Ownership Structure and Economic Growth

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Ownership Structure ⇒ Economic Growth?

- BlackRock, Vanguard, State Street, and Fidelity control 30% of votes of S&P 500 firms
- Top 10 chaebols account for half of stock market capitalization and exports in Korea
- Firms maximizing shareholder values ⇒
 Partially internalize externalities for commonly owned firm
- Ownership structure (common ownership, cross ownership, M&A, FDI, ...) =>
 Economic growth?
 - Business stealing effect
 - Technology spillover effect



Quantitative Schumpeterian Growth Model with Ownership Structure

- Existing Schumpeterian growth models:
 - Lack of strategic interaction (e.g., monopolistic competition)
 - Very few firms in Markov perfect equilibrium
- This paper: Many oligopolists + Ownership structure
 - Exercise: Public patenting firms in the US (\simeq 1000 firms)
- Quantify three inter-firm networks:
 - Ownership structure
 - Product market rivalry
 - Technology spillover
- Common ownership in the US:
 - Internalization of business stealing $\Longrightarrow q \downarrow \downarrow$
 - Internalization of technology spillover $\implies q \uparrow$

Literature

- Competition & Innovation:
 - d'Aspremont and Jacquemin (1988); Aghion et al. (2001, 2005); Acemoglu and Akcigit (2012); Aghion et al. (2013); Bloom et al. (2013); Lopez and Vives (2019); Peters (2020); Akcigit and Ates (2021, 2023); Liu et al. (2022);
 - Cavenaile et al. (2023): Anton et al. (2023, 2024): Kini et al. (2024): Hopenhayn and Okumura (2024)
 - Quantitative endogenous growth models matched to firm-(pair-)level data Ownership structure \implies economic growth.
- Hedonic Demand / Empirical IO:
 - Lancaster (1966); Rosen (1974); Berry et al. (1995); Nevo (2001); Pellegrino (2024); Ederer and Pellegrino (2024) Dynamic general equilibrium / R&D
- Oligopoly / Common Ownership / Market Power:
 - Rubinstein and Yaari (1983); Rotemberg (1984); Neary (2003); Atkeson and Burstein (2008); Gutierrez and Philippon (2017); He and Huang (2017); Azar et al. (2018, 2022); Autor et al. (2020); Baqaee and Farhi (2020);
 - De Loecker et al. (2020); Azar and Vives (2021); Edmond et al. (2023)

Simple Static Partial Equilibrium Model

- Firm $i \in \{1, ..., n\}$ chooses quantity q_i and R&D effort x_i
- Inverse demand: $\mathbf{p}(\mathbf{q}) = \mathbf{b} \Sigma \mathbf{q}$
- ullet CRS production technology with marginal cost: $\mathbf{m}(\mathbf{x}) = \mathbf{a} \mathbf{\Omega}\mathbf{x}$
- Cost of R&D: $c_i(x_i) = \frac{1}{2}x_i^2$

Common Ownership Weights

- ullet ${f K}=[\kappa_{ii}]$: common ownership weights that firm i places on the profit of firm j
- \bullet More overlapping ownership b/w firm i and $j\Longrightarrow$ Higher κ_{ij}

Proportional Influece

- Diagonal elements κ_{ii} are normalized to 1 for all firm i
- K = I: dispersed ownership (each firm maximizes its own value)
- $\mathbf{K} = [\mathbf{1}]$: monopoly (maximizes total producer surplus)

Cournot & R&D Game

• Firm *i*'s profit:

$$\begin{split} \pi_i(\mathbf{q}, \mathbf{x}) &= q_i[p_i - m_i] - c_i(x_i) \\ &= q_i \left[b_i - \sum_{i=1}^n \sigma_{ij} q_j - a_i + \sum_{i=1}^n \omega_{ij} x_j \right] - \frac{1}{2} x_i^2 \end{split}$$

 \bullet Given $\left\{q_j,x_j\right\}_{j\neq i}$, firm i chooses q_i and x_i to maximize $\sum_i \kappa_{ij}\pi_j(\mathbf{q},\mathbf{x})$

Impact of Common Ownership on R&D

 \bullet Comparative statics where $\left\{q_k,x_k\right\}_{k\neq i}$ are held constant:

$$\frac{\partial x_i}{\partial \kappa_{ij}} = \frac{q_j}{2 - \omega_{ii}^2} (2\omega_{ij} - \omega_{ii}\sigma_{ij}) \qquad \forall \ j \neq i$$

- SOC: $2 > \omega_{ii}^2$
- Internalize business stealing effect: $\partial^2 x_i/\partial \kappa_{ij}\partial \sigma_{ij} < 0$
- Internalize technology spillover effect: $\partial^2 x_i/\partial \kappa_{ij}\partial \omega_{ij} > 0$

Overview of Identification Strategy

Networks	Measurement
Common ownership weight ${f K}$	Institutional investor holdings in 13f filings (Backus et al., 2021)
Product market rivalry $oldsymbol{\Sigma}$	Product proximity (Hoberg and Phillips, 2016): Text analysis of business description in 10k filings
Technology spillover Ω	Technology proximity (Bloom et al., 2013): Patent classification

Oligopolistic Schumpeterian Growth Model

Linear quadratic aggregator (final good):

$$Y_t = \mathbf{q}_t^T \mathbf{b}_t - \frac{1}{2} \mathbf{q}_t^T \mathbf{\Sigma} \mathbf{q}_t$$

Linear inverse demand:

$$\mathbf{p}_t = \mathbf{b}_t - \mathbf{\Sigma} \mathbf{q}_t$$

- CRS production technology: $q_{i,t} = a_{i,t}l_{i,t}$
- Each firm has knowledge capital $z_{i,t}$
- Each firm allocates knowledge capital to improve labor productivity and product quality:

$$\zeta a_{i,t} + b_{i,t} = z_{i,t}$$

Law of Motion of Knowledge Capital

$$d\mathbf{z}_t = \left(\underbrace{\Omega\mathbf{z}_t}_{\text{technology spillover}} + \underbrace{\mu\mathbf{x}_t}_{\text{R\&D}}\right)dt + \underbrace{\gamma\mathbf{z}_t dW_t}_{\text{shocks}}$$

- $\Omega = [\omega_{ii}]$: technology spillover matrix
- $x_{i,t} = \sqrt{d_{i,t}}$
 - $d_{i,t}$: R&D cost in terms of final good
 - Innovation elasticity is 0.5
- μ , γ : positive scalars

Market Clearing and Preference

Inelastic labor supply:

$$L = \sum_{i} l_{i,t}$$

Final good market clearing:

$$C_t + \underbrace{\sum_i d_{i,t}} = Y_t$$

Risk neutral representative household:

$$\max \ \mathbf{E}_t \left[\int_t^\infty \exp \left(-\rho s \right) C_s ds \right]$$

Cournot-Nash Equilibrium

Firm i's gross profit before subtracting dynamic R&D cost:

$$\pi_{i,t} = p_{i,t}q_{i,t} - w_tl_{i,t} = \left(b_{i,t} - \frac{1}{a_{i,t}}w_t - \sum_i \sigma_{ij}q_{j,t}\right)q_{i,t} \quad \text{where} \quad \zeta a_{i,t} + b_{i,t} = z_{i,t}$$

- Given w_t , $z_{i,t}$, and $\left\{q_{j,t}\right\}_{i \neq i}$, firm i chooses $a_{i,t}$, $b_{i,t}$, and $q_{i,t}$ to maximize $\sum_{j} \kappa_{ij} \pi_{j,t}$
- Quantity is a linear function of knowledge capital:

$$\mathbf{q}_t = \left\{ \underbrace{2\frac{\zeta}{L}\mathbf{J}}_{\text{substitutability}} + \underbrace{\mathbf{K} \circ \mathbf{\Sigma}}_{\text{ownership weight} \times \text{substitutability}} \right\}^{-1} \mathbf{z}_t$$

- J: matrix with all elements equal to 1
- Ownership-weighted gross profits are expressed in quadratic form: $\sum_i \kappa_{ij} \pi_{j,t} = \mathbf{z}_t^T \mathbf{Q}^i \mathbf{z}_t$

Linear-Quadratic Differential Game

• Given other players' strategy $\left\{x_{j,t}\right\}_{i \neq i, t \geq 0}$, firm i chooses R&D effort $\left\{x_{i,t}\right\}_{t \geq 0}$ to maximize

$$\max_{\left\{x_{i,t}\right\}_{t\geq0}}\quad V^{i}\left(\mathbf{z}_{0}\right)\equiv\mathbf{E}_{0}\left[\int_{0}^{\infty}\exp\left(-\rho t\right)\left\{\sum_{j}\kappa_{ij}\left(\pi_{j,t}-x_{j,t}^{2}\right)\right\}dt\right]$$

subject to $d\mathbf{z}_t = (\mathbf{\Omega}\mathbf{z}_t + \mu\mathbf{x}_t) dt + \gamma\mathbf{z}_t dW_t$

Firm i's HJB equation:

$$\rho V^{i}\left(\mathbf{z}\right) = \max_{x_{i}} \left\{ \mathbf{z}^{T} \mathbf{Q}^{i} \mathbf{z} - \sum_{j} \kappa_{ij} x_{j}^{2} + V_{\mathbf{z}}^{i}\left(\mathbf{z}\right) \left[\mathbf{\Omega} \mathbf{z} + \mu \mathbf{x}\right] + \frac{\gamma^{2}}{2} \mathbf{z}^{T} V_{\mathbf{z}\mathbf{z}}^{i}\left(\mathbf{z}\right) \mathbf{z} \right\}$$

HJB Equations ⇒ Riccati Equations

- Guess and verify $V^{i}\left(\mathbf{z}\right) = \mathbf{z}^{T}\mathbf{X}^{i}\mathbf{z}$ (for any \mathbf{z})
- ullet \mathbf{X}^i is the solution of stacked algebraic Riccati equations lacktriangle
- All public patenting firms in the US in our dataset \simeq 1000 firms \Longrightarrow
 - $1000^3 = 1$ billion undetermined coefficients

Oligopolistic Schumpeterian	Computation time	# of firms	Productivity space
Cavenaile et al. (2023)	$O(2^n)$	4	6-point grid
Our model	$O(n^4)$	≈ 1000	Continuous

BGP in Deterministic Economy

- R&D strategy: $x_{i,t} = (\mu \mathbf{X}_i^i)^T \mathbf{z}_t$ where \mathbf{X}_i^i is the i th column of \mathbf{X}^i
- The law of motion is rewritten as $d\mathbf{z}_t = \mathbf{\Phi}\mathbf{z}_t dt + \gamma \mathbf{z}_t dW_t$ where

$$\underbrace{\boldsymbol{\Phi}}_{\text{technology transition matrix}} \equiv \underbrace{\boldsymbol{\Omega}}_{\text{spillover}} + \underbrace{\mu^2 \left[\begin{array}{ccc} \mathbf{X}_1^1 & \cdots & \mathbf{X}_n^n \end{array} \right]^T}_{\text{B&D}}$$

Theorem

Consider the deterministic economy ($\gamma=0$). If the technology transition matrix ${\bf \Phi}$ is irreducible, then:

- (i) There exists largest positive eigenvalue of Φ , g, and associated strictly positive eigenvector, \mathbf{z}^* .
- (ii) There exists a globally stable BGP such that the knowledge capital growth rate of all firms is g, and the knowledge capital distribution is a scalar multiple of z^* .
 - Proof: Perron–Frobenius Theorem
 - " Φ is irreducible" \iff "All firms are directly or indirectly connected technologically"

BGP in Deterministic Economy

• In BGP, \mathbf{a}_t , \mathbf{b}_t , \mathbf{z}_t , and \mathbf{q}_t grow at the same rate

Technology Choice:
$$\zeta a_{i,t} + b_{i,t} = z_{i,t}$$
 Linear Production Technology:
$$q_{i,t} = a_{i,t} l_{i,t}$$
 Inelastic Labor Supply:
$$L = \sum_i l_{i,t}$$

• Linear and quadratic term in \mathbf{q}_t of output grow at the same rate: Equilibrium Summary

$$Y_t = \mathbf{q}_t^T \mathbf{b}_t - \frac{1}{2} \mathbf{q}_t^T \mathbf{\Sigma} \mathbf{q}_t$$

Aggregation

Apply Ito's lemma to

$$\begin{aligned}
\log Y_t &= \log \left(\mathbf{z}_t^T \mathbf{Q} \mathbf{z}_t \right) \\
d\mathbf{z}_t &= \mathbf{\Phi} \mathbf{z}_t dt + \gamma \mathbf{z}_t dW_t \implies g_t
\end{aligned}$$

Expected utility is expressed in quadratic form:

$$\mathbf{E}_t \left[\left. \int_t^\infty \exp\left(-\rho s\right) C_s ds \right| \mathbf{z}_t \right] = \mathbf{z}_t^T X \mathbf{z}_t$$

ullet Solve the equilibrium once \Longrightarrow Can compute expected growth and utility for any \mathbf{z}_t

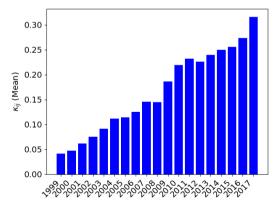




Common Ownership Weight

- Backus et al. (2021) construct a dataset on investors' holdings based on Form 13F
- Baseline: Rotemberg (1984) proportional influence assumption





Product Substitutability

- Hoberg and Phillips (2016) estimates product similarity using business descriptions in 10-K
- Pellegrino (2024) estimates α to align with the cross-price elasticity of demand

$$\underbrace{\sigma_{ij}}_{\text{substitutabiliy}} = \alpha \times \text{product similarity b/w } i \text{ and } j \quad (i \neq j)$$

Technological Proximity

- Technological profile of firm i
 - The vector of the share of patents held by firm i in each technology class
 - Baseline: group-level classifications (≈ 4000)
- Jaffe (1986) technology proximity measure $\tilde{\omega}_{ij}$:
 - Cosine similarity of the technological profiles b/w firm i and j

Initial Distribution of Knowledge Capital

- 1. Gross profit (before subtracting R&D cost) $\pi_{i,t} \longleftarrow$ "Revenue" "Costs of goods sold"
 - Deflated by GDP deflator for inter-temporal comparison
- 2. Quantity $\mathbf{q}_t \longleftarrow \pi_{i,t} = \sum_i \kappa_{ij} \sigma_{ij} q_{i,t} q_{i,t}$
- 3. $\zeta/L \Leftarrow$ match the cost share of the sample firms
- 4. Knowledge capital $\mathbf{z}_t \longleftarrow \mathbf{q}_t = \left\{2\frac{\zeta}{L}J + \Sigma + K \circ \Sigma\right\}^{-1}\mathbf{z}_t$

Technology Spillover $\Omega=eta imes$ Technology Proximity $\tilde{\Omega}$

$$\boldsymbol{z}_{i,t+1} - \boldsymbol{z}_{i,t} = \beta \sum_{j \neq i} \tilde{\omega}_{ij,t} \boldsymbol{z}_{j,t} + \text{Year FE}_t + \boldsymbol{\epsilon}_{i,t}$$

	(1)	(2)	(3)
	$z_{i,t+1} - z_{i,t}$	$z_{i,t+1} - z_{i,t}$	$z_{i,t+1} - z_{i,t}$
Σ ~	0.000191***	0.000152***	0.000140***
$\sum_{j eq i} ilde{\omega}_{ij,t} z_{j,t}$	(0.000035)	(0.000035)	(0.000039)
DOD Even and it was		.037**	
√R&D Expenditure		(0.021)	
Year Fixed Effects	✓	✓	√
IV			\checkmark
IV 1st Stage F-statistics			4176
No. observations	16,324	15,173	14,181

SEs clustered by years and 4-digit naics industries are reported in parentheses. * p < 0.1, ** p < 0.05, *** p < 0.01.

IV: User cost of R&D, driven by state-level tax variations (Wilson, 2009; Bloom et al., 2013)

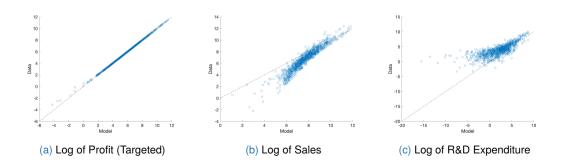
Identification: Summary

 $\bullet \ \ \text{Publicly available data} + \text{Compustat}$

Notation	Description	Value	Source
$\Psi^T\Psi$	Product proximity		Form 10-K, Hoberg and Phillips (2016)
$\widetilde{\Omega}$	Technological proximity		USPTO, Patent classification
K	Common ownership weights		Form 13F, Backus et al. (2021)
α	Product proximity \rightarrow Substitutability	.12	Pellegrino (2024)
β	Technological proximity \rightarrow Spillover	.00014	Estimate the law of motion
γ	St.d. of idiosyncratic shocks	.027	Estimate the law of motion
ζ/L	Labor augmentation efficiency	.0063	Compustat, Cost of goods sold
ho	Discount rate	.10	
μ	R&D efficiency	.05	1.6% economic growth rate

Fit b/w Model and Data

Model (x-axis) vs Data (y-axis): firm-level profits (targeted), sales and R&D expenditures



Total Output

Total output		Ownership (Baseline: 2017)			
(Social Optimum: 100)	Dispersed	Mean=1999	Uniform	Baseline	Monopoly
Baseline	91.30	91.02	90.78	89.08	89.17
Only Business Steal $oldsymbol{\Omega} = [0]$	91.30	91.02	90.78	89.08	89.17
Only Tech Spill $\mathbf{\Sigma} = \mathbf{I}, \ \zeta/L = 0$	75.00	75.00	75.00	75.00	75.00

- ullet Inelastic labor supply \Longrightarrow changes in total output arise from misallocation
- Common ownership worsens product misallocation

Total R&D Expenditure

Total R&D Expenditure	Ownership (Baseline: 2017)					
(Social Optimum: 100)	Dispersed	Mean=1999	Uniform	Baseline	Monopoly	
Baseline	26.16	25.90	25.56	22.36	19.36	
Only Business Steal						
$\mathbf{\Omega} = [0]$	28.15	27.79	27.07	23.42	19.80	
Only Tech Spill						
$\Sigma = I, \zeta/L = 0$	18.27	18.34	18.75	18.86	19.84	

- Internalization of business stealing > Internalization of technology spillover
- Network heterogeneity is important

Expected Growth Rate

Expected economic	Ownership (Baseline: 2017)					
growth rate (%)	Dispersed	Mean=1999	Uniform	Baseline	Monopoly	
Baseline	1.796	1.793	1.791	1.753	1.713	
Only Business Steal $oldsymbol{\Omega} = [0]$	1.097	1.094	1.093	1.062	1.020	
Only Tech Spill $\mathbf{\Sigma} = \mathbf{I}, \zeta/L = 0$	2.051	2.054	2.068	2.072	2.107	

• 0.043 pp (2.4%) lower growth under common ownership compared to dispersed ownership

Expected Social Welfare

Expected Social Welfare		Ownership (p (Baseline: 2017)		
(Social Optimum: 100)	Dispersed	Mean=1999	Uniform	Baseline	Monopoly
Baseline	87.72	87.42	87.16	85.25	85.18
Only Business Steal $oldsymbol{\Omega} = [0]$	88.83	88.53	88.30	86.44	86.41
Only Tech Spill $\mathbf{\Sigma} = \mathbf{I}, \ \zeta/L = 0$	68.81	68.82	68.88	68.89	69.02

• 2.8% CE welfare loss under common ownership compared to dispersed ownership

Firm Value Share

Firm value	Ownership (Baseline: 2017)				
share (%)	Dispersed	Mean=1999	Uniform	Baseline	Monopoly
Baseline	28.74	33.43	29.63	34.34	40.92
Only Business Steal $oldsymbol{\Omega} = [0]$	27.91	28.80	32.60	33.51	40.14
Only Tech Spill $\mathbf{\Sigma} = \mathbf{I}, \zeta/L = 0$	64.82	64.81	64.76	64.74	64.63

• Firm value share is 5.6% lower under common ownership compared to dispersed ownership

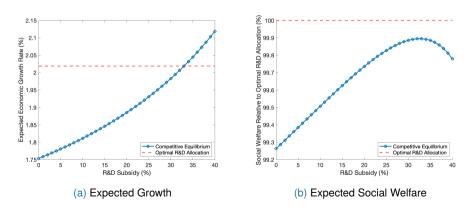
When Common Ownership Affects only R&D Decisions

Investors may only influence R&D decisions (d'Aspremont and Jacquemin, 1988)

	Ownership Structure			
	Dispersed	Common R&D	Baseline	
Output (Social Optimum: 100)	91.30	91.30	89.08	
R&D Expenditure (Social Optimum: 100)	26.17	19.76	22.36	
Growth Rate (%)	1.796	1.726	1.753	
Social Welfare (Social Optimum: 100)	87.72	87.49	85.25	
Firm Value Share (%)	28.74	29.04	34.34	

- Lowest R&D expenditure and growth rate
- Intermediate social welfare

Uniform R&D Subsidy Social Optimum



- Optimal rate is s=33%, which increases g by 0.25 pp (14%)
- CE Welfare loss relative to optimal R&D allocation is reduced to 0.1% (Initially 0.7%)

Conclusion

- Quantitative Schumpeterian growth model with ownership structure
 - Match to data at firm (pair) level
- Common ownership in the US:
 - 1. Internalization of business stealing effect $\Longrightarrow g \downarrow \downarrow$
 - 2. Internalization of technology spillover effect $\Longrightarrow g \uparrow$
- Application:
 - Chaebols in Korea
 - Zaibatsu (pre-WWII) and cross-shareholding (late 20th century) in Japan
 - FDI / multinational companies and international technology diffusion

Share of Top 5 Shareholders in Largest Market Cap Firms (Back)

Microsoft	
Vanguard	9.20%
Blackrock	7.75%
Steven Ballmer	4.48%
State Street	3.97%
Fidelity	2.66%

Nvidia	
Vanguard	8.93%
BlackRock	7.74%
Fidelity	4.12%
State Street	3.97%
Jensen Huang	3.80%

Apple	
Vanguard	9.29%
Blackrock	7.48%
State Street	3.96%
Fidelity	2.27%
Geode Capital	2.26%

Google	
Vanguard	7.36%
Blackrock	6.47%
State Street	3.39%
Fidelity	3.01%
Sergey Brin	2.99%

Amazon	
Jeffrey Bezos	8.58%
Vanguard	7.77%
Blackrock	6.50%
State Street	3.44%
Fidelity	3.10%

Meta	
Vanguard	7.55%
Blackrock	6.50%
Fidelity	5.38%
Accel IX LP	3.88%
State Street	3.40%

Equity Investments by Big tech in Al Startups (Back)

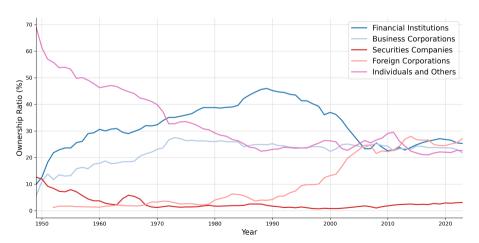
Shareholding percentage	Microsoft	Google	Amazon
OpenAl (ChatGPT)	49%	_	_
Anthropic (Claude)	_	14%	23%

Technology & Product Proximity: Example

Tesla vs. Ford	
Technology Proximity	0.11
Product Proximity	0.15

Apple vs. Intel	
Technology Proximity Product Proximity	0.57 0.00
1 Toddot 1 Toxininty	0.00

Ownership Ratio by Holder Types in Japan



Rotemberg (1984) Proportional Influence

- $o \in \{1, 2, ..., n_o\}$: owners
- s_{io} : the proportion of shares in firm i owned by owner o where $\sum_{o} s_{io} = 1$
- $\hat{V}_{i,t}$: value of firm i
- $\tilde{V}_{o,t} \equiv \sum_i s_{io} \hat{V}_{i,t}$: value of owner o
- Firms' objective:

$$\sum_o s_{io} \tilde{V}_{o,t} \propto \sum_j \kappa_{ij} \hat{V}_{j,t}$$

where

$$\kappa_{ij} \equiv \mathbf{s}_i^T \mathbf{s}_j / \mathbf{s}_i^T \mathbf{s}_i \quad \text{where} \quad \mathbf{s}_i \equiv \left[s_{i1}, ..., s_{io}, ..., s_{in_o}\right]^T$$

Total Surplus

• Total surplus for product *i*:

$$ts_i(\mathbf{q},\mathbf{x}) = \pi_i(\mathbf{q},\mathbf{x}) + cs_i(\mathbf{q}) = q_i \left[b_i - \frac{1}{2} \sum_{i=1}^n \sigma_{ij} q_j - a_i + \sum_{i=1}^n \omega_{ij} x_j \right] - \frac{1}{2} x_i^2$$

R&D Externalities

- 1. Business stealing effect
 - Innovators steel the business (profits) of other firms
- 2. Technology spillover effect
 - Innovation improves the productivity of other firms
- 3. Appropriability effect (market power)
 - Innovators cannot appropriate the entire consumer surplus

R&D Allocation and Externalities

Firms maximize common owner weighted profits:

$$\mathbf{x}^* = (\mathbf{K} \circ \mathbf{\Omega})[\mathbf{\Sigma} + \mathbf{K} \circ \mathbf{\Sigma} - \mathbf{\Omega}(\mathbf{K} \circ \mathbf{\Omega})]^{-1}(\mathbf{b} - \mathbf{a})$$

Firms maximize common owner weighted total surplus (*):

$$\mathbf{x}_{TS}^* = (\mathbf{K} \circ \mathbf{\Omega}) \left[\frac{1}{2} (\mathbf{\Sigma} + \mathbf{K} \circ \mathbf{\Sigma}) - \mathbf{\Omega} (\mathbf{K} \circ \mathbf{\Omega}) \right]^{-1} (\mathbf{b} - \mathbf{a})$$

- $\mathbf{K} = [1]$ in $(\star) \Longrightarrow$ Social Optimum
- Externalities: (i) Appropriability, (ii) Business stealing, (iii) Technology spillover

Generalized Hedonic-Linear Demand (Pellegrino, 2024)

- $i \in \{1, 2, ..., n\}$: firms / products
- 1 unit of product *i* provides
 - 1 unit of idiosyncratic characteristic $k \in \{1, 2, ..., n\}$
 - $\psi_{k,i}$ unit of shared characteristic $k \in \{n+1, n+2, ..., n+n_k\}$ where $\sum_k \psi_{k,i}^2 = 1$
- Aggregate each characteristic:

$$y_{k,t} = \begin{cases} q_{k,t} & k = 1, 2, ..., n \\ \sum_{i} \psi_{k,i} q_{i,t} & k = n + 1, n + 2, ..., n + n_k \end{cases}$$

• Linear quadratic aggregator over characteristics:

$$Y_t = (1-\alpha)\sum_{k=1}^n \left(\underbrace{\hat{b}_{k,t}y_{k,t} - \frac{1}{2}y_{k,t}^2}_{\text{idiosyncratic characteristic}} \right) + \alpha \sum_{k=n+1}^{n+n_k} \left(\underbrace{\hat{b}_{k,t}y_{k,t} - \frac{1}{2}y_{k,t}^2}_{\text{shared characteristic}} \right)$$

Generalized Hedonic-Linear Demand (Pellegrino, 2024)

Quality:

$$b_i = (1 - \alpha)\,\hat{b}_i + \alpha \sum_{k=n+1}^{n+n_k} \psi_k \hat{b}_k$$

• Inverse demand:

$$rac{\mathbf{p}}{D} = \mathbf{b} - \mathbf{\Sigma} \mathbf{q}$$

• Inverse cross price elasticity of demand:

$$rac{\partial \log p_i}{\partial \log q_i} = -rac{q_j}{p_i} \cdot \sigma_{ij}$$

Cross price elasticity of demand:

$$\frac{\partial \log q_i}{\partial \log p_j} = -\frac{p_j}{q_i} (\mathbf{\Sigma}^{-1})_{ij}$$

Static Profits

- Real gross profit: $\frac{\pi_{i,t}}{P_{t}} = \sum_{i} \kappa_{ij} \sigma_{ij} q_{i,t} q_{j,t}$
- Firms choose labor productivity and product quality: $\zeta a_{i,t} = \sqrt{\zeta rac{w_t}{P_t}}$, $b_{i,t} = z_{i,t} \sqrt{\zeta rac{w_t}{P_t}}$
- Labor market clearing: $L=\sum_i rac{q_{i,t}}{a_{i,t}} \Longrightarrow \sqrt{\zeta rac{w_t}{P_t}} = rac{\zeta}{L} \sum_i q_{i,t}$
- $ullet \ \mathbf{q}_t = \mathbf{N}\mathbf{z}_t \ ext{where} \ N \equiv \left\{ 2rac{\zeta}{L}\mathbf{J} + \mathbf{\Sigma} + \mathbf{K} \circ \mathbf{\Sigma}
 ight\}^{-1}$
- N_i : the *i* th row of N
- Ownership weighted profit:

$$\sum_{i} \kappa_{ij} \frac{\pi_{j,t}}{P_t} = \sum_{i} \kappa_{ij} \sum_{h} \kappa_{jh} \sigma_{jh} q_{j,t} q_{h,t} = \mathbf{z}_t^T \mathbf{Q}^i \mathbf{z}_t$$

where

$$\mathbf{Q}^{i} = \frac{1}{2} \sum_{i} \kappa_{ij} \sum_{h} \kappa_{jh} \sigma_{jh} \left(N_{j}^{T} N_{h} + N_{h}^{T} N_{j} \right)$$

Riccati Equations

• $V^{i}(\mathbf{z}) = \mathbf{z}^{T}\mathbf{X}^{i}\mathbf{z}$ where \mathbf{X}^{i} is the solution of the stacked Riccati equation

$$0 = \mathbf{Q}^{i} - \mu^{2} \sum_{i} \kappa_{ij} \mathbf{X}_{j}^{j} \left(\mathbf{X}_{j}^{j} \right)^{T} + \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \left(\mathbf{\Phi} - \frac{1}{2} \left(\rho - \gamma^{2} \right) \mathbf{I} \right)^{T} \mathbf{X}^{i} + \mathbf{X}^{i} \mathbf{X}^{i} \mathbf{X}^{i} + \mathbf{X}^{i} \mathbf{$$

- $\mathbf{X}_{i}^{i} \equiv \text{the } i \text{ th column of } \mathbf{X}^{i}$
- $\mathbf{\Phi} \equiv \mathbf{\Omega} + \mu^2 \begin{bmatrix} \mathbf{X}_1^1 & \cdots & \mathbf{X}_n^n \end{bmatrix}^T$
- Algorithm: Given $[\mathbf{X}_{\tau}^1 \cdots \mathbf{X}_{\tau}^n]$, update $[\mathbf{X}_{\tau-\Delta}^1 \cdots \mathbf{X}_{\tau-\Delta}^n]$ by

$$-\frac{\mathbf{X}_{\tau}^{i}-\mathbf{X}_{\tau-\Delta}^{i}}{\Delta}=\mathbf{Q}^{i}-\mu^{2}\sum_{j}\kappa_{ij}\mathbf{X}_{j,\tau}^{j}\left(\mathbf{X}_{j,\tau}^{j}\right)^{T}+\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\mathbf{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}\right)\boldsymbol{I}\right)^{T}\mathbf{X}_{\tau}^{i}+\mathbf{X}_{\tau}^{i}\left(\boldsymbol{\Phi}_{\tau}-\frac{1}{2}\left(\rho-\gamma^{2}$$

Summary of Equilibrium

Description	Expression
Production strategy	$\mathbf{q}_t = N\mathbf{z}_t$
R&D strategy	$\mathbf{x}_t = \mu ilde{X} \mathbf{z}_t$
Law of motion	$d\mathbf{z}_t = (\Omega \mathbf{z}_t + \mu \mathbf{x}_t) dt + \gamma \mathbf{z}_t dW_t$
Profit of final producers	$\Pi_t^F/P_t = \mathbf{q}_t^T\left(rac{1}{2}\Sigma ight)\mathbf{q}_t$
Total operating profit of firms	$\Pi_t/P_t = \mathbf{q}_t^T \left(\overline{\frac{1}{2}} \Sigma \circ (K + K^T) \right) \mathbf{q}_t$
Labor income	$w_t L/P_t = \mathbf{q}_t^T \left(rac{\zeta}{L} J \right) \mathbf{q}_t$
Output	$Y_t = \mathbf{q}_t^T \left(\frac{\zeta}{L} J + \frac{1}{2} \Sigma + \frac{1}{2} \Sigma \circ (K + K^T) \right) \mathbf{q}_t$
Consumption	$C_t = Y_t - \mathbf{x}_t^T \mathbf{x}_t$

Output and Expected Utility

• Output: $Y_t = \mathbf{q}_t^T Q \mathbf{q}_t$ where

$$Q = \frac{\zeta}{L}J + \frac{1}{2}\Sigma + \frac{1}{2}\Sigma \circ (K + K^T)$$

Expected utility:

$$V(\mathbf{z}_t) \equiv \mathbf{E}_t \left[\left. \int_t^\infty \exp\left(-\rho s\right) C_s ds \right| \mathbf{z}_t \right] = \mathbf{z}_t^T X \mathbf{z}_t$$

where X is the solution of the Lyapunov equation (obtained from households' HJB equation):

$$0 = Q - \mu^2 \tilde{X}^T \tilde{X} + X \left(\Phi - \frac{1}{2} \left(\rho - \gamma^2 \right) I \right) + \left(\Phi - \frac{1}{2} \left(\rho - \gamma^2 \right) I \right)^T X$$

Social Optimum

- Static optimal allocation: $\mathbf{q}_t^* = N^*\mathbf{z}_t$ where $N^* \equiv \left\{2\frac{\zeta}{L}J + \Sigma\right\}^{-1}$
- Optimal output: $Y_t^* = \mathbf{z}_t^T Q^* \mathbf{z}_t$ where $Q^* = \frac{1}{2} N^*$
- Optimal expected utility:

$$V^*\left(\mathbf{z}_t\right) \equiv \mathbf{E}_t \left[\left. \int_t^\infty \exp\left(-\rho s\right) C_s ds \right| \mathbf{z}_t \right] = \mathbf{z}_t^T X^* \mathbf{z}_t,$$

where X^* is the solution of the Riccati equation (obtained from planner's HJB equation):

$$0 = Q^* - \mu^2 \left(X^*\right)^2 + X^* \left(\Phi^* - \frac{1}{2} \left(\rho - \gamma^2\right) I\right) + \left(\Phi^* - \frac{1}{2} \left(\rho - \gamma^2\right) I\right) X^*$$

- Optimal R&D: $\mathbf{x}_t^* = \mu X^* \mathbf{z}_t$
- Optimal technology transition matrix: $\Phi^* = \Omega + \mu^2 X^*$

Stochastic Process of Output

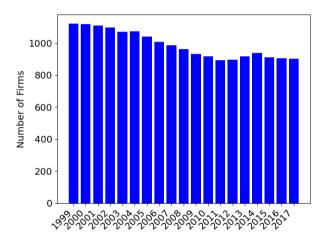
Applying It's lemma,

$$d\log Y_t = \left[\frac{\mathbf{z}_t^T \left(Q\Phi + \Phi^T Q\right)\mathbf{z}_t}{Y_t} + \gamma^2 \left\{\frac{\sum_i z_{i,t}^2 Q_{ii}}{Y_t} - \frac{2\mathbf{z}_t^T Q \operatorname{diag}\left(\mathbf{z}_t^2\right)Q\mathbf{z}_t}{Y_t^2}\right\}\right] dt + \frac{2\gamma \mathbf{z}_t^T Q \operatorname{diag}\left(\mathbf{z}_t\right)}{Y_t} dW_t$$

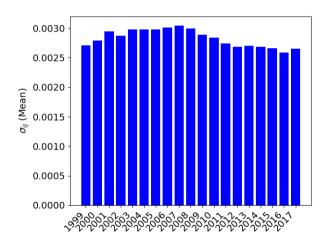
where $Y_t = \mathbf{z}_t^T Q \mathbf{z}_t$ and $\Phi = \Omega + \mu^2 \widetilde{X}$

Description	Expression
Tech Spillover	$\mathbf{z}_t^T (Q\Omega + \Omega Q) \mathbf{z}_t / Y_t$
R&D	$\mu^2 \mathbf{z}_t^T \left(Q\widetilde{X} + \widetilde{X}^T Q\right) \mathbf{z}_t / Y_t$
Ito	$\gamma^2\left\{\sum_i z_{i,t}^2 Q_{ii}/Y_t - 2\mathbf{z}_t^T Q \mathrm{diag}\left(\mathbf{z}_t^2 ight) Q \mathbf{z}_t/Y_t^2 ight\}$
Total	$\mathbf{E}\left[d\log Y_{t} ight]$

Number of Sample Firms

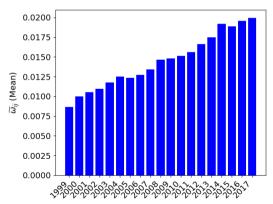


Trend of Product Substitutability



Technological Proximity

- Merge USPTO data with Compustat firms using DISCERN 2 dataset (Arora et al., 2024)
- Jaffe measure, Group-level patent classification, Stack for 5 years



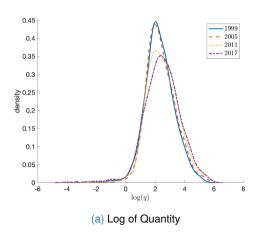
Distributions of Estimated Knowledge Capital and Quantity

3.5

2.5

0.5

density 2



(b) Log of Knowledge Capital

 $6.2 \log(z)$

5.6 5.8

1999

- 2005

..... 2011

First Stage Back

	(1)
Dependent Variable:	$z_{i,t}$
User cost of R&D	-39.495^{***}
User cost of had	(4.7044)
Year Fixed Effects	√
No. observations	12,947

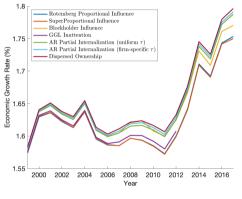
SEs clustered by years and 4-digit naics industries are reported in parentheses.

• IV: User cost of R&D, driven by state-level tax variations (Wilson, 2009; Bloom et al., 2013)

Alternative Corporate Governance Models: Ederer and Pellegrino (2024)

- 1. Super-proportional influence: $\tilde{\kappa}_{ij} = \frac{\sum_{z=1}^{Z} s_{iz} \gamma_{iz} s_{jz}}{\sum_{z=1}^{Z} s_{iz} \gamma_{iz} s_{iz}}$ where $\gamma_{iz} = \sqrt{s_{iz}}$
- 2. Blockholder influence: $\tilde{\kappa}_{ij} = \frac{\sum_{z=1}^{Z} s_{iz} b_{iz} s_{jz}}{\sum_{z=1}^{Z} s_{iz} s_{iz} s_{iz}}$ $(i \neq j)$, where $b_{iz} = 1$ if $s_{iz} > 5\%$
- 3. Rational investor inattention
 - Gilje et al. (2020) (GGL) estimate the probability that an investor votes against Institutional Shareholders Service recommendations
 - Utilize the estimate to capture the investor's level of attention
- 4. Governance frictions and entrenchment
 - Azar and Ribeiro (2021) (AR) estimate an objective function where the manager of firm i discounts other firms' profit by τ_i

Alternative Corporate Governance Models



Social Welfare Relative to Dispersed Ownership (%) Rotemberg Proportional Influence SuperProportional Influence Blockholder Influence - GGL Inattention AR Partial Internalization (uniform τ) AR Partial Internalization (firm-specific τ) - Dispersed Ownership 96.5 2000 2002 2008 2010 2012 2014 2016 Year

(a) Expected Growth

(b) Expected Social Welfare

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