# CT.2306: Signal & Systems II

# Report

Processing motion signals from a PTZ camera



Philéas CURTIL, Thomas MAFILLE, Rémy MAILLARD

January  $7^{\text{th}}$ , 2024



Made with LaTeX

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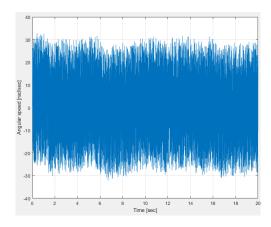
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## 1 Data visualization

1) When we load data-proj.mat, we can see that there are two vectors in the file:

Name Size omega 1x20001 t 1x20001

2) Plot of the angular speed *omega* as a function of time.



```
To obtain this graph:

figure(1)
plot(t, omega)
grid on
hold on
xlabel('Time [sec]')
ylabel('Angular speed [rad/sec]'
)
```

Figure 1: Angular speed as a function of time

It is not possible to use the signal as it is now, mostly because there is too much information (too noisy) or the window is too large. This signal is continuous (analog). Electronic control devices requires digital signals.

## 2 Analog filtering

3) The sampling period  $T_{e_1}$  can be calculated with :

```
Te1=t(2)-t(1)
>>Te1 =
1.0000e-03
```

4) Plot of the amplitude spectrum of omega(t), with the use of the workshop 5:

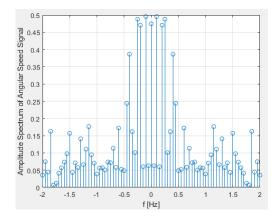


Figure 2: DFT plot of omega(t)

```
To obtain this graph:
```

```
% Plot of the DFT of omega(t)
Te2 = 0.05;
Fe1=1/Te1;
Tf=t(end);
N=Tf/Te1;
f1 = -Fe1 * (N/2-1)/N : Fe1/N : 0;
f2=Fe1/N:Fe1/N:(N/2)*Fe1/N;
f = [f2, f1];
w = zeros(N,1);
for m=1:N
  for k=1:N
    w(m) = w(m) + omega(k) * exp(-1i
       *2*pi*m*k/N);
  end
end
figure(2)
stem(f,abs(w)/N)
grid on
xlim([-2 2])
xlabel('f [Hz]')
ylabel('Amplitude Spectrum of
   Angular Speed Signal')
```

5) The frequencies contained inside the signal are ranging from -2 Hz to 2 Hz with a step of 0.05.

```
F_{max} = 2Hz
```

6) The cutoff frequency is  $f_c = 2Hz$ . On Matlab:

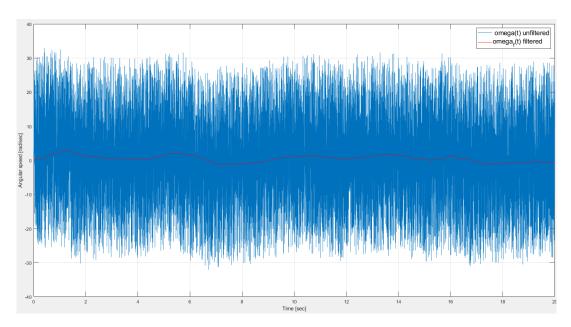


Figure 3: omega(t) filtered and unfiltered  $(omega_f(t))$ 

```
To obtain this graph:
```

```
% filter design
t1=0:Te1:t(end)-Te1;
fc=0.2;
wc=2*pi*fc;

H1=tf(1,[1/(2*pi*fc) 1]);
wf=lsim(H1,omega,t);

% plot of filtered signal
figure(1);
plot(t,wf,'r')
hold off
grid on
legend(' omega(t) unfiltered','omega_{f}(t) filtered','Fontsize',
14)
```

#### On Simulink:

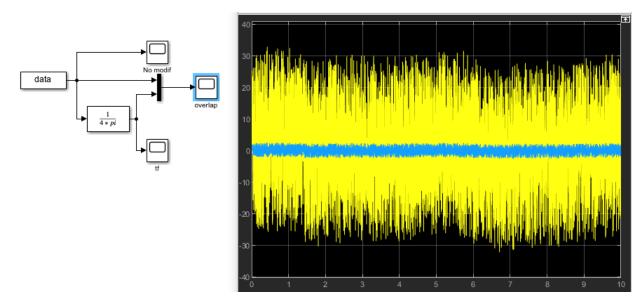


Figure 4: Simulink

We need to add a part in the Matlab code as well :

7) Plot of the amplitude spectrum of  $omega_f(t)$ , with the use of the workshop 5:

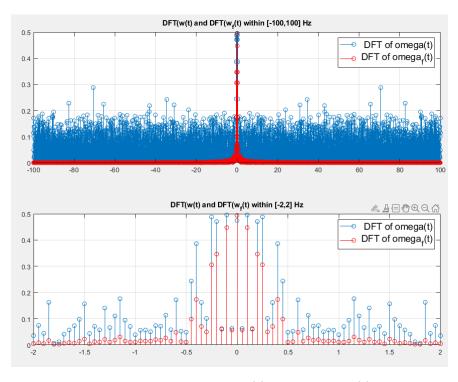


Figure 5: DFT plot of omega(t) and  $omega_f(t)$ 

```
subplot(2,1,2);\\ stem(f,abs(w)/N), hold on\\ stem(f,abs(wf1)/N, 'r'), hold off\\ grid on\\ xlim([-2 2])\\ legend(' DFT of omega(t)','DFT of omega_{f}(t)','Fontsize',14)\\ title('DFT(w(t) and DFT(w_{f}(t) within [-2,2] Hz'))
```

legend(' DFT of omega(t)','DFT of omega\_{f}(t)','Fontsize',14)

title('DFT(w(t) and DFT( $w_{f}(t)$  within [-100,100] Hz')

xlim([-100 100])

## 3 Sampling

8) To create a vector  $omega_e(t)$  which contains the values of the vector  $omega_f(t)$  with a period between the values of  $T_{e2} = 0.05$  sec.

```
temp1 = 1:round(Te2/Te1):length(t);
we=wf(temp1);
Te = t(temp1);
```

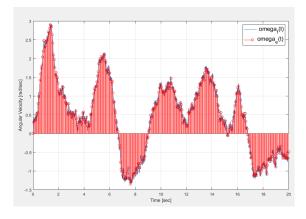
9) To get the size of  $omega_e(t)$ , we use :

```
>> size(we)
ans =
401 1
```

10) The new vector  $t_e$  which corresponds to the vector  $omega_e(t)$  can be created using:

```
temp1 = 1:round(Te2/Te1):length(t);
we=wf(temp1);
Te = t(temp1);
```

11) Plot of  $omega_f(t)$  and  $omega_e(t)$ :



```
figure(4)
plot(t,wf), hold on
xlabel('Time [sec]')
ylabel('Angular Velocity [rad/
    sec]')
grid on
stem(Te,we, 'r'), hold off
legend(' omega_{f}(t)','omega_{e}(t)','Fontsize',14)
```

Figure 6: Plot of  $omega_f(t)$  and  $omega_e(t)$ 

To plot the graph between 10 and 12, we add xlim([10 12]) to the Matlab code.

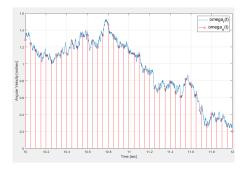


Figure 7: Plot of  $omega_f(t)$  and  $omega_e(t)$ , focused between 10 and 12

```
figure(4)
plot(t,wf), hold on
xlim([10 12])
xlabel('Time [sec]')
ylabel('Angular Velocity [rad/
    sec]')
grid on
stem(Te,we, 'r'), hold off
legend(' omega_{f}(t)','omega_{e}(t)','Fontsize',14)
```

#### 12) Plot of omega(t), $omega_f(t)$ and $omega_e(t)$ :

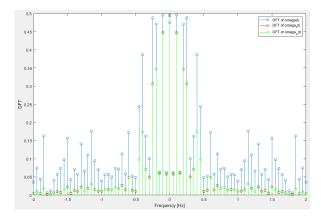


Figure 8: Plot of  $omega_f(t)$  and  $omega_e(t)$ 

```
Fe2=1/Te2;
Tf2=Te(end);
N2=Tf2/Te2;
f3 = -Fe2 * (N2/2 - 1) / N2 : Fe2/N2 : 0;
f4=Fe2/N2:Fe2/N2:(N2/2)*Fe2/N2;
f_2=[f4,f3];
we_dft = zeros(N2,1);
for m = 1 : N2
    for k = 1 : N2
        we_dft(m) = we_dft(m) +
           we(k) * exp(-1i*2*pi*
           m*k/N2);
    end
end
figure (5)
stem(f,abs(w)/N), hold on
stem(f,abs(wf1)/N, 'r')
stem(f_2,abs(we_dft)/N2, 'g'),
   hold off
xlabel('Frequency [Hz]')
ylabel('DFT')
legend({'DFT of omega(t)', 'DFT
   of omega_f(t)', 'DFT of
   omega_e(t)'})
xlim([-2 2])
```

## 4 Angular position and acceleration

13) To calculate the angular acceleration omegadot(t) and the position theta(t):

```
% angular acceleration
wd_start=(we(2)-we(1))/Te2;
wd_end=(we(end)-we(end-1))/Te2;
wd_mid=zeros(8,1);
for i=2:N2-1
    wd_mid(i)=(we(i+1)-we(i-1))/(2*Te2);
end
wd=[wd_start;wd_mid;wd_end];

% angular position
theta=zeros(N2,1);

for i=1:N2
    for k=1:i+2
        theta(i)=theta(i)+Te2*we(k);
    end
end
```

14) We can now plot the two graphs for theta(t) and omega'(t):

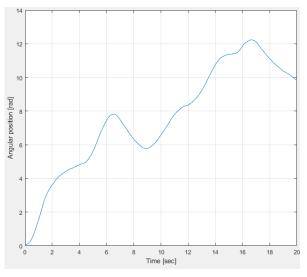


Figure 9: Plot of theta(t)

Figure 10: Plot of omega'(t)

To get the plots:

```
t_ang=0:Te2:Te(end)-Te2;

figure(6)
plot(t_ang, theta)
xlabel('Time [sec]')
ylabel('Angular position [rad]')
grid on
```

```
figure(7)
plot(Te,wd)
xlabel('Time [sec]')
ylabel('Angular acceleration [rad/s^2]')
grid on
```

15) The plot of the DFt of theta(t) and omega'(t):

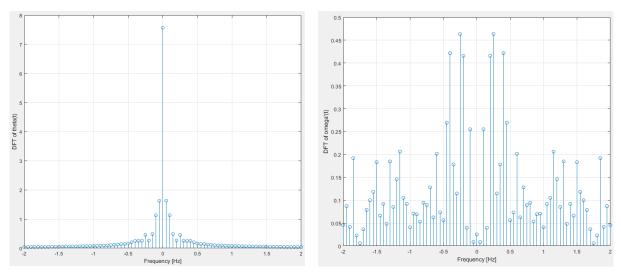


Figure 11: Plot of DFT(theta(t))

Figure 12: Plot of DFT(omega'(t))

To get the plots and calculate the DFT of omega'(t) and theta(t):

```
wd_dft=zeros(N2,1);
for m=1:N2
    for k=1:N2
        wd_dft(m) = wd_dft(m) + wd(k) * exp(-1i*2*pi*m*k/N2);
    end
end
theta_dft = zeros(N2,1);
for m=1:N2
    for k=1:N2
        theta_dft(m)=theta_dft(m)+theta(k)*exp(-1i*2*pi*m*k/N2);
    end
end
figure(8)
stem(f_2,abs(theta_dft)/N2)
xlim([-2 2])
grid on
xlabel('Frequency [Hz]')
ylabel('DFT of theta(t)')
figure (9)
stem(f_2,abs(wd_dft)/N2)
xlim([-2 2])
grid on
xlabel('Frequency [Hz]')
ylabel("DFT of omega'(t)")
```

# 5 Digital filtering

- 16) A
- 17) A
- 18) A