Príklad: Majme preurčený systém rovníc

$$-14,16\hat{\theta}_{0} + \hat{\theta}_{1} = -2,04$$

$$-12,6\hat{\theta}_{0} + \hat{\theta}_{1} = 0$$

$$-7,08\hat{\theta}_{0} + \hat{\theta}_{1} = 4,08$$

$$-4,92\hat{\theta}_{0} + \hat{\theta}_{1} = 7,92$$

1. Rekurzívna metóda najmenších štvorcov

$$\begin{pmatrix} -14,16 & 1 \\ -12,6 & 1 \\ -7,08 & 1 \\ -4,92 & 1 \end{pmatrix} \begin{pmatrix} \hat{\theta}_0 \\ \hat{\theta}_1 \end{pmatrix} = \begin{pmatrix} -2,04 \\ 0 \\ 4,08 \\ 7,92 \end{pmatrix} \qquad n=2$$

$$\mathbf{\check{S}tart} \quad \boxed{\mathbf{P}_{N} = \left(\mathbf{H}_{N}^{\mathsf{T}}\mathbf{H}_{N}\right)^{-1}} \quad \boxed{\hat{\boldsymbol{\theta}}_{N}^{\star} = \mathbf{P}_{N}\mathbf{H}_{N}^{\mathsf{T}}\mathbf{y}_{N}}$$

$$\begin{split} \mathbf{N} &= 2 & \mathbf{H}_{2} = \begin{pmatrix} -14,16 & 1 \\ -12,6 & 1 \end{pmatrix} \\ \mathbf{R}_{2} &= \mathbf{H}_{2}^{\mathsf{T}} \mathbf{H}_{2} = \begin{pmatrix} -14,16 & -12,6 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} -14,16 & 1 \\ -12,6 & 1 \end{pmatrix} = \begin{pmatrix} 359,2656 & -26,76 \\ -26,76 & 2 \end{pmatrix} \\ \mathbf{P}_{2} &= \mathbf{R}_{2}^{-1} = \begin{pmatrix} 359,2656 & -26,76 \\ -26,76 & 2 \end{pmatrix}^{-1} = \begin{pmatrix} 0,8218 & 10,9961 \\ 10,9961 & 147,6272 \end{pmatrix} \\ \hat{\boldsymbol{\theta}}_{2}^{\star} &= \begin{pmatrix} 0,8218 & 10,9961 \\ 10,9961 & 147,6272 \end{pmatrix} \begin{pmatrix} -14,16 & -12,6 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -2,04 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1,3077 \\ 16,4769 \end{pmatrix} \end{split}$$

$$\begin{aligned} \textbf{d}_{N+1} &= \textbf{P}_N \textbf{h}_{N+1} & \rho_{N+1} &= \left(1 + \textbf{h}_{N+1}^T \textbf{d}_{N+1} \right)^{-1} \\ \textbf{e}_{N+1} &= \textbf{y}_{N+1} - \textbf{h}_{N+1}^T \hat{\boldsymbol{\theta}}_N^* & Q(\hat{\boldsymbol{\theta}}_{N+1}^*) &= Q(\hat{\boldsymbol{\theta}}_N^*) + \rho_{N+1} \textbf{e}_{N+1}^2 \\ \hat{\boldsymbol{\theta}}_{N+1}^* &= \hat{\boldsymbol{\theta}}_N^* + \rho_{N+1} \textbf{e}_{N+1} \textbf{d}_{N+1} & \textbf{P}_{N+1} &= \left(\textbf{I} - \rho_{N+1} \textbf{d}_{N+1} \textbf{h}_{N+1}^T \right) \textbf{P}_N \end{aligned}$$

$$\mathbf{d}_{3} = \begin{pmatrix} 0.8218 & 10.9961 \\ 10.9961 & 147.6272 \end{pmatrix} \begin{pmatrix} -7.08 \\ 1 \end{pmatrix} = \begin{pmatrix} 5.1775 \\ 69.7752 \end{pmatrix}$$

$$\rho_{3} = \left[1 + \left(-7.08 & 1 \right) \begin{pmatrix} 5.1775 \\ 69.7752 \end{pmatrix} \right]^{-1} = 0.0293$$

$$\mathbf{e}_{3} = 4.08 - \left(-7.08 & 1 \right) \begin{pmatrix} 1.3077 \\ 16.4763 \end{pmatrix} = -3.1384$$

$$Q_{4} = 0 + 0.0293 & 3.1384^{2} = 0.2886$$

$$Q_3 = 0 + 0,0293.3,1384^2 = 0,2886$$

$$\hat{\mathbf{\theta}}_{3}^{\star} = \begin{pmatrix} 1,3077 \\ 16,4769 \end{pmatrix} - 0,0293.3,1384 \begin{pmatrix} 5,1775 \\ 69,7752 \end{pmatrix} = \begin{pmatrix} 0,8314 \\ 10,0585 \end{pmatrix}$$

$$\mathbf{P}_{3} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - 0,0293. \begin{pmatrix} 5,1775 \\ 69,7752 \end{pmatrix} (-7,08 \ 1) \mathbf{P}_{2} = \begin{pmatrix} 0,0362 & 0,4076 \\ 0.4076 & 4.9309 \end{pmatrix}$$

$$\mathbf{d}_4 = \begin{pmatrix} 0,0362 & 0,4076 \\ 0,4076 & 4,9309 \end{pmatrix} \begin{pmatrix} -4,92 \\ 1 \end{pmatrix} = \begin{pmatrix} 0,2299 \\ 2,9256 \end{pmatrix}$$

$$\rho_4 = \left[1 + \left(-4,92 \quad 1\right) \begin{pmatrix} 0,2299 \\ 2,9256 \end{pmatrix}\right]^{-1} = 0,3579$$

$$e_4 = 7,92 - \left(-4,92 \quad 1\right) \begin{pmatrix} 0,8314 \\ 10,0585 \end{pmatrix} = -1,9520$$

$$Q_4 = Q_3 + 0.3579 \cdot 1.9520^2 = 1.6522$$

$$\hat{\boldsymbol{\theta}}_{4}^{\star} = \begin{pmatrix} 0,8314 \\ 10,0585 \end{pmatrix} - 0,3579 \cdot 1,9520 \begin{pmatrix} 0,2299 \\ 2,9256 \end{pmatrix} = \begin{pmatrix} 0,9920 \\ 12,1020 \end{pmatrix}$$

2. Odmocninová verzia RMNŠ

$$\mathbf{P}_{2} = \left(\mathbf{H}_{2}^{\mathsf{T}}\mathbf{H}_{2}\right)^{-1} = \begin{pmatrix} 0.8218 & 10.9961 \\ 10.9961 & 147.6272 \end{pmatrix}$$

Štart: N=2 Určenie **G**₂ Choleskeho algoritmom

$$\begin{split} g_{11} &= \pm \sqrt{p_{11}} \\ g_{1j} &= \frac{1}{g_{11}} p_{1j} & j = 2, 3, ..., n \\ g_{ii} &= \pm \sqrt{p_{ii} - \sum_{k=1}^{i-1} g_{ki}^2} & i = 2, 3, ..., n \\ g_{ij} &= \frac{1}{g_{ii}} \left(p_{ij} - \sum_{k=1}^{i-1} g_{ki} g_{kj} \right) & j = i+1, ..., n \end{split}$$

$$g_{11} = \sqrt{0.8218} = 0.9066$$
 $g_{12} = \frac{10.9961}{0.9066} = 12.1296$

$$g_{22} = \sqrt{147,6272 - 12,1296^2} = 0,7071$$

$$\begin{aligned} g_{22} &= \sqrt{147,6272 - 12,1296^2} = 0,7071 \\ G_2 &= \begin{pmatrix} 0,9066 & 12,1296 \\ 0 & 0,7071 \end{pmatrix} \end{aligned}$$

$$\hat{\boldsymbol{\theta}}_2^{\star} = \boldsymbol{\mathsf{G}}_2^{\mathsf{T}} \boldsymbol{\mathsf{G}}_2 \boldsymbol{\mathsf{H}}_2^{\mathsf{T}} \boldsymbol{\mathsf{y}}_2 = \begin{pmatrix} 1,3077\\16,4769 \end{pmatrix}$$

$$\begin{aligned} & \mathbf{e}_{N+1} = \mathbf{y}_{N+1} - \mathbf{h}_{N+1}^T \hat{\mathbf{\theta}}_N^* \\ & \rho_{N+1} = \left(1 + \mathbf{z}_{N+1}^T \mathbf{z}_{N+1}\right)^{-1} \\ & \hat{\mathbf{\theta}}_{N+1}^* = \hat{\mathbf{\theta}}_N^* + \rho_{N+1} \mathbf{e}_{N+1}^T \mathbf{g}_{N+1}^T \end{aligned} \qquad \qquad \mathbf{z}_{N+1} = \mathbf{G}_N \mathbf{h}_{N+1} \\ & \mathbf{Q} (\hat{\mathbf{\theta}}_N^*) + \rho_{N+1} \mathbf{e}_{N+1}^T \mathbf{e}_{N+1}^T \\ & \mathbf{G}_{N+1} = \left(\mathbf{I} - \frac{\rho_{N+1}}{1 + \sqrt{\rho_{N+1}}} \mathbf{z}_{N+1} \mathbf{z}_{N+1}^T \right) \mathbf{G}_N$$

$$e_3 = 4,08 - \left(-7,08 \quad 1\right) \begin{pmatrix} 1,3077 \\ 16,4763 \end{pmatrix} = -3,1384$$

$$\mathbf{z}_{3} = \begin{pmatrix} 0,9066 & 12,1296 \\ 0 & 0,7071 \end{pmatrix} \begin{pmatrix} -7,08 \\ 1 \end{pmatrix} = \begin{pmatrix} 5,7112 \\ 0,7071 \end{pmatrix}$$

$$\rho_3 = \left\lceil 1 + \left(5,7112 \quad 0,7071 \right) \binom{5,7112}{0,7071} \right\rceil^{-1} = 0,0293$$

$$Q_3 = 0 + 0.0293.3.1384^2 = 0.2886$$

$$\boldsymbol{\hat{\theta}}_{3}^{\star} = \begin{pmatrix} 1{,}3077 \\ 16{,}4769 \end{pmatrix} - 0{,}0293.3{,}1384 \begin{pmatrix} 0{,}9066 & 0 \\ 12{,}1296 & 0{,}7071 \end{pmatrix} \begin{pmatrix} 5{,}7112 \\ 0{,}7071 \end{pmatrix} = \begin{pmatrix} 0{,}8314 \\ 10{,}0584 \end{pmatrix}$$

$$\mathbf{G}_{3} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \frac{0,0293}{1 + \sqrt{0,0293}} \cdot \begin{pmatrix} 5,7112 \\ 0,7071 \end{pmatrix} (5,7112...0,7071) \\ \mathbf{G}_{2} = \begin{pmatrix} 0,1665 & 2,1569 \\ -0,0961 & -0,5276 \end{pmatrix}$$

$$e_4 = 7,92 - \left(-4,92 \quad 1\right) \begin{pmatrix} 0,8314 \\ 10,0585 \end{pmatrix} = -1,9520$$

$$\mathbf{z}_4 = \mathbf{G}_3 \begin{pmatrix} -4.92 \\ 1 \end{pmatrix} = \begin{pmatrix} 1.3375 \\ -0.0768 \end{pmatrix}$$

$$\rho_4 = \left[1 + \left(1{,}3375 - 0{,}0768\right) \left(1{,}3375 - 0{,}0768\right)\right]^{-1} = 0{,}3578$$

$$Q_4 = Q_3 + 0.3578 \cdot 1.9520^2 = 1.6522$$

$$\hat{\pmb{\theta}}_{4}^{\star} = \begin{pmatrix} 0,8314 \\ 10,0585 \end{pmatrix} - 0,3578.1,9520 \begin{pmatrix} 0,1665 & -0,0961 \\ 2,1569 & -0,5276 \end{pmatrix} \begin{pmatrix} 1,3375 \\ -0,0768 \end{pmatrix} = \begin{pmatrix} 0,9919 \\ 12,1018 \end{pmatrix}$$

3. Rekurzívne algoritmy Peterku

$$\begin{pmatrix} -14,16 & 1 \\ -12,6 & 1 \\ -7,08 & 1 \\ -4,92 & 1 \end{pmatrix} \begin{pmatrix} \hat{\theta}_0 \\ \hat{\theta}_1 \end{pmatrix} = \begin{pmatrix} -2,04 \\ 0 \\ 4,08 \\ 7,92 \end{pmatrix} \qquad \lambda = 1$$

$$\lambda = 1$$

Štart: Nech N=3

$$\mathbf{V}_{3} = \mathbf{Z}_{3}^{\mathsf{T}} \mathbf{Z}_{3} = \begin{pmatrix} -14.16 & -12.6 & -7.08 \\ 1 & 1 & 1 \\ -2.04 & 0 & 4.08 \end{pmatrix} \begin{pmatrix} -14.16 & 1 & -2.04 \\ -12.6 & 1 & 0 \\ -7.08 & 1 & 4.08 \end{pmatrix} = \begin{pmatrix} 409.39 & -33.84 & 0 \\ -33.84 & 3 & 2.04 \\ 0 & 2.04 & 20.81 \end{pmatrix}$$

$$\mathbf{R}_{3} = \mathbf{V}_{3}^{-1} = \begin{pmatrix} 2.431 & 29.375 & -2.880 \\ 29.375 & 355.375 & -34.841 \\ -2.88 & -34.841 & 3.464 \end{pmatrix}$$

3.1 REFIL (Odmocninový rozklad)

$$\begin{split} g_{nn} &= \sqrt{r_{nn}} \\ g_{nj} &= \frac{1}{g_{nn}} r_{nj} & j = 1, ..., n-1 \\ g_{ii} &= \sqrt{r_{ii} - \sum_{k=i+1}^{n} g_{ki}^{2}} & i = n-1, ..., 1 \\ g_{ij} &= \frac{1}{g_{ii}} \left(r_{ij} - \sum_{k=i+1}^{n} g_{ki} g_{kj} \right) & j = i-1, ..., 1 \end{split}$$

Štart: Na ilustráciu vypočítame maticu \mathbf{G}_3 z matice \mathbf{R}_3 :

$$\begin{split} g_{33} &= \sqrt{r_{33}} = \sqrt{3,4638} = 1,8611 \\ g_{32} &= \frac{r_{32}}{g_{33}} = \frac{-34,8407}{1,8611} = -18,7202; \\ g_{31} &= \frac{r_{31}}{g_{33}} = \frac{-2,8799}{1,8611} = -1,5474 \\ g_{22} &= \sqrt{r_{22} - g_{32}^2} = \sqrt{355,375 - 18,7202^2} = 2,2205 \\ g_{21} &= \frac{r_{21} - g_{31}g_{32}}{g_{22}} = \frac{29,375 - 1,5474 \cdot 18,7202}{2,2205} = 0,1835 \\ g_{11} &= \sqrt{r_{11} - g_{21}^2 - g_{31}^2} = \sqrt{2,4306 - 0,1835^2 - 1,5474^2} = 0,0494 \\ \mathbf{G}_3 &= \begin{pmatrix} 0.0494 & 0 & 0 \\ 0.1835 & 2.2205 & 0 \\ -1.5474 & -18.7202 & 1.8611 \end{pmatrix} = \begin{pmatrix} \mathbf{\Gamma} & \mathbf{0} \\ \mathbf{g}^\mathsf{T} & \gamma \end{pmatrix} \end{split}$$

$$\begin{split} \hat{\pmb{\theta}}_{k}^{\star} &= -\frac{\pmb{g}}{\gamma} & Q(\hat{\pmb{\theta}}_{k}) = \frac{1}{\gamma^{2}} \\ \pmb{f}_{k+1} &= \pmb{G}_{k} \pmb{z}_{k+1} \\ \pmb{s}_{0}^{2} &= \lambda^{2} & \pmb{s}_{q}^{2} = \pmb{s}_{q-1}^{2} + \pmb{f}_{q}^{2} & q = 1, 2, ..., k \\ \\ ^{k+1} g_{ij} &= \frac{1}{\lambda} \frac{\pmb{s}_{i-1}}{\pmb{s}_{i}} \binom{^{k}}{\mathbf{s}_{ij}} - \frac{\pmb{f}_{i}}{\pmb{s}_{i-1}^{2}} \sum_{m=j}^{i-1} \pmb{f}_{m}^{k} \pmb{g}_{mj} \end{split}$$

$$\hat{\boldsymbol{\theta}}_{3}^{\star} = \frac{1}{1.8611} \begin{pmatrix} 1,5474 \\ 18,7202 \end{pmatrix} = \begin{pmatrix} 0,831 \\ 10,058 \end{pmatrix}$$

$$Q(\hat{\boldsymbol{\theta}}_{3}^{\star}) = \frac{1}{1.8611^{2}} = 0,2887$$

$$\mathbf{f_4} = \mathbf{G_3z_4} = \begin{pmatrix} 0.0494 & 0 & 0 \\ 0.1835 & 2.2205 & 0 \\ -1.5474 & -18.7202 & 1.8611 \end{pmatrix} \begin{pmatrix} -4.92 \\ 1 \\ 7.92 \end{pmatrix} = \begin{pmatrix} -0.2432 \\ 1.3175 \\ 3.6332 \end{pmatrix} = \begin{pmatrix} \mathbf{f_1} \\ \mathbf{f_2} \\ \mathbf{f_3} \end{pmatrix}$$

$$s_0^2 = 1$$

$$s_1^2 = s_0^2 + f_1^2 = 1 + 0.2432^2 = 1.0591$$

$$s_2^2 = s_1^2 + f_2^2 = 1,0591^2 + 1,3175^2 = 2,7948$$

$$s_3^2 = s_2^2 + f_3^2 = 2,7948^2 + 3,6332^2 = 15,9948$$

$$s_0 = 1$$

$$s_1 = 1,0291$$

$$s_2 = 1,6718$$

$$s_3 = 3,9994$$

$$g_{11} = \frac{s_0}{s_1}g_{11} = \frac{0,0494}{1,0291} = 0,0480$$

$$g_{22} = \frac{s_1}{s_2}g_{22} = \frac{1,0291}{1,6718}2,2205 = 1,3669$$

$$g_{33} = \frac{s_2}{s_3}g_{33} = \frac{1,6718}{3,9994}1,8611 = 0,7780$$

$$g_{21} = \frac{s_1}{s_2} \left(g_{21} - \frac{f_2}{s_1^2} f_1 g_{11} \right) = \frac{1,0291}{1,6718} \left[0,1835 - \frac{1,3175}{1,0291^2} . (-0,2432).0,0494 \right] = 0,1222$$

$$g_{31} = \frac{s_2}{s_3} \left(g_{31} - \frac{f_3}{s_2^2} (f_1 g_{11} + f_2 g_{21}) \right) =$$

$$=\frac{1,6718}{3,9994}\left[-1,5474-\frac{3,6332}{1,6718^2}(1,3175.0,1835-0,2432.0,0494)\right]=-0.7718$$

$$g_{32} = \frac{s_2}{s_3} \left(g_{32} - \frac{f_3}{s_2^2} f_2 g_{22} \right) = \frac{1,6718}{3,9994} \left[-18,7202 - \frac{3,6332}{1,6718^2} 1,3175.2,2205 \right] = -9.4149$$

$$\mathbf{G}_{4} = \begin{pmatrix} 0.048 & 0 & 0 \\ 0.1222 & 1.3669 & 0 \\ -0.7717 & -9.4149 & 0.778 \end{pmatrix} = \begin{pmatrix} \mathbf{\Gamma} & \mathbf{0} \\ \mathbf{g}^{\mathsf{T}} & \gamma \end{pmatrix}$$

$$\hat{\mathbf{\theta}}_{4}^{\star} = \frac{1}{0.7780} \begin{pmatrix} 0.7717 \\ 9.4149 \end{pmatrix} = \begin{pmatrix} 0.9919 \\ 12.1018 \end{pmatrix}$$

$$Q(\hat{\mathbf{\theta}}_{4}^{\star}) = \frac{1}{0.7780^{2}} = 1,6522$$

3.2 LDFIL (LDL rozklad)

$$\begin{aligned} d_i &= r_{ii} - \sum_{k=i+1}^n d_k I_{ki}^2 & & i = n, \dots, 1 \\ I_{ij} &= \frac{1}{d_i} \bigg(r_{ij} - \sum_{k=i+1}^n I_{ki} d_k I_{kj} \bigg) & & j = i-1, \dots, 1 \\ I_{ii} &= 1 & & \end{aligned}$$

Štart: Na ilustráciu vypočítame rozklad matice **R**₃:

$$\begin{split} \mathbf{R}_3 &= \begin{pmatrix} 2.4306 & 29.375 & -2.8799 \\ 29.375 & 355.375 & -34.8407 \\ -2.8799 & -34.8407 & 3.4638 \end{pmatrix} \\ &= \mathbf{R} = \begin{pmatrix} \mathbf{A}^\mathsf{T} & \mathbf{A} \\ \mathbf{0}^\mathsf{T} & 1 \end{pmatrix} \begin{pmatrix} \mathbf{\Delta} & \mathbf{0} \\ \mathbf{A}^\mathsf{T} & 1 \end{pmatrix} \begin{pmatrix} \mathbf{A} & \mathbf{0} \\ \mathbf{A}^\mathsf{T} & 1 \end{pmatrix} \\ & \\ \mathbf{A}_3 &= \mathbf{R}_{33} & 3.4638 \\ \mathbf{I}_{32} &= \frac{\mathbf{R}_{32}}{\mathbf{d}_3} &= \frac{-34.8407}{3.4638} = -10.0525 \\ & \\ \mathbf{I}_{31} &= \frac{\mathbf{R}_{31}}{\mathbf{d}_3} &= \frac{-2.8799}{3.4638} = -0.8314 \\ & \\ \mathbf{d}_2 &= \mathbf{R}_{22} - \mathbf{d}_3 \mathbf{I}_{32}^2 &= 355.375 - 3.4638.10.0585^2 = 4.9306 \\ & \\ \mathbf{I}_{21} &= \frac{\mathbf{R}_{21} - \mathbf{d}_3 \mathbf{I}_{32} \mathbf{I}_{31}}{\mathbf{d}_2} &= \frac{29.375 - 3.4638.10.0585.0.8314}{4.9306} = 0.0827 \\ & \\ \mathbf{d}_1 &= \mathbf{R}_{11} - \mathbf{d}_3 \mathbf{I}_{31}^2 - \mathbf{d}_2 \mathbf{I}_{21}^2 &= 2.4306 - 3.4638.0.8314^2 - 4.9306.0.0827^2 = 0.0024 \\ & \\ \mathbf{R}_3 &= \begin{pmatrix} 1 & 0.0827 & -0.8314 \\ 0 & 1 & -10.0585 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0.0024 & 0 & 0 \\ 0 & 4.9306 & 0 \\ 0 & 0 & 3.4638 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0.0827 & 1 & 0 \\ -0.8314 & -10.0585 & 1 \end{pmatrix} \end{split}$$

$$\begin{split} \hat{\boldsymbol{\theta}}_{k}^{\star} &= -\boldsymbol{\lambda} & Q(\hat{\boldsymbol{\theta}}_{k}^{\star}) = \frac{1}{d} \\ \boldsymbol{f}_{k+1} &= \boldsymbol{L}_{k} \boldsymbol{z}_{k} \\ \boldsymbol{s}_{0}^{2} &= \lambda^{2} \\ \boldsymbol{s}_{q}^{2} &= \lambda^{2} + \sum_{k=1}^{q} d_{k} f_{k}^{2} = \boldsymbol{s}_{q-1}^{2} + d_{q} f_{q}^{2} & q = 1, \dots, n \\ \\ \boldsymbol{k}^{+1} d_{i} &= {}^{k} d_{i} \frac{1}{\lambda^{2}} \frac{\boldsymbol{s}_{i-1}^{2}}{\boldsymbol{s}_{i}^{2}} & {}^{k+1} \boldsymbol{I}_{ij} &= {}^{k} \boldsymbol{I}_{ij} - \frac{f_{i}}{\boldsymbol{s}_{i-1}^{2}} \sum_{m=j}^{i-1} f_{m} {}^{k} d_{m} {}^{k} \boldsymbol{I}_{mj} \end{split}$$

$$\hat{\boldsymbol{\theta}}_{3}^{\star} = -\boldsymbol{\lambda} = \begin{bmatrix} 0.8314 \ 10.0585 \end{bmatrix}^{T}$$

$$Q(\hat{\boldsymbol{\theta}}_3^*) = \frac{1}{d} = \frac{1}{3.4638} = 0.2887$$

$$\mathbf{f}_4 = \mathbf{L}_3 \mathbf{z}_4 = \begin{pmatrix} 1 & 0 & 0 \\ 0.0827 & 1 & 0 \\ -0.8314 & -10.0585 & 1 \end{pmatrix} \begin{pmatrix} -4.92 \\ 1 \\ 7.92 \end{pmatrix} = \begin{pmatrix} -4.92 \\ 0.5933 \\ 1.9521 \end{pmatrix}$$

$$s_0 = 1$$

 $s_1^2 = s_0^2 + d_1 f_1^2 = 1 + 0,0024.4,92^2 = 1,0591$

$$s_2^2 = s_1^2 + d_2 f_2^2 = 1,0591 + 4,9306.0,5933^2 = 2,7948$$

$$s_3^2 = s_2^2 + d_3 f_3^2 = 2,7948 + 3,4638.1,9521^2 = 15,9948 = \lambda^2 + f^\mathsf{T} \, \mathsf{D} \, f$$

$$d_1 = \frac{s_0^2}{s_1^2} d_1 = \frac{1}{1,0591} 0,0024 = 0,0023 \qquad \qquad I_{21} = I_{21} - \frac{f_1 f_2}{s_1^2} d_1 = 0,0894$$

$$d_2 = \frac{s_1^2}{s_2^2}d_2 = \frac{1,0591}{2,7948}4,9306 = 1,8685$$

$$I_{32} = I_{32} - \frac{f_2f_3}{s_2^2}d_2 = -12,1018$$

$$d_3 = \frac{s_2^2}{s_3^2}d_3 = \frac{2,7948}{15,9948}3,4638 = 0,6052 \qquad \qquad I_{31} = I_{31} - \frac{f_3}{s_3^2} \Big[I_{21}f_1d_1 + f_2d_1\Big] = -0,9919$$

$$I_{21} = I_{21} - \frac{f_1 f_2}{s_1^2} d_1 = 0,0894$$

$$I_{32} = I_{32} - \frac{f_2 f_3}{s_2^2} d_2 = -12,1018$$

$$I_{31} = I_{31} - \frac{f_3}{s_3^2} [I_{21}f_1d_1 + f_2d] = -0,9919$$

$$\mathbf{D}_4 = \begin{pmatrix} 0.0023 & 0 & 0 \\ 0 & 1.8685 & 0 \\ 0 & 0 & 0.6052 \end{pmatrix} \qquad \mathbf{L}_4 = \begin{pmatrix} 1 & 0 & 0 \\ 0.0894 & 1 & 0 \\ -0.9919 & -12.1018 & 1 \end{pmatrix}$$

$$\mathbf{L}_4 = \begin{pmatrix} 1 & 0 & 0 \\ 0.0894 & 1 & 0 \\ -0.9919 & -12.1018 & 1 \end{pmatrix}$$

$$\boldsymbol{\hat{\theta}}_4 = -\boldsymbol{\lambda} = \begin{bmatrix} 0.9919 & 12.1018 \end{bmatrix}^T$$

$$Q(\hat{\boldsymbol{\theta}}_{4}^{*}) = \frac{1}{d} = \frac{1}{0.6052} = 1.6522$$