

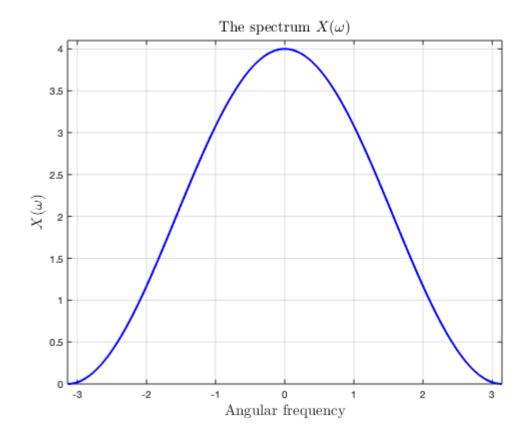
TTT4120 Digital Signal Processing Solutions for Problem Set 2

Problem 1:

(a).

The spectrum $X(\omega)$ can be found and plotted as follows.

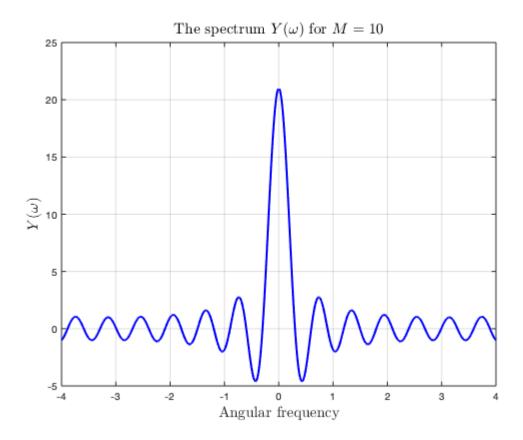
$$X(\omega) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n} = e^{j\omega} + 2 + e^{-j\omega} = 2 + 2\cos\omega$$



(b). The spectrum $Y(\omega)$ can be found as follows.

$$\begin{split} Y(\omega) &= \sum_{n = -\infty}^{\infty} y[n] e^{-j\omega n} = \sum_{n = -M}^{M} e^{-j\omega n} \quad l = n + M = \sum_{l = 0}^{2M} e^{-j\omega(l - M)} \\ &= e^{j\omega M} \sum_{l = 0}^{2M} e^{-j\omega l} = e^{j\omega M} \frac{1 - e^{-j\omega(2M + 1)}}{1 - e^{-j\omega}} = \frac{e^{j\omega M} - e^{-j\omega(M + 1)}}{1 - e^{-j\omega}} \\ &= \frac{e^{-\frac{j\omega}{2}}}{e^{-\frac{j\omega}{2}}} \frac{\left(e^{j\omega(M + \frac{1}{2})} - e^{-j\omega(M + \frac{1}{2})}\right)}{\left(e^{\frac{j\omega}{2}} - e^{-\frac{j\omega}{2}}\right)} = \frac{\sin\left(\omega(M + \frac{1}{2})\right)}{\sin\left(\frac{\omega}{2}\right)} \end{split}$$

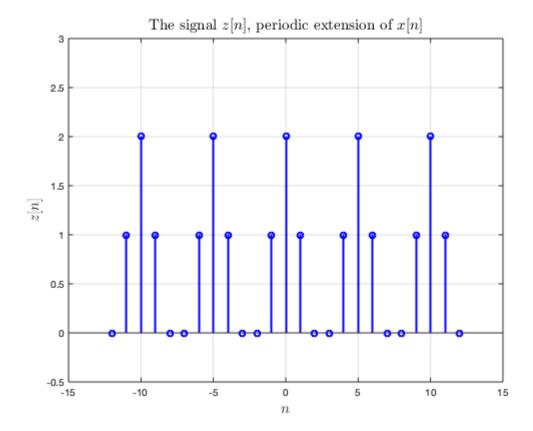
The sketch is shown in the following Figure.



(c).
Because they are even signals.

(d).

A sketch of z[n] for N = 5 is shown as follows.



The Fourier coefficients are given by:

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} z[n] e^{-j2\pi kn/N}, \ k = 0, \dots, N-1.$$

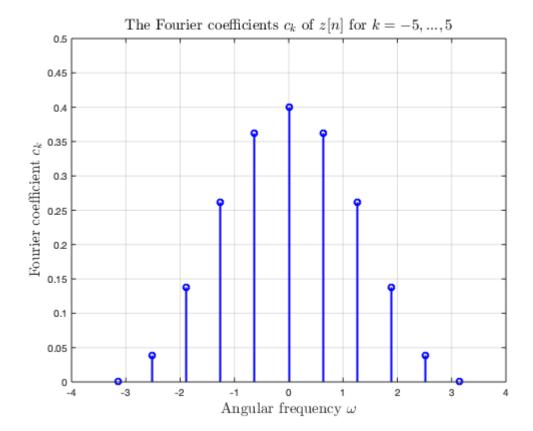
Note that we sum from 0 up to N-1. Thus, the first two samples are 2 and 1 respectively, and the last sample is 1. All other samples are 0. The coefficients could be calculated over any other period.

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} z[n] e^{-j2\pi k n/N} = \frac{1}{N} (2 + e^{-j2\pi k/N} + e^{-j2\pi k(N-1)/N})$$

$$= \frac{1}{N} (2 + e^{-j2\pi k/N} + e^{-j2\pi k} e^{j2\pi k/N}) = \frac{1}{N} (2 + e^{-j2\pi k/N} + e^{j2\pi k/N})$$

$$= \frac{1}{N} (2 + 2\cos(2\pi k/N))$$

The Fourier coefficients are displayed as follows.



(e).

We have the following.

$$X(f) = 2 + 2\cos(2\pi f)$$

$$c_k = \frac{1}{N}(2 + 2\cos(2\pi k/N))$$

Thus, we see that

$$c_k = \frac{1}{N} X \left(\frac{k}{N} \right).$$

This means that the Fourier coefficients are (scaled) samples of the continuous spectrum X(f). This always holds true: a periodic extension in the time domain equals sampling in the frequency domain.

Problem 2:

(a).

For the first case, we use the time-shift property of the DTFT, and get

$$X_1(\omega)=e^{j3\omega}X(\omega)$$

(b).

For the second case, we use the time-reversal property of the DTFT, and it follows that

$$X_2(\omega) = X(-\omega)$$

(c).

For the third case notice that:

$$x_3[n] = x[3-n] = x[-(n-3)] = x_2[n-3]$$

so that by the time-reversal and time-shift properties, it follows that

$$X_3(\omega) = e^{-j3\omega}X_2(\omega) = e^{-j3\omega}X(-\omega)$$

(d).

For the last case, we have that

$$X_4(\omega) = \text{DTFT}\{x[n] * w[n]\} = X(\omega)W(\omega).$$

Problem 3:

(a).

By taking the DTFT of both sides of the first difference equation, we get

$$\begin{split} Y(\omega) &= X(\omega) + 2e^{-j\omega}X(\omega) + e^{-2j\omega}X(\omega) \\ H_1(\omega) &= \frac{Y(\omega)}{X(\omega)} = 1 + 2e^{-j\omega} + e^{-2j\omega} = e^{-j\omega}(e^{j\omega} + 2 + e^{-j\omega}) = e^{-j\omega}(2 + 2\cos\omega). \end{split}$$

And for the second case, we get

$$Y(\omega) = -0.9Y(\omega)e^{-j\omega} + X(\omega)$$

$$H_2(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{1}{1 + 0.9e^{-j\omega}}.$$

(b).

We already have the frequency response $H_1(\omega)$ on polar form. Thus, the magnitude is simply

$$|H_1(\omega)| = 2 + 2\cos\omega.$$

Since $2 + 2\cos\omega \ge 0$ for all ω , the phase is simply

$$\Theta_1(\omega) = \angle H_1(\omega) = -\omega.$$

The magnitude response of the second system can be found as follows.

$$|H_2(\omega)| = \left| \frac{1}{1 + 0.9e^{-j\omega}} \right| = \frac{1}{|1 + 0.9e^{-j\omega}|}$$
$$= \frac{1}{\sqrt{(1 + 0.9\cos\omega)^2 + (0.9\sin\omega)^2}} = \frac{1}{\sqrt{1 + 1.8\cos\omega + 0.81}}$$

To find the phase, we can write $H_2(\omega)$ as

$$H_2(\omega) = \frac{1}{W(\omega)},$$

where $W(\omega) = 1 + 0.9e^{-j\omega}$. Then, the phase is given by

$$\Theta_2(\omega) = \angle H_2(\omega) = -\angle W(\omega).$$

Since $Re\{W(\omega)\} > 0$ for all ω , we have

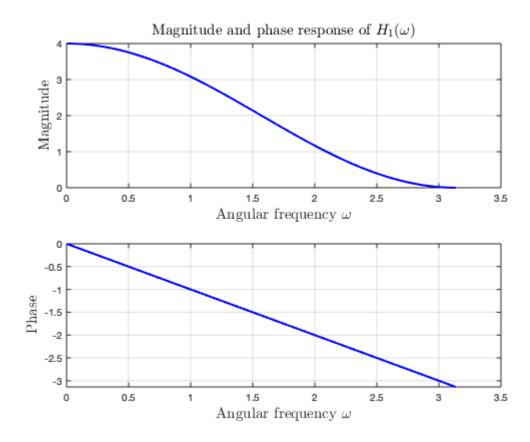
$$\angle H_2(\omega) = -\tan^{-1}\left(\frac{-0.9\sin\omega}{1 + 0.9\cos\omega}\right) = \tan^{-1}\left(\frac{0.9\sin\omega}{1 + 0.9\cos\omega}\right).$$

We notice that all magnitude functions are even and that all phase functions are odd. This is a property of real signals.

(c).

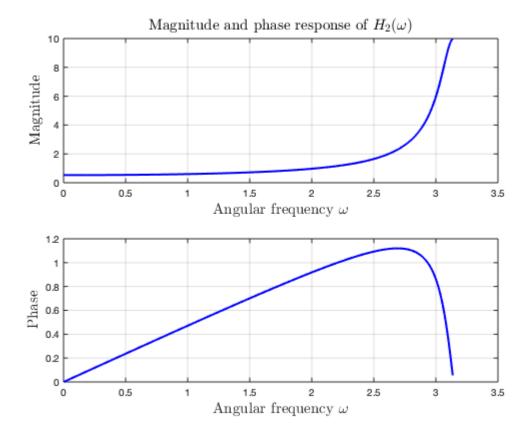
The frequency response of the first filter can be found and plotted by as following.

```
[H_1, w] = freqz([1 2 1], [1]);
subplot(2, 1, 1);
plot(w, abs(H_1));
subplot(2, 1, 2);
plot(w, angle(H 1));
```



For the second filter, we change the freqz command as follows which gives the frequency response of the second filter.

```
[H 2, w] = freqz([1], [1 0.9]);
```



(d).

From the plots of the magnitude responses, we can see that the first filter attenuates high frequencies more than low frequencies. Thus, this is a lowpass filter. The second filter attenuates low frequencies more than high frequencies. Thus, this is a highpass filter.

(e).

The response of a LTI-system $H(\omega)=|H(\omega)|e^{j\Theta(\omega)}$ to a sinusoidal input signal $x[n]=A\cos(\omega_0n+\theta)$ equals

$$y[n] = A|H(\omega_0)|\cos(\omega_0 n + \theta + \Theta(\omega_0)).$$

Thus, the output of the first system is

$$y_1[n] = \frac{1}{2} |H_1(\frac{\pi}{2})| \cos(\frac{\pi}{2}n + \frac{\pi}{4} + \Theta_1(\frac{\pi}{2})) = \frac{1}{2} \cdot 2\cos(\frac{\pi}{2}n + \frac{\pi}{4} - \frac{\pi}{2}) = \cos(\frac{\pi}{2}n - \frac{\pi}{4}).$$

Likewise, the output of the second system is

$$y_{2}[n] = \frac{1}{2} |H_{2}(\frac{\pi}{2})| \cos(\frac{\pi}{2}n + \frac{\pi}{4} + \Theta_{2}(\frac{\pi}{2}))$$

$$= \frac{1}{2} \frac{1}{\sqrt{1.81 + 1.8\cos(\frac{\pi}{2})}} \cos(\frac{\pi}{2}n + \frac{\pi}{4} + \tan^{-1}(\frac{0.9\sin(\frac{\pi}{2})}{1 + 0.9\cos(\frac{\pi}{2})})$$

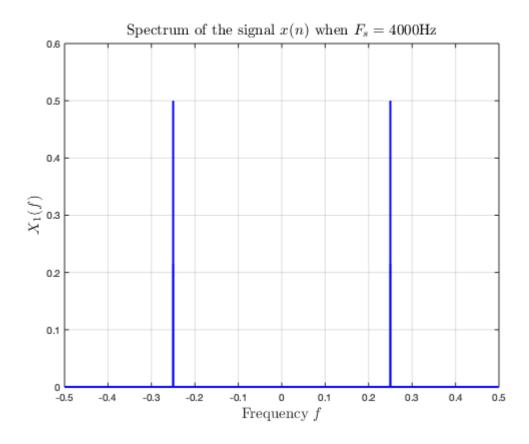
$$= \frac{1}{2} \frac{1}{\sqrt{1.81}} \cos(\frac{\pi}{2}n + \frac{\pi}{4} + \tan^{-1}(\frac{9}{10})) \approx \frac{1}{2} \frac{1}{\sqrt{1.81}} \cos(\frac{\pi}{2}n + 1.52).$$

Problem 4:

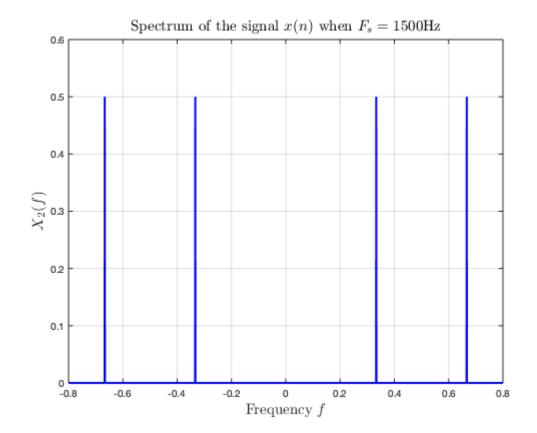
(a).

The spectra of the sampled signals are shown in the following Figures. The latter has a wider range of frequencies than the required $f \in [-\frac{1}{2}, \frac{1}{2}]$ to help making difference between alias components and signal components. The theory behind this is in ch.6.

$$F s=4000$$



F s=1500



(b).

Matlab-code for generating the signal corresponding to $F_s = 4000$:

```
t = [0:1/4000:1-1/4000];

cos4000 = cos(1000*2*pi*t);
```

And for the signal corresponding to $F_s = 1500$:

```
t = [0:1/1500:1-1/1500];

cos1500 = cos(1000*2*pi*t);
```

The sounds can be played with the commands:

```
sound(cos4000,4000);
pause(1)
sound(cos1500,1500);
```

They sound different because the signal incurred aliasing in the sampling. To be able to reconstruct $x_a(t)$ from a sampled signal, the sampling theorem requires that $F_s > 2F_{\rm max}$, where $F_{\rm max}$ is the highest frequency component of the signal. In this case,the signal has only one frequency component, at $1000{\rm Hz}$. Thus, we require $F_s > 2000{\rm Hz}$.