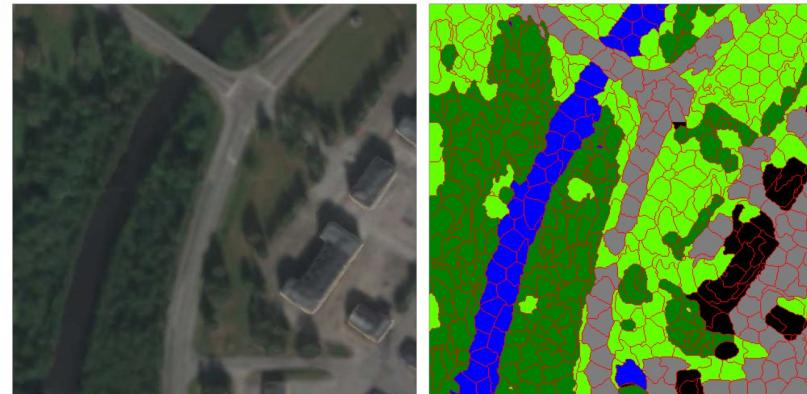


Satellite Image Segmentation

Advanced Image Processing - 22/01/2026

Colin Manyri



Project Overview and Objectives

Project Objectives

- Implement and compare multiple image segmentation methods. (thresholding, histograms, CNN)
 - Challenges of optimizing computational complexity (low-power computer).
 - Focus on methodology over absolute performance metrics

- I. Dataset Presentation and Feature Extraction
 - II. Multiples image segmentations techniques
 - III. Inference, Post-Processing, and Predictions
 - IV. Results and Performances
 - V. Conclusion and Perspectives

Presentation of the Dataset

Land Cover from Aerial Imagery - LandCover.ai

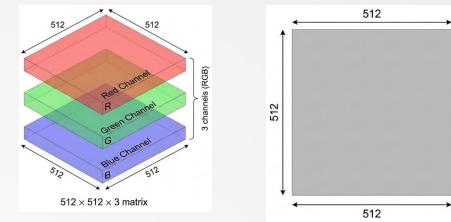
A dataset for mapping of buildings, woodlands, water and roads from Als.



Dataset structure

<https://landcover.ai.linuxpolska.com/>

- **Images:** Around 10,000 satellite images, with a resolution of 512×512 , stored in *.jpg* format.
- **Masks (Labels):** Each image is associated with a **monochannel** segmentation mask, used as ground truth and stored in *.png* format.



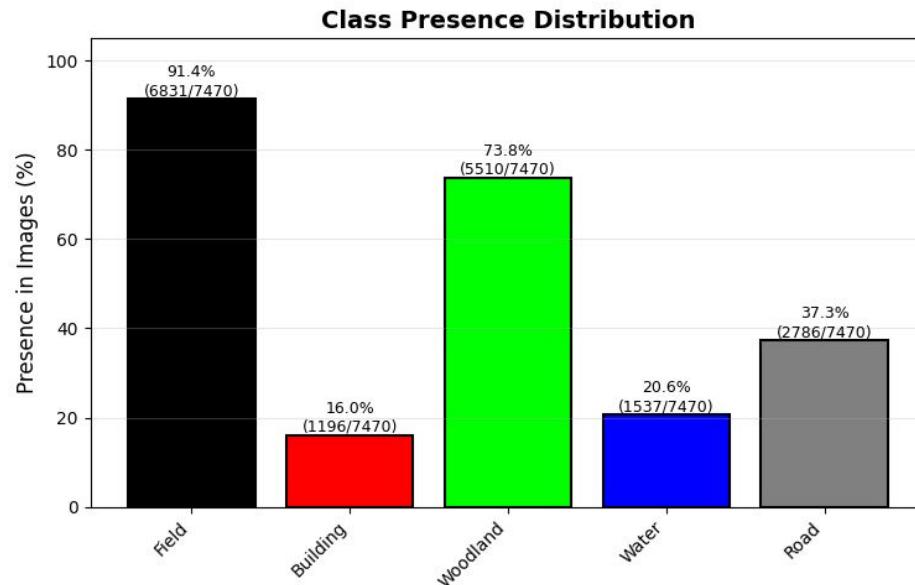
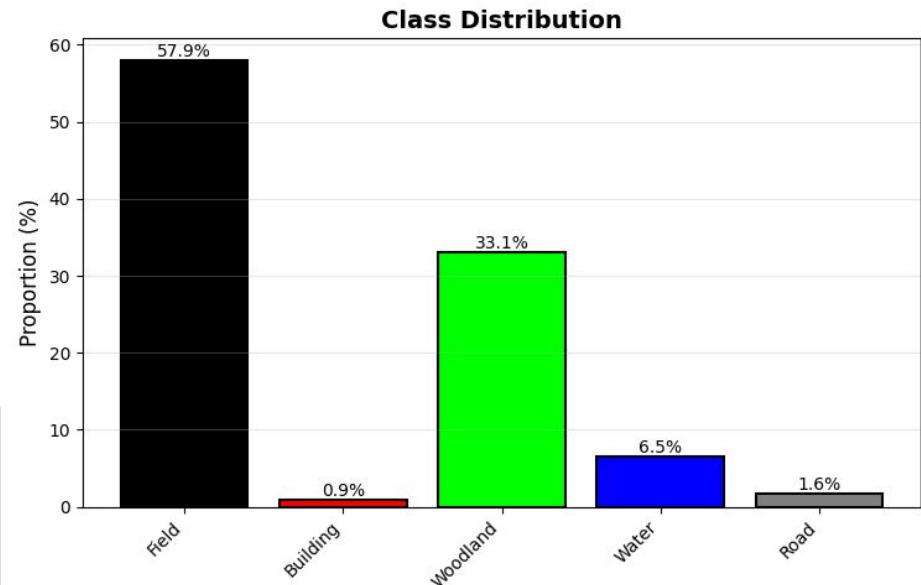
- **Data Splits:** The dataset is divided into ***Train*, *Val* and *Test*** subsets for model development and evaluation.
- **Classes:** The segmentation task includes 5 semantic classes: *Field*, *Woodland*, *Building*, *Water*, and *Road*.



About the classes

Class imbalance: lots of *Field*, few *Buildings* and *Roads*.

- **Accuracy is misleading:** high accuracy ≠ good classification.
- **Focus on minority classes:** monitor recall and consider alternative metrics (F1, IoU).
- **Use data augmentation or class weighting** to help underrepresented classes.



Feature choice

The current observation

- Heterogeneous dataset
- Images vary in intensity, texture, etc...
- **Hard to know a priori which features are most discriminative.**

The best solution

- Extracting a broad set of features (color, texture, geometry, multi-scale context) ensures all possible discriminative cues are captured.
- Dimensionality reduction (PCA) or feature selection can be applied later.

Robustness for probabilistic models : Ensures that all relevant patterns can be captured by histogram-based or learning-based models.

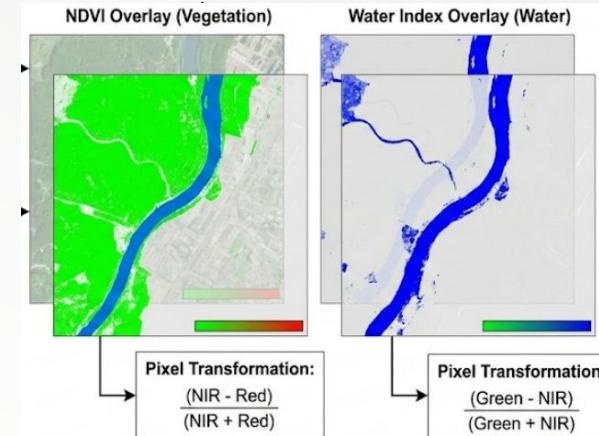
Color / Spectral
RGB, HSV

Intensity / Context:
Grayscale, Multi-scale Blur

Gradient / Geometry
Gradient, Anisotropy

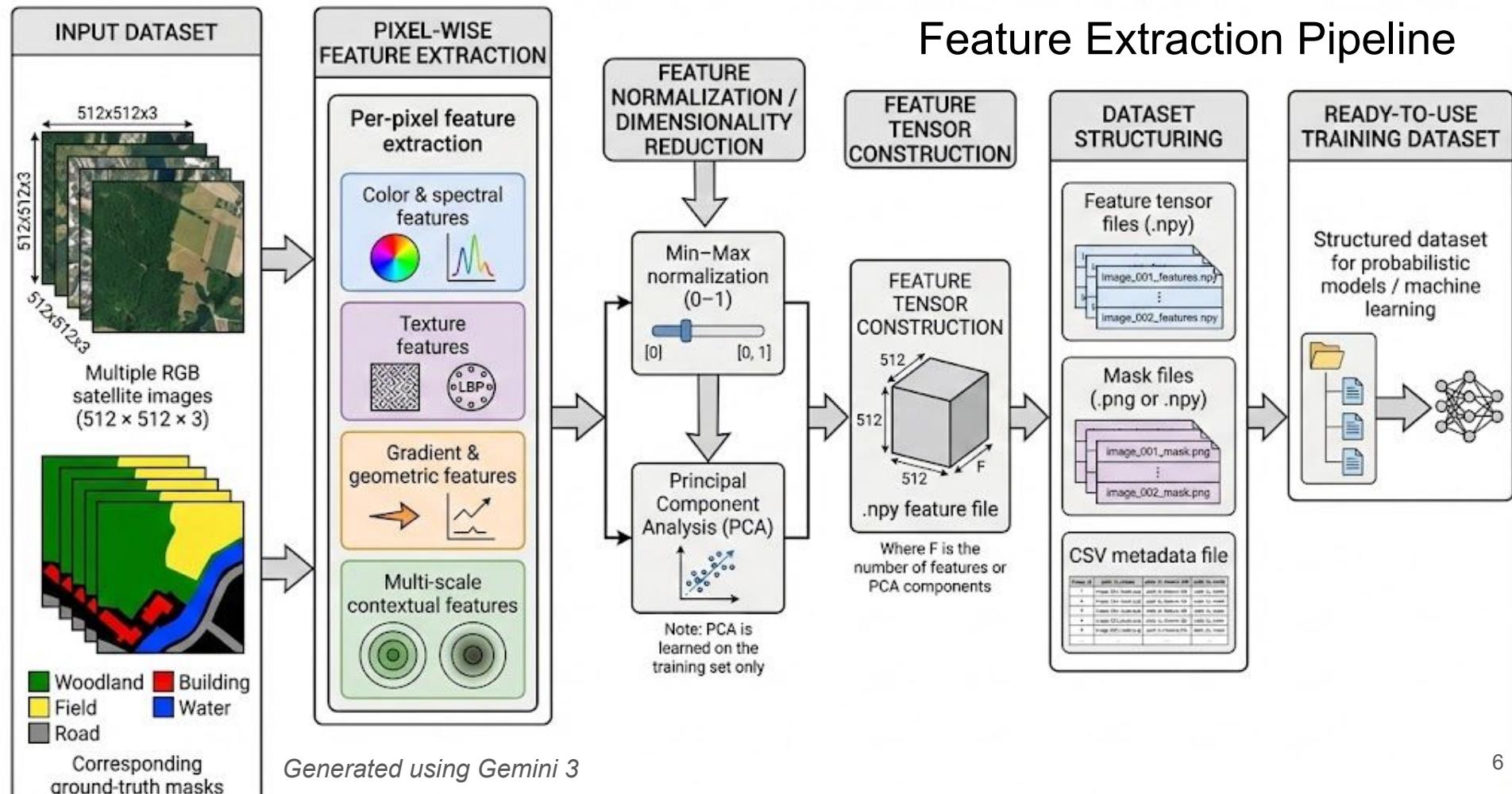
Texture
Variance, Entropy, LBP

Indices
NDVI, Water

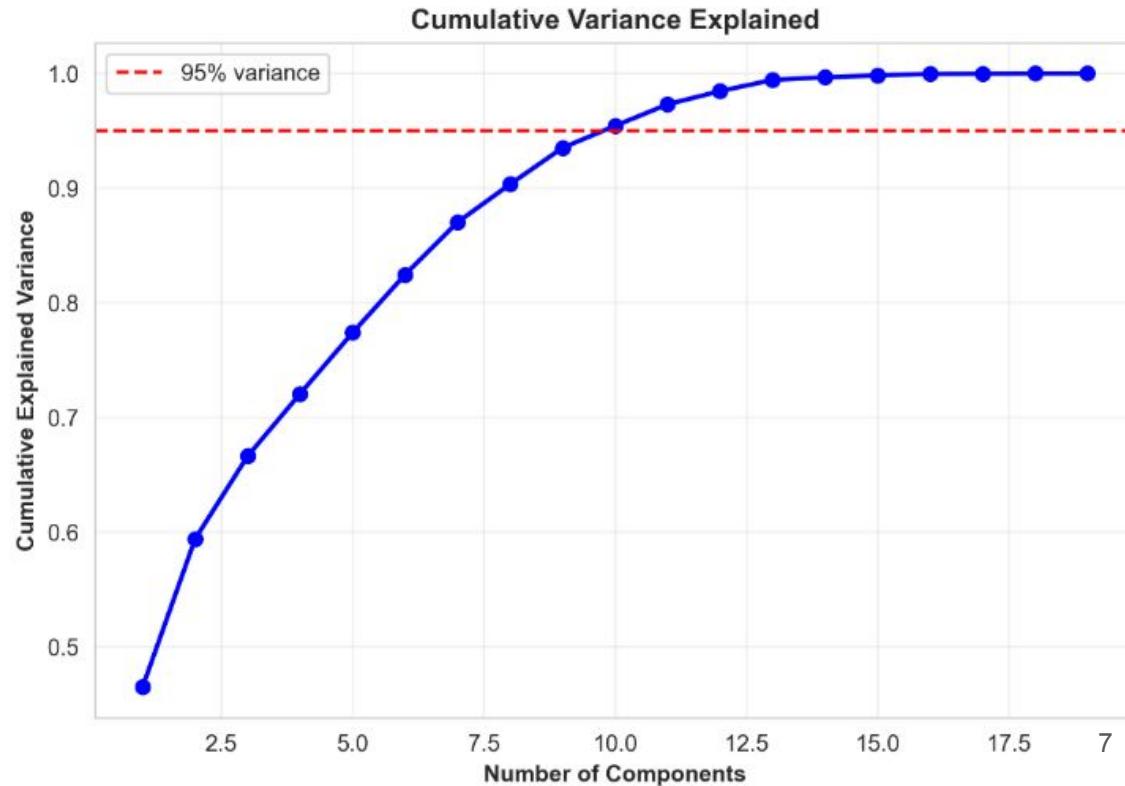
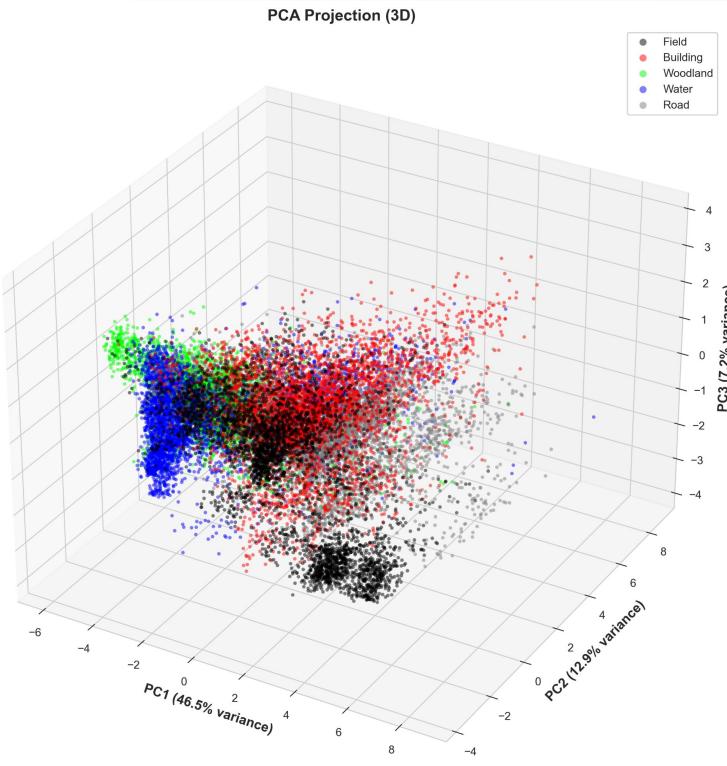


I. Feature Extraction

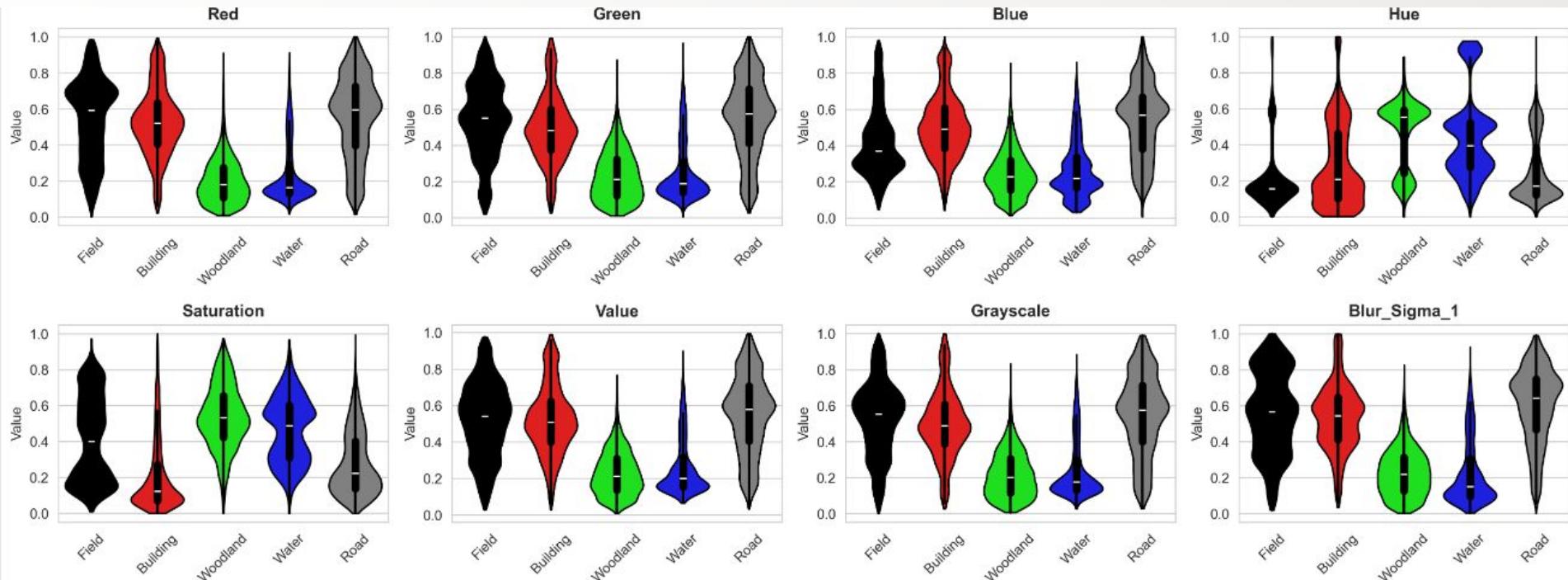
Feature Extraction Pipeline



Selected Feature analysis



Selected Feature analysis



Histogram-Based Probabilistic Segmentation

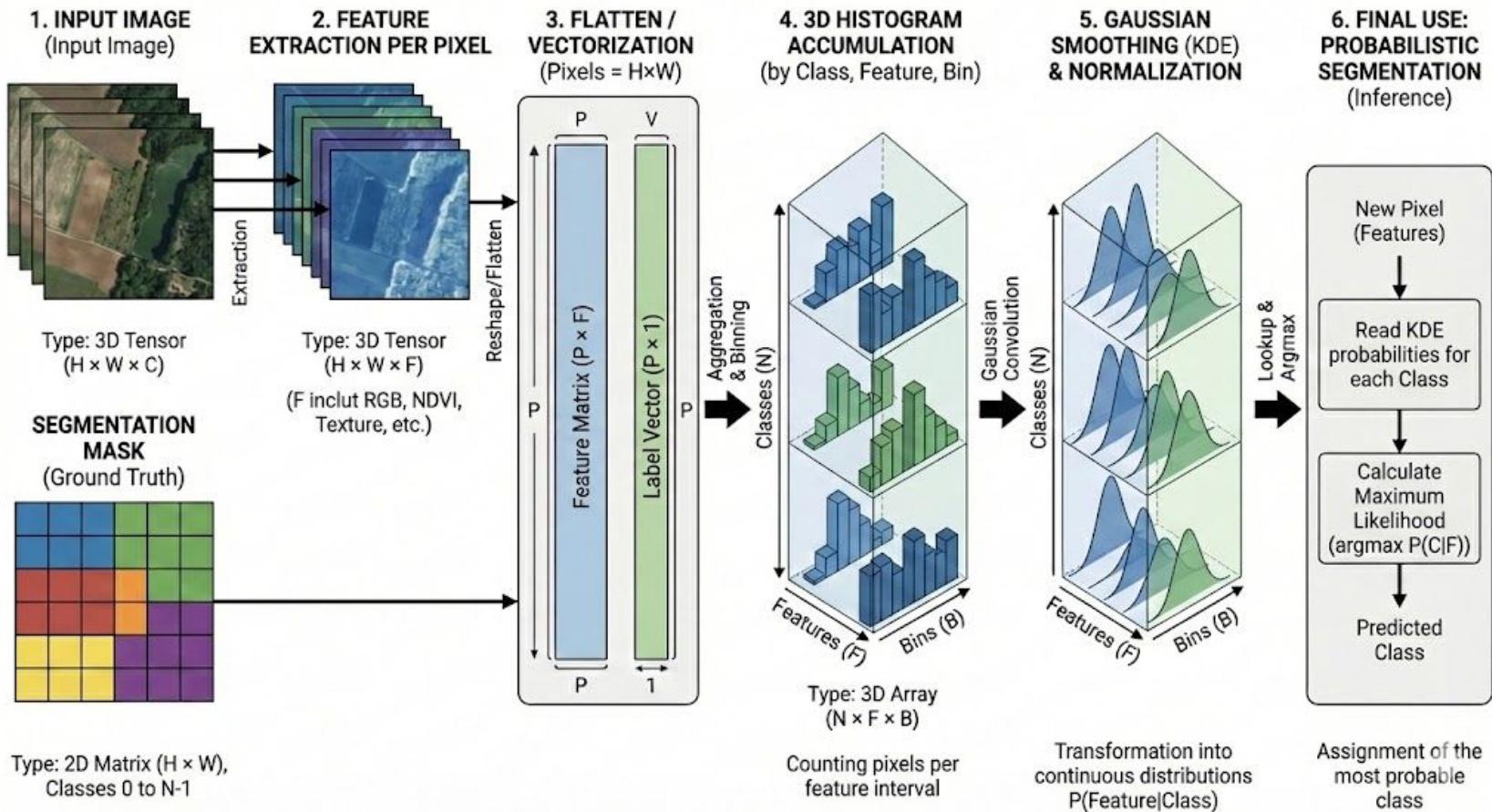
- Each pixel is represented by a **feature vector** $\mathbf{x} \in \mathbb{R}^F$
- For each class c , a **feature distribution** is learned using **histograms**
- Segmentation is performed by assigning each pixel to the most probable class:
- Feature space is discretized into bins
- For each class c , a histogram estimates the density:

$$\hat{c} = \arg \max_c P(\mathbf{x} | c)$$

$$P(\mathbf{x} | c) \approx \frac{N_{c,\text{bin}(\mathbf{x})}}{N_c}$$

| Aspect | Multi-thresholding | Histogram-based Segmentation | | | | | |
|----------------------|------------------------|-----------------------------------|---|---|---|---|---|
| Decision type | Hard, binary decision | Soft, probabilistic decision | | | | | |
| Feature usage | Single or few features | Multi-dimensional feature vectors | | | | | |
| Decision boundary | Fixed thresholds | Data-driven decision surfaces | ● | ● | ● | ● | ● |
| Handling uncertainty | Not modeled | Explicitly modeled | ● | ● | ● | ● | ● |
| Class overlap | Poorly handled | Naturally handled | ● | ● | ● | ● | ● |
| Robustness to noise | Low | Higher | ● | ● | ● | ● | ● |

Histogram-Based Probabilistic Segmentation

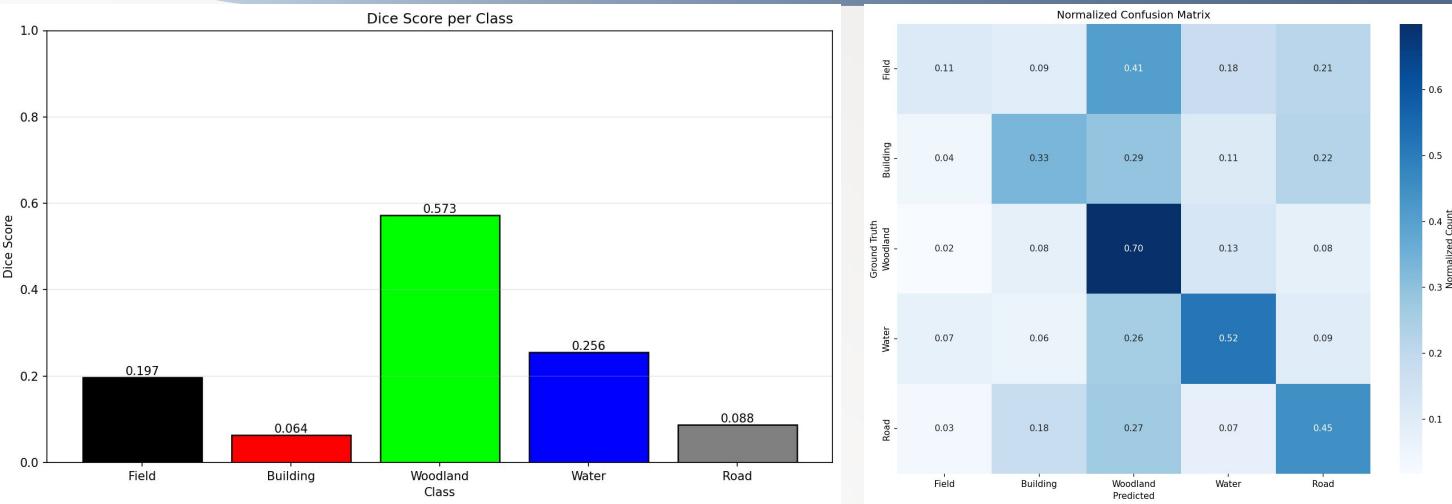


II. Image segmentations techniques

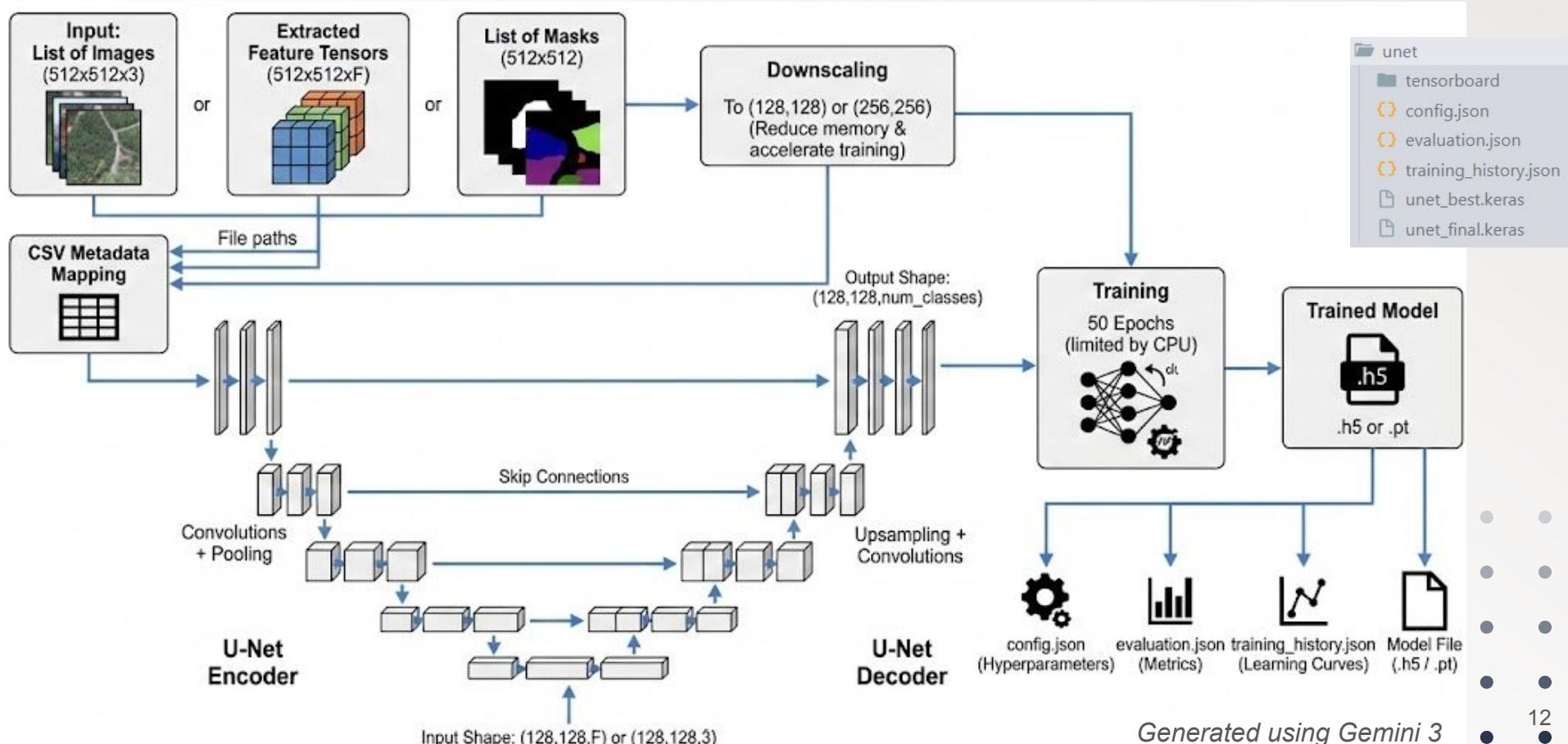
Results

Histogram

Very bad results
for now

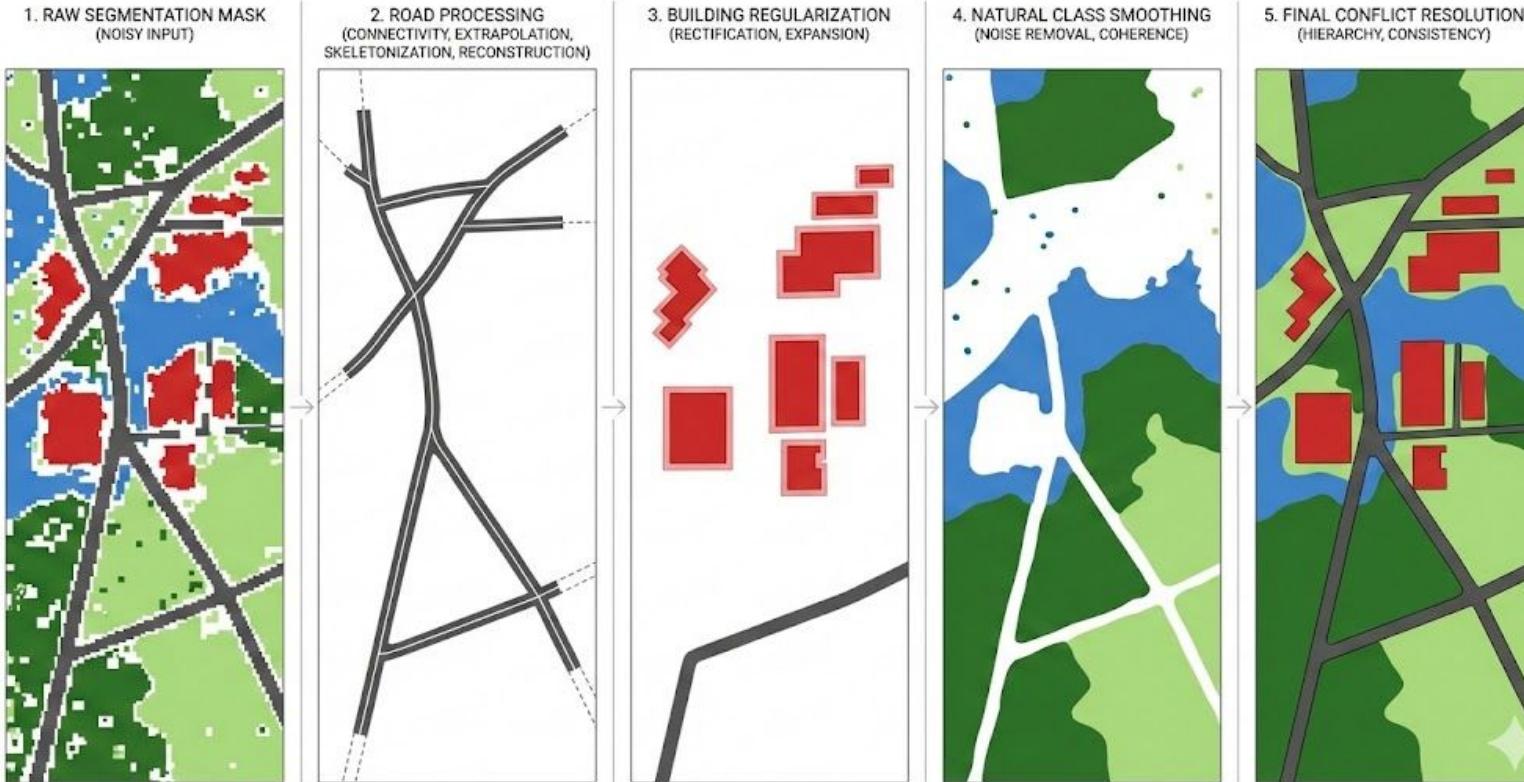


Another Technique: CNN Pipeline using U-Net

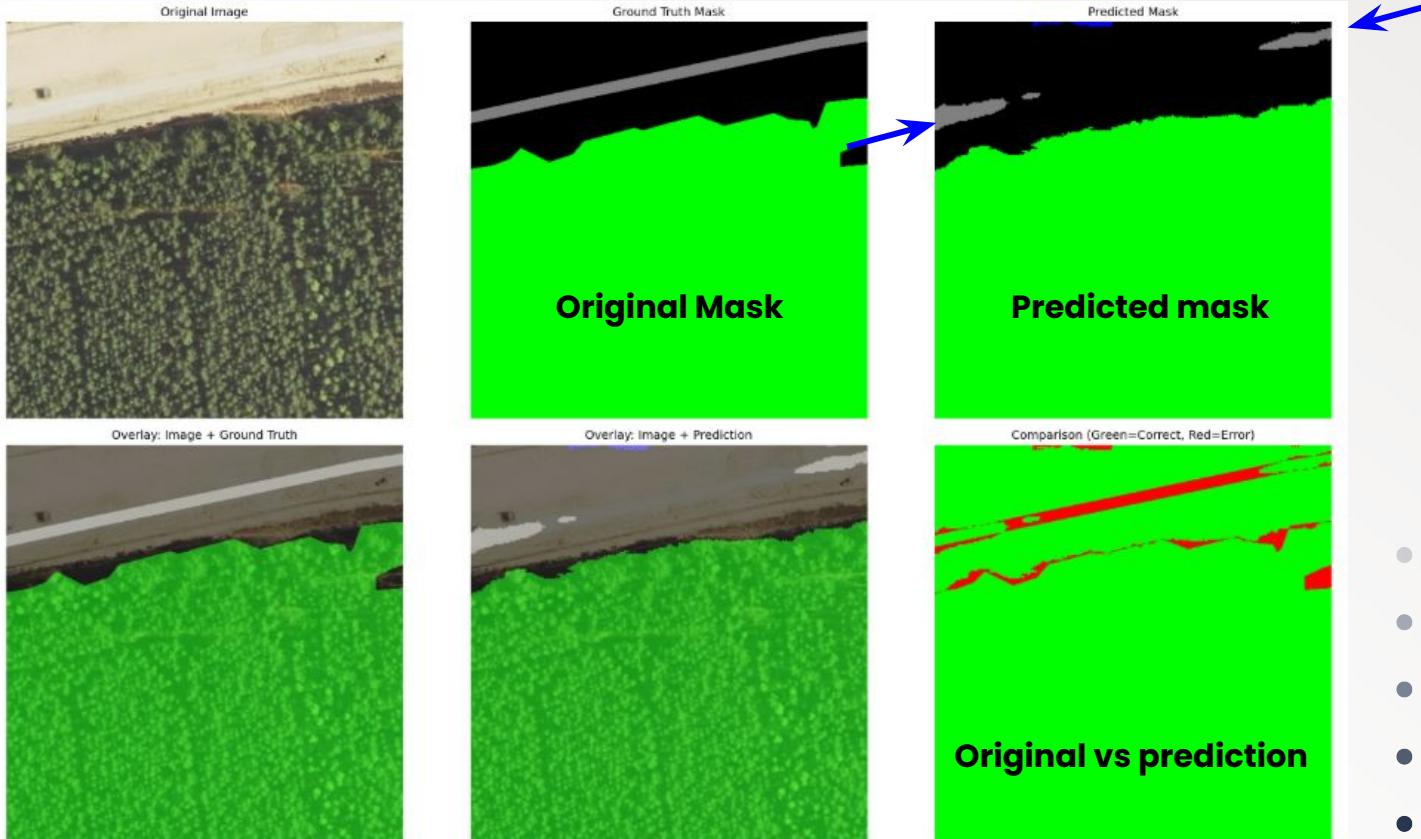


Post-Processing : Main Ideas

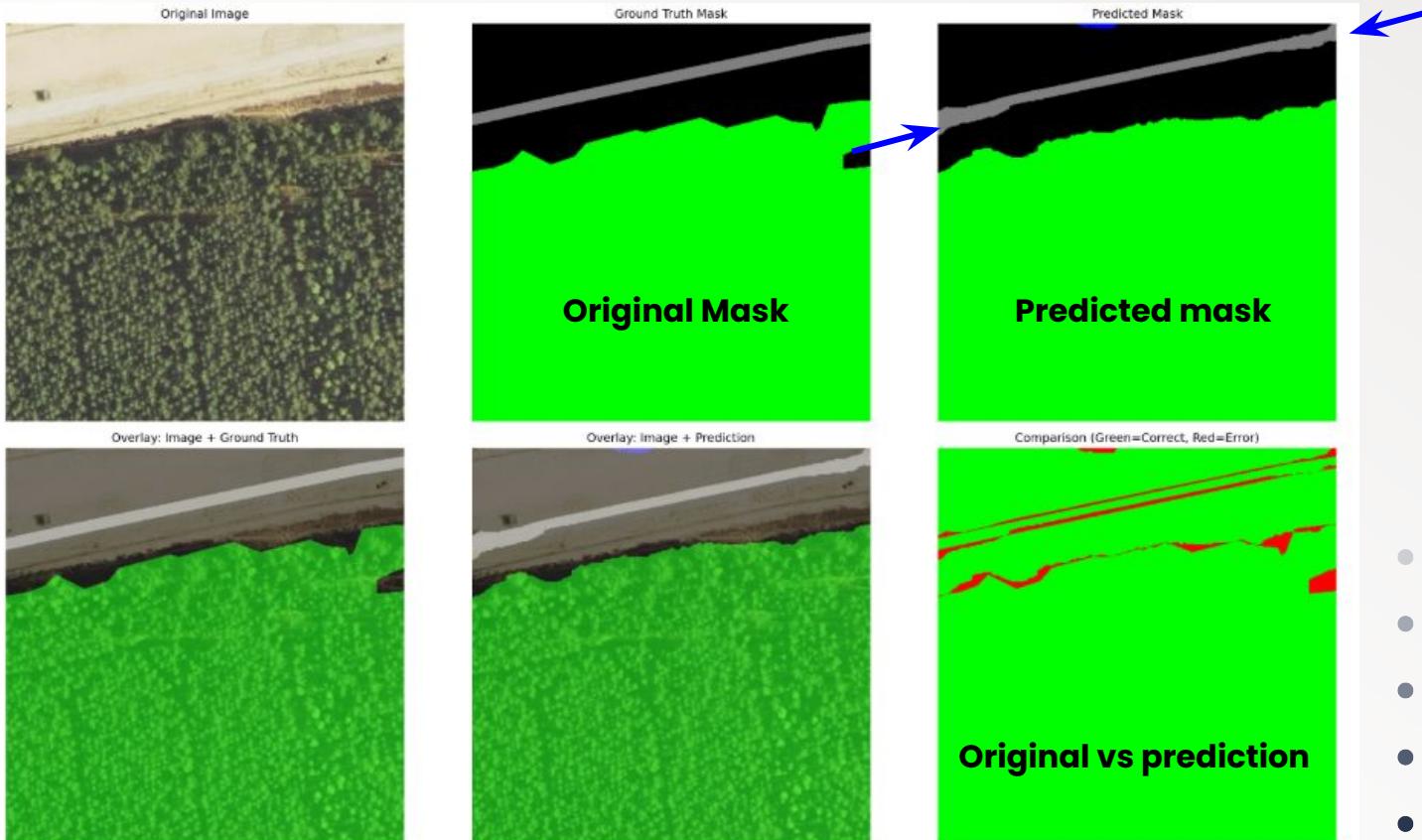
SEMANTIC SEGMENTATION POST-PROCESSING PIPELINE: SATELLITE IMAGERY



Post-Processing Example : *Before*



Post-Processing Example : After



Choice of Evaluation Metrics

Dice Coefficient

- Measures **spatial overlap** between prediction and ground truth
- Sensitive to **false negatives and false positives**, unlike accuracy
- Ideal for **imbalanced classes**

$$\text{Dice} = \frac{2TP}{2TP + FP + FN}$$

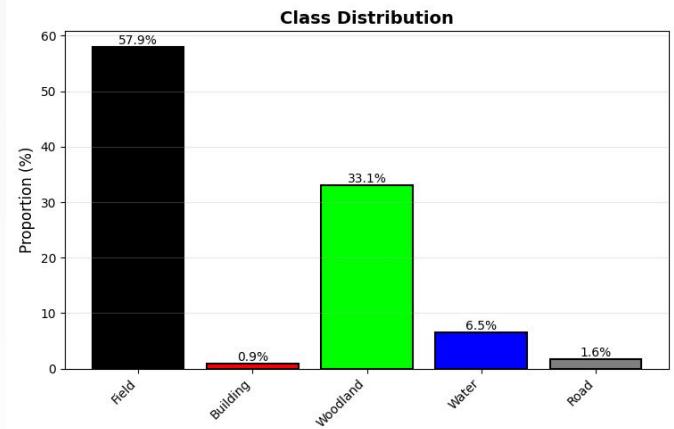
- TP (*True Positives*)
- FP (*False Positives*)
- FN (*False Negatives*)

Why not Accuracy

- Large class imbalance in satellite images
- accuracy can be **misleadingly high**

Class-specific strategy

- **Roads and Buildings**: prioritize **high recall**
- Slight over-prediction (FP) is acceptable

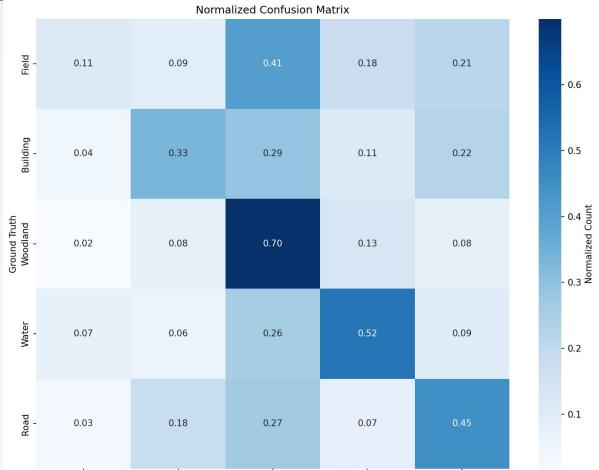
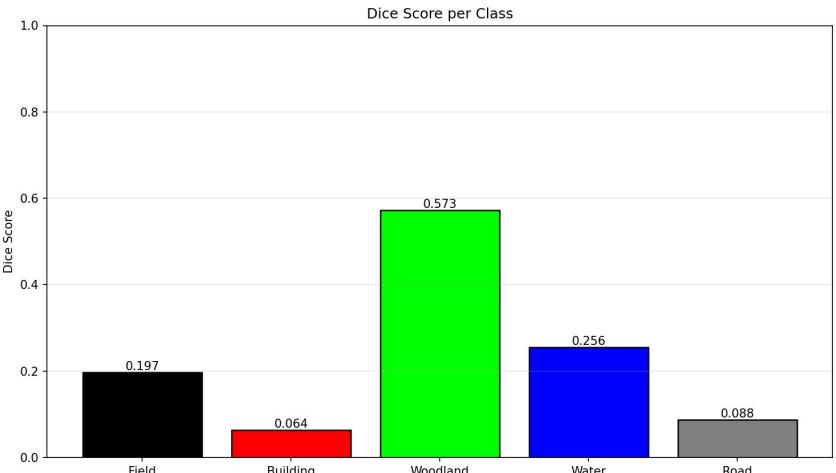


IV. Results and Performances

Results

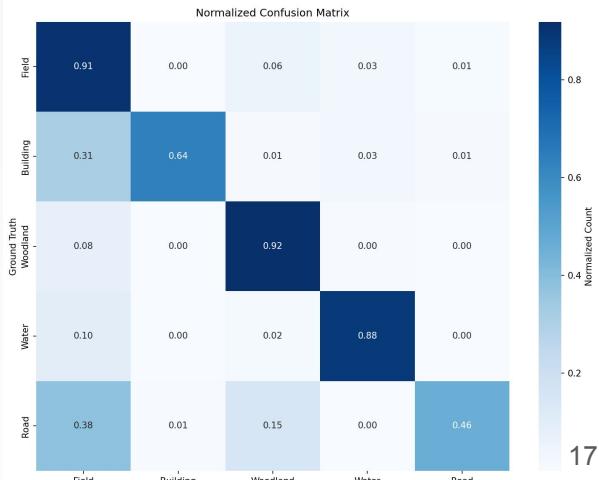
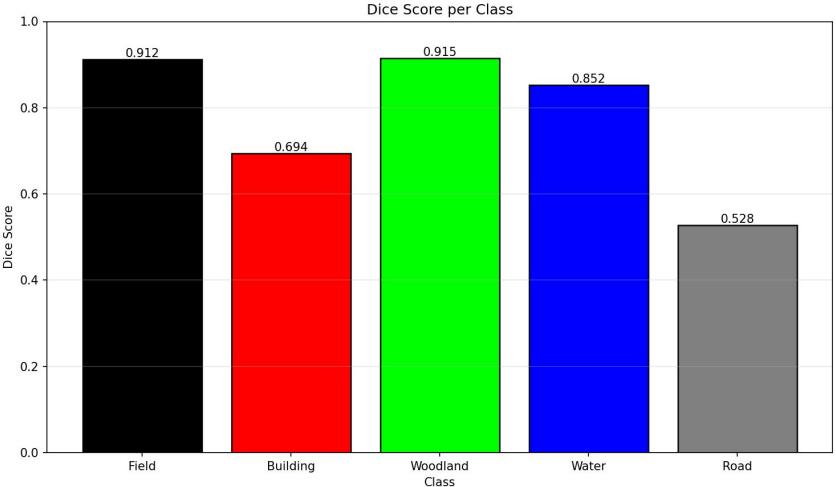
Histogram

Very bad results
for now



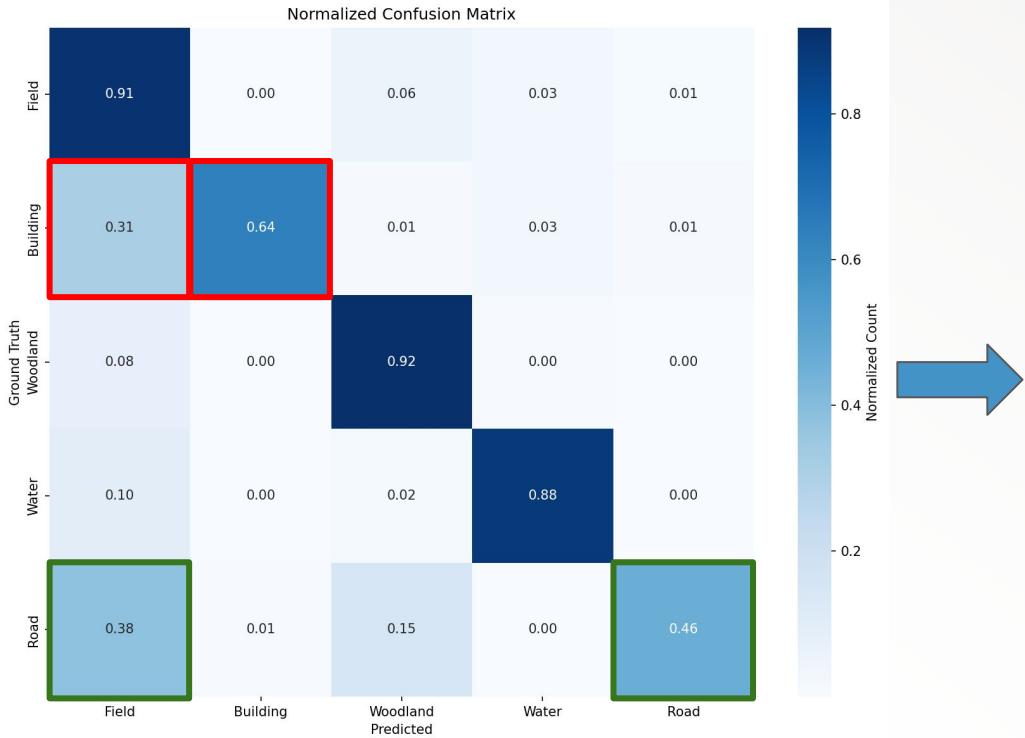
Unet

Good results
Moderate Dice
on Building and Road

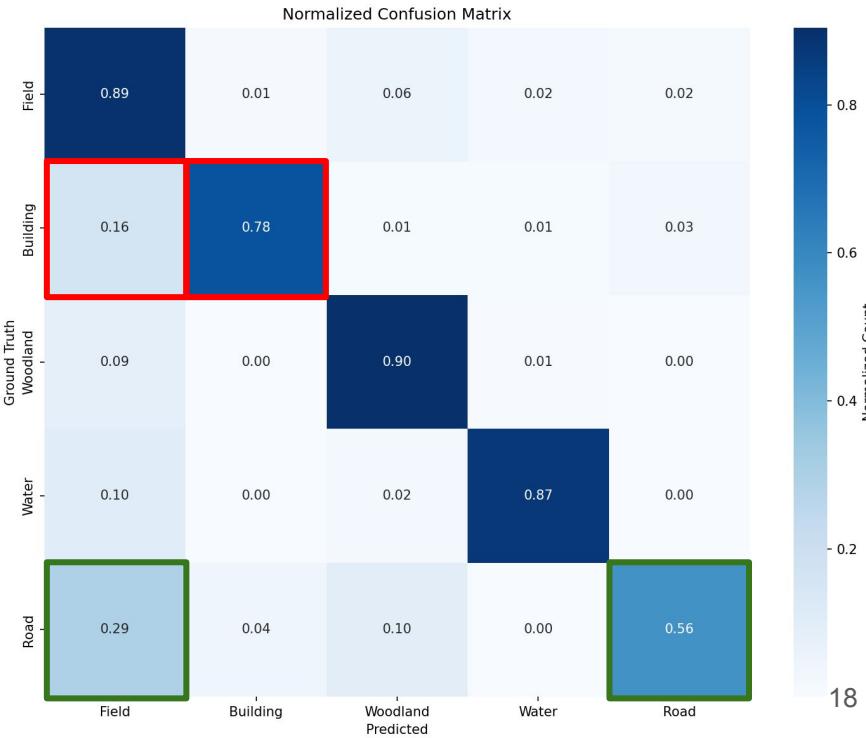


Post-Processing Impact

Before Post-Processing

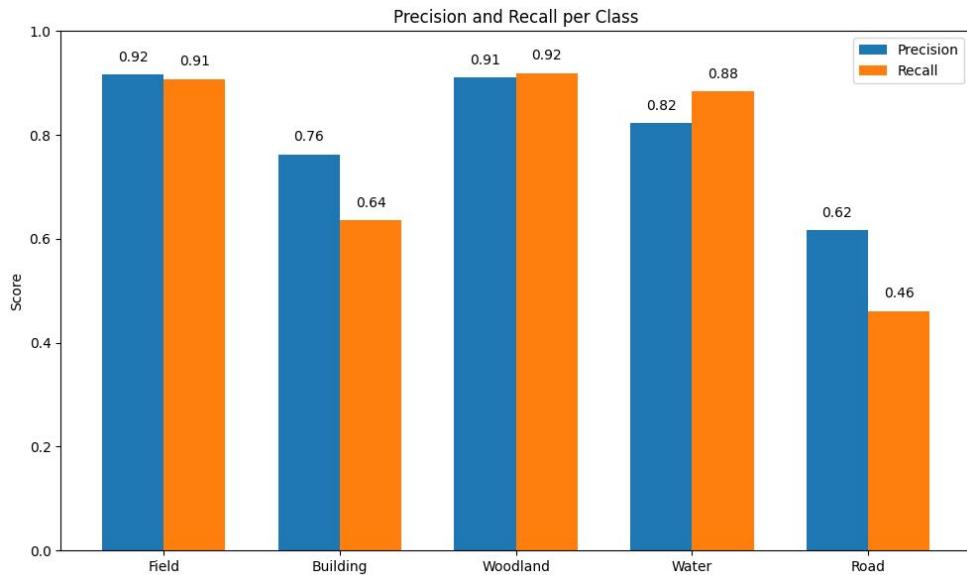


After Post-Processing

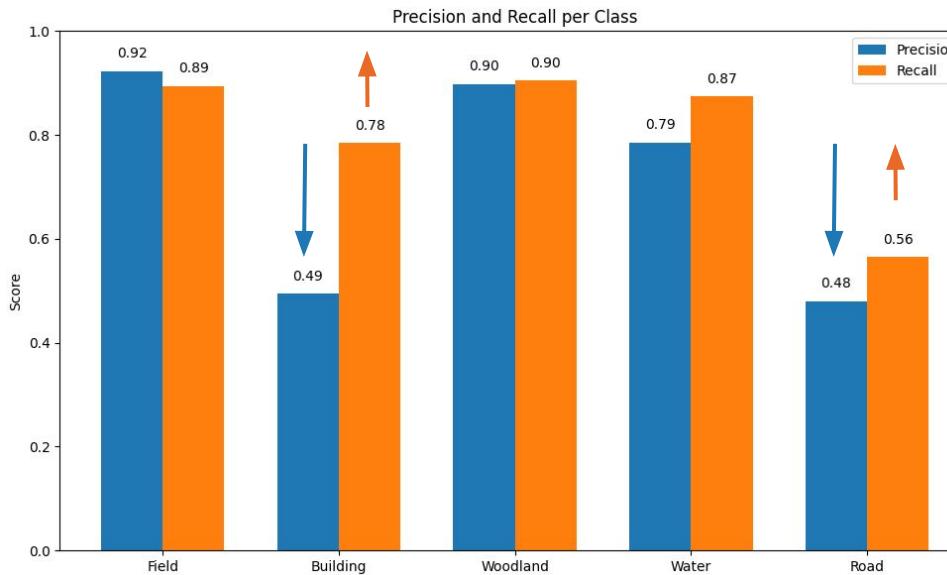


Post-Processing Impact

Before Post-Processing



After Post-Processing



Conclusion : Improvement Perspectives

Learning & Actions Taken

- **Built a pipeline** for feature extraction, preprocessing, training, and evaluation
- **Achieved good U-Net segmentation results**, while handling class imbalance and prioritizing recall for small structures
- Learned the importance of selecting relevant features for effective segmentation

Perspectives / Future Work

- **Improve computation efficiency**, code robustness
- **Explore better histogram-based methods** and additional or more relevant features
- **Improve Post-Processing pipeline** for better performances

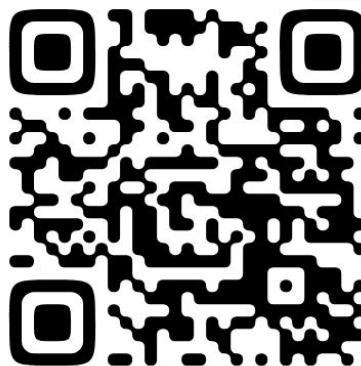


References :

First image: <https://www.mdpi.com/2072-4292/8/4/329>

Dataset Official Link: <https://landcover.ai.linuxpolska.com/>

Dataset Kaggle Link: <https://www.kaggle.com/datasets/aletbm/land-cover-from-aerial-imagery-landcover-ai>



GitHub Repository





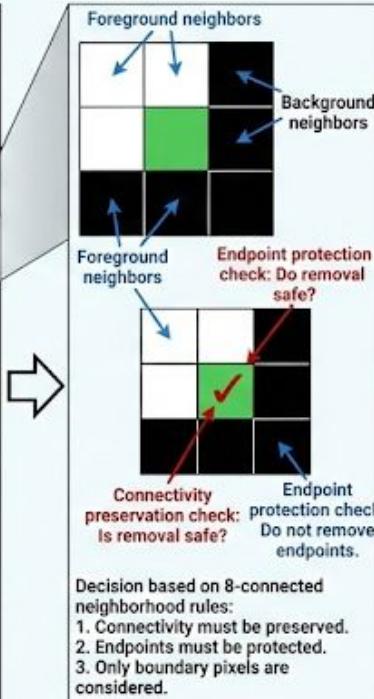
IMAGE SKELETONIZATION PROCESS: STEP-BY-STEP EXPLANATION



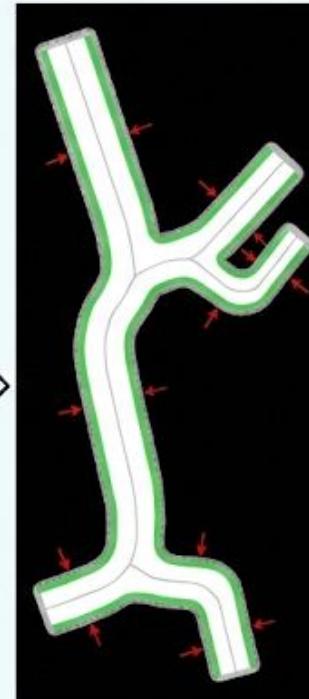
Binary input image



Boundary pixels
(candidates for removal)

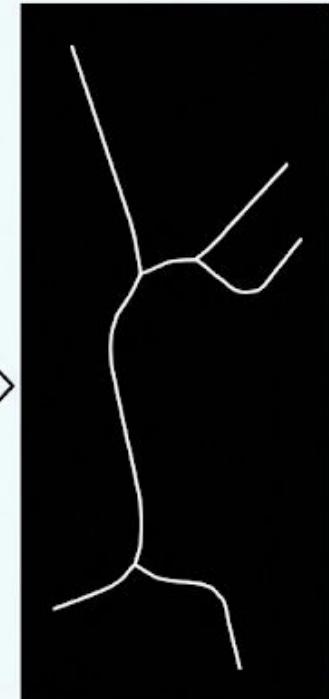


Neighborhood Analysis



Iterative thinning while
preserving topology

Pixels are removed layer by layer from the outside in, ensuring that the shape's topology (number of connected components and holes) remains unchanged.



Final skeleton
(topology preserved)

The resulting structure is a minimal, one-pixel-wide representation that retains the essential shape and connectivity of the original binary object.

