

Task 1:

Dijkstra's Shortest Path Finder

Code Dijkstra's algorithm to find the shortest path from a start node to every other node in a weighted graph with positive weights.

ANS:

```
package com.Day15;
import java.util.*;
public class Dijkstra {
    // Class to represent a graph edge
    static class Edge {
        int target;
        int weight;
        Edge(int target, int weight) {
            this.target = target;
            this.weight = weight;
        }
    }
    // Class to represent a node in the priority queue
    static class Node implements Comparable<Node> {
        int vertex;
        int distance;
        Node(int vertex, int distance) {
            this.vertex = vertex;
            this.distance = distance;
        }
        @Override
        public int compareTo(Node other) {
            return Integer.compare(this.distance, other.distance);
        }
    }
    // Method to find the shortest path from a start node to all other nodes
    public static int[] dijkstra(List<List<Edge>> graph, int start) {
        int numVertices = graph.size();
        int[] distances = new int[numVertices];
        boolean[] visited = new boolean[numVertices];
        PriorityQueue<Node> pq = new PriorityQueue<>();
        // Initialize distances array with infinity
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Arrays.fill(distances, Integer.MAX_VALUE);
distances[start] = 0;
// Add the start node to the priority queue
pq.add(new Node(start, 0));
while (!pq.isEmpty()) {
    // Extract the node with the smallest distance
    Node currentNode = pq.poll();
    int currentVertex = currentNode.vertex;
    // Skip if the node is already visited
    if (visited[currentVertex]) continue;
    visited[currentVertex] = true;
    // Process all adjacent nodes
    for (Edge edge : graph.get(currentVertex)) {
        int neighbor = edge.target;
        int newDist = distances[currentVertex] + edge.weight;
        // If a shorter path to the neighbor is found
        if (newDist < distances[neighbor]) {
            distances[neighbor] = newDist;
            pq.add(new Node(neighbor, newDist));
        }
    }
}
return distances;
}

public static void main(String[] args) {
    // Example graph represented as an adjacency list
    int numVertices = 5;
    List<List<Edge>> graph = new ArrayList<>();
    // Initialize graph with empty lists
    for (int i = 0; i < numVertices; i++) {
        graph.add(new ArrayList<>());
    }
    // Add edges to the graph (example graph)
    graph.get(0).add(new Edge(1, 10));
    graph.get(0).add(new Edge(4, 5));
    graph.get(1).add(new Edge(2, 1));
    graph.get(1).add(new Edge(4, 2));
}

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graph.get(2).add(new Edge(3, 4));
graph.get(3).add(new Edge(0, 7));
graph.get(3).add(new Edge(2, 6));
graph.get(4).add(new Edge(1, 3));
graph.get(4).add(new Edge(2, 9));
graph.get(4).add(new Edge(3, 2));
// Run Dijkstra's algorithm from start node 0
int startNode = 0;
int[] distances = dijkstra(graph, startNode);
// Print the shortest distances from the start node to all other
nodes
System.out.println("Shortest distances from node " + startNode
+ ":");
for (int i = 0; i < distances.length; i++) {
    System.out.println("To node " + i + " : " + distances[i]);
}
}
}

```

OUTPUT:

Shortest distances from node 0:

To node 0 : 0

To node 1 : 8

To node 2 : 9

To node 3 : 7

To node 4 : 5