## Exercise on df

## Degrees of freedom in regression models

This exercise covers topics that are discussed in Ch. 5 and in Ch. 6.2 in the textbook.

Many of the regression methods that we are discussing are linear in y, that is the fitted value  $\hat{f}(x)$  is a linear combination of the observed  $y_i$ . Let  $\{x_i, y_i, i = 1, ..., N\}$  be the training data where  $x_i \in R^p$ . Let  $\hat{f} = (\hat{f}(x_1), ..., \hat{f}(x_N))^T$  be the fitted values in the training points. Linearity in y then corresponds to the existence of a matrix S such that  $\hat{f} = Sy$ .

a) Consider first ordinary linear regression based on the model  $y = X\beta + \epsilon$ . Find S in this case, and show that  $\operatorname{trace}(S) = p$ .

In general the matrix S will depend on some complexity parameter  $\lambda$  and we will then write  $S_{\lambda}$  which we call the *smoother matrix*. We define the *effective degrees of freedom* for a regression model that is linear in y by

$$\mathrm{df}_{\lambda} = \mathrm{trace}(S_{\lambda})$$

- b) Argue why this is a reasonable definition for the ordinary linear regression model.
- c) Show that also k-nearest neighbor, the Nadaraya-Watson estimate and local linear regression are linear in y.
- d) For k-nearest neighbor, show that  $\mathrm{df}_{\lambda}=N/k$ . Discuss this result. Hint: Identify the diagonal elements of  $S_{\lambda}$ .