Assignment7

November 25, 2024

1 Assignment 7

1.1 Objective

Build a Long Short-Term Memory (LSTM) recurrent neural network to predict the current global active power at the time step (t), given prior measurements at the time step (t-1).

2 Recurrent Neural Network

2.1 Part 1 - Data Preprocessing

2.1.1 Importing the libraries

```
import required libraries
import pandas as pd
import numpy as np
from sklearn.preprocessing import MinMaxScaler
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
from tensorflow.keras.callbacks import EarlyStopping, ModelCheckpoint,
ReduceLROnPlateau
from sklearn.metrics import mean_absolute_error, mean_squared_error, r2_score
import tensorflow as tf
import matplotlib.pyplot as plt
```

2.1.2 Importing the training set

```
print("Dataset head:")
display(df.info())
```

Dataset head:

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 2075259 entries, 0 to 2075258

Data columns (total 8 columns):

#	Column	Dtype	
0	DateTime	datetime64[ns]	
1	Global_active_power	float64	
2	<pre>Global_reactive_power</pre>	float64	
3	Voltage	float64	
4	Global_intensity	float64	
5	Sub_metering_1	float64	
6	Sub_metering_2	float64	
7	Sub_metering_3	float64	
<pre>dtypes: datetime64[ns](1), float64(7)</pre>			
memory usage: 126.7 MB			

None

2.2 Checking for missing data

Filling missing data using forward fill method

```
[45]: # Check for missing values
print("\nMissing values:")
display(df.isnull().sum())

# Fill missing values (e.g., forward-fill)
df.fillna(method='ffill', inplace=True)
```

Missing values:

```
DateTime
                              0
Global_active_power
                          25979
Global_reactive_power
                          25979
Voltage
                         25979
Global_intensity
                         25979
Sub_metering_1
                         25979
Sub_metering_2
                         25979
Sub_metering_3
                         25979
dtype: int64
```

2.3 Create Time Sequence

Created reusable functions to prepare the time sequences

```
[46]: # Create sequences function
      def prepare_sequences(data, seq_length):
          """Prepare sequences for time series prediction"""
          X, y = [], []
          for i in range(seq_length, len(data)):
              X.append(data[i-seq_length:i, 0])
              y.append(data[i, 0])
          return np.array(X), np.array(y)
      def create_sequences(data, seq_length):
          """Create sequences for time series prediction"""
          xs, ys = [], []
          for i in range(len(data) - seq_length):
              x = data[i:(i + seq_length)]
              y = data[i + seq_length]
              xs.append(x)
              ys.append(y)
          return np.array(xs), np.array(ys)
```

```
[47]: #Visualize time series
    time = pd.Series(range(len(df)))

# Set parameters
    seq_length = 100  # Number of time steps to look back
    train_split = 0.8  # Training data percentage

# Extract and normalize the data
    data = df['Global_active_power'].values.reshape(-1, 1)

# Split into train and test sets
    train_size = int(len(data) * train_split)
    X_train = time[:train_size]
    y_train = data[:train_size]
    X_test = time[train_size:]
    y_test = data[train_size:]

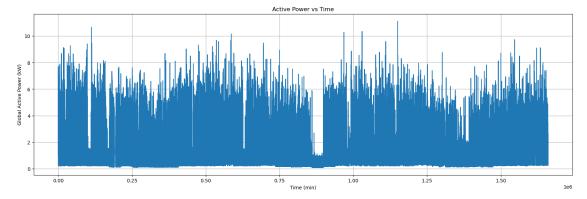
print("Training set shape:", X_train.shape)
    print("Test set shape:", X_test.shape)
```

Training set shape: (1660207,) Test set shape: (415052,)

The sequence length greatly determines the training time and long term sequence. I initially tried to train the model on a yearly basis but it would take over 50 hours to complete the training process. I then reduced it to 100 data points.

```
[48]: #Visualize the time series data plt.figure(figsize=(20, 6)) # Width=10 inches, Height=6 inches
```

```
plt.plot(X_train, y_train)
plt.xlabel('Time (min)')
plt.ylabel('Global Active Power (kW)')
plt.title('Active Power vs Time')
plt.grid(True)
plt.show()
```



Looking at the data plotted above, there does not seem to have any obvious correlation. It might be worth noting that there is sudden drop in the middle of the data that could coincide with a storm/ strike which would cause a power outage.

2.4 Normalization and feature scaling

```
[49]: # Normalize the series using MinMaxScaler
scaler = MinMaxScaler(feature_range=(0, 1))
x_train_scaled = scaler.fit_transform(np.array(y_train).reshape(-1, 1)).
flatten()
x_valid_scaled = scaler.transform(np.array(y_test).reshape(-1, 1)).flatten()
# Now the data is scaled to the range [0, 1] for both training and validation
```

3 Preparing Features and labels

```
[50]: # parameters
window_size = 100
batch_size = 64
shuffle_buffer_size = 1000

# Define the dataset function to create windowed datasets for training and_______
validation

def window_dataset(series, window_size, batch_size, shuffle_buffer):
    dataset = tf.data.Dataset.from_tensor_slices(series)
    dataset = dataset.window(window_size + 1, shift=1, drop_remainder=True)
```

3.1 Part 2 - Building and Training the RNN

3.1.1 Build model

Since the data spans over a couple years and has resolution of 1 minute, I decided to overlook the convolution layer for short term patterns. Instead, I opted for two layers of LSTM before applying a regression layer.

I also changed the default learning rate to 0.001 to make sure the model does not miss subtle changes.

There are **dropouts** included to help with overfitting.

```
[]: from tensorflow.keras import layers, models
     from keras.models import Sequential
     from keras.layers import Dense
     from keras.layers import LSTM
     from keras.layers import Dropout
     # Define the model
     model = models.Sequential([
         # 1. LSTM Layer for capturing temporal dependencies
         layers.LSTM(64, return_sequences=True, input_shape=[window_size, 1]),
         layers.Dropout(0.2), # Dropout layer to prevent overfitting
         layers.LSTM(64),
         layers.Dropout(0.2),
         # 2. Dense Layers for final prediction
         layers.Dense(32, activation="relu"),
         layers.Dense(1) # Final output layer for regression
     ])
     # Compile the model with Mean Absolute Error (MAE) loss
     model.compile(loss="mae", optimizer=tf.keras.optimizers.Adam(learning_rate=0.
      →001))
```

model.summary()

c:\Users\kylea\anaconda3\lib\site-packages\keras\src\layers\rnn\rnn.py:204:
UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.

super().__init__(**kwargs)

Model: "sequential_2"

Layer (type)	Output Shape	Param #
lstm_4 (LSTM)	(None, 100, 64)	16,896
dropout (Dropout)	(None, 100, 64)	0
lstm_5 (LSTM)	(None, 64)	33,024
dropout_1 (Dropout)	(None, 64)	0
dense_4 (Dense)	(None, 32)	2,080
dense_5 (Dense)	(None, 1)	33

Total params: 52,033 (203.25 KB)

Trainable params: 52,033 (203.25 KB)

Non-trainable params: 0 (0.00 B)

3.1.2 Train Model

```
callbacks=[early_stopping]
)
# Plot training and validation loss
plt.plot(history.history['loss'], label='Training Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title("Training and Validation Loss")
plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.legend()
plt.show()
Epoch 1/100
  25940/Unknown 1902s 73ms/step - loss: 0.0135
c:\Users\kylea\anaconda3\lib\contextlib.py:137: UserWarning: Your input ran out
of data; interrupting training. Make sure that your dataset or generator can
generate at least `steps_per_epoch * epochs` batches. You may need to use the
`.repeat()` function when building your dataset.
  self.gen.throw(typ, value, traceback)
25940/25940
                        2089s
80ms/step - loss: 0.0135 - val_loss: 0.0097
Epoch 2/100
25940/25940
                        2074s
80ms/step - loss: 0.0103 - val_loss: 0.0144
Epoch 3/100
25940/25940
                        1998s
77ms/step - loss: 0.0100 - val_loss: 0.0134
Epoch 4/100
25940/25940
                        2166s
84ms/step - loss: 0.0098 - val_loss: 0.0130
Epoch 5/100
25940/25940
                        2056s
79ms/step - loss: 0.0271 - val_loss: 0.0184
Epoch 6/100
25940/25940
                        1918s
74ms/step - loss: 0.0169 - val_loss: 0.0113
Epoch 7/100
25940/25940
                        1959s
76ms/step - loss: 0.0136 - val_loss: 0.0131
Epoch 8/100
25940/25940
                        1996s
77ms/step - loss: 0.0112 - val_loss: 0.0165
Epoch 9/100
25940/25940
                        2009s
77ms/step - loss: 0.0106 - val_loss: 0.0165
Epoch 10/100
25940/25940
                        2027s
```

78ms/step - loss: 0.0101 - val_loss: 0.0188

Epoch 11/100

25940/25940 2026s

78ms/step - loss: 0.0097 - val_loss: 0.0189



The model took over 6 hours to train thanks to early stopping.

By applying an epoch count of 100, I was hoping to train it for long enough to detect variations for whole few years. However, early stopping with a patience of 10 stopped and stored the best model at 11 epochs.

The Validation lossed and training losses are not what you would typically expect, where the loss would decrease gradually as more iterations are carried out. However, the training loss does tend to a lower value as more epochs are reached.

4 Forecasting

```
[65]: # Make predictions on the validation set
predictions_scaled = model.predict(val_set)

# Inverse the scaling of predictions
```

```
predictions_rescaled = scaler.inverse_transform(predictions_scaled)
# Extract labels (y_test) from the validation dataset
y_test = []
for _, label in val_set.as_numpy_iterator():
    y_test.extend(label)
# Convert y_test to a NumPy array
y_test = np.array(y_test).reshape(-1, 1)
# Perform inverse scaling on y test
y_test_rescaled = scaler.inverse_transform(y_test)
# Now you can plot or calculate error metrics for predictions rescaled vs_{\sqcup}
 \rightarrow y_test_rescaled
# Calculate MAE and RMSE on the validation set
mae = mean_absolute_error(y_test_rescaled, predictions_rescaled)
rmse = np.sqrt(mean_squared_error(y_test_rescaled, predictions_rescaled))
print(f'Mean Absolute Error (MAE): {mae}')
print(f'Root Mean Squared Error (RMSE): {rmse}')
```

6484/6484

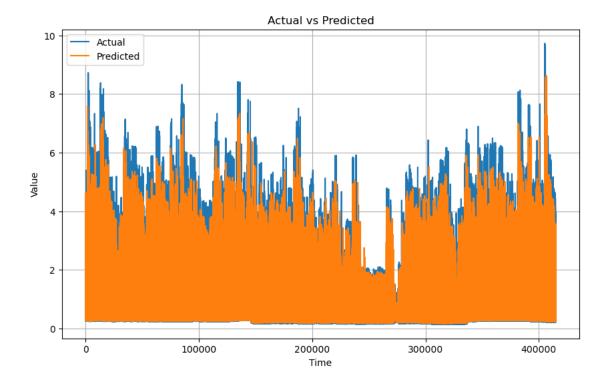
202s 31ms/step

c:\Users\kylea\anaconda3\lib\contextlib.py:137: UserWarning: Your input ran out
of data; interrupting training. Make sure that your dataset or generator can
generate at least `steps_per_epoch * epochs` batches. You may need to use the
`.repeat()` function when building your dataset.
 self.gen.throw(typ, value, traceback)

Mean Absolute Error (MAE): 0.7632860695659317 Root Mean Squared Error (RMSE): 1.1027162040206708

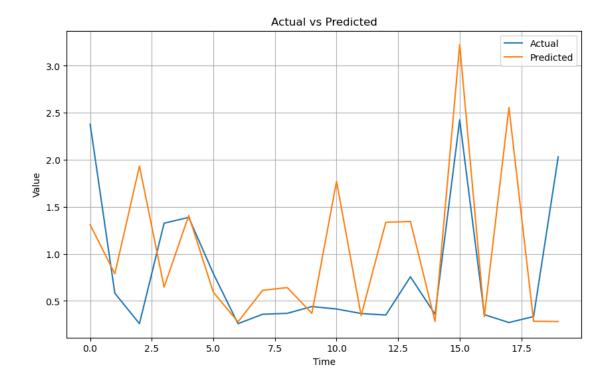
The results of Mean Absolute Error and Root Mean Square Error are pretty small but they are not insignificant. Since 0.7 over the range of about 9 represents a relative error of 8%, the model can be said to be about 92% accurate.

```
[73]: # Align predictions and y_test
plt.figure(figsize=(10, 6))
plt.plot(y_test_rescaled, label="Actual")
plt.plot(predictions_rescaled, label="Predicted")
plt.title("Actual vs Predicted")
plt.xlabel("Time")
plt.ylabel("Value")
plt.grid(True)
plt.legend()
plt.show()
```



This figure shows the prediction on the validation set as compared to the actual data. Generally, the prediction has similar trends as to the actual values, but do not match the same absolute values. To observe the trends closer we can plot the data on zoomed in figure.

```
[75]: # Align predictions and y_test - zoomed in
    plt.figure(figsize=(10, 6))
    plt.plot(y_test_rescaled[:20], label="Actual")
    plt.plot(predictions_rescaled[:20], label="Predicted")
    plt.title("Actual vs Predicted")
    plt.xlabel("Time")
    plt.ylabel("Value")
    plt.grid(True)
    plt.legend()
    plt.show()
```



The zoomed-in data graph shows that the prediction and actual values do not well. The model was able to predict one peak at time 15 though.

5 Observations:

Pattern Matching: The predicted values (orange line) generally follow the overall trend of the actual values (blue line), but there are notable deviations in some regions. Peaks and troughs are sometimes exaggerated in the predictions compared to the actual data.

Error Distribution: There are moments where the predictions align closely with the actual values, indicating the model captures some temporal dependencies well. In some cases, the predictions significantly overshoot or undershoot the actual values, suggesting the model struggles with extreme values or variability in the data.

Noise Handling: The model appears to introduce some noise, likely due to insufficient smoothing or overfitting on the training set.

Lagging Effect: Predictions seem to lag slightly behind the actual values in some instances, which may indicate room for improvement in capturing short-term temporal patterns.

6 Conclusions:

The model demonstrates an ability to learn general trends in the data but struggles with extreme fluctuations, which may indicate insufficient training or the need for feature engineering. The root

mean squared error (RMSE) and other metrics calculated earlier should guide the quantitative evaluation. From the visual plot, it is clear that further optimization is required.

To improve performance: 1. Tune the model architecture by experimenting with additional LSTM layers or attention mechanisms. 2. Adjust hyperparameters like the learning rate, batch size, and the number of epochs. 3. Consider feature engineering or introducing additional features to provide more context to the model. 4. Evaluate the impact of window size on model predictions.