

view_frames Result
Recorded at time: 102.772

map

agent1/odom

agent1/base_link

agent1/gripper_1a

agent1/gripper_1b

agent1/gripper_2a

agent1/gripper_2b

agent1/gripper_3a

agent1/gripper_3b

agent1/gripper_4a

agent1/gripper_4b

agent1/imu_link

agent1/laser

agent1/back_left_wheel

agent1/back_right_wheel

agent1/front_left_wheel

agent1/front_right_wheel

Broadcaster: /agent1/hector_slam
Average rate: 6.601
Buffer length: 4.999
Most recent transform: 102.724
Oldest transform: 97.725

Broadcaster: /gazebo
Average rate: 1.249
Buffer length: 4.004
Most recent transform: 102.725
Oldest transform: 98.721

Broadcaster: /agent1/robot_state_publisher
Average rate: 50.2
Buffer length: 5.0
Most recent transform: 102.767
Oldest transform: 97.767

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Broadcaster: /agent1/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /agent1/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /agent1/robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 102.706
Oldest transform: 97.806

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Buffer length: 4.9
Most recent transform: 102.706
Oldest transform: 97.806

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