Stanford CS224W: How Expressive are Graph Neural Networks?

CS224W: Machine Learning with Graphs Jure Leskovec, Stanford University http://cs224w.stanford.edu



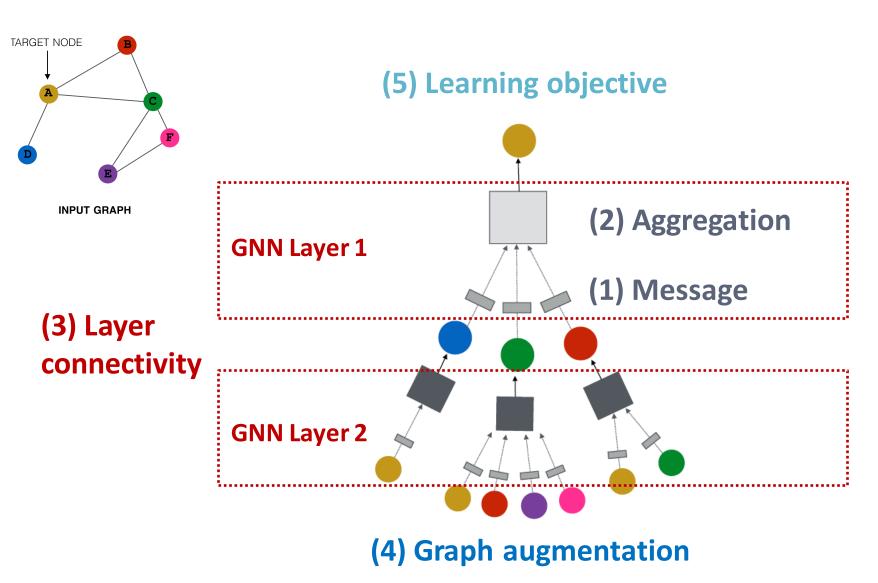
ANNOUNCEMENTS

- Homework 1 due on Thursday (2/2)
- Based on course feedback, we will hold in-person OHs every week on Wednesday 9-11 AM PT.
 Location will be updated on the OH calendar.

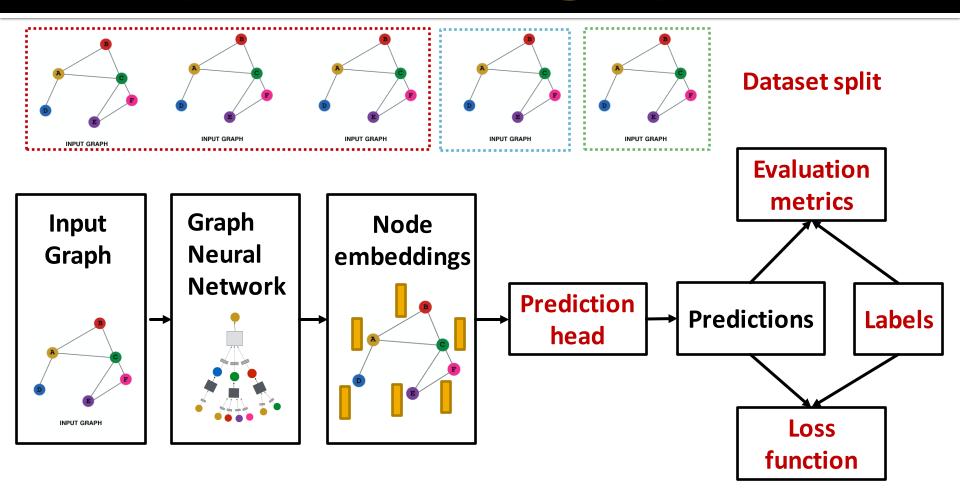
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Recap: A General GNN Framework



Recap: GNN Training Pipeline



Implementation resources:

PyG provides core modules for this pipeline

GraphGym further implements the full pipeline to facilitate GNN design

Theory of GNNs

How powerful are GNNs?

- Many GNN models have been proposed (e.g., GCN, GAT, GraphSAGE, design space).
- What is the expressive power (ability to distinguish different graph structures) of these GNN models?
- How to design a maximally expressive GNN model?

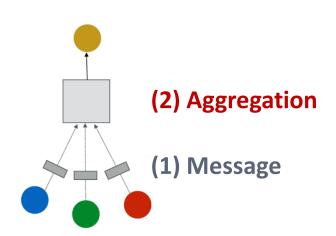
Background: A Single GNN Layer

We focus on message passing GNNs:

• (1) Message: each node computes a message $\mathbf{m}_{u}^{(l)} = \mathrm{MSG}^{(l)}\left(\mathbf{h}_{u}^{(l-1)}\right)$, $u \in \{N(v) \cup v\}$

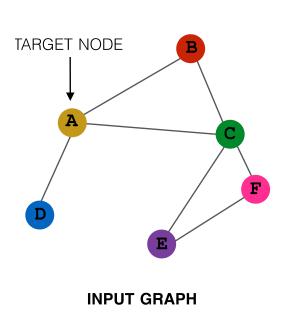
(2) Aggregation: aggregate messages from neighbors

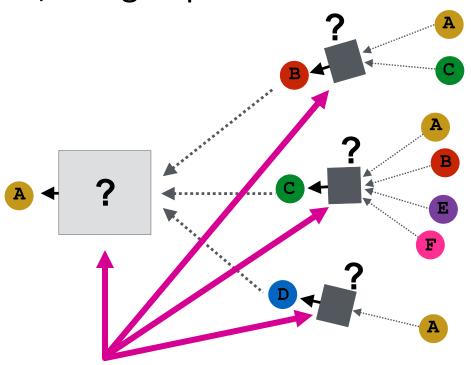
$$\mathbf{h}_{v}^{(l)} = \mathrm{AGG}^{(l)}\left(\left\{\mathbf{m}_{u}^{(l)}, u \in N(v)\right\}, \mathbf{m}_{v}^{(l)}\right)$$



Background: Many GNN Models

- Many GNN models have been proposed:
 - GCN, GraphSAGE, GAT, Design Space etc.

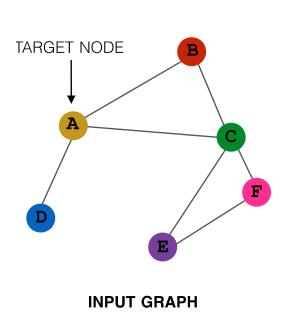


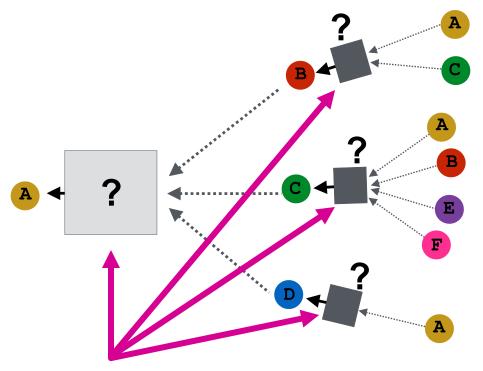


Different GNN models use different neural networks in the box

GNN Model Example (1)

GCN (mean-pool) [Kipf and Welling ICLR 2017]

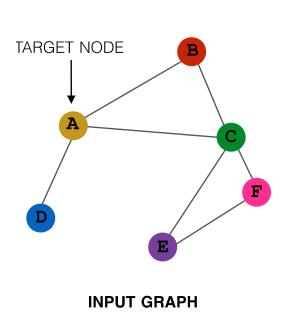


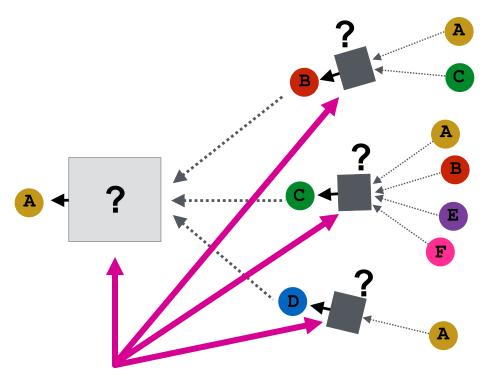


Element-wise mean pooling + Linear + ReLU non-linearity

GNN Model Example (2)

GraphSAGE (max-pool) [Hamilton et al. NeurIPS 2017]

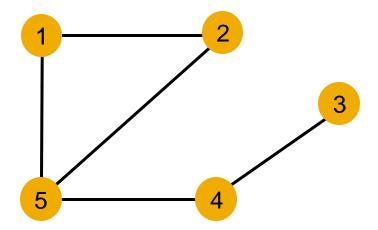




MLP + element-wise max-pooling

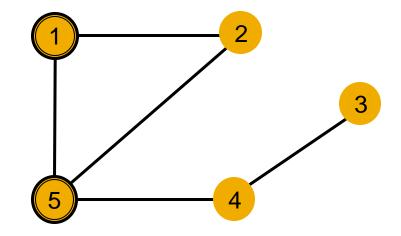
Note: Node Colors

- We use node same/different colors to represent nodes with same/different features.
 - For example, the graph below assumes all the nodes share the same feature.

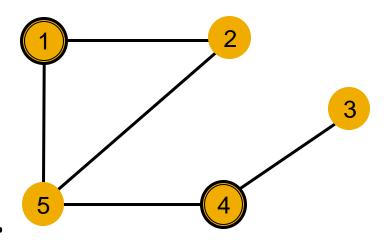


Key question: How well can a GNN distinguish different graph structures?

- We specifically consider local neighborhood structures around each node in a graph.
 - Example: Nodes 1 and 5 have different neighborhood structures because they have different node degrees.

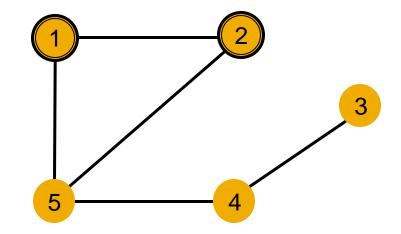


- We specifically consider local neighborhood structures around each node in a graph.
 - Example: Nodes 1 and 4 both have the same node degree of 2. However, they still have different neighborhood structures because their neighbors have different node degrees.



Node 1 has neighbors of degrees 2 and 3. Node 4 has neighbors of degrees 1 and 3.

- We specifically consider local neighborhood structures around each node in a graph.
 - Example: Nodes 1 and 2 have the **same** neighborhood structure because they are symmetric within the graph.



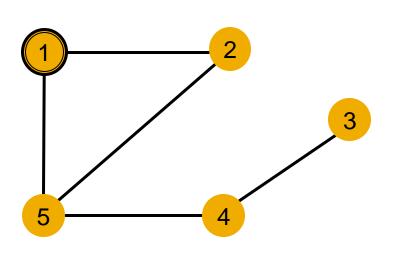
Node 1 has neighbors of degrees 2 and 3. Node 2 has neighbors of degrees 2 and 3. And even if we go a step deeper to 2nd hop neighbors, both nodes have the same degrees (Node 4 of degree 2)

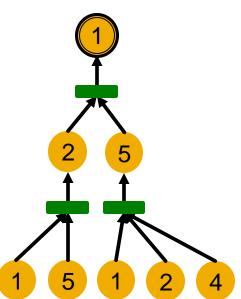
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- Key question: Can GNN node embeddings distinguish different node's local neighborhood structures?
 - If so, when? If not, when will a GNN fail?
- Next: We need to understand how a GNN captures local neighborhood structures.
 - Key concept: Computational graph

Computational Graph (1)

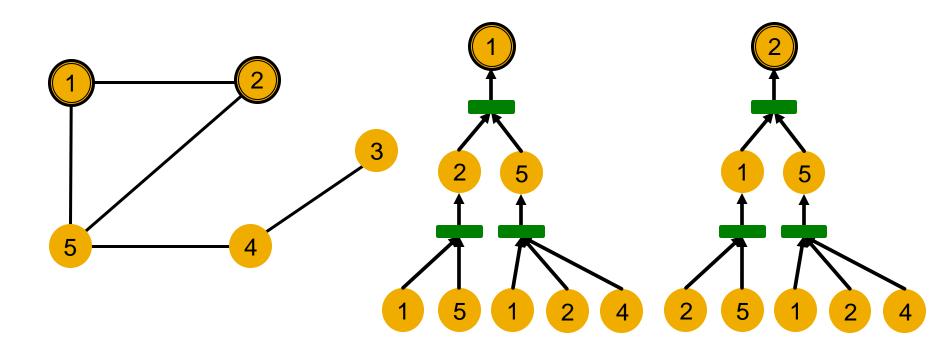
- In each layer, a GNN aggregates neighboring node embeddings.
- A GNN generates node embeddings through a computational graph defined by the neighborhood.
 - Ex: Node 1's computational graph (2-layer GNN)





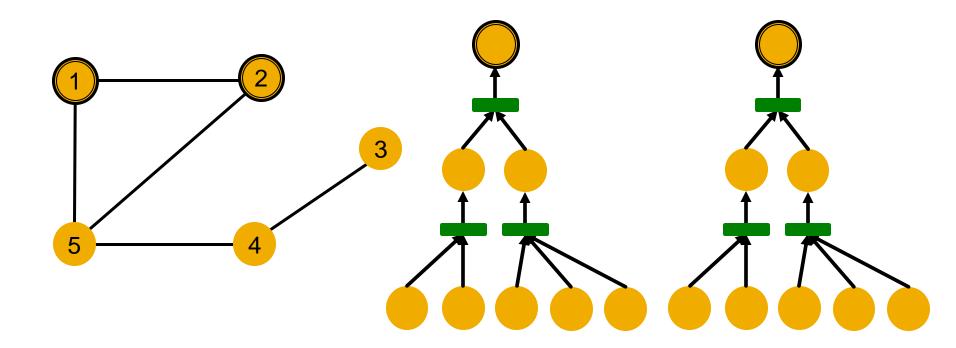
Computational Graph (2)

Ex: Nodes 1 and 2's computational graphs.



Computational Graph (3)

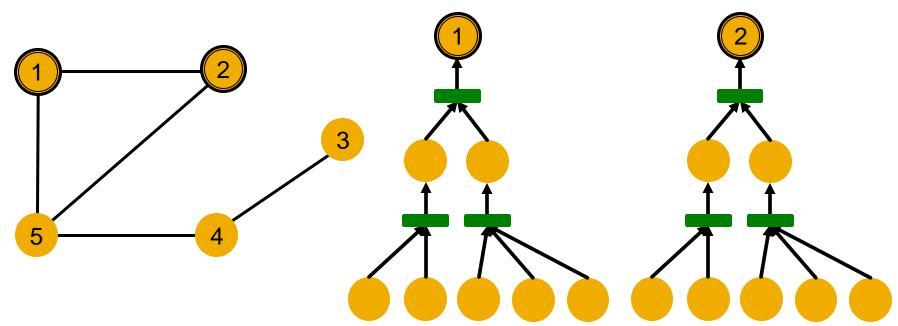
- Ex: Nodes 1 and 2's computational graphs.
- But GNN only sees node features (not IDs):



Computational Graph (4)

- A GNN will generate the same embedding for nodes 1 and 2 because:
 - Computational graphs are the same.
 - Node features (colors) are identical.

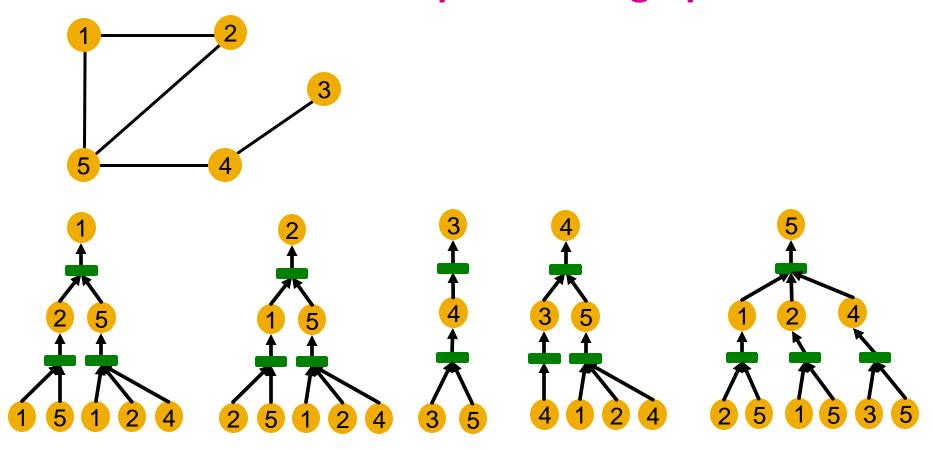
Note: GNN does not care about node ids, it just aggregates features vectors of different nodes.



GNN won't be able to distinguish nodes 1 and 2

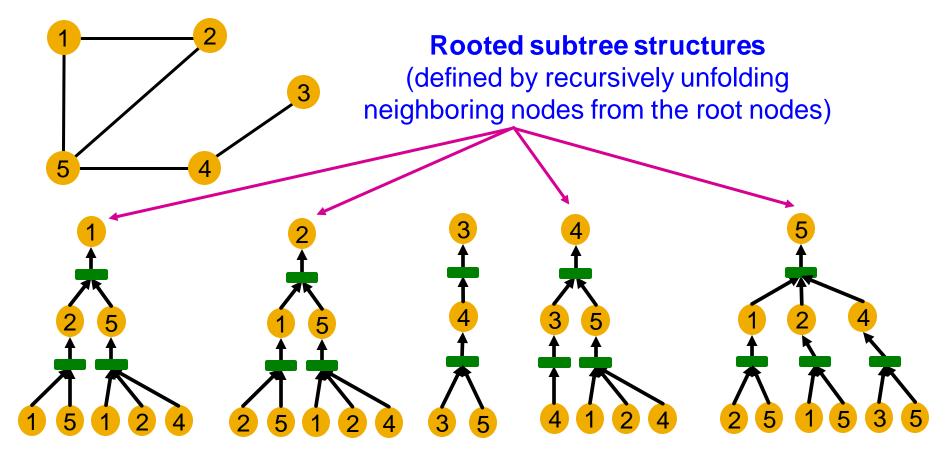
Computational Graph

 In general, different local neighborhoods define different computational graphs



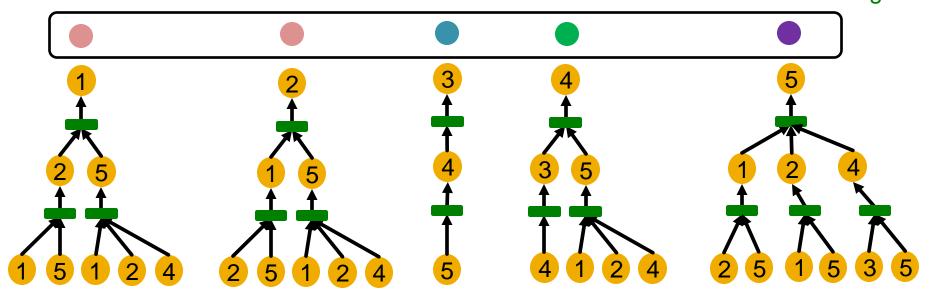
Computational Graph

 Computational graphs are identical to rooted subtree structures around each node.



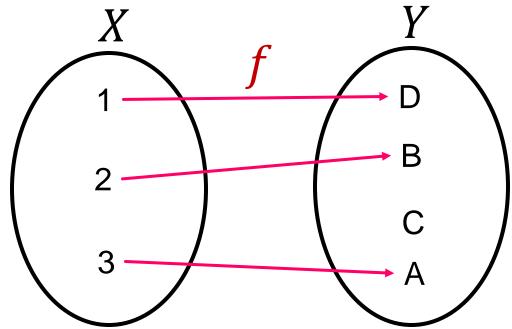
Computational Graph

- GNN's node embeddings capture rooted subtree structures.
- Most expressive GNN maps different rooted subtrees into different node embeddings (represented by different colors).

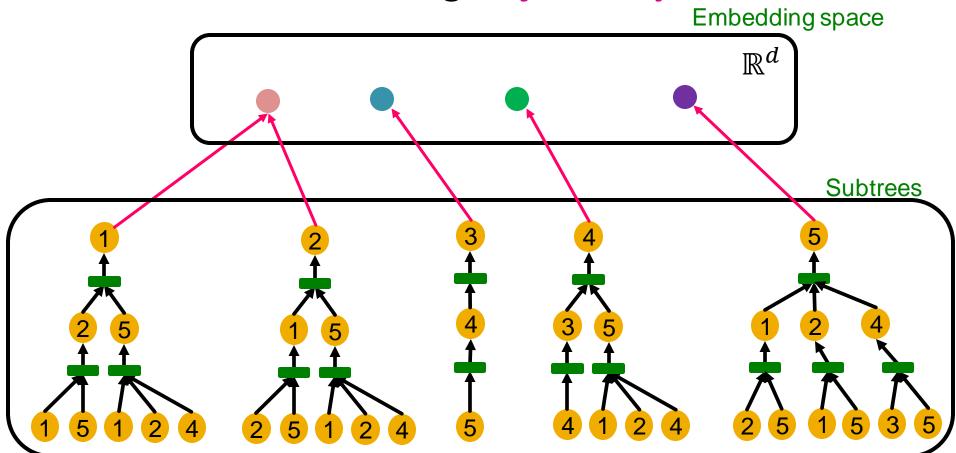


Recall: Injective Function

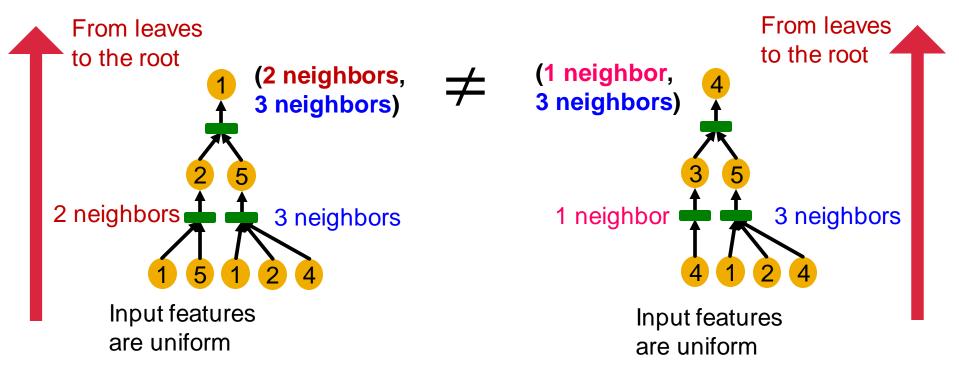
- Function $f: X \to Y$ is injective if it maps different elements into different outputs.
- Intuition: f retains all the information about input.



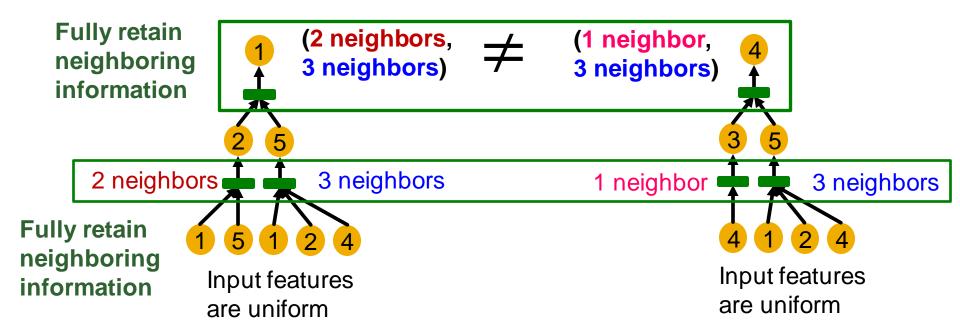
 Most expressive GNN should map subtrees to the node embeddings injectively.



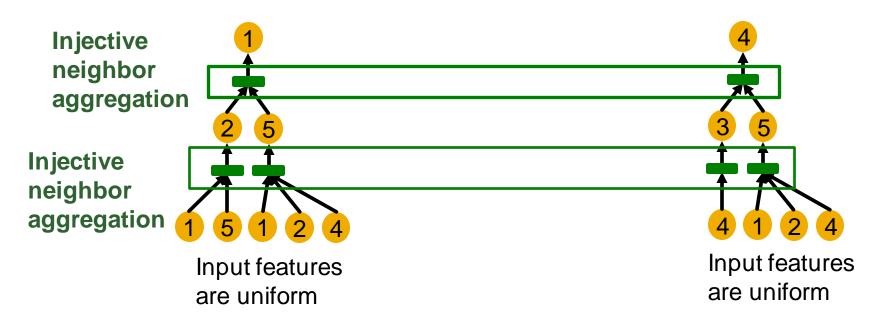
 Key observation: Subtrees of the same depth can be recursively characterized from the leaf nodes to the root nodes.



 If each step of GNN's aggregation can fully retain the neighboring information, the generated node embeddings can distinguish different rooted subtrees.

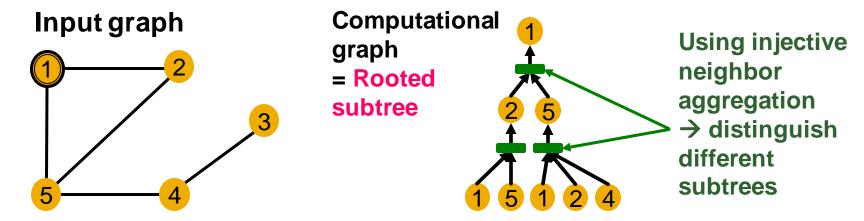


- In other words, most expressive GNN would use an injective neighbor aggregation function at each step.
 - Maps different neighbors to different embeddings.



Summary so far

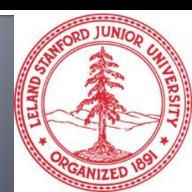
 To generate a node embedding, GNNs use a computational graph corresponding to a subtree rooted around each node.



 GNN can fully distinguish different subtree structures if every step of its neighbor aggregation is injective.

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Expressive Power of GNNs

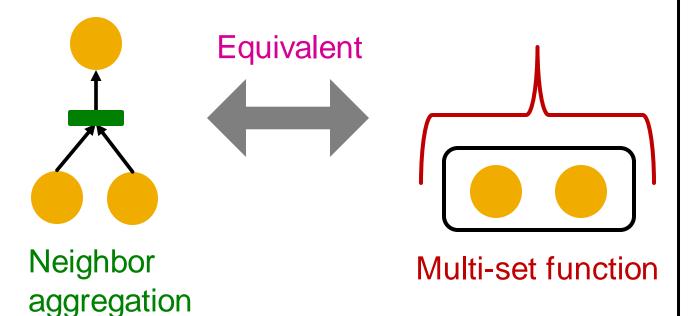
- Key observation: Expressive power of GNNs can be characterized by that of neighbor aggregation functions they use.
 - A more expressive aggregation function leads to a more expressive a GNN.
 - Injective aggregation function leads to the most expressive GNN.

Next:

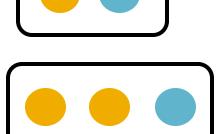
Theoretically analyze expressive power of aggregation functions.

Neighbor Aggregation

Observation: Neighbor aggregation can be abstracted as a function over a multi-set (a set with repeating elements).



Examples of multi-set



Same color indicates the same features.

Neighbor Aggregation

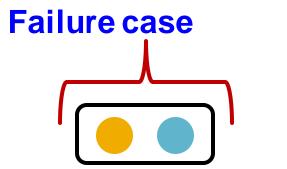
- Next: We analyze aggregation functions of two popular GNN models
 - GCN (mean-pool) [Kipf & Welling, ICLR 2017]
 - Uses element-wise mean pooling over neighboring node features

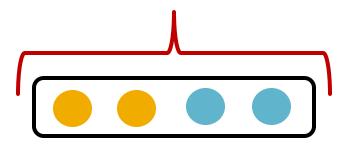
$$Mean(\{x_u\}_{u\in N(v)})$$

- GraphSAGE (max-pool) [Hamilton et al. NeurIPS 2017]
 - Uses element-wise max pooling over neighboring node features

$$Max(\{x_u\}_{u\in N(v)})$$

- GCN (mean-pool) [Kipf & Welling ICLR 2017]
 - Take **element-wise mean**, followed by linear function and ReLU activation, i.e., max(0, x).
 - **Theorem** [Xu et al. ICLR 2019]
 - GCN's aggregation function cannot distinguish different multi-sets with the same color proportion.







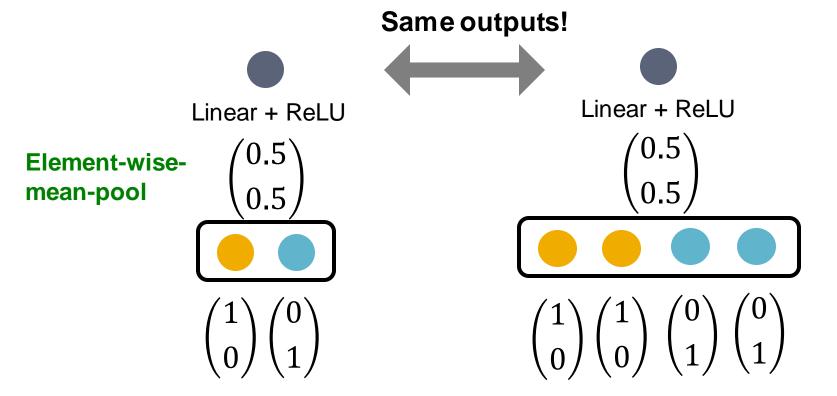
Neighbor Aggregation

- For simplicity, we assume node features (colors) are represented by one-hot encoding.
 - Example: If there are two distinct colors:

$$= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

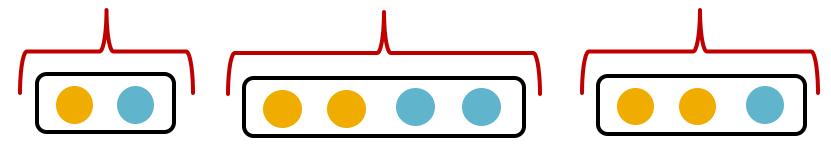
This assumption is sufficient to illustrate how GCN fails.

- GCN (mean-pool) [Kipf & Welling ICLR 2017]
 - Failure case illustration



- GraphSAGE (max-pool) [Hamilton et al. NeurIPS 2017]
 - Apply an MLP, then take element-wise max.
 - **Theorem** [Xu et al. ICLR 2019]
 - GraphSAGE's aggregation function cannot distinguish different multi-sets with the same set of distinct colors.

Failure case



Why?

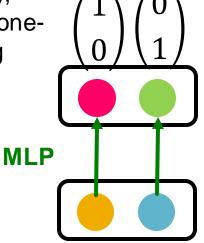
- GraphSAGE (max-pool) [Hamilton et al. NeurIPS 2017]
 - Failure case illustration

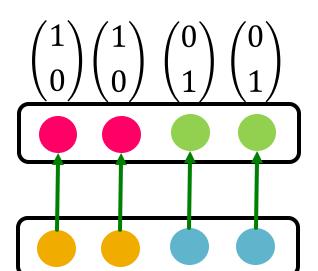
The same outputs!

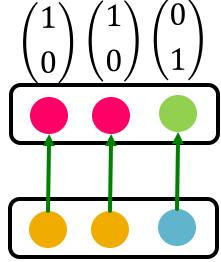
Element-wisemax-pool

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix} \qquad \qquad \begin{pmatrix} 1 \\ 1 \end{pmatrix} \qquad \qquad \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

For simplicity, assume the one-hot encoding after **MLP**.







Summary So Far

- We analyzed the expressive power of GNNs.
- Main takeaways:
 - Expressive power of GNNs can be characterized by that of the neighbor aggregation function.
 - Neighbor aggregation is a function over multi-sets (sets with repeating elements)
 - GCN and GraphSAGE's aggregation functions fail to distinguish some basic multi-sets; hence not injective.
 - Therefore, GCN and GraphSAGE are **not** maximally powerful GNNs.

Designing Most Expressive GNNs

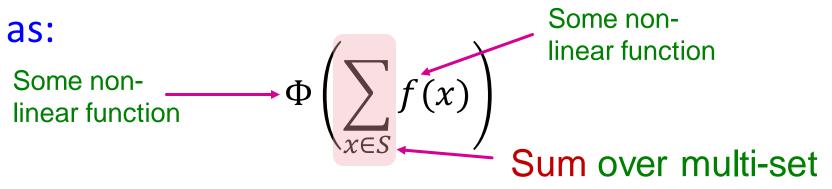
- Our goal: Design maximally powerful GNNs in the class of message-passing GNNs.
- This can be achieved by designing injective neighbor aggregation function over multisets.
- Here, we design a neural network that can model injective multiset function.

Injective Multi-Set Function

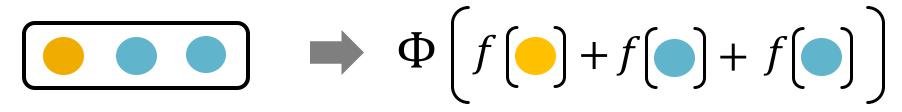


Theorem [Xu et al. ICLR 2019]

Any injective multi-set function can be expressed



S: multi-set



Injective Multi-Set Function

Proof Intuition: [Xu et al. ICLR 2019]

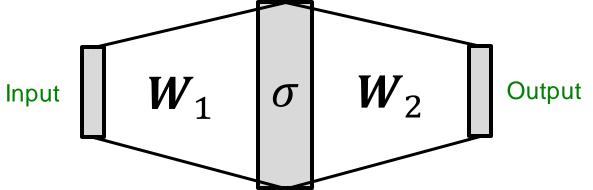
f produces one-hot encodings of colors. Summation of the one-hot encodings retains all the information about the input multi-set.

$$\Phi\left(\sum_{x\in S}f(x)\right)$$

Example:
$$\Phi\left(f\left(\begin{array}{c} +f\left(\begin{array}{c} \\ \end{array}\right) +f\left(\begin{array}{c} \\ \end{array}\right) +f\left(\begin{array}{c} \\ \end{array}\right)\right)$$
 One-hot
$$\begin{pmatrix} 1\\0 \end{pmatrix} +\begin{pmatrix} 0\\1 \end{pmatrix} +\begin{pmatrix} 0\\1 \end{pmatrix} =\begin{pmatrix} 1\\2 \end{pmatrix}$$

Universal Approximation Theorem

- How to model Φ and f in $\Phi(\sum_{x \in S} f(x))$?
- We use a Multi-Layer Perceptron (MLP).
- Theorem: Universal Approximation Theorem [Hornik et al., 1989]
 - 1-hidden-layer MLP with sufficiently-large hidden dimensionality and appropriate non-linearity $\sigma(\cdot)$ (including ReLU and sigmoid) can approximate any continuous function to an arbitrary accuracy.



Injective Multi-Set Function



We have arrived at a neural network that can model any injective multiset function.

$$\mathrm{MLP}_{\Phi} \left(\sum_{x \in S} \mathrm{MLP}_{f}(x) \right)$$

 In practice, MLP hidden dimensionality of 100 to 500 is sufficient.

Most Expressive GNN

- Graph Isomorphism Network (GIN) [Xu et al. ICLR 2019]
 - Apply an MLP, element-wise sum, followed by another MLP.

$$\mathrm{MLP}_{\Phi} \left(\sum_{x \in S} \mathrm{MLP}_{f}(x) \right)$$

- Theorem [Xu et al. ICLR 2019]
 - GIN's neighbor aggregation function is injective.
- No failure cases!
- GIN is THE most expressive GNN in the class of message-passing GNNs we have introduced!

Full Model of GIN

- So far: We have described the neighbor aggregation part of GIN.
- We now describe the full model of GIN by relating it to WL graph kernel (traditional way of obtaining graph-level features).
 - We will see how GIN is a "neural network" version of the WL graph kernel.

Relation to WL Graph Kernel

Recall: Color refinement algorithm in WL kernel.

- Given: A graph G with a set of nodes V.
 - Assign an initial color $c^{(0)}(v)$ to each node v.
 - Iteratively refine node colors by

$$c^{(k+1)}(v) = \text{HASH}\left(c^{(k)}(v), \left\{c^{(k)}(u)\right\}_{u \in N(v)}\right),$$

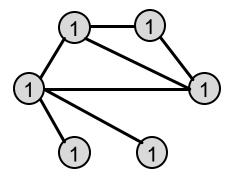
where HASH maps different inputs to different colors.

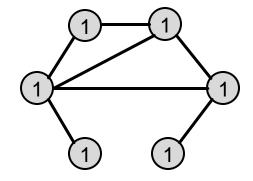
• After K steps of color refinement, $c^{(K)}(v)$ summarizes the structure of K-hop neighborhood

Color Refinement (1)

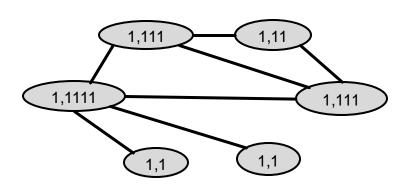
Example of color refinement given two graphs

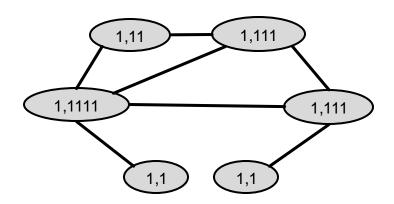
Assign initial colors





Aggregate neighboring colors



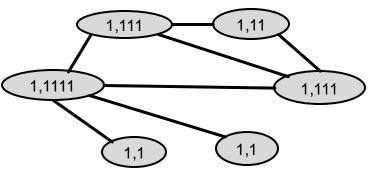


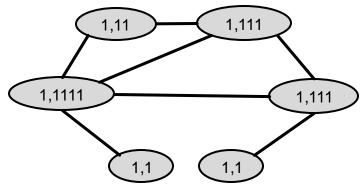
Color Refinement (2)



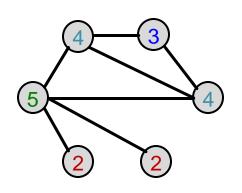
Example of color refinement given two graphs

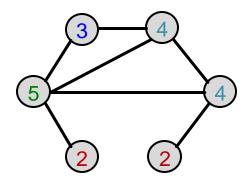
Aggregated colors:





Injectively HASH the aggregated colors





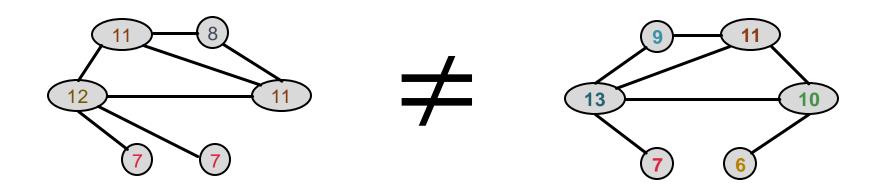
HASH table: Injective!

1,1	>	2
1,11	>	3
1,111	>	4
1,1111	>	5

Color Refinement (3)

Example of color refinement given two graphs

- Process continues until a stable coloring is reached
- Two graphs are considered isomorphic if they have the same set of colors.



GIN uses a neural network to model the injective HASH function.

$$c^{(k+1)}(v) = \text{HASH}\left(c^{(k)}(v), \left\{c^{(k)}(u)\right\}_{u \in N(v)}\right)$$

Specifically, we will model the injective function over the tuple:

$$(c^{(k)}(v), \{c^{(k)}(u)\}_{u \in N(v)})$$

Root node features

Neighboring node colors

Theorem (Xu et al. ICLR 2019)

Any injective function over the tuple Root node
$$\{c^{(k)}(v), \{c^{(k)}(u)\}_{u \in N(v)}\}$$
 Neighboring node features

can be modeled as

$$MLP_{\Phi}\left((1+\epsilon)\cdot MLP_{f}(c^{(k)}(v))) + \sum_{u\in N(v)} MLP_{f}(c^{(k)}(u))\right)$$

where ϵ is a learnable scalar.

If input feature $c^{(0)}(v)$ is represented as onehot, direct summation is injective.

• We only need Φ to ensure the injectivity.

GINConv
$$c^{(k)}(v)$$
 $\{c^{(k)}(u)\}_{u\in N(v)}$ $=$ MLP $_{\Phi}$ $(1+\epsilon)\cdot c^{(k)}(v)+\sum_{u\in N(v)}c^{(k)}(u)$ Neighboring node features This MLP can provide "one-hot" input

feature for the next layer.



- GIN's node embedding updates
- Given: A graph G with a set of nodes V.
 - Assign an **initial vector** $c^{(0)}(v)$ to each node v.
 - Iteratively update node vectors by

$$c^{(k+1)}(v) = \text{GINConv}\left(\left\{c^{(k)}(v), \left\{c^{(k)}(u)\right\}_{u \in N(v)}\right\}\right)$$

Differentiable color HASH function

where GINConv maps different inputs to different embeddings.

• After K steps of GIN iterations, $c^{(K)}(v)$ summarizes the structure of K-hop neighborhood.

GIN and WL Graph Kernel

GIN can be understood as differentiable neural version of the WL graph Kernel:

	Update target	Update function
WL Graph Kernel	Node colors (one-hot)	HASH
GIN	Node embeddings (low-dim vectors)	GINConv

- Advantages of GIN over the WL graph kernel are:
 - Node embeddings are low-dimensional; hence, they can capture the fine-grained similarity of different nodes.
 - Parameters of the update function can be learned for the downstream tasks.

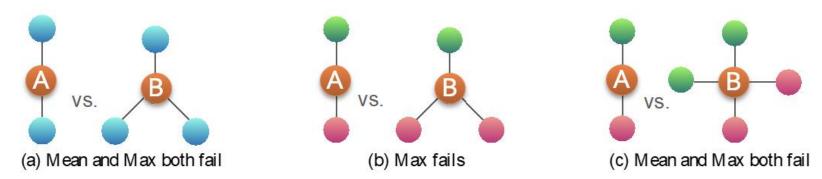
Expressive Power of GIN



- Because of the relation between GIN and the WL graph kernel, their expressive is exactly the same.
 - If two graphs can be distinguished by GIN, they can be also distinguished by the WL kernel, and vice versa.
- How powerful is this?
 - WL kernel has been both theoretically and empirically shown to distinguish most of the realworld graphs [Cai et al. 1992].
 - Hence, GIN is also powerful enough to distinguish most of the real graphs!

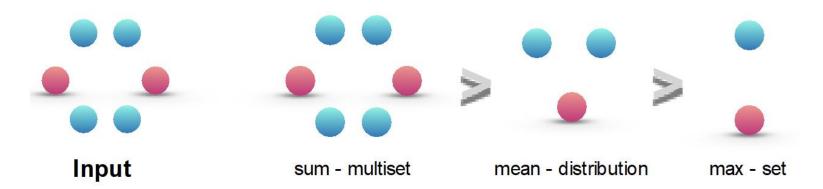
Discussion: The Power of Pooling

Failure cases for mean and max pooling:



Colors represent feature values

Ranking by discriminative power:

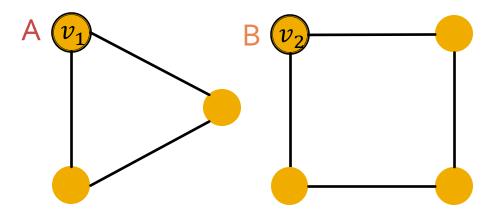


Improving GNNs' Power

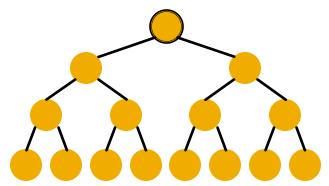
Can the expressive power of GNNs be improved?

 There are basic graph structures that existing GNN framework cannot distinguish, such as difference in cycles.

Graphs



Computational graphs for nodes v_1 and v_2 :



- GNNs' expressive power can be improved to resolve the above problem. [You et al. AAAI 2021, Li et al. NeurIPS 2020]
 - Stay tuned for Lecture 15: Advanced Topics in GNNs

Summary of the Lecture

- We design a neural network that can model injective multi-set function.
- We use the neural network for neighbor aggregation function and arrive at GIN----the most expressive GNN model.
- The key is to use element-wise sum pooling, instead of mean-/max-pooling.
- GIN is closely related to the WL graph kernel.
- Both GIN and WL graph kernel can distinguish most of the real graphs!

Stanford CS224W: When Things Don't Go As Planned

CS224W: Machine Learning with Graphs Jure Leskovec, Stanford University http://cs224w.stanford.edu



General Tips

Data preprocessing is important:

- Node attributes can vary a lot! Use normalization
 - E.g. probability ranges (0,1), but some inputs could have much larger range, say (-1000, 1000)
- Optimizer: ADAM is relatively robust to learning rate
- Activation function
 - ReLU activation function often works well
 - Other good alternatives: <u>LeakyReLU</u>, <u>PReLU</u>
 - No activation function at your output layer
 - Include bias term in every layer
- Embedding dimensions:
 - 32, 64 and 128 are often good starting points

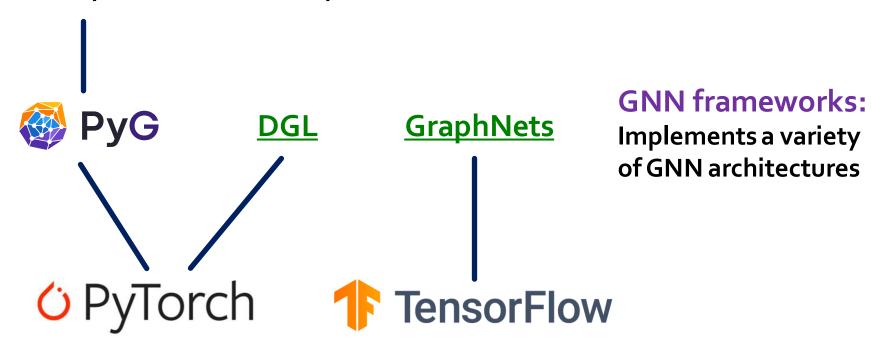
Debugging Deep Networks

- Debug issues: Loss/accuracy not converging during training
 - Check pipeline (e.g. in PyTorch we need <u>zero_grad</u>)
 - Adjust hyperparameters such as learning rate
 - Pay attention to weight parameter <u>initialization</u>
 - Scrutinize loss function!
- Important for model development:
 - Overfit on (part of) training data:
 - With a small training dataset, loss should be essentially close to 0, with an expressive neural network
 - Monitor the training & validation loss curve

Resources on Graph Neural Networks

GraphGym:

Easy and flexible end-to-end GNN pipeline based on PyTorch Geometric (PyG)



Auto-differentiation frameworks

Resources on Graph Neural Networks

Tutorials and overviews:

- Relational inductive biases and graph networks (Battaglia et al., 2018)
- Representation learning on graphs: Methods and applications (Hamilton et al., 2017)

Attention-based neighborhood aggregation:

Graph attention networks (Hoshen, 2017; Velickovic et al., 2018; Liu et al., 2018)

Embedding entire graphs:

- Graph neural nets with edge embeddings (Battaglia et al., 2016; Gilmer et. al., 2017)
- Embedding entire graphs (Duvenaud et al., 2015; Dai et al., 2016; Li et al., 2018) and graph pooling (Ying et al., 2018, Zhang et al., 2018)
- Graph generation and relational inference (You et al., 2018; Kipf et al., 2018)
- How powerful are graph neural networks(Xu et al., 2017)

Embedding nodes:

- Varying neighborhood: Jumping knowledge networks (Xu et al., 2018), GeniePath (Liu et al., 2018)
- Position-aware GNN (You et al. 2019)

Spectral approaches to graph neural networks:

- Spectral graph CNN & ChebNet (Bruna et al., 2015; Defferrard et al., 2016)
- Geometric deep learning (Bronstein et al., 2017; Monti et al., 2017)

Other GNN techniques:

- Pre-training Graph Neural Networks (Hu et al., 2019)
- GNNExplainer: Generating Explanations for Graph Neural Networks (Ying et al., 2019)