## Benchmarking Combinatorially with Python

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#### Introduction

You have an awesome algorithm, **but**:

How can you ensure that it behaves better w.r.t. state-of-the-art?

- ♦ Theoretically? What if it's too complex?
- By comparing its performances on different scenarios with different state-of-the-art algorithms?



**Problem:** the scenarios and the comparing algorithms may lead to too many combinations!

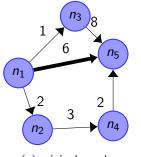
**Goal:** design a extensible framework that automatically performs all the combinations required for your performance testing;

**Result** a new Python software called phd-tester which performs automatic testing. Code available at

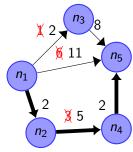
HTTPS://GITHUB.COM/KOLDAR/PHDTESTER

**Context:** *dynamic* single agent pathfinding (given a weighted directed graph  $\mathcal{G} = \langle N, E \rangle$ , a *start* vertex s, a *goal* vertex t, what is the optimal path allowing an agent to reach t from s?); *dynamic* in the sense that, at the beginning of each pathfinding, some (arbitrary) edges temporary increase their cost (*perturbations*).

**Example**: going from  $s = n_1$  to  $t = n_5$ 



(a) original graph



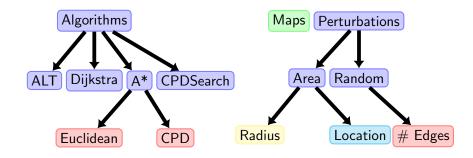
(b) Graph temporary altered

# A Motivating Example (2)

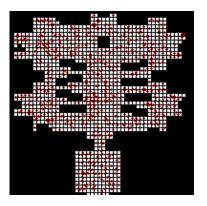
#### We can solve it:

- ♦ 4 Algorithms: Dijkstra, ALT, A\* + Euclidean Distance, A\* + CPD, **CPD** search (our technique!);
- On which map? hrt201, dustwallowkeys, mazes512-1-4. rooms16-003, ...;
- ♦ How to generate perturbations? Randomly? If so how many Edges should we affect? Or by affecting a specific Area along the optimal path? If so, how Wide the area is? Where should we affect the Path?

# A Motivating Example (3)



## A Motivating Example (4)



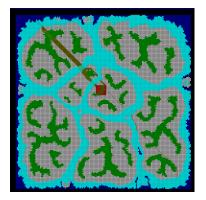


Figure: Example of perturbation policies. perturbations are shown in red. Left: random; Right: area

$$|Algs| = 5, |Maps| = 4, |Perturbations| = 2$$
 $\downarrow \downarrow$ 

$$Algs \times Maps \times Perturbations = 32$$

But R depends on parameter E while A depends on W and P parameters!

If we can choose the parameters:

- $-E \in \{1\%, 5\%, 10\%\}$ :
- $-P \in \{20\%, 50\%, 100\%\}$ :
- $W \in \{5, 10, 15\}$ :

Maximum combinations:  $32 \cdot |E \times P \times W| = 864!$  If we add new parameters (which, in research, it happens quite often) maximum combinations significantly increases!

#### Talk Outline

The talk will be outlined as follows:

- Background: Software used;
- Proposed Technique: KS001 and phd-tester;
- Experiments: testing with CPD Search;
- Conclusion and Future Works: integration with CSPs and generates automatic report pdf;

### CSV file format

- Easy for storing data in "tabular" format:
- Human readable;
- can be read by tabular softwares (i.e., Excel, LibreOffice Calc);

```
INVOICE DETAIL - Notepad
     Edit Format View Help
"ID", "BILL DATE", "VENDOR", "BAN"
1,11/8/2008 0:00:00,"ATT-NRC
2,11/8/2008 0:00:00,"ATT-NRC
                                          3107020003552
3,11/8/2008 0:00:00,
11.11/8/2008 0:00:00.
17,11/8/2008 0:00:00,"ATT-NRC
18,11/8/2008 0:00:00,"ATT-NRC
19,11/8/2008 0:00:00, "ATT-NRC
```

20,11/8/2008 0:00:00, "ATT-NRC"

- Language: Python 3[.6]: duck typing, scripting, ABC library, usually installed by default;
- ArangoDB: NoSQL graph-based database; basically we can store JSON; Compactly represent data;
- $\diamond$  Pandas: allows operations on "dataframe" ( $\approx$  CSV);

```
▼ 6 properties, 427 bytes
"manifest version": 2,
"name": "JSON Lite".
"version": "0.12".
"description":
large files, collapse items",
"browser action": { ▼ 1 property, 40 bytes
  "default popup": "README.html"
"content scripts": [ ▼ 1 item, 167 bytes
  { ▼ 4 properties, 157 bytes
     "all frames": true,
     "matches": [ ▼ 1 item, 30 bytes
       "<all urls>"
     "js": [ ▼ 1 item, 30 bvtes
       "content.is"
     "run at": "document end"
```

## Design Patterns

- template: abstract class provides general behaviour with an concrete unmodifiable method m whilst derived classes implements single tasks used in m (e.g., java.awt.Component);
- Interface: allows usage of methods from a not-well specified object abstracting from its actual implementation;
- API: a method or a service a library or a third-party system provides to the developer in order to perform a task;

#### Main Ideas

Each **test**  $t \in \mathcal{T}$  involves a **stuff**  $s \in \mathcal{S}$  to test (e.g., algorithm) and an **environment**  $e \in \mathcal{E}$  where the test occurs (e.g., path finding map) Each **stuff(environment)** is a tuple of n(m) values of parameters  $p_i \in \mathcal{P}$  (e.g., number of edge to perturbate, heuristic to use), where each parameter value  $v_i$  has a specific domain  $\mathcal{D}_i \cup \{nil\}$  (NIL). All Elements in  $\mathcal{S}(\mathcal{E})$  share the same tuple structure.

The final application is composed by 2 parts:

- **1** a **library** which the user call and provide a *template design* pattern with easy APIs (provided by phd-tester);
- 2 a user code which implements the template design pattern, providing mandatory information about the test as well as actually call the program to test (pro: test can be coded with any language!).

## Template to follow

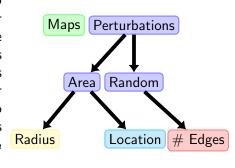
High-level steps in the template provided by the framework:

- the user specifies all the parameter values he wants (e.g., perturbation generation policy ∈ {random, area});
- $oldsymbol{\circ}$  the application generates all the required tests  $\mathcal{T}^* \subseteq \mathcal{T}$ ;
- **3** the application executes all the tests  $t \in \mathcal{T}^*$ ;
- the application produces generate n CSVs representing test outcome (note  $n \ge |\mathcal{T}^*|$ );

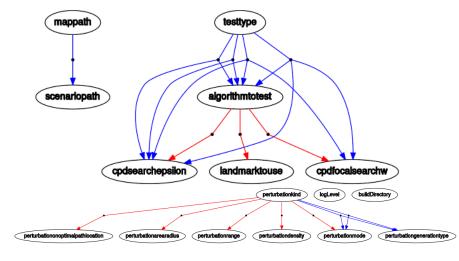
# Option Graph

The user specifies all the parameter values he wants (e.g., perturbation generation policy  $\in$  {random, area});

By command line. In order to build the CLI interface, developer needs in *user code* to declare the **option graph**:  $\forall p_i \in \mathcal{P}$  say its domain  $\mathcal{D}_i$ , and what constraints it implies (e.g., if parameter perturbationPolicy is set to random, then the CLI needs to specify parameter value edge number).



## Example of Option graph



### **CLI** generated

```
usage: main.py [-h] [--algorithmtotest values ALGORITHMTOTEST VALUES]
               [--cpdsearchepsilon values CPDSEARCHEPSILON VALUES]
               [--cpdfocalsearchw values CPDFOCALSEARCHW VALUES]
               [--landmarktouse values LANDMARKTOUSE VALUES]
               [--testtype values TESTTYPE VALUES]
               [--mappath values MAPPATH VALUES]
               [--scenariopath values SCENARIOPATH VALUES]
               [--perturbationkind values PERTURBATIONKIND VALUES]
               [--perturbationgenerationtype values PERTURBATIONGENERATIONTYPE VALUES]
               [--perturbationmode values PERTURBATIONMODE VALUES]
               [--perturbationonoptimalpathlocation_values_PERTURBATIONONOPTIMA<u>LPATHLOCATION_VALUES]</u>
               [--perturbationarearadius values PERTURBATIONAREARADIUS VALUES]
               [--perturbationrange values PERTURBATIONRANGE VALUES]
               [--perturbationdensity values PERTURBATIONDENSITY VALUES]
               [--logLevel LOGLEVEL] [--buildDirectory BUILDDIRECTORY]
optional arguments:
 -h. --help
                        show this help message and exit
  --algorithmtotest values ALGORITHMTOTEST VALUES
                        . Accepted values are CPD-SEARCH CPD-FOCAL-SEARCH ALT
  --cpdsearchepsilon values CPDSEARCHEPSILON VALUES
  --cpdfocalsearchw values CPDFOCALSEARCHW VALUES
                        Focal Search W bound
  --landmarktouse values LANDMARKTOUSE VALUES
  -- testtype values TESTTYPE VALUES
                        . Accepted values are OPTIMAL BOUNDED
```

### Generation of $\mathcal{T}^*$

the application generates all the required tests  $\mathcal{T}^* \subseteq \mathcal{T}$ .

 $\mathcal{T}^*$  represents all the tests which we are required to execute. Some cartesian products in  $\mathcal{S} \times \mathcal{E}$  are simply invalid (e.g., number of edges to perturbate set to 'nil' when the perturbation policy is random).

phd-tester exploits the option graph not only to generate the CLI, but also to detect parameters dependencies.

**Example:** Given a  $t \in \mathcal{T}$  if perturbation policy is random, require that number of edges $\neq$  'nil': if it is true, add t in  $\mathcal{T}^*$ ).

The application produces generate n CSVs representing test outcome (note  $n \ge |\mathcal{T}^*|$ );

In this step the **user code** has all the freedom it desires. Usually the developer is expected to call an external program (e.g., coded in C or in C++) that actually performs the test. As a side effect, one or more CSVs are expected to be produced somewhere (i.e., file system, ArangoDB,  $mySQL \Rightarrow \textbf{Data source}$ ).

- ♦ **Problem:** how to identify which CSVs have been generated by which test  $t \in \mathcal{T}^*$ ?
- Solution: by creating a new naming convention of file: KS001;

#### KS001 standard

#### Idea

The filename is composed by basename and extension. basename is a **ordered** sequence of substring separated by |, and it is optionally prefixed by a label. Each substring is a unordered sequence of keyvalues string, separated by \_. Each keyvalue follows the pattern key=value.

```
filename := identifier? '|' dictionaries '|' extension? dictionaries := dictionary ( '|' dictionaries )* dictionary := name ':' keyvalues* | keyvalues keyvalues := keyvalue ( '_' keyvalues )* keyvalue := key '=' value
```

```
name := string
identifier := [^|]+
extension := string
key := string
value := string
string := ([^=_|:]|'='{2}|'_'{2}|'|'{2}|':'{2})+
```

```
mp=16room_003.map_pd=0.1_pgt=PER-SCENARIO_pk=RANDOM
_pm=MULTIPLY_pr=[3,3]_sp=16room__003.map.scen
|generated:type=id-over-time|.csv
```

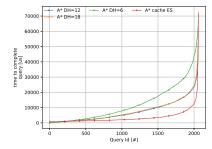
- doubling special characters if shown in key(value);
- ♦ aliasing of key(values) to avoid long names (you may reach path size limit);
- labelling of dictionary increase readability;
- phd-tester offers a set of function to query and manage KS001 compliant strings;

# Generation of interesting data (1)

The application produces generate n CSVs representing test outcome (note  $n \ge |\mathcal{T}^*|$ );

We use all the CSVs produced in the previous phase and stored in a **data source** to generate *new* CSVs representing the benchmarks (and optionally, the related graphs as well).

Performance over query id (times SORTED)
use\_bound=False use\_anytime=False perturbation\_mode=MULTIPLY perturbation\_range=[10,10] area\_radius=[15,15] optimal\_path\_ratio=[0,95]



# Generation of interesting data (2)

phd-tester dynamically generate these csv(image).

- each csv(image) is often produced by analyzing one or more outputs of tests in  $\mathcal{T}^*$ :
- ophd-tester provides masks, which acts as filter allowing the software to fetch a subset of  $\mathcal{T}^*$  to consider to produce a new csv(image) (e.g., produce time used by all algorithm depending on the number of edge perturbated in the map);
- ♦ The number of CSVs to analyze may be huge (maybe over 30000, each with 100 an more rows!). phd-tester used pandas along with dask to concurrently computes the operations  $\Rightarrow$  fast:
- CurveChanger: allows to further alters the functions generated by adding/removing/sorting values;

#### Conclusions and Future Works

#### In conclusion:

- ♦ We have developed phd-tester, an extensible framework to combinatorially testing algorithms, parametrized both in regard of what we're testing and of the environment of the test;
- proposed a naming convention of files which is both human readable and software parsable (KS001);
- developed a mechanism to concurrently computed generated data and plot it;
- ♦ **Future works:** integrate MySQL as data source; generate automatic pdf reports of the tests done; Use a CSP to build the option graph. See https://github.com/Koldar/phdTester/issues for further works to be done.