

AXI based NOC

I got frustrated with existing NOC solutions, so why not try my own?

why NOC?

In almost every ASIC, there is region called SOC. System On a Chip. It is a collection of modules that should work together.

Usual ingredients are CPUs, DMAs, Accelerators, Register files, Communication modules, Off-chip memory controllers,

On chip memories Rams, Roms, Flash embedded, Security and more that now i forgot.

To make them into a coherent system, conventional way is to hang them all on a NOC.

Network on a chip.

At Virata, years ago, we created ring based NOC, that didn't have masters and slaves and was passing messages at

pretty high speed between all members. Instead of Masters and Slaves, all members of the system were sitting in a few circles, passing messages around, until it hit the addressee.

(More can be found in my gitHub)

Sweet memories..., but nowadays all ingredients have AXI, AHB or APB interfaces (and couple more weirder ones).

Choices

There used to be 3 vendors + ARM selling NOC creators to You. They come with fancy configuration app.

I say "used to" because they are being swallowed and not sure to exist on the market much longer.

All apps create ugly unreadable RTL code. My guess it is on purpose to make it look sophisticated and

hard to implement Yourself.

There is also open-source (like OpenSoC) but for me it is "תפסת מרובה לא תפסת" syndrom. For non Hebrew readers - it approximately translates to "there is no value in exces".

My rings-inspired NOC is still great, but it is scary to conventional designer and their managers.

This is the reason i thought of AXI NOC from scratch.

Recently, projects i came across in companies i work for, could benefit from simple NOC that doesn't require a dedicated person cooking the (Arteris Sonics netSpeed) for the duration

of the project and beyond. About hardships of these commercial solutions You can read in my older Linky-Dinky post. And anyway, most of them are not that relevant or alive.

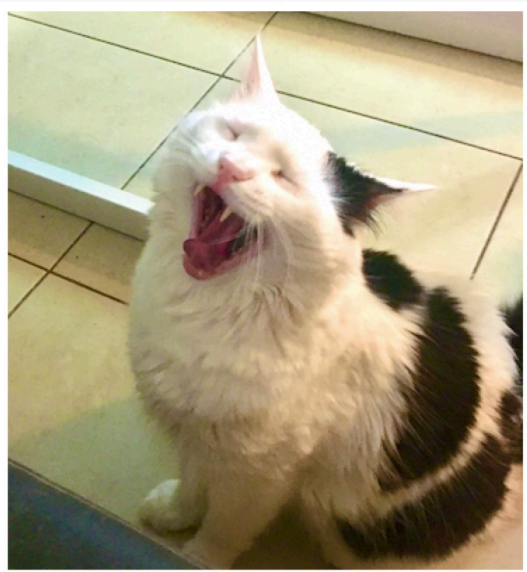
The setup of AXI NOC

Suppose You have few masters and bunch of slaves.

The task is to enable masters to access slaves with max reasonable efficiency.

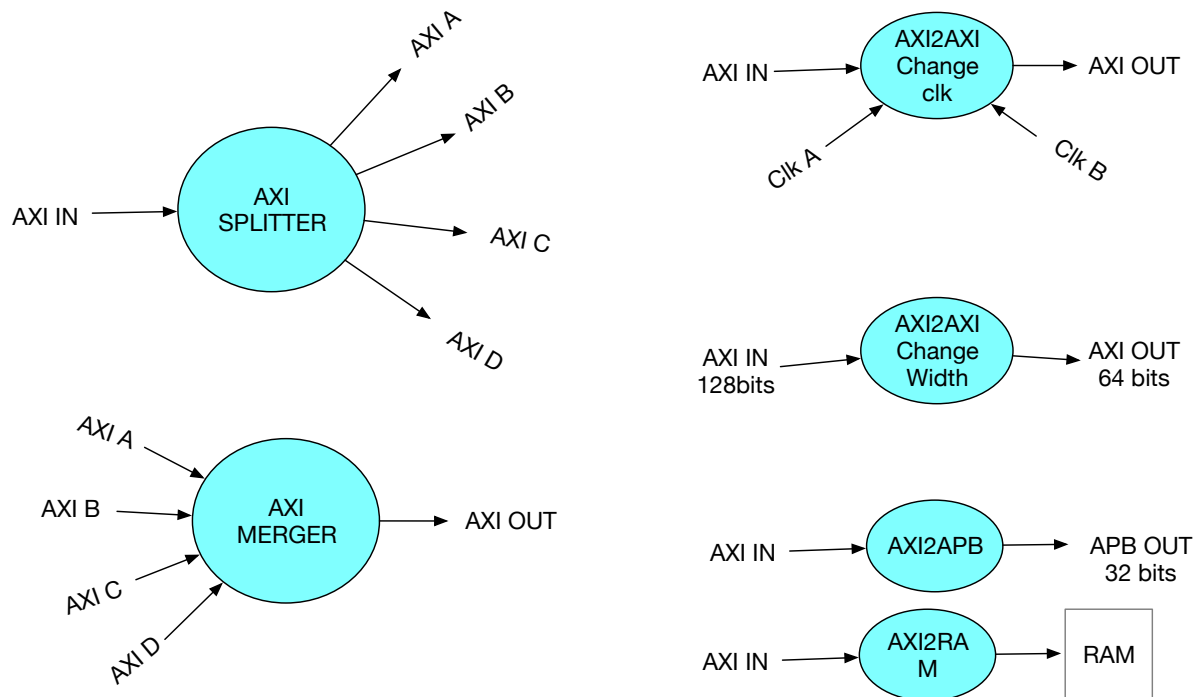
Complications and restrictions:

1. The slaves might have APB or AXI interfaces.
2. We should support several clock regions.
3. For first viable, the AXI is 64 bits data and 32bits address.
4. Not all Masters can access all Slaves. There should be easy way to configure that too.
5. AXI in standard has 4 busses without clear job, that 90% of designs don't know what to do with them: size, prot, cache and qos. In this design, instead, i allocate "extras" bus with configurable width. Do with it whatever.
6. Cut combi paths into manageable timing pieces, layout friendly, latency of clock here and clock there is not a problem.
7. QOS is for losers.
8. Keep it simple, focused. I dont expect it to save the world or make coffee. My cat can do that.



The idea

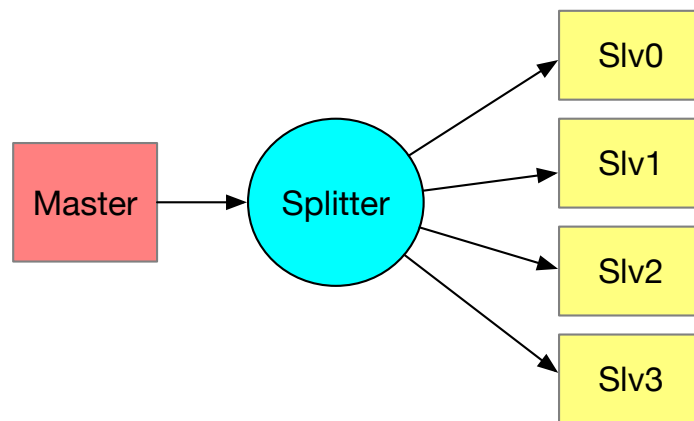
We define and implement a limited set of building blocks. For the first version there are only six.



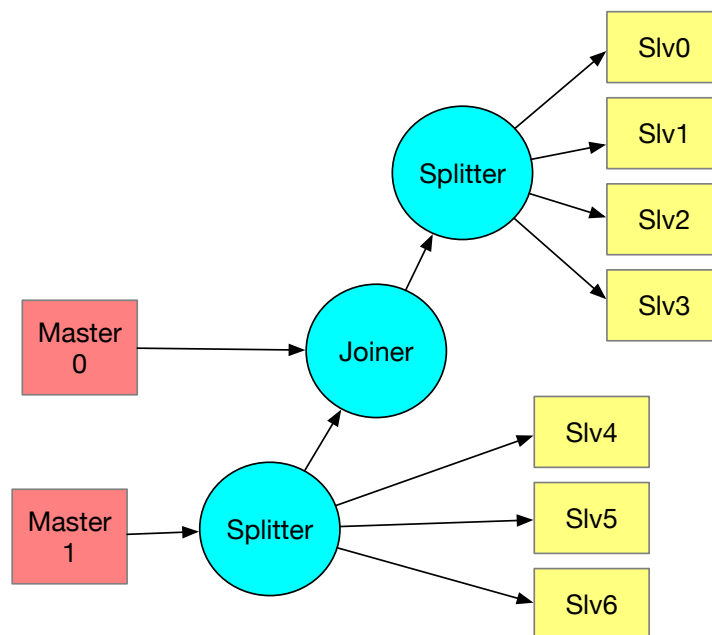
1. splitter module has one incoming AXI port and up to four outgoing. Each incoming burst is routed to appropriate out port.
2. merger module has up to four incoming ports and single outgoing port.
3. clock changer module is inserted between two different clock domains.
4. axi2ram module is demo module to connect ram to this noc.
5. axi2apb module is translation to apb slaves.
6. (planned) change AXI width module. e.g. from 128 to 64 and back. Keep in mind, that AXI is two way street. Modules have to keep tabs on what going through the in order to route response correctly back. All nodule introduce a clock delay between ports.
7. (planned) SERDES. Optimizing serializer of the traffix. Full AXI is handful bunch of wires. The traffix can be made thinner busses.

Connecting the dots

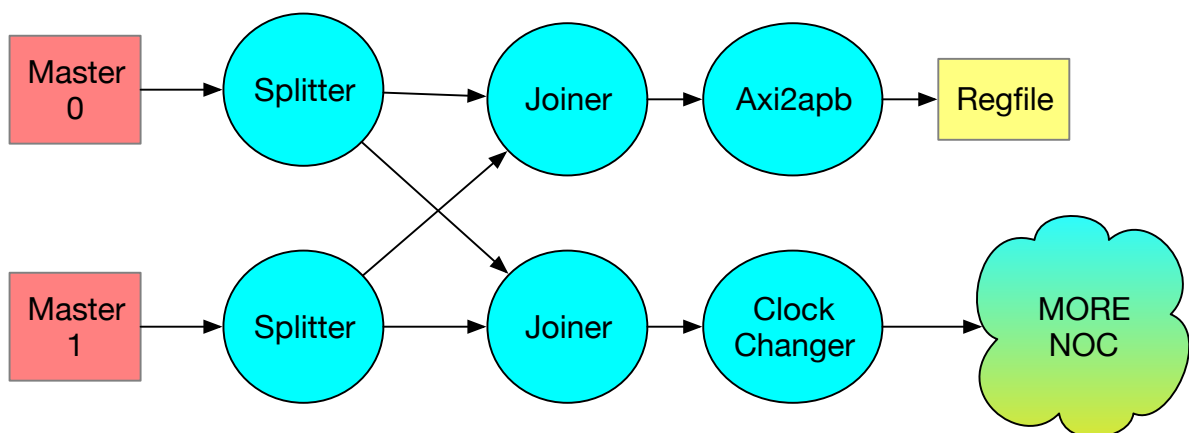
Here is an example of simplest master and 4 slaves



Here is example of non-symmetric network.



Example of APB and ClockChanger.



Let's build the dot

I like graphviz and use "dot" language to make documentation and in this case also to describe a design.

The advantage is a simple input language and instant visualization. No special tricks.

No tedious graphic application.

Modest python script reads the "dot" source and creates a real RTL module.

It also creates "verilog instance" text to use in chip integration.

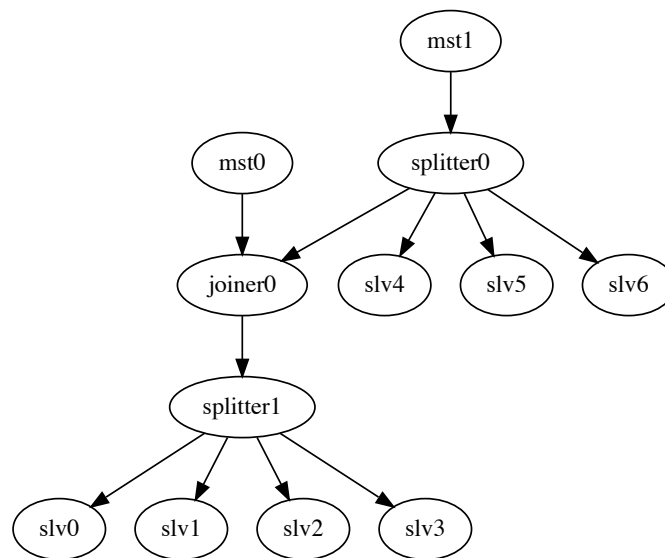
And stand alone python test-bench (planned).

The RTL module of NOC is a straightforward mapping of the source file, keeping the names and thus facilitating easy debug and verification.

Here an example of dot code (source of the non-symmetric example)

```
digraph example1 {  
  
    mst0 -> joiner0 ;  
    mst1 -> splitter0 ;  
    splitter0 -> joiner0 ;  
    splitter0 -> slv4;  
    splitter0 -> slv5;  
    splitter0 -> slv6;  
    joiner0 -> splitter1;  
    splitter1 -> slv0;  
    splitter1 -> slv1;  
    splitter1 -> slv2;  
    splitter1 -> slv3;  
}
```

Here is the graph representation by "dot" compiler:



The RTL created is too long for document, Examples (runnable!) can be found in my gitHub vlsistuff.

Addressing. Important and tricky.

Usually NOC route traffic based on transaction address.

The steering of the writes and reads is based on pre compiled address tables.

We do the opposite.

Merger modules don't have any address sensitivity. Only splitter modules must decide which output port to use.

The simple solution: take two msb bits of address and use them as index to decide where to send the transaction. On selected downstream port the address is shifted two bits left. So the next decision point have fresh two bits.

The software in masters, should be aware of this shifting, and configuration script, adds "shift value" for each slave. This number is used by connection to slave to shift the address back. If the slave is 3 layers from master, it will receive address shifted six butts right.

CPU software gets a table of addresses for each slave, adapted for each master CPU. In all NOCs it is pretty much the same.

If this addressing will be too confusing, we may switch back to more conservative table based traffic steering.

What is the status

in my github, clone: <https://github.com/greenblat/vlsistuff.git>

there is directory called axi_noc. All is (will be shortly) there. Including building block RTLs and few demos.

What's next?

- One of the advantages and key features of ring based (no masters nor slaves, but all modules can listen and talk) was its totality - meaning ALL interaction of any module with SOC was through the NOC. No out of band and no dedicated interrupt wires. All messaging between servers and clients was done by NOC.
In my AXI NOC we may utilize the READ channel of AXI to convey messages from slaves back to masters. Thus replacing ad-hoc interrupt contraptions.
- Another painful aspect is error reporting. In AXI, errors (bresp and rresp) come back to a hapless master. Usually there is no idea what to do with them. In best case, it just raises interrupt.
In RINGS, All errors arrived to a predefined master, called the ANCHOR. There was one place to deal with system errors. The error messages arrived at fifo attached to the ANCHOR and it could deal with them at its own pace. Similar idea is good to implement here.
- Adding SER-DES option. Serialize AXI bus to any requested wire width and reconstruct it on the other end..
- Adding Safety features:
 1. Policeman. Keeping traffic legal.
 2. ECC options. Not trivial
 3. Encryption / Decryption on critical links

What's missing

1. Currently, Fixed priority in service. Will be made round robin or something.
2. Some modules are in development stage: clock and width changers.
3. Not enough verification. Ongoing. But overall it is operational.
4. Not going to add AHB interfaces. You probably have them already. If not, good for You.
5. Not going to build it in VHDL. Enough weapons as it is.