

DifferentialDrive::Init



```
graph LR; A[DifferentialDrive::Init] --> B[Wheel::Init];
```

A diagram showing a call from `DifferentialDrive::Init` to `Wheel::Init`. The first box is white with a black border, and the second box is gray with a black border. A blue arrow points from the right side of the first box to the left side of the second box.

Wheel::Init