

DifferentialDrive::Init



```
graph LR; A[DifferentialDrive::Init] --> B[Wheel::Init]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is gray and contains the text 'DifferentialDrive::Init'. The right box is white and contains the text 'Wheel::Init'. A blue arrow points from the right side of the gray box to the left side of the white box.

Wheel::Init