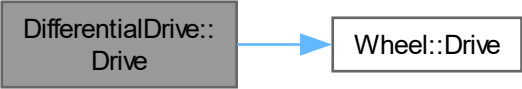


DifferentialDrive::
Drive



```
graph LR; A[DifferentialDrive:: Drive] --> B[Wheel:: Drive]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is gray and contains the text 'DifferentialDrive:: Drive'. The right box is white and contains the text 'Wheel:: Drive'. A blue arrow points from the right side of the gray box to the left side of the white box.

Wheel::Drive