

## TMA4180

## Optimisation I Spring 2017

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Solutions to exercise set 3

- a)  $\nabla f = Qx b$  and  $\nabla^2 f = Q$  from calculus. Since Q is symmetric positive definite (SPD), it follows that f is strictly convex on  $\mathbb{R}^n$ , and as such, there is at most one global minimum of f. Furthermore, this global minimum  $x^*$  must be a stationary point satisfying  $\nabla f(x^*) = 0$ . We conclude that  $x^* = Q^{-1}b$ , since Q is invertible (all eigenvalues of Q are positive, and hence, different from zero).
  - b) Newton's method reads

$$x_{k+1} = x_k + p_k,$$

where  $p_k = -(\nabla^2 f_k)^{-1} \nabla f_k$ , with  $\nabla f_k := \nabla f(x_k)$ , and  $\nabla^2 f_k := \nabla^2 f(x_k)$ . Therefore, given any  $x_0$ , we find that

$$x_1 = x_0 - Q^{-1}(Qx_0 - b) = Q^{-1}b = x^*,$$

that is, Newton's method converges after one step.

c) With chosen direction  $p_k$  in position  $x_k$ , and selected preliminary step length  $\alpha$  and some parameter  $c_1 \in (0,1)$ , backtracking line search iteratively reduces  $\alpha$  until

$$f(x_k + \alpha p_k) \le f(x_k) + c_1 \alpha \nabla f_k^{\top} p_k. \tag{*}$$

In our case,

$$f(x_k + \alpha p_k) = f(x_k) + \alpha \nabla f_k^{\top} p_k + \frac{1}{2} \alpha^2 p_k^{\top} \nabla^2 f_k p_k$$

by exact Taylor expansion (f is a quadratic form), and

$$p_k^{\top} \nabla^2 f_k \, p_k = -\nabla f_k^{\top} (\nabla^2 f_k)^{-\top} \nabla^2 f_k \, p_k = -\nabla f_k^{\top} p_k,$$

because  $\nabla^2 f$  (and its inverse) is symmetric. Inserting these expressions into  $(\star)$  yields that

$$\left(1 - \frac{\alpha}{2}\right) \alpha \nabla f_k^{\top} p_k \le c_1 \alpha \nabla f_k^{\top} p_k.$$

Now, since  $p_k$  is a descent direction (Q is SPD), this gives the criterion

$$c_1 \le 1 - \frac{\alpha}{2}.$$

Hence, if  $\alpha = 1$ , then  $c_1 \le 1/2$  is required, and, conversely, if  $c_1 \le 1/2$ , then the method accepts step lengths  $\alpha \le 2(1 - c_1)$ ; in particular,  $\alpha = 1$  is OK.

2 a) 
$$\nabla f = (4x - 2y + 6x^2 + 4x^3, 2y - 2x)$$
 and

$$\nabla^2 f = \begin{bmatrix} 4 + 12x + 12x^2 & -2 \\ -2 & 2 \end{bmatrix},$$

Hence, stationary points satisfy y = x by the first component of  $\nabla f$ , while the second component yields that  $0 = 2x(1 + 3x + 2x^2) = x(x+1)(2x+1)$ . Thus critical points of f are (0,0),  $(-\frac{1}{2},-\frac{1}{2})$ , and (-1,-1). Now,

$$\nabla^2 f(0,0) = \begin{bmatrix} 4 & -2 \\ -2 & 2 \end{bmatrix} = \nabla^2 f(-1,-1) \quad \text{and} \quad \nabla^2 f(-\frac{1}{2}, -\frac{1}{2}) = \begin{bmatrix} 1 & -2 \\ -2 & 2 \end{bmatrix}$$

has eigenvalues  $3 \pm \sqrt{5} > 0$  and  $(3 \pm \sqrt{17})/2$  (one positive, and one negative), respectively. We conclude that (0,0), and (-1,-1) are strict local minima, while  $(-\frac{1}{2},-\frac{1}{2})$  is a saddle point. Moreover, since  $\nabla^2 f$  remains SPD both for x>0 and x<-1 (the value of y is irrelevant), it follows that (0,0) and (-1,-1) are the only candidates for global minima. Evaluating f(0,0)=0=f(-1,-1), shows that both are global minimisers of f.

**b)** Gradient descent method equals  $(x_{k+1}, y_{k+1}) = (x_k, y_k) + p_k$ , with  $p_k = -\nabla f_k$ . Starting with preliminary step length  $\alpha$ ,  $\rho = 1/2$ , and  $c_1 = 1/4$ , we accept a new step provided

$$f((x_0, y_0) + \alpha p_0) \le f(x_0, y_0) + c\alpha \nabla f(x_0, y_0)^{\top} p_0 = 1 - 2\alpha$$

using that  $p_0 = -\nabla f(x_0, y_0) = (2, -2)$ .

Beginning with  $\alpha = 1$ , we reject the first try since  $f((x_0, y_0) + \alpha p_0) = 13 > -1$ . Reducing to  $\alpha \leftarrow \rho \alpha = 1/2$ , still gives rejection, but  $\alpha = 1/4$  succeeds, because  $f((x_0, y_0) + \alpha p_0) = 1/16 \le 1/2$ . Hence, we put  $(x_1, y_1) = (-\frac{1}{2}, -\frac{1}{2})$ , and proceed with a new round. However,  $(x_1, y_1)$  is a critical (saddle) point for f, so the gradient method stops here, thereby failing to converge to a minimiser.

c) Similarly as in b), the backtracking acceptance criterion for Newton's method reads

$$f((x_0, y_0) + \alpha p_0) \le f(x_0, y_0) + c\alpha \nabla f(x_0, y_0)^{\top} p_0 = 1 - \frac{1}{2}\alpha,$$

since  $p_0 = -\nabla^2 f(x_0, y_0)^{-1} \nabla f(x_0, y_0) = (0, -1)$  and  $c_1 = 1/4$ . Starting with  $\alpha = 1$ , we have  $f((x_0, y_0) + \alpha p_0) = 0 \le 1/2$ , so the step is accepted. We then put  $(x_1, y_1) = (x_0, y_0) + p_0 = (-1, -1)$ . This point is a global minimiser, the conclusion being that Newton's method converged in one step.

3 See file tma4180s17 = x03 = 3.m on the website.