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Boundary condition

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Abstract

Write abstract

1 Introduction

2 Giant viable cluster

Consider a multiplex network with L layers. Let $g_0^{(i)}$ and $g_1^{(i)}$ be the generating functions of respectively the degree and the excess degree in layer i . Moreover define u_i as the probability that a vertex reached after following an edge in layer i is not part of the giant viable cluster. Then if we pick a vertex v at random the probability S that it is part of the giant viable cluster can be written as

$$S = P_0 \left(\bigcap_{i=1}^L \exists w \in N_i(v) \ w \in GVC \right). \quad (1)$$

By requiring that the layers are independent from one others, we can rewrite S as a product

$$S = \prod_{i=1}^L P_0 (\exists w \in N_i(v) \ w \in GVC) \quad (2)$$

$$= \prod_{i=1}^L [1 - P(w \notin GVC \ \forall w \in N_i(v))] \quad (3)$$

$$= \prod_{i=1}^L \left[1 - \sum_{k=0}^{\infty} P((w \notin GVC \ \forall w \in N_i(v) | \deg(v) = k) p_k^{(i)} \right] \quad (4)$$

$$= \prod_{i=1}^L \left[1 - \sum_{k=0}^{\infty} u_i^k p_k^{(i)} \right] \quad (5)$$

$$= \prod_{i=1}^L [1 - g_0^{(i)}(u_i)]. \quad (6)$$

{Multiplex GCC size final}

We can find u_j by a similar reasoning. First note that $1 - u_j$ is the probability that a vertex reached by following an edge in layer j is in the

giant viable cluster. Which as before can be written in the form

$$1 - u_j = P_1^{(j)} \left(\bigcap_{i=1}^L \exists w \in N_i(v) \ w \in GVC \right) \quad (7)$$

$$= \prod_{i=1}^L P_1^{(j)} (\exists w \in N_i(v) \ w \in GVC). \quad (8)$$

Since the layers are independent, the fact that we reached v by following an edge in layer j to reach vertex v is irrelevant in all other layers. However in layer j this means that the degree distribution follows the distribution $q_k^{(j)}$ rather than $p_k^{(j)}$. Putting this together we get

$$1 - u_j = \left[1 - \sum_{k=0}^{\infty} u_j^k q_k^{(j)} \right] \prod_{\substack{i=1 \\ i \neq j}}^L \left[1 - \sum_{k=0}^{\infty} u_i^k p_k^{(i)} \right] \quad (9)$$

$$= \left[1 - g_1^{(j)}(u_j) \right] \prod_{\substack{i=1 \\ i \neq j}}^L \left[1 - g_0^{(i)}(u_i) \right]. \quad (10)$$

{Multiplex u final}

Is this section too precise and should the results be given with just a citation ?

3 Boundary condition

Equations (6) and (10) are in principle sufficient to determine the size S of the giant viable cluster in a multiplex network. We see that there always exists a trivial solution

$$u_j = 1, \quad \forall j, \quad (11)$$

$$S = 0. \quad (12)$$

Moreover this is the only solution for which $S = 0$. Indeed since $g_0^{(j)}$ is a strictly increasing function, we have

$$g_0^{(j)}(z) = 0 \quad \Leftrightarrow \quad z = 1. \quad (13)$$

So if $S = 0$, there exists k such that $u_k = 1$. If we put it back in eq. (10), it forces $1 - u_j = 0$ for all j , and thus all u_j are one.

Something about the fact that the degree distributions are determined by some set of parameters λ_j

We now introduce the following notations:

$$\mathbf{u} = (u_1, u_2, \dots, u_L) \quad (14)$$

$$\boldsymbol{\lambda} = (\lambda_1, \lambda_2, \dots, \lambda_N) \quad (15)$$

$$f_j(\boldsymbol{\lambda}, \mathbf{u}) = 1 - u_j - \left[1 - g_1^{(j)}(u_j) \right] \prod_{\substack{i=1 \\ i \neq j}}^L \left[1 - g_0^{(i)}(u_i) \right] \quad (16)$$

{Definition fj}

and the function

$$F : \mathbb{R}^N \times D_L \rightarrow \mathbb{R}^L \quad (17)$$

$$(\boldsymbol{\lambda}, \mathbf{u}) \mapsto F(\boldsymbol{\lambda}, \mathbf{u}) = (f_1(\boldsymbol{\lambda}, \mathbf{u}), f_2(\boldsymbol{\lambda}, \mathbf{u}), \dots, f_L(\boldsymbol{\lambda}, \mathbf{u})), \quad (18)$$

{Definition F}



Continuous/discontinuous phase transition and consequences

where $D_L = [0, 1]^L$. Since the $g_0^{(i)}$ and $g_1^{(i)}$ are analytic with respect to the u_i , the function

$$F_{\lambda} : D_L \rightarrow \mathbb{R}^L \quad (19)$$

$$\mathbf{u} \mapsto F_{\lambda}(\mathbf{u}) = F(\lambda, \mathbf{u}), \quad (20)$$

for a given parameter vector λ is continuously differentiable as well. Therefore we can define its Jacobi matrix $J(\lambda, \mathbf{u})$ as having coefficients

$$[J(\lambda, \mathbf{u})]_{ij} = \frac{\partial f_i(\lambda, \mathbf{u})}{\partial u_j}. \quad (21)$$

In terms of the introduced notation, solving eq. (10) is equivalent to finding \mathbf{u}^* such that

$$F(\lambda, \mathbf{u}^*) = 0. \quad (22)$$

Assuming that F (and not only F_{λ}) is continuously differentiable and that we know a solution \mathbf{u}^* for some parameter vector λ^* , we can use the implicit function theorem which give us the following:

If $\det[J(\lambda, \mathbf{u}^*)] \neq 0$ then there is an open neighbourhood $U \subset \mathbb{R}^L$ of λ^* such that there is a unique continuously differentiable function $h : U \rightarrow D_L$ with

$$h(\lambda^*) = \mathbf{u}^* \quad (23)$$

$$F(\lambda, h(\lambda)) = 0, \quad \forall \lambda \in U. \quad (24)$$

{Implicit solution for F}

The result in which we are interested here however comes from the contrapositive statement, namely that if we can not find suitable neighbourhood U and function h , then the determinant of the Jacobi matrix $J(\lambda, \mathbf{u})$ must be zero. We now prove that it arises if λ^* is a critical point of a phase transition.

First notice that in the context of multiplex network a phase transition appears between the trivial solution $\mathbf{u}_T = (1, 1, \dots, 1)$ (where $S = 0$) and non trivial solutions ($S > 0$). However, the trivial solution \mathbf{u}_T solves eq. (10) for any generating function and thus for any parameter vector λ . This implies that at one side of the phase transition only one solution exists, while on the other at least two does. Therefore if there is a continuous phase transition at λ^* , for any U open containing λ we can define two distinct functions on U that fulfil eq. (24), the trivial $h_T(\lambda) = \mathbf{u}_T$ and another function h corresponding to the non trivial solutions. Therefore the function h of the implicit function theorem is not uniquely defined and thus $\det[J(\lambda^*, \mathbf{u}^*)] = 0$.

On the other hand, for a discontinuous phase transition at $\boldsymbol{\lambda}^*$, there are two sequences $\boldsymbol{\lambda}_n$ and \mathbf{u}_n such that

$$\lim_{n \rightarrow \infty} \boldsymbol{\lambda}_n = \boldsymbol{\lambda}^* \quad (25)$$

$$\lim_{n \rightarrow \infty} \mathbf{u}_n \neq \mathbf{u}_T \quad (26)$$

$$F(\boldsymbol{\lambda}_n, \mathbf{u}_n) = 0. \quad (27)$$

This implies that no continuous function h can be defined to solve eq. (24). Therefore, once again, we have $\det [J(\boldsymbol{\lambda}^*, \mathbf{u}^*)] = 0$.

More ex-
planation
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