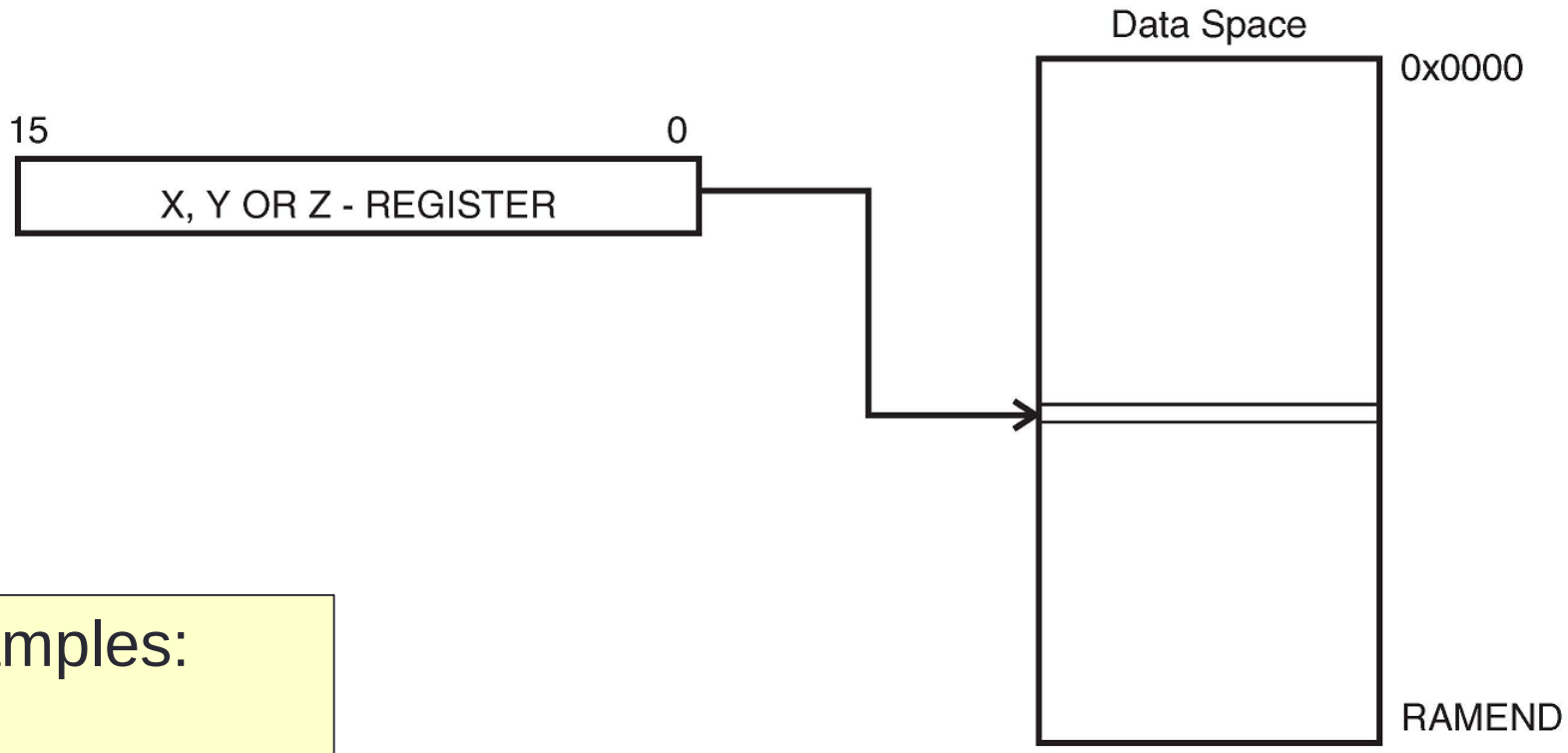
- 32-bit



Examples:

```
STS   0x1000, R16
```

Data Indirect

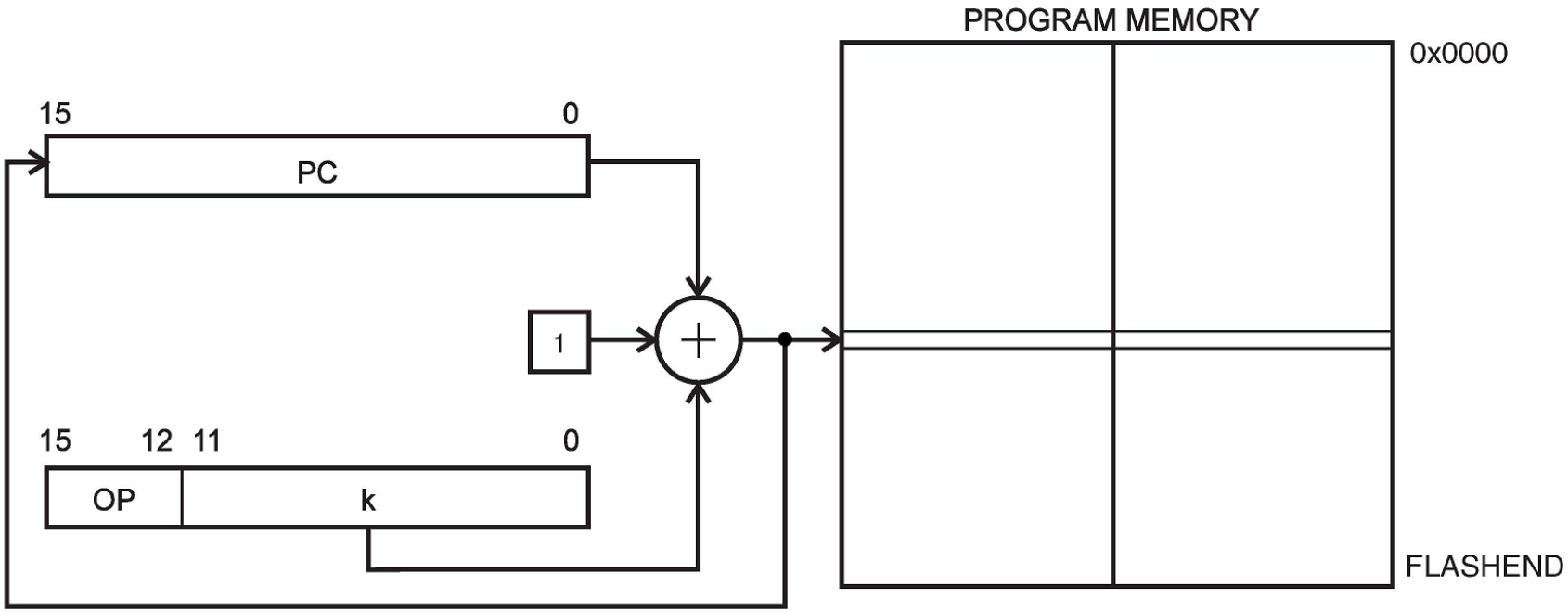


Examples:

```
LD    R16, Y
ST    Z, R16
```

Relative Program Addressing

- Program counter (PC) is involved



Examples:

RJMP

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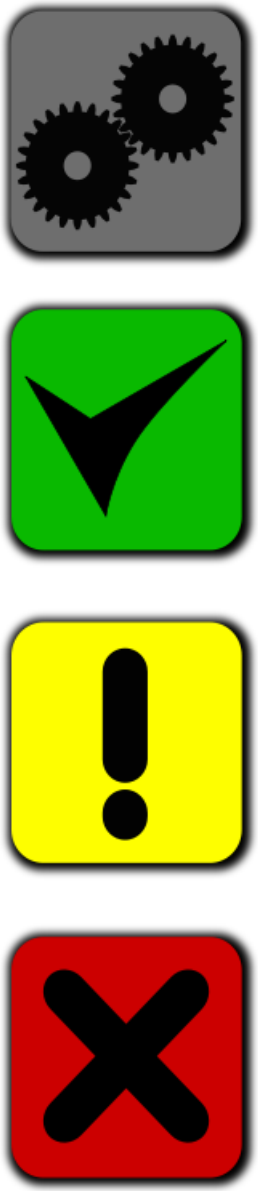
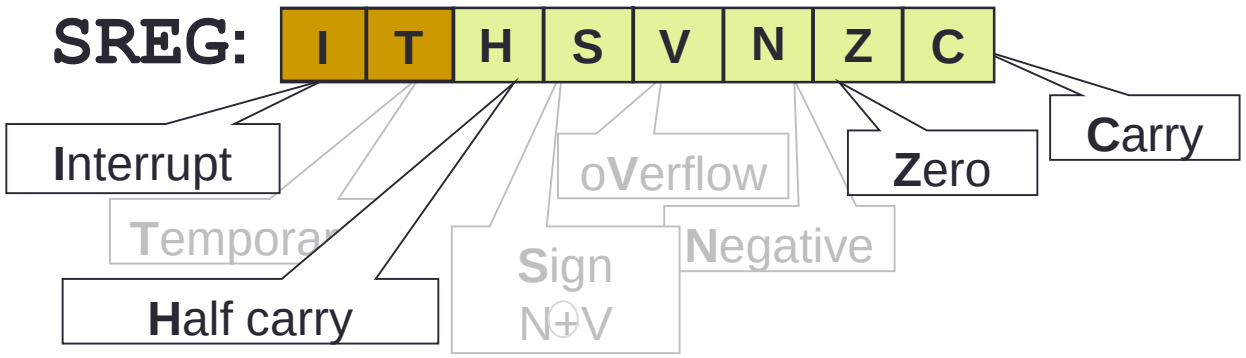
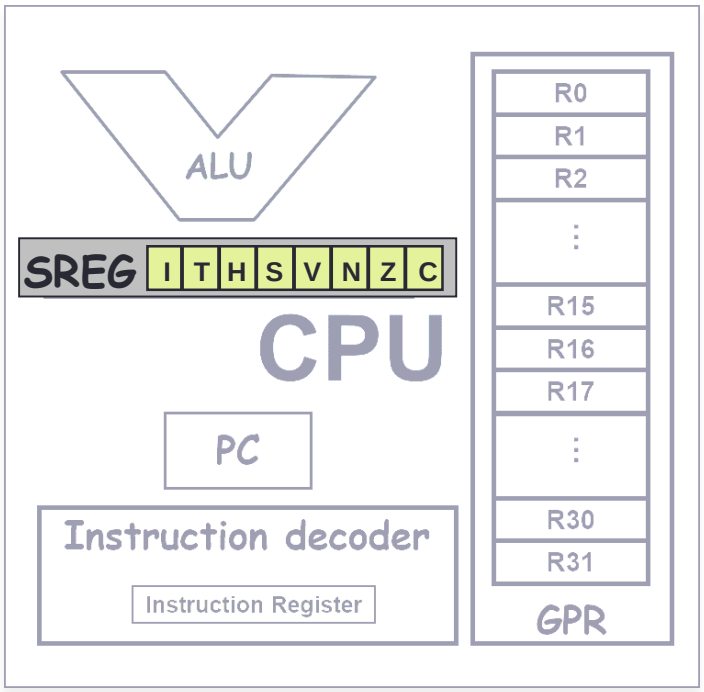


Status Register (SREG)





Status Flags

- Information regarding “arithmetic calculation” results
- Altered automatically by the ALU after each instruction executed
- Used for a subsequent conditional jump instruction

GPR:

D7	D6	D5	D4	D3	D2	D1	D0

Zero:

Carry:

Half carry:

C, H, and Z Flags

- Carry, half-carry, and zero flags

Example: Show the status of the C, H, and Z flags after the subtraction of 0x9C from 0x9C in the following instructions:

```
LDI     R20, 0x9C
LDI     R21, 0x9C
SUB     R20, R21        ;subtract R21 from R20
```

Solution:

```
    $9C     1001 1100
-   $9C     1001 1100
    $00     0000 0000       R20 = $00
```

C = 0 because R21 is not bigger than R20 and there is no borrow from D8 bit.
Z = 1 because the R20 is zero after the subtraction.
H = 0 because there is no borrow from D4 to D3.

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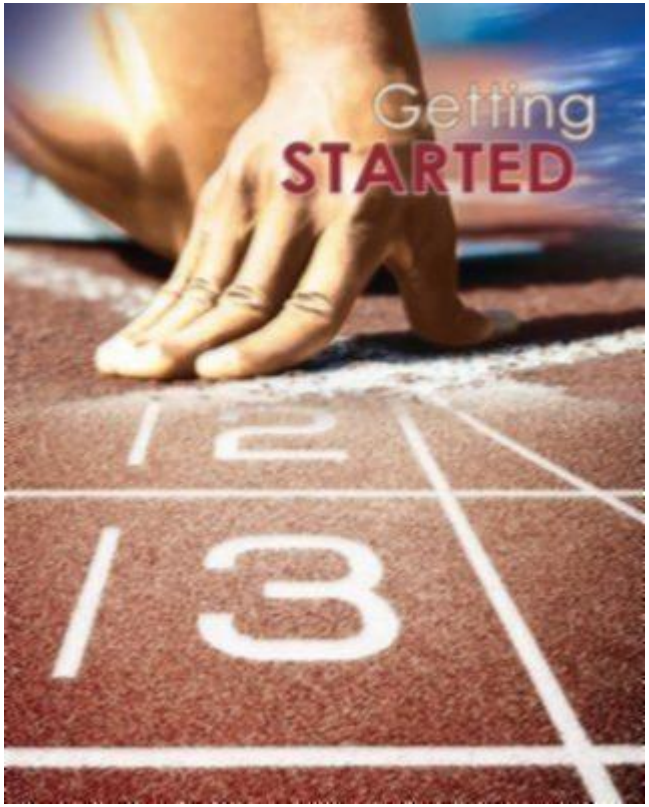

Reference

- ATmega328P datasheet
- AVR 8-bit instruction set
- AVR1022: assembler user guide
- M. A. Mazidi, S. Naimi, and S. Naimi, *The AVR Microcontroller and Embedded Systems: Using Assembly and C*, Prentice Hall, 2010
- AVR GCC library help http://nongnu.org/avr-libc/user-manual/modules.html