



SUMMER INTERNSHIP Embedded C

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TASK 12

Hands-on Activity-1

- ☐ Write a program to count no. of bits which are set in given binary pattern
- ☐ Write a program to set 5th and 12th bits in a 16-bit unsigned integer
- ☐ Write a program to clear 6th and 19th bits in a 32-bit unsigned integer
- ☐ Write a program to flip even positioned bits in a 16-bit unsigned integer
- ☐ An IP Address will be in the form of "a.b.c.d" format, where a, b, c, d will be in the range of 0-255. Given a, b, c, d values (or string format) pack them into 32-bit unsigned integer.
- ☐ Given an unsigned 32-bit integer holding packed IPv4 address, convert it into "a.b.c.d" format.
- ☐ Convert MAC address into 48-bit binary pattern
- ☐ Convert 48-bit binary pattern as MAC address
- ☐ Arduino examples using Bare metal code (Register level Bit Manipulations)
 - ➔ Blinky
 - ➔ LED controlling using PushButton

Q1)

```
#include <stdio.h> int
countSetBits(int n) {
int count = 0; while
(n) { count += n
& 1; n >>= 1;
}
return count;
}
int main() { int num; prin ("Enter an integer: ");
scanf("%d", &num); int setBits = countSetBits(num);
prin ("Number of set bits in %d is %d\n", num, setBits);
return 0;
}
```

Q2)

```
#include <stdio.h>
int main()
{
unsigned short int value = 0; unsigned short int mask = (1 << 4) |
(1 << 11); value |= mask; prin ("The value after setting the 5th and
12th bits is: %u\n", value);
return 0;
}
```

Q3)

```
#include <stdio.h> unsigned int
clearBits(unsigned int num) { unsigned int
mask = ~(1 << 5) | (1 << 18)); return
num & mask;
```

```

}

int main() {    unsigned int num;    prin ("Enter a 32-bit unsigned
integer: ");    scanf("%u", &num);    unsigned int result =
clearBits(num);    prin ("Result after clearing the 6th and 19th bits:
%u\n", result);

    return 0;
}

```

Q4)

```

#include <stdio.h> unsigned short
flipEvenBits(unsigned short num) {    unsigned
short mask = 0x5555;    return num ^ mask;
}

```

```

int main() {    unsigned short num;    prin ("Enter a 16-bit unsigned
integer: ");    scanf("%hu", &num);    unsigned short result =
flipEvenBits(num);    prin ("Result after flipping the even-positioned
bits: %hu\n", result);

    return 0;
}

```

Q5)

```

#include <stdio.h> unsigned int packIP(unsigned char a, unsigned char b, unsigned char
c, unsigned char d) {    return (a << 24) | (b << 16) | (c << 8) | d;

}

```

```

int main() {    unsigned char a = 192;
unsigned char b = 168;    unsigned char c = 1;
unsigned char d = 100;    unsigned int packedIP

```

```
= packIP(a, b, c, d);    prin ("Packed IP address:
0x%X\n", packedIP);
```

```
    return 0;
}
```

Q6)

```
#include <stdio.h> int main() {    unsigned int packed_ip =
0xC0A80164;    unsigned char a = (packed_ip >> 24) & 0xFF;
unsigned char b = (packed_ip >> 16) & 0xFF;    unsigned char c
= (packed_ip >> 8) & 0xFF;    unsigned char d = packed_ip &
0xFF;        prin ("The unpacked IP address is:
%u.%u.%u.%u\n", a, b, c, d);    return 0;
}
```

Q7)

```
#include <stdio.h> #include <stdlib.h> unsigned long long
convertMACAddress(const char *mac) {
    unsigned int bytes[6];

    if (sscanf(mac, "%x:%x:%x:%x:%x:%x", &bytes[0], &bytes[1], &bytes[2], &bytes[3], &bytes[4],
&bytes[5]) != 6) {        fprintf(stderr, "Invalid MAC
address format.\n");        exit(EXIT_FAILURE);
    }

    unsigned long long macBinary = 0;
    for (int i = 0; i < 6; ++i) {
        macBinary = (macBinary << 8) | (bytes[i] & 0xFF);
    }

    return macBinary;
}

int main() {    char macString[18];    prin ("Enter MAC address
in the format XX:XX:XX:XX:XX:XX: ");    if (scanf("%17s",
```

```

macString) != 1) {    fprin (stderr, "Failed to read MAC
address.\n");    return EXIT_FAILURE;
}

    unsigned long long macBinary = convertMACAddress(macString);
prin ("MAC address in 48-bit binary pa ern: %012llx\n", macBinary);

    return 0;
}

```

Q8)

```

#include <stdio.h> #include <stdlib.h>

void binaryToMac(const char* binary)
{
    unsigned int bytes[6] = {0};    for (int i = 0; i <
48; ++i) {    bytes[i / 8] = (bytes[i / 8] << 1) |
(binary[i] - '0');    }

    prin ("MAC Address: %02X:%02X:%02X:%02X:%02X:%02X\n",
        bytes[0], bytes[1], bytes[2], bytes[3], bytes[4], bytes[5]);
}

int main() {
    const char* binary_pa ern = "10101010101110111100110011011110111111111111";
    binaryToMac(binary_pa ern);

    return 0;
}

```

Task 14

1)bare metal blinky using arduino1

```
#define F_CPU 16000000UL
```

```

#include <avr/io.h>

#include <util/delay.h>

int main(void)
{
    // Set pin 7 (PD7) as an output
    DDRD |= (1 << PD7);

    while (1)
    {
        PORTD |= (1 << PD7);

        _delay_ms(1000);

        PORTD &= ~(1 << PD7);

        _delay_ms(1000);
    }

    return 0;
}

```

2)bare metal push button

```

#define F_CPU 16000000UL

#include <avr/io.h>

#include <util/delay.h>

const uint8_t buttonPin = PD2;

const uint8_t ledPin = PB5;

uint8_t buttonState = 0; void
setup() {

    DDRD &= ~(1 << buttonPin);

    PORTD |= (1 << buttonPin);

    DDRB |= (1 << ledPin);

}

int main(void) {

```

```

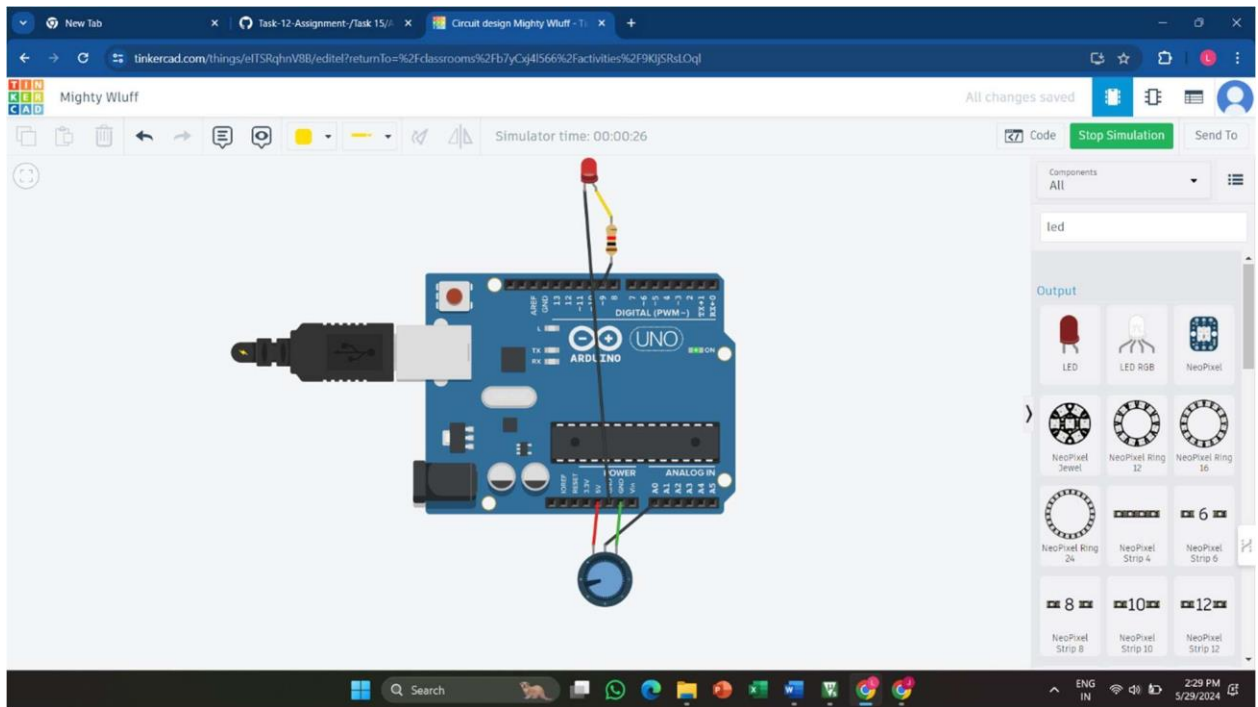
    setup();    while (1) {        bu onState =
PIND & (1 << bu onPin);

    if (bu onState) {
        PORTB |= (1 << ledPin);
    } else {
        PORTB &= ~(1 << ledPin);
    }
    _delay_ms(10);
}
return 0;
}

```

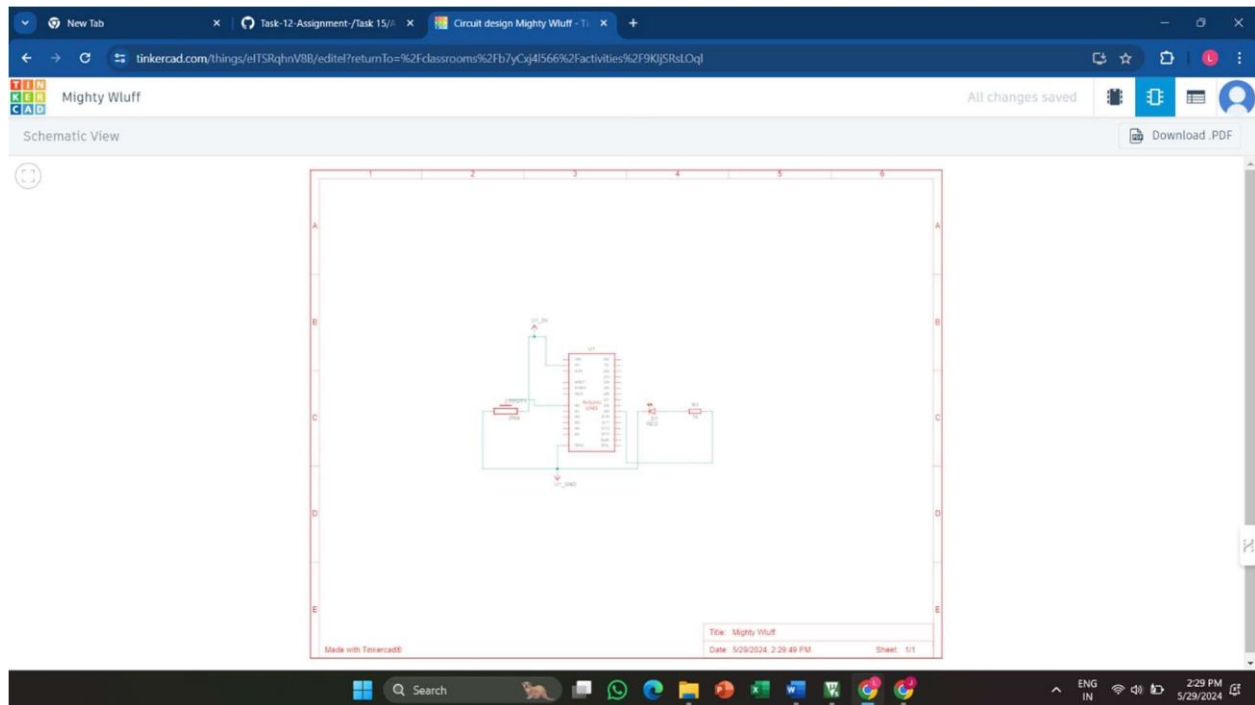
Task 15

Analog Read (Poten ometer)



Component List

Name	Quantity	Component
U1	1	Arduino Uno R3
Rpot1	1	250 kΩ Potentiometer
R1	1	1 kΩ Resistor
D1	1	Red LED



```
// Constants for pin assignments const int potPin = A0; // Pin where
the poten ometer is connected const int ledPin = 9; // Pin where
the LED is connected
```

```
// Variable to store the poten ometer value int
potValue = 0;
```

```
void setup() {
    // Ini alize the LED pin as an output
    pinMode(ledPin, OUTPUT);
}
```

```
void loop() {
    // Read the value from the poten ometer potValue
    = analogRead(potPin);
```

```
// Map the potentiometer value to the PWM range (0-255)  int  
ledValue = map(potValue, 0, 1023, 0, 255);
```

```
// Set the brightness of the LED  
analogWrite(ledPin, ledValue);
```

```
// Small delay to smooth out the reading  
delay(10);  
}
```

Analout Output(fading)

```
const int ledPin = 9;    // Pin where the LED is connected
```

```
void setup() {  
    // Initialize the LED pin as an output  
    pinMode(ledPin, OUTPUT);  
}
```

```
void loop() { // Fade in from 0 to 100^6  for (int brightness  
= 0; brightness <= 100^6; brightness++) {  
    analogWrite(ledPin, brightness); // Set the brightness  
    delay(10); // Wait for 10 milliseconds  
}
```

```
// Fade out from 100^6 to 0  for (int brightness = 100^6;  
brightness >= 0; brightness--) {    analogWrite(ledPin,  
brightness); // Set the brightness    delay(10); // Wait for  
10 milliseconds  
}
```

}

New Tab

Task-12-Assignment / Task 15/


Circuit design Mighty Wluff - 1

tinkercad.com/things/eITSRqhnV8B-mighty-wluff/edit

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Mighty Wluff


All changes saved

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Component List

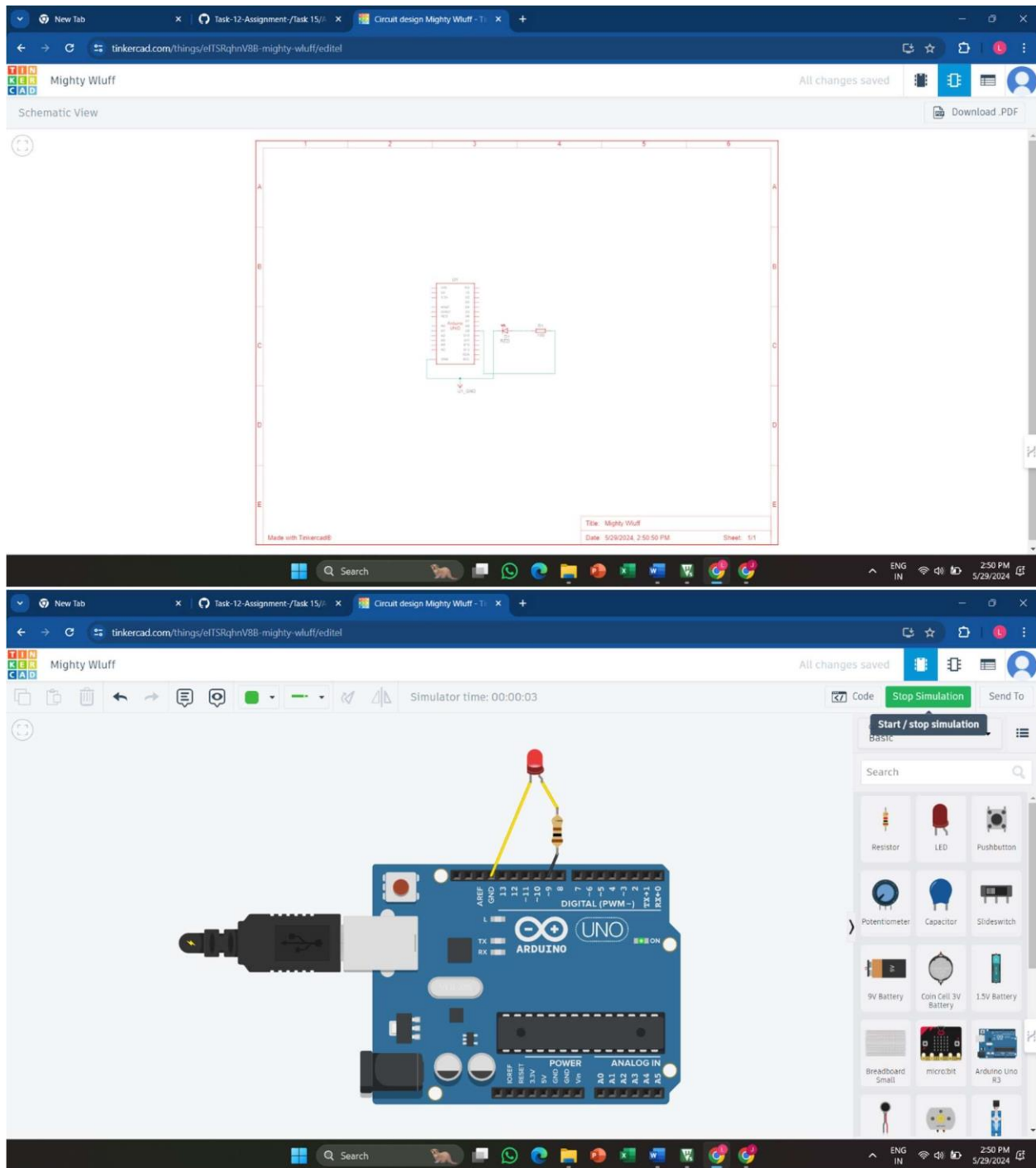
Name	Quantity	Component
R1	1	100 Ω Resistor
D1	1	Red LED
U1	1	Arduino Uno R3

Search



ENG IN

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Digital Input using Interrupt

`const int bu onPin = 2; // Pin where the push bu on is connected vola le`

`bool bu onPressed = false; // Flag to indicate bu on press void setup() {`

`pinMode(bu onPin, INPUT); // Set the bu on pin as input`

```
attachInterrupt(digitalPinToInterrupt(bu onPin), bu onPressISR, RISING); // Attach interrupt on rising edge
```

```
Serial.begin(9600); // Initialize serial communication  
}
```

```
void loop() { if (bu  
onPressed) {  
    Serial.println("Bu on Pressed!"); // Print message when bu on is pressed  
    bu onPressed = false; // Reset the flag  
}  
}
```

```
void bu onPressISR() { bu onPressed = true; // Set the flag to  
indicate bu on press  
}
```

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Buttons: All changes saved, Download CSV

Component List

Name	Quantity	Component
U1	1	Arduino Uno R3
R1	1	10 kΩ Resistor
S1	1	Pushbutton

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