Nanosatellite Reaction Wheels (RW-0.03)



| Momentum | Nominal: 0.03 Nms Peak: 0.04 Nms (at 5 V supply) |
|-----------------------------|---|
| Torque | ±2 mNm at 0.02 Nms ±0.5 mNm at 0.04 Nms (at 5 V supply) |
| Control Mode | Speed or torque with built-in control CPU |
| Command / Telemetry | UART or I ² C/SMBus |
| Mechanical | Dimensions: 50 mm x 50 mm x 40 mm Mass: 185 g |
| Supply Voltage | Nominal: 3.4 V to 6.0 V Maximum: 8 V |
| Supply Power (in vacuum) | 1.8 W @ 0.02 Nms, +2 mNm 0.3 W @ 0.04 Nms, steady state 0.1 W @ 0.01 Nms, steady state |
| Environment | Thermal: −40°C to +70°C (operating) Vibration: >12 g _{RMS} Radiation: >20 krad dose |
| Reliability | Diamond coated hybrid ball bearings Redundant motor windings Radiation lot-screened parts (optional) |
| Heritage | 30 Units total on-orbit, on 12 satellites First launch April 28, 2008, all still working well. Demonstrated 12 arc-sec RMS pointing on 7 kg satellite |
| Price | US\$25,000 each, +US\$2,000 for radiation lot-screened parts |







