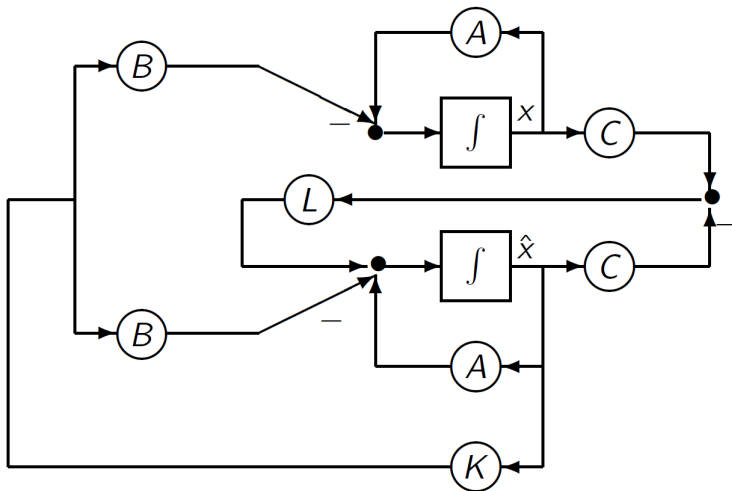


Observer-Based Control — 2



Notice that $u(t) = -K\hat{x}(t)$