



User Manual

LokSound V3.0 / V3.5
LokSoundXL
LokSound micro

4th edition, August 2005



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1. Introduction

Congratulations on purchasing a LokSound decoder. With LokSound your engines will sound like the prototype. You will soon notice that your LokSound equipped engines are in the center of attention on any layout.

Of course, you would like to install this decoder immediately, but first we kindly request you to read the following remarks:

Please read this manual carefully before carrying out the installation!!! Although LokSound decoders are very robust, incorrect wiring may destroy the module!

Due to its factory settings your new LokSound decoder can generally be used as is. In addition you may choose from a multitude of options that will help you adjust your LokSound decoder perfectly better to your model. Please familiarize yourself with the decoder before installing it and adjusting any parameters. Also note the recommendations regarding installation.

Important warning:

- LokSound decoders are designed for use in model trains only
- Avoid mechanical force or pressure on the decoder
- Do not expose to wet and humid conditions
- Do not remove the heat shrink sleeve on the decoder
- Never solder on the circuit board, extend cables if necessary
- Never wrap the decoder in insulation tape, since this may cause overheating
- Always disconnect the circuit when installing the decoder
- Make sure that neither the LokSound decoder nor any blank wire ends may come into contact with the engine chassis (risk of short circuit). Cover any blank ends of unused wires.
- Make sure that no wires are squeezed or cut by the model's transmission parts when reassembling the engine

Handle the speaker with extreme care: Do not touch the membrane or apply pressure! Solder speaker connections quickly and only at the intended contacts! Pay close attention to the instructions for installing the speaker!

If you adhere to these warnings your LokSound decoder will reward you with trouble-free operation and long life.

ESU electronic solutions ulm GmbH & Co. KG
August 2005

This manual has several Chapters explaining step by step how to proceed:

Chapter 2 provides an overview of the characteristics of LokSound and LokSoundXL decoders.

Chapter 3 describes installation and connection. In Chapter 3.1 installation of LokSound decoders for HO, TT, N and O gauge are explained while Chapter 3.2 deals with the LokSoundXL for larger scale models (O, I, II,...).

LokSound decoders are suitable for most digital command control systems. **Chapter 4** provides an overview on which digital and analogue systems may be used to operate LokSound decoders as well as some particularities with certain systems.

If you want to modify the preset running characteristics and/or sound effects we strongly recommend to read **Chapter 5**. Here you will gain an insight regarding the many options and how to adjust various parameters. You will also learn how to reset the decoder to the factory settings. The LokProgrammer (Art. No. 53451) makes setting any parameter of your LokSound decoder as easy as making a phone call or sending an email.

Chapter 6 contains the answers to Frequently Asked Questions.

In **Chapter 7** a table provides all you need to know regarding the programming of decoder characteristics as outlined in Chapter 5.

2. Characteristics of the LokSound decoders

The LokSound decoder is a universal electronic module for installation in model engines of most common scales. We recommend LokSound for all engines in TT, HO gauge as well as smaller engines in O gauge. LokSoundXL is best suited for larger scales such as O, I, II and G gauge. ESU LokSound decoders revolutionize any model train layout. They intelligently combine a sophisticated digital decoder and a digital sound module. With LokSound you can run your engine with load control and many auxiliary functions while enjoying the original sound of the prototype. Its unique features provide flexibility and safety in operation that you have come to expect from a state of the art decoder. Even future standards are no problem for LokSound: its flash technology allows adaptation to the latest developments.

Multi-protocol operation: LokSound decoders understand both, the commonly used Märklin® / Motorola® – format and the NMRA / DCC - system. Thus LokSound may be used with almost all currently available digital command control systems. Amongst others LokSound was tested with:

- Digitrax® systems
- Lenz Digital Plus®
- ROCO® digital is cool®
- Atlas® commander
- Bachmann® E-Z command®
- Märklin® 6021
- Uhlenbrock® Intellibox (DCC+Motorola® System)
- ZIMO MX-1 (DCC-Operation)
- Fleischmann® Twin-Center
- LGB® MTS® control

Automatic change between all four operating modes during operation (AC , DC , DCC digital, Märklin® digital)

Universal motor connection: All types of motors commonly used for model trains may be connected to LokSound:

- DC motors (e.g. Bühler, Mabuchi, etc)
- Coreless motors (e.g. Faulhaber, Maxxon, Hitachi)
- Alternating current motors (AC motors)

High motor pulse frequency: The pulse frequency of 32 kHz (!) assures absolutely smooth running. Thus the motor runs silently and without any whine, heat generation is minimized and lifetime is prolonged. Even coreless motors may be operated with LokSound decoders without any problem.

Motor control: LokSound offers fourth generation load control. It may be adapted to suit each individual motor and can be switched off. Suitable for DC motors and coreless motors. Therefore your engine will always travel at the selected speed, no matter how large the load is or whether the engine is traveling up or down gradients.

Dynamic Drive Control (DDC): back EMF active at low speeds for smooth slow running with reduced influence at high speeds.

Back EMF for conventional operation: Back EMF is also active in conventional AC or DC mode. The user has full control of motor and acceleration.

4 function outputs: In addition to the two lighting outputs, two more function outputs are available: switch on a smoke generator or the interior lighting or activate a digital coupler by pressing a button! Lighting effects and individually dimmable lamps help to make your models even more prototypical you will have lots of fun.

Revolutionary function mapping: All functions can be allocated to any of 20 function buttons. Multiple allocations are possible allowing for the combination of sound and functions, e.g. the sound of shoveling coal and light flickering in the firebox. Also, we have integrated the latest NMRA DCC standards covering the use of F13 - F20

Helper mode for consist: With the Helper Function the user can select whether the engine runs standalone, head-of-consist, mid-of-consist or end-of-consist.

Consist mode CVs: influence the behavior of the function keys with the added CV 21 and 22.

Brake sections: LokSound decoders recognize (and respond to) the most common brake systems: besides the Lenz brake generator, the Märklin® brake track is also supported.

Circuit protection: the motor output and all function outputs are short circuit protected .

Please make sure that the total current does not exceed the maximum permitted current for the function outputs and avoid short circuits between the outputs: LokSound circuits are protected but an external voltage at the terminals of a function output may destroy the circuitry.

conventional operation: LokSound decoders may be operated on AC- and DC layouts without any problems.

Easy programming: Even with Märklin® 6021 all functions may be changed comfortably without opening the engine.

A digital, four-tone sound module with unique characteristics:

Prototype sounds: sounds of prototype engines were sampled using high fidelity microphones and recorded digitally on the flash memory module. Thus your engines sound exactly like the prototype!

With four independent channels your engine sounds even more realistic, since you can simultaneously add 3 sound effects to the running sound. Pumps, power switches and squealing brakes can all be heard at the same time. The exhaust chuffs of steam engines vary with the revs of the drivers and the load. Now you can really hear your engine work. Diesel engines can now simulate the reduced revs of the diesel while the engine is coasting. The running sound and the sound of the fans (blowers) in electric engines is now separated. Additional sound effects can be activated by pressing a function button.

Random sounds: sound effects such as air pump, water pump, shoveling coal, discharging compressed air, etc. are randomly triggered. Such sounds can be configured differently for stationary or moving engines.

Individual volume control: You can individually control the volume for prime mover sounds, bell, horn and auxiliary sounds.

Analog Sound: Even on conventional DC (or AC) layouts you will hear all prime mover sounds synchronized to the operation condition.

3. Installation of LokSound decoders

3.1. Connecting LokSound decoders in N, TT, H0, 0 gauge models

3.1.1 Installation requirements

The engine must be in good mechanical condition: only an engine running smoothly in analogue mode should be modified for digital operation. An engine running poorly in analogue mode will not operate satisfactorily in digital mode – even with the best digital decoder. Check and clean or replace any wear and tear parts such as motor brushes, wheel contacts, lamps etc.

Always remove the engine from the track when doing maintenance work or modifications. Make sure that no voltage is applied – intentionally or accidentally – while you work on the model.

Pin Description	Color Code
1 motor terminal right	orange
2 rear light	yellow
3 function F1	green
4 track connection left	black
5 motor terminal left	gray
6 headlight	white
7 common (+pole)	blue
8 track connection right	red



Figure1: NEM652 interface

Pin	Description	Color Code
1	motor terminal right	orange
2	motor terminal left	gray
3	track connection right	red
4	track connection left	black
5	head light	white
6	rear light	yellow



Figure1: NEM651 interface

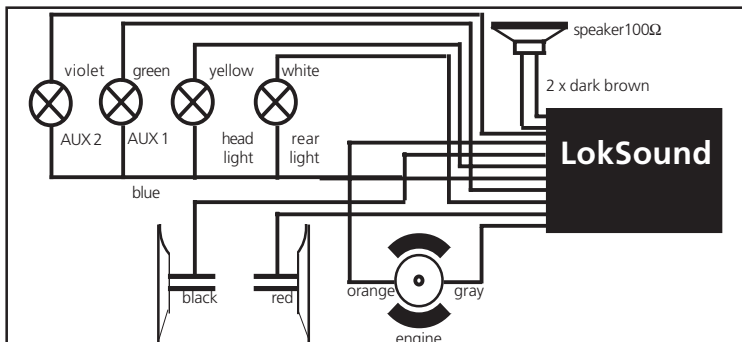


Figure 2: Wiring of engines with DC motor and isolated functions

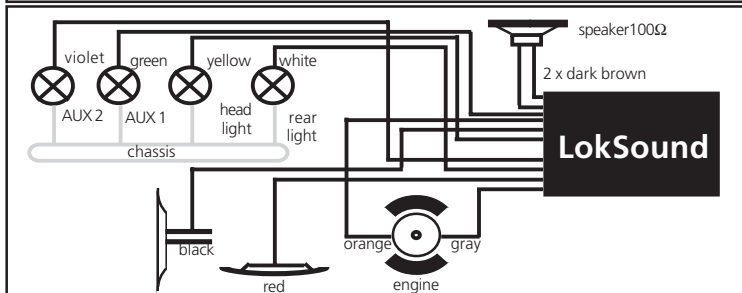


Figure 3a: Wiring of engines with DC motors and functions with the common pole connected to the chassis

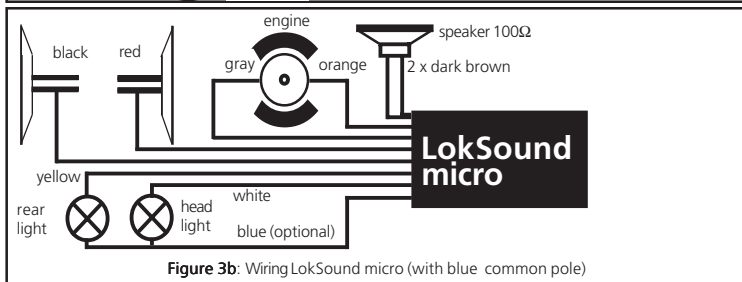


Figure 3b: Wiring LokSound micro (with blue common pole)

LokSound decoders have a certain size: make sure, that the decoder fits easily into the engine, that no pressure is applied when replacing the housing onto the chassis and that no wires are squeezed between other parts. Further, make certain that moving parts such as transmissions and trucks are not obstructed by wires.

Never pack a LokSound decoder in foam pads etc. The decoder heats up during operation; good heat dissipation is essential.

Electronic components are sensitive to electrostatic charges: always make sure that your work place is grounded. If necessary, use an earthed wristband.

When installing the decoder make sure that no metal part of the chassis touches any components of the decoder.

3.1.2 Engines with DCC interface

LokSound is supplied with an NMRA DCC 8-pin plug as shown in figure 1. Installation in engines with DCC socket is particularly easy:

- Remove the body! Follow the instructions in the manual of the engine!
- Remove the analogue plug or directional relay. Please keep the plug / relay for future use
- Insert the decoder plug with pin 1 (the side with the red/orange wire) into the side of the socket that is usually marked with *, +, • or 1. Avoid bending any pins. Do not rely on the assumption that the wires have to lead in a certain direction, the marking is the only valid reference.
- Place the decoder in a suitable location within the engine and fasten it with double sided tape or a drop of hot glue.
- Now fix the speaker in a suitable place. See Chapter 3.2.4

3.1.3 Engines without interface

Not every engine has a digital interface and thus the wiring becomes more elaborate: Disconnect any existing wires within the engine and any connection to the chassis. Both motor contacts must be insulated, make sure there isn't any connection to the chassis, the wheels or the pantographs. This may easily be overlooked particularly in Fleischmann® models!

After installing the decoder please check all connections with an Ohmmeter and watch for any short circuits between motor- and current pick-ups.

How to proceed depends on how the headlights and other functions are wired in the engine:

- a) If headlights and functions are insulated from the engine chassis (free of any voltage) proceed as per figure 2.
- b) Headlights and functions may be connected with their common to the track voltage (e.g. almost all Märklin® -engines and older Fleischmann® or ROCO® engines) as per figure 3a

Don't get confused by the fact that both figure 2 and 3a show how to wire DC - and coreless motors. How to wire a universal motor (Märklin®) is shown in figure 5.

- Connect the red wire to the right rail pick-up (or center pick-up in AC models), the black wire to the left rail pick-up (common rails in AC models).
- Connect the backup lights to the yellow wire, the headlights to the white wire.
- Connect the green wire to the function output AUX-1. Allocate the function button later.
- Connect the purple wire to the function output AUX-2. Allocate the function button later.
- Connect the speaker to the two dark-brown wires.
- If the headlights and functions are insulated from the chassis (see figure 3a) connect all commons to the blue wire. Make sure the blue wire has no contact to the engine chassis.

3.1.3.1 Connecting DC motors

- Connect the orange wire with the motor terminal, that was originally wired to the right wheel pick-up (center pick-up in AC models).
- The gray wire goes to the terminal, that was originally connected to the left wheel pick-up (common rails for AC models).
- Exchanging the wires changes direction of travel.
- Some engines with the Märklin® 5-pole high performance drive may have 3 RFI suppressors soldered to the motor shield.
- The two suppressors that connect the motor terminals with the motor chassis must be removed (see figure 4).

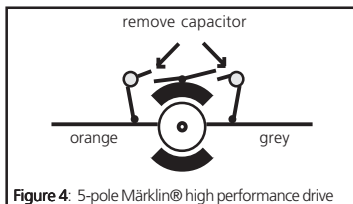


Figure 4: 5-pole Märklin® high performance drive

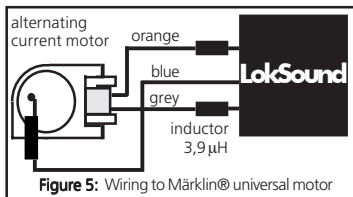


Figure 5: Wiring to Märklin® universal motor

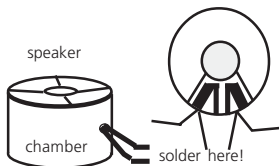
3.1.3.2 Connecting universal motors

Figure 5 shows how a universal motor (e.g. AC motor by Märklin®) is connected to a LokSound decoder:

- Connect the orange wire with the motor terminal that was originally connected with the center pick-up.
- Connect the gray wire to the motor terminal that was originally connected to the common / wheel pick-up.
- Exchanging the wires will change direction of travel.
- Solder an inductor (choke) with at least 3.9 mH to each motor terminal. They are available as spare parts from Märklin® under article number 516520.
- The RFI suppression inductor remains attached to the collector terminal of the motor and has to be soldered to the blue wire.

Please note: If a universal motor is connected LokSound will automatically deactivate Back EMF Control. The principle of Back EMF Control does not work with universal motors.

3.1.4 Connecting the speaker



LokSound decoders may only be used with the speakers supplied by ESU GmbH & Co. KG. They have an impedance of 100 Ohm. The use of speakers from other manufacturers may cause considerable distortion and in extreme cases, may even destroy the LokSound decoder.

The correct position of the speaker is crucial to achieve high quality sound. A speaker that is installed without a sound chamber will not generate good sound. Therefore carefully select the location and sound chamber for the speaker.

The speaker must be installed in such a way that the sound waves are not unduly blocked.

Please handle speakers with extreme care: don't apply pressure or touch the membrane! The speaker's magnets are very powerful! Keep all metal items away and secure the speaker firmly when soldering. The soldering iron may pull the speaker due the magnetic field and destroy it.

Make sure that the total current for the function outputs does not exceed the permitted current rating and avoid short circuits between outputs. Although the output circuits are protected, a high voltage on the terminals or a short circuit may cause damage.

Connect the speaker to the 2 dark brown wires of the LokSound module. Make sure that you use a small soldering iron (max. 20W) and only heat the marked spots as shown in the figure (close to the edge of the small contact plate). Polarity is not important. An optimal sound effect is achieved by putting the speaker into a sound chamber, which is supplied with the speaker. This will increase the sound pressure and channel the sound in one direction. Without sound chamber the sound effect may be unsatisfactory. Feed the speaker wires through a small hole in the sound chamber.

3.1.5 Connecting auxiliary function devices

Any load may be connected to the lighting and auxiliary function outputs as long as it doesn't exceed the maximum current (see technical data in the appendix of this manual). Note that the overload protection of the decoder reacts quickly and will switch off all functions immediately in case of an overload or short circuit.

Therefore use only 16 V lamps (or a higher voltage) and a maximum nominal current of 50mA: incandescent lamps have a high starting current and may trigger the overload protection during switch-on.

Use only digital smoke generators (e.g. Seuthe No. 11) for engines whose lighting and auxiliary function outputs are connected as shown in figure 2. Other smoke generators draw too much current. There are smoke generators with more than 250mA nominal current on the market!

Engines that are wired as shown in figure 3 need an analogue smoke generator e.g. Seuthe No. 10.

3.1.6 Connecting a wheel sensor

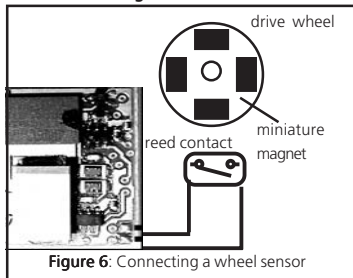


Figure 6: Connecting a wheel sensor

To synchronize the exhaust chuffs with the revs of the drivers an external sensor can be (but does not have to be) used. The sensor input is described in figure 6. The LokSound micro does not support this sensor input.

LokSound decoders support reed contacts or mechanical contacts.

If a reed contact is to be used, a miniature magnet (available at hobby shops) must be attached to the driving wheel axle in such a way that the magnet releases the reed contact once every turn. Miniature reed contacts have been proven to be very reliable. They are available at special electronics stores.

Suitable magnets may be bought at model train shops. (e.g. Mini-track magnets) which might have to be shaped to fit.

All double pole (mechanical) contacts that are insulated (not connected to the chassis) are suitable.

Before the wheel sensor will work various CVs have to be programmed. See Chapter 5.2.4 on page 21.

3.2. Connecting the LokSoundXL decoder

The LokSoundXL decoder is partly supplied as an open circuit board. Do not remove the shrink sleeve, as there will be no warranty. Like any electronic device handling the LokSoundXL requires some care:

Please make absolutely certain that the module does not have contact with any metal parts: risk of short circuits!

The LokSoundXL has a few more terminals required for the sound effects. LokSoundXL is supplied with screw terminals for easy wiring without soldering. Please note the following:

- LokSoundXL decoders have two screw terminalstrips (No. 1 + No. 2):
- Please make sure, that you always use the correct terminal!
- Make certain, that the cable size is large enough for the terminals (min 0.20mm²)
- Tinn the ends of the wires or use cable glands
- Take care to avoid short circuits while inserting the wires into the terminals.
- Use a suitable screw driver. Hold down the screw terminals while tightening the screws to avoid any mechanical force on the circuit board.
- Provide adequate RFI suppression of the motor: a 100 nF capacitor parallel to the motor terminals is the absolute minimum.

Please note, that RFI suppression may be achieved by different means. We recommend to leave the chokes supplied with the engine in the circuit.

- However, all RFI suppression capacitors that connect the motor terminals with the (motor) chassis must be removed (see figure 4).

3.2.1 General hints

When modifying an engine for digital operation please take note of the following:

Make sure that no motor terminal is connected to the wheel pick-ups or pantographs; otherwise the decoder may be destroyed. Separate all connections including possible electrical contact via the engine chassis.

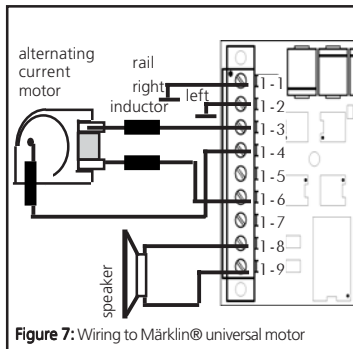
The LokSoundXL has a suresize and requires adequate space. Take care, that the decoder fits easily into the engine, that no pressure is applied when replacing the housing onto the chassis and that no wires are squeezed between other parts. Further, make certain that moving parts such as transmissions and trucks are not obstructed by wires.

Fix the decoder with double sided adhesive tape, some hot glue or screws, but never pack it into foam pads, etc. The decoder heats up during operation and good heat dissipation is essential.

After installation, please check all connections with an Ohmmeter and search for possible short circuits, particularly between the motor terminals and the wheel pick-ups.

3.2.2 Wiring diagram

Figures 8 and 9 show the general wiring layout for LokSoundXL decoders: The left terminal strip (No. 1) contains all connections required for running and sound. The right terminal strip (No. 2) is solely for auxiliary function outputs.



Please make sure you do not confuse the terminals. Wrong wiring may cause damage or destruction of the decoder – despite the protective circuitry!

Connect the right wheel pick-up to terminal 1-1 and the left one to terminal 1-2. Terminals 1-3, 1-4 and 1-6 are reserved for the motor. For DC and coreless motors only terminals 1-3 and 1-6 are used. Details are described in Chapter 3.2.3.1 and 3.2.3.2

A wheel sensor can be wired to terminals 1-4 and 1-5. Details are explained in Chapter 3.2.6.1

The speaker is to be connected to terminals 1-8 and 1-9. Installation of the speaker is explained in Chapter 3.2.4. Terminal strip 2 serves for the wiring of headlights and auxiliary functions only.

Please note that the common of all outputs is terminal 2-9 (positive voltage). Details are explained in Chapter 3.2.5.2 and 3.2.5.3.

3.2.3.1 Connecting a DC- or coreless motor

According to the general wiring diagram on page 12. Please note, that any suppression chokes should remain in the motor leads. The parameters for load control vary depending on the type of motor (Bühler, Mabuchi, Faulhaber) and have to be adjusted accordingly. Also refer to Chapter 5.2.1

When wiring the motor, please note that terminals 1-3 and 1-6 are used (the ones in between remain disconnected)!

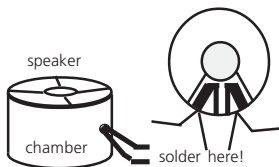
3.2.3.2 Connecting an alternating current (with field coils) motor

To simplify the modification of older I gauge models with universal motors (with field coils) the motor can be wired straight to the LokSoundXL decoder:

The field coil is wired to the terminals 1-3 and 1-6. Swapping the terminals results in change of direction. The suppressor choke remains with one contact on the motor terminal. The other lead is wired to terminal 1-4 of the decoder. As soon as a universal motor is connected to LokSoundXL, load control is automatically switched off. Universal motors are not suitable for load control.

3.2.4 Installing the speaker

You may only use the specially adapted speakers (1 Watt, 32 Ohm) provided by ESU GmbH & Co. KG for LokSoundXL decoders.



Other speakers will distort the sound and may cause damage or destruction of the decoder.

We can not recommend the use of speakers designed for HO decoders either.

The appropriate location within the model is crucial for excellent sound reproduction. A speaker without the sound chamber will never generate excellent sound. Therefore carefully select the space for the speaker and the sound chamber within the model. The speaker must be installed in such a way that the sound waves are not unduly blocked.

Please handle speakers with extreme care: don't apply pressure or touch the membrane! The speaker's magnets are very powerful! Keep all metal items away and secure the speaker firmly when soldering.

Connect the speaker to the terminals 1-8 and 1-9 of the LokSoundXL module. Make sure that you use a small soldering iron (max. 20W) and only heat the marked spots as shown in the figure (close to the edge of the small contact plate). Polarity is not important. Make sure no solder drips on the membrane.

An optimal sound effect is achieved by putting the speaker in a sound chamber, which is supplied with the speaker. This will increase the sound pressure and channel the direction of sound. Without sound chamber the sound effect may be unsatisfactory. Feed the speaker wires through a small hole into the sound chamber.

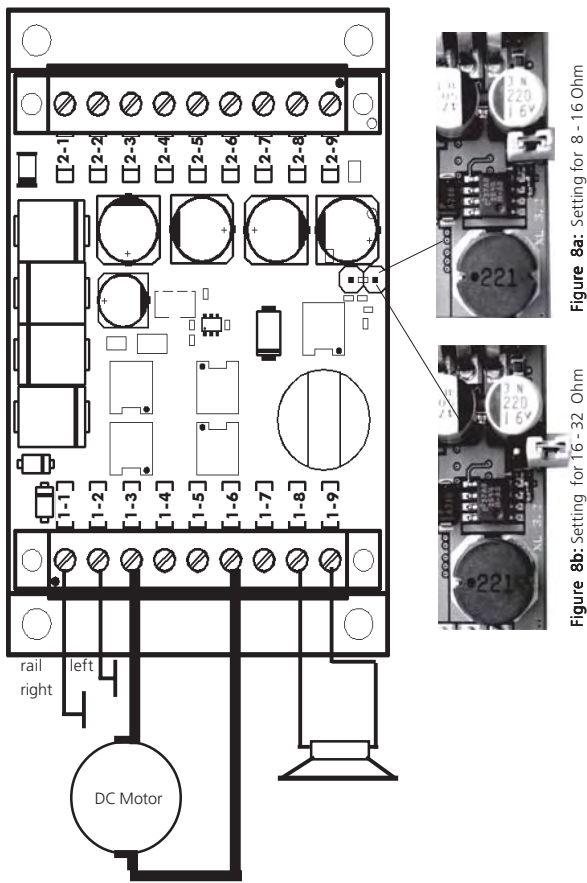


Figure 8: Connecting the LokSoundXL decoder

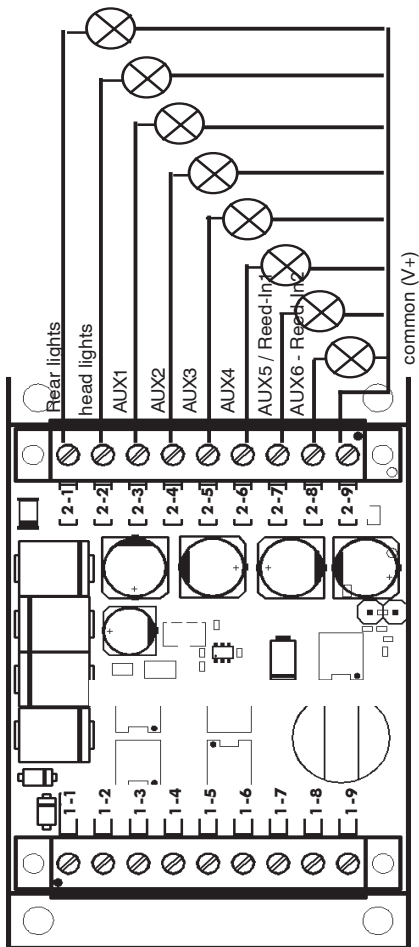


Figure 9: Connecting the LokSoundXL decoder

3.2.5.1 Auxiliary function outputs

LokSoundXL has 8 (!) function outputs, two of which are reserved for headlights. The remaining 6 (AUX 1 through AUX 6) can be used for lighting, smoke generators, couplers, etc.

However, before you can use these outputs, you have to activate them as described in Chapter 5.2.3.

The brightness of the outputs can be adjusted individually in 15 steps for each output. Each function output can also be programmed to provide certain lighting effects (blinking, etc.).

After you have checked above points you may switch on the power.

We strongly recommend to carry out this initial check on a track section with overload protection. Programming tracks of modern digital systems offer this protection. Our LokProgrammer (part Number 53451) also offers extremely reliable overload protection.

The pre-set engine address is 03.

Does the engine travel in both directions?

Turn the lights on: are they operating correctly? If the LokSound decoder was built into an engine with NMRA / DCC interface: check if the plug has been inserted correctly.

3.2.5.2 Connecting headlights

Headlights and back-up lights are to be wired to terminal block 2 as per figure 3.

Generally, the outputs will have the full track voltage (between 14 and 25 Volts, depending on the power supply). Therefore you should equip your engine with lamps suitable for that voltage. In older models the lamps may be connected to the chassis (e.g. Märklin). In this case you may not wire the return from the lamp to the terminal 2-9. Thus the lamp works against the common return (chassis).

In many models LEDs or 1.5 Volt lamps are used. They can also be operated with LokSoundXL decoders, but not without some preparation: use a 1k Ohm / 0.5 Watt resistor in series with each LED or 1.5 Volt lamp. You also have to reduce the output voltage to 1.5 V by setting the appropriate CV as per Chapter 5.2.3.

When using 1.5 Volt lamps it is not sufficient to reduce the brightness (dimming level) via the CV. Due to the PWM-mechanism the full voltage will be applied for

short intervals. The lamps have to be replaced by others that are suitable for 19 Volts.

3.2.5.3 Connecting auxiliary functions

The function outputs AUX 1 to AUX 6 can be used for many different purposes, such as switching a smoke generator, interior lights, automatic change of headlights according to the rules of the Swiss Railways (SBB), etc. Please note, that the outputs are intended for resistive loads such as lamps, smoke generators, relays, etc. the direct connection of a motor is not recommended due to its inductive peaks. Use a relay to switch the motor.

3.3.6.1 Connecting a wheel sensor

To synchronize the exhaust chuffs with the revs of the drivers an external sensor can be used. The sensor input is available on terminal 1-7.

The LokSoundXL decoder supports reed contacts, mechanical contacts or Hall sensors. Many models (e.g. Bachmann or Märklin®) are supplied complete with mechanical contacts.

3.2.6.2 Connecting a reed contact with magnet

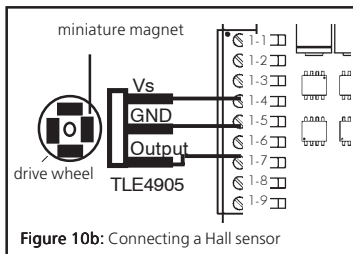
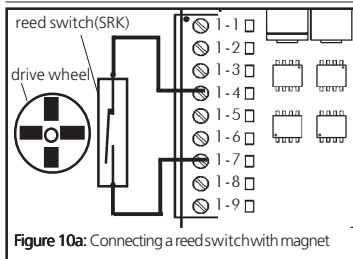
If a reed contact is to be used one miniature magnet (available at hobby shops) for each exhaust chuff must be attached to the driving wheel axle in such a way that the magnet triggers the reed contact once every turn.

Miniature reed contacts have been proven to be very reliable. They are available at special electronics stores. Suitable magnets may be purchased at model train shops. (e.g. mini-track magnets).

3.2.6.3 Connecting a mechanical contact

Many models are supplied complete with a mechanical contact. It has to be connected in the same way as a reed contact, namely to terminals 1-4 and 1-7.

All double pole (mechanical) contacts that are insulated from the chassis may be used.

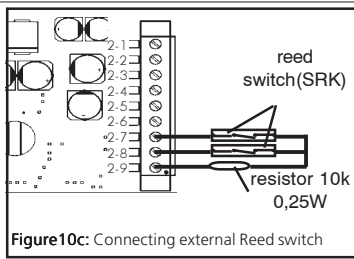


3.2.6.4 Connecting a Hall sensor

A Hall sensor is an electronic circuit that responds to an alternating magnetic field similar to a reed 4.2.1 Using Märklin® 6021.

LokSound decoders may be used with all Märklin® control devices or compatible systems. The functions F1 to F4, however, can only be activated with the „new Motorola® format“. To activate this format put DIP switch 2 of the 6021 to the upper („On“) position. Hall sensors are easier to adjust since the distance between sensor and magnet is not critical. A commonly used hall sensor, that can be purchased via mail order is the TLE4905 by Siemens / Infineon.

The terminal Vs of the TLE4905 has to be wired to terminal 1-4, GND to terminal 1-5 and the Pin Output to terminal 1-7.



3.2.7 Connecting additional reed switch

LokSoundXL decoders have two additional inputs that can trigger various functions. The main purpose of these inputs is to trigger sounds by means of track magnets. A reed switch has to be wired to one of these inputs and a magnet is to be placed at the appropriate location on the layout. Every time the engines passes that spot a sound effect will be triggered.

With the aid of these sensors users of the LGB MZS with Lokmaus can also trigger the many sound effects of the LokSoundXL decoder.

The inputs REED-IN1 and REED-IN2 share the terminals 2-7 and 2-8 with the auxiliary function outputs AUX 5 and AUX 6. Therefore AUX 5 and AUX 6 are not available if you use these inputs.

4. Set Up and installation of the decoder

After successful installation you may now operate the decoder.

The following will outline how you can check if you have installed the decoder correctly. Chapter 4.1 describes analogue operation. In Chapter 4.2 you will learn how to operate LokSound with various digital systems.

Before changing any decoder settings (e.g. engine address, sound volume) we recommend to read Chapter 5. There you will learn which parameters are available and how they may be adjusted with the most common DCC command stations.

After installation you may test the LokSound decoder as follows:

please check all connections carefully using an Ohm-meter: - are there any short circuits between the motor terminals and the wheel pick-ups?

Are all connections between motor terminals and the chassis isolated?

Are lamps connected properly and isolated from the chassis?

Is the decoder installed safely to avoid contact with the chassis?

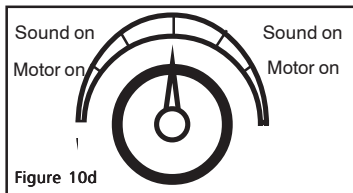
Is there sufficient space around the LokSound decoder to allow for heat dissipation?

Could the LokSound decoder or any of the wires be squeezed when refitting the housing?

Is the speaker installed in such a way that sound can emit from the engine without obstruction?

4.1 Analogue operation

4.1.1 DC operation



Operation using a conventional DC controller is possible without any problems except for one limitation. The engine will only start moving when the track voltage reaches 7–8 Volts. Maximum speed will be reached when turning the controller to the limit. This is absolutely normal and is due to the minimum voltage the LokSound decoder requires for operation. Running sounds are available in this operating mode but not additional sound effects.

4.2 Digital operation

4.1.2 AC operation with conventional Märklin® controller

Operation with conventional Märklin® controllers works as you know it from other models. Speed is controlled by turning the knob.

To change direction the knob has to be turned to the left beyond the stop position.

Please note: The engine must have completely stopped before changing direction. Never change direction while the engine is moving!

4.2.2 Using DCC

LokSound may be operated with any DCC compatible system. When using Lenz digital plus version 3.0 the auto detect function does not work with 14 speed steps. Set 28/128 speed steps at all times. The auto-detect function is activated every time the decoder receives power (when turning on power to the layout) or when you switch on the headlights. During this process the headlights have to be switched on and you have to turn the control knob (or slide control) until the lights burn steadily. Should you change the speed step setting during operation you have to interrupt power to the decoder for a short time in order to reactivate the auto detect function.

4.3 Resetting to factory pre-set values

You may reset the decoder settings to the factory pre-set values at any time. Write value 08 in CV 08. A reset of the sound files is only possible with the aid of the LokProgrammer 53451.

5. Adjusting decoder parameters

Chapter 5 provides information on how to change the settings of LokSound decoders. Please take your time to read and understand the somewhat complex explanations. After the introduction into the world of decoder parameters (called CVs) in Chapter 5.1, you will find in Chapter 5.2 all you need to know about the effects different CVs have on the properties of LokSound decoders.

Chapter 5.3 explains how CVs may be set with various DCC command stations as well as the Märklin® command stations. You will find a complete list of all CVs in Chapter 7.1.

5.1 CVs of LokSound decoders

LokSound decoders are compatible with the NRMA / DCC standard. This means that all parameters controlling the properties of LokSound decoders are stored in so called CVs (Configuration Variables). LokSound decoders support 230 variables. This large number of CVs indicates the multitude of possibilities available with LokSound decoders.

In order to get the best out of your decoder and to easily manage this large number of settings, we recommend the use of our LokProgrammer, part no. 53451.

With the help of the LokProgrammer all CVs may be programmed easily and comfortably on your PC. Please note that CVs that are not programmed properly could impede the performance of the decoder. The LokProgrammer part no. 50450 is not suitable for programming this decoder.

All CVs may be programmed without the LokProgrammer by using any DCC system that is NMRA / DCC compatible or with Märklin® 6021.

Chapter 5.3 explains, how it works.

In each CV, values from 0 to 255 may be stored.

The properties of the decoder vary depending on the stored value. When you check the list of CVs in Chapter 7.1 you will notice that most CVs have numerical values.

For example CV 1 contains the engine address. This number may vary between 1 and 127 (see range of values).

Please note that not all CVs have factory pre-set values:

Some CV values vary depending on the type of sound effect. While most CVs require numerical values, others represent storage locations that manage various functions simultaneously (mostly switching on or off). CVs 29 and 49 are good examples: for these CVs the value has to be calculated individually, depending on the parameters you want to adjust:

First you decide which options should be turned on or off. In the column „value“ you will find two numbers for each option. The value 0 indicates that the option is switched off, otherwise the value may range from 1 to 128. Add all values of the individual options to get the total value to be written into the CV.

Example 1: Let's assume you want to use the Intellibox DCC with 128 speed steps and analogue detection should be active (because you want to control some locos in analogue mode). All other options are turned off. CV 29 shows the value 6 ($0 + 2 + 4 + 0 = 6$).

Example 2: You want to turn the volume of the decoder down. Set CV 63 to a value between 1 and 64, let's say 25.

5.2 Important settings of LokSound

Details of the most important CVs may be found in Chapter 5.2. Please study these instructions carefully before you do any program changes.

Careful deliberation will help you to find the optimal settings to achieve the desired effects with your LokSound decoder.

The factory setting is 3.

5.2.1 Back EMF control (load control)

LokSound decoders utilize fourth generation load control assuring constant speed regardless of the actual load when using DC motors. Load control was optimized and tested with motors from:

- ROCO®,
- Bachmann (Liliput),
- BRAWA®,
- Märklin®,
- LGB,
- Bühler,
- Mabuchi.

Load control may be deactivated (if desired).

Please note that load control is always turned off when using AC motors – no matter what settings are used.

AC motors are not suitable for load control

How to switch on load control

Set the first bit of CV 49. Read out the CV: load control is deactivated if the value is 0 or 2. To activate it, just add 1 to the actual value and enter. Example: CV 49 reads 2. To activate load control set CV 49 to 3. You will find a detailed description of all possible values for CV 49 in Chapter 7.1.

Parameters of Back EMF control

The internally used PI-control algorithm of Back EMF control depends on 3 parameters: the control reference voltage is stored in CV 53, the control parameters are in CVs 54 and 55.

Reference voltage:

In CV 53 you set the voltage that should come back from the motor.

This value depends on the track voltage and the coefficient of utilization of the motor. A coefficient of 75 % and a track voltage of 16 Volts adds up to a voltage of $16\text{ V} * 75\% = 12\text{ Volts}$. This value has to be written into CV 56. The voltage (here: 12 V) may be entered in 0.25V-increments. This results in a value of $30 (12\text{ V} * 2.5)$ for CV 53. If you don't know the exact motor coefficient, you may obtain the value experimentally as follows:

Check if the engine really reaches top speed at the highest speed step or if you cannot detect any speed changes at the maximum speed step. In the latter

case you have to reduce the value for CV 56, in the first case increase the value. The internal PI regulation of LokSound can be adjusted with CV 54 and CV 55. Depending on the type of motor the parameters may have to be adjusted to achieve optimal running performance.

LokSound decoders are factory pre-set for the use with ROCO®, Brawa®- or Kato motors.

Parameter „K“, stored in CV 54, influences how strongly load control will effect the driving performance. The higher the value, the more load control will respond to any changes. Adjust this value with care, because too high values could lead to irregular and „hard“ driving performance. If you prefer smooth running, try to reduce the value step by step until you reach an optimum.

Parameter „I“, stored in CV 55 provides important information to the LokSound decoder regarding the motor type used: certain electric motors respond differently to adjustments of the rpm's. The longer a motor takes to respond, the lower the value in CV 55. However, it is not easy to recognize the degree of inertia. In general: the more poles a motor has and the bigger it is, the more fly wheels it has, the slower it is and the lower the value should be set in CV 55.

For optimal programming proceed as follows:

Read out the value in CV 53 as described above. Leave the value of CV 55 (parameter I..I.) for the time being and test the engine. Now change the value of CV 54 in steps of 5 downwards or upwards and monitor the running properties of the engine. If there is no improvement leave the value of CV 54 and change the value of CV 55 (intensity of control) in steps of 5 until an optimum is reached.

Please note, that incorrectly set parameters may impede the effect of Back EMF control to the point that the motor may stop altogether. Refer to our website <http://www.loksound.de> for suggested values for commonly used motor / drive combinations such as:

Parameters for Fleischmann® motors

Engines with the traditional Fleischmann® motor should be programmed as follows:

CV 54 = about 14 – 18

CV 55 = 20

Parameters for Märklin® high performance motor

The 5-pole high performance motor from Märklin® (series 37xxx) is well suited for the LokSound decoder when programmed as follows:

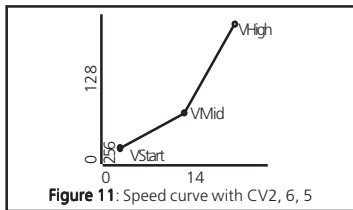
CV 54 = about 20 – 25

CV 55 = 38

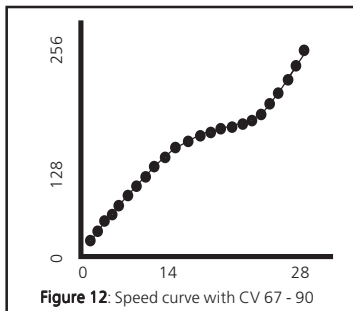
5.2.2 Speed Curve

LokSound decoders recognize 256 internal speed steps. They may be adapted to the characteristics of each engine and assigned to the available speed steps (14, 28 or 128). NMRA allows two choices:

Speed curve via CV 2, 5 and 6 (figure 11).



Set the starting voltage in CV 2 and the maximum speed with CV 5. CV 6 represents the medium speed. You may define the shape of the curve (straight or with two different gradients). This mode is activated via CV 29 (see Chapter 7.1).



You may also define an individual speed curve:

Store the speed curve values in CVs 67 to 94 (as per figure 12). Those 28 values will determine the 256 speed steps. This method permits optimizing the running performance. This mode is also activated via CV 29. We recommend the use of the ESU Lok-Programmer and its software for easy calculation and programming.

5.2.3 Auxiliary function outputs

LokSound decoders have 4 physical function outputs, two for directional lighting, two for auxiliary loads.

Additional 10 functions may be activated by pressing a button to trigger various sound effects.

If you do not want to use the physical function outputs AUX 1 and AUX 2 you may control two additional sound effects (12 in total).

In addition the functions „sound on / off“ and „acceleration on / off“ are available. The latter turns off the acceleration- and deceleration rate and is often used for precise control of the engines particularly while shunting. In „shunting mode“ the speed is halved.

Assignment of function buttons

The outputs may be assigned to the available function buttons. Each function button is linked to a CV in which any number of events may be combined. Page 26-27 shows the different possible combinations and also the ex-factory setting.

Please note:

- Some functions are directional.
- Your DCC command station may not have all necessary function buttons.
- Each of the function outputs must be turned on or off separately.

The value that has to be entered into each individual control-CV is calculated as follows:

Switching on function outputs

Each of the function outputs can / must be turned on, before it can be used. You may program any of eight available lighting effects for each output:

- Dimmer: normal, continuous power to load
- Blinking light: the output blinks with an adjustable frequency
- Inverse blinking light: the output blinks as usual but in opposite sequence. This permits to activate alternately blinking lights.
- Strobe
- Double Strobe
- Random, fire box
- Smoke, for controlling the intensity of the smoke generator
- Zoom
- Mars light
- Gyr light

There is a CV (CV 113 - 120) for each output, in which the desired mode may be stored. Please note that you may deactivate each output by assigning „0“ if it is not needed. CVs 117 – 120 are only available on LokSoundXL.

The lighting outputs are factory pre-set to „on“. In steam engines this is also true for the AUX 1 output that is assigned to the headlight button.

Dimming of lamps

With LokSound you may dim the lamps in 15 steps to adapt the brightness optimally to your model. The lamps are pulsed, i.e.: they are continuously switched on and off. The brightness of each output may be adjusted separately. The desired dimming value (0 to 15) has to be added to the value of the corresponding control-CV (113 - 120) that defines the function mode.

Blinking frequency and duration of „bright period“

If a function output has been set to „blinking“ or „inverse blinking“, the duration of the „bright period“ (defines blinking frequency) and the on / off ratio have to be taken from CV 112 (see Chapter 7.1).

The „bright period“ is adjustable in 33 steps. It is always a multiple of 65.5 milliseconds. The On / Off ratio is adjustable in 16 steps from 1/16 to 16/16. A ratio of 8/16 indicates that the light output remains „on“ for the same period as it is „off“. The value to be entered into the control-CV 113 is calculated as follows:

Duration of „On“ period (value: 0 – 15) *
16 + On / Off ratio

Examples

• Example 1: smoke generator on AUX 1 and F5.

Let's assume you want to control a smoke generator with function button F5 that should be connected to output AUX 1. Please refer to the installation instructions in Chapter 2.5. The output AUX 1 must be activated and assigned to the F5 button:

First we activate the output. In this example we want to use the dimming function (the output must be active continuously) and set at 100% brightness. CV 115 controls output AUX 1 (see paragraph 7.1). The value to be entered in CV 115 is 15 for maximum brightness.

Now we have to assign function button F5 to output AUX 1: refer to figure 13: control-CV 171 controls the F5 button (third column). In CV 171 we enter those functions that should be switched with the F5 button. We look at the table in figure 13, locate the intersection of the row for F5 and column AUX 1 and find the number (in this case 4). Once we enter this value in CV 171 the F5 button controls the output AUX 1. In order to also switch AUX 1 with F5 when reversing the same value has to be entered in CV 174.

• Example 2: blinking light on AUX 2 and F6

We want to connect a „blinking light“ to AUX and control it via the F6 function button. We also want the brightness to be set to 6/15 of the maximum value. The „bright period“ and the „On / Off“ ratio are set as described in paragraph 5.2.3.3.

First we have to activate output AUX 2 and set it to „blinking“. We achieve this by entering 16 (for blinking) + 5 (= 6/15 of maximum brightness) = 21 in CV 116.

Next we assign output AUX 2 to the F6 button. We enter the functions to be controlled via F6 into control-CV 177. Again we consult the table in figure 13, find the intersection between row F6 (forward) and column AUX 2 and enter the number (in this case 8) from the table in CV 177. Now the F6 „forward“ button controls the output AUX 2. To program the same for reversing enter value 8 in CV 183.

• Example 3: Deceleration on / off with F5

Here we want to activate / deactivate the acceleration / deceleration with F5. This function represents a „logical“ function and not a „physical“ output and thus does not have to be configured. We

only have to assign the function „deactivate deceleration“ to the F5 key by entering value 1 in CV 172 (see figure 13). If the same effect should work while reversing enter 1 in CV 175. We recommend a PC and LokProgrammer for programming function outputs:

LokSound decoders offer so many possible combinations that it is recommended to use the LokProgrammer (part no. 53451) in conjunction with a personal computer.

5.2.4 Sound adaptation

LokSound decoders offer many possibilities to adjust sound effects. All parameters are stored in CVs that, like all others, may be modified. Adaptation of revolutions for diesel and pitch for steam exhaust chuffs. The revolutions of a diesel motor may be modified with 2 CVs:

Enter the revolutions of the idling diesel motor in CV 59. The standard value of 32 permits reproduction of the sound at original speed, while value 16 reduces this to half speed.

Enter the revolutions at maximum speed (respectively maximum revs) in CV 60:

Value 255 means double the original speed. Use the same parameters when adapting the pitch of the exhaust chuffs for steam engines:

The interval of the exhaust chuffs should be shorter and vary in pitch with increasing speed.

Specific settings for steam engines

To simulate a steam engine you have to synchronize the exhaust chuffs with the revolutions of the drivers. There are two ways to achieve this:

- With an external wheel sensor
- Speed step dependent

Depending on the method selected, certain CVs have to be set accordingly. LokSound is factory pre-set to speed step dependent adjustment.

Using a wheel sensor

The wheel sensor must be connected as described in Chapter 3.1.6 and 3.2.6. Then two more parameters have to be adjusted:

Set CV 57 to value 0 and enter a value ≥ 1 in CV 58. CV 58 defines after how many pulses by the sensor the next exhaust chuff will be reproduced. Normally one exhaust chuff per pulse should be played.

Speed step dependent method

With this method the interval between exhaust chuffs is set with CV 57 and CV 58. This method is recommended if an external wheel sensor cannot be used.

The adaptation of this variable to the wheel / gearbox combination may require some experiments. It pays to spend some time in order to achieve an optimal result. This feature works best with Back EMF control.

With Märklin® engines with universal motor (Back EMF is always switched off) only a compromise can be reached. I

- Set CV 57 to 10 and CV 58 to 110.
- Put the engine onto the track and drive it with speed step 1 (sound is switched on).
- Measure the time in seconds it takes the driver to complete one turn at this speed.
- Divide the time by 0.064.
- Enter a rounded value without decimal points in CV 57, e.g. 0.9 seconds / 0.064 = 14-5= Value 9.
- Increase the speed and check whether the exhaust chuffs match the turns of the drivers.

If the exhaust chuffs are too fast, increase the value in CV 58 gradually, if they are too slow, decrease the value in CV 58.

In this case we recommend the use of an external wheel sensor. For CV adaptation proceed as follows:

Adjusting the volume by CV

The volume of LokSound decoders may be adapted gradually. For the master volume, enter the desired value in CV 63. Permitted values are: 0 (quiet) to 64 (loud).

However, for controlling the volume of the horn, there exists CV 121. You can enter the desired volume level here.

For the volume of the bell, CV122 is responsible and with CV123, you can control the volume of the other auxiliary sounds.

Mute / Adjusting volume by function key

The LokSound V3.5 decoders offers a mute function. You can enable the mute by pressing the F8 button.

For LokSound V3.5, you can also easily adjust the volume during normal operation by the F8 function button: Press the F8 button two times quickly in series. Each time you do this, the volume is increased by one step up to the max. After you have reached the maximum volume, the volume is reset to the lowest value again. You can toggle through 4 different volume levels.

Random sound effects

CV 61 and CV 62 define the frequency of random sounds that are played while a steam engine is stationary. CV 61 contains the minimal time between 2 random sounds, CV 62 the maximum. Both represent an interval in which LokSound randomly selects and plays sounds. The unit of both CVs is 1.0 second.

Example: the minimum interval in CV 61 should be 8 seconds. Enter 8 into CV 61. The maximum interval in CV 62 should be 30 seconds. Enter 30 in CV 62.

Doppler effect

LokSound V3.5 offers a Doppler effect. While blowing the horn by pressing the F2 button, release the F2 button for a very short time and press the button again. This will enable the doppler mode: The horn continues to blow, but - depending on the actual speed- the pitch of the horn- and prime mover sounds are lowered.

You can end the Doppler by releasing the horn button. After some 5 seconds, the horn and diesel engine will return to their normal operation.

5.2.5 Brake sections

LokSound decoders respond to the most commonly used brake generators on the market:

- Lenz-brake generator in DCC operation
- Märklin® brake track

As soon as the LokSound decoder recognizes a brake command it brakes with the deceleration set in CV 4. After this forced stop (once the signal aspect has changed) the engine begins to move again and

accelerates according to the value set in CV 3. In order to support this function some CVs have to be programmed. This feature is activated in CV 51.

Lenz brake generator

The Lenz brake generator LG 100 uses the mechanisms recommended by the NMRA standards and is supported by LokSound decoders. Write value 8 in CV 51.

Märklin® brake track

Instead of digital signals the Märklin® brake track supplies a DC voltage to the tracks. To activate this you must write 1 in CV 51. Do not activate the Märklin® brake track and the analogue DC operation at the same time, because the DC supplied by the Märklin® brake track could be interpreted as analogue DC. With CV 50 you can switch off the analogue mode (see paragraph 7.1).

5.2.6. Märklin® address

In order to be able to use functions F5 to F9 with the Märklin® 6021 command station LokSound decoders have a second Märklin® address. It is always the following number to the actual address. Set bit 3 in CV 49.

5.2.7 Speed settings for DC operation

You can individually adjust the starting voltage and the maximum speed for the conventional DC operation. CV 125 is responsible for starting voltage. The higher the value is, the more voltage is applied to the motor when started. For the maximum speed in DC mode, you can reduce it by lowering the value stored in CV 126.

5.3 Adjusting CVs

After having been introduced to the effects controlled by CVs in Chapters 5.1 and 5.2 we now need to clarify how to set the CVs. In principle there are 3 possibilities:

- With a PC and LokProgrammer (article no. 53451)
- With a DCC compatible digital command station (e.g. Intellibox, Lenz digital plus)
- With Märklin® 6021

Depending on the system used the procedure varies

5.3.1 Using the LokProgrammer

The LokProgrammer by **ESU GmbH & Co. KG** offers the easiest method to adjust CVs of LokSound decoders:

It is done with a mouse click using your MS-Windows® computer. The LokProgrammer eliminates searching for various CV numbers and values. With the LokProgrammer you can modify the sounds of LokSound decoders and you may also create your own sound effects.

The LokProgrammer (order no. 53451) is available at model train outlets complete with detailed operating instructions.

The LokProgrammer part no. 50450 is not suitable for programming LokSound decoders version 3.5.

5.3.2 Using DCC systems

There is no „one fits all“ instruction for programming CVs with various DCC systems. There are too many differences between the popular DCC systems. Whenever possible you should use the DCC direct mode or DCC paged mode.

Lenz digital plus

There are various software versions available of the Lenz digital plus command station. You need firmware version 2.3 or 3.0 in order to program LokSound decoders. Contact Lenz for more details regarding upgrades of older versions.

Use „paged CV“ mode for programming. Depending on the firmware version the „CV mode“ might cause problems.

Older command stations such as „Digital plus“, „Lenz compact“ and „Arnold Digital“ create another phenomenon:

Programming is not possible.

The Lenz command station displays „err02“, the Arnold command station „short circuit“:

This is caused by the very sensitive overload protection of the digital system. The LokSound decoder with the built in audio amplifier uses a higher current than other decoders and thus triggers the overload protection. To rectify this, solder a 47 Ohm (0.5 Watt) resistor in one of the two wires connecting the digital command station with the programming track. See figure 13.

5.3.3 Using Märklin® 6021

With the Märklin® command station you cannot modify standard CVs as it does not comply with the NMRA DCC standards. However, the most important CVs of LokSound decoders may be changed with a specific programming mode.

Please note: this applies only to CVs from 1 to 79, and only for values from 1 to 79.

Programming mode for 6021:

Set the drive control knob to 0. Remove any other engines from the track. Observe the blinking signals of the engine! Press the „stop“- and „go“ button of the 6021 simultaneously until a reset has been triggered. Alternately you can remove the power plug for a moment. Press the „stop“ button in order to switch off the track voltage. Enter the current decoder address (alternately: 80).

- Confirm by activating change of direction (turning the control knob beyond the stop position towards the left) and hold the knob, then press the „go“ button.
- The LokSound decoder is now in programming mode (headlights are blinking). Now enter the number of the parameter (CV) you want to change (two digit number).
- Confirm by activating change of direction (double blinking headlights).
- Now enter the new value for the CV (2 digits).
- Confirm by activating change of direction (headlights light up for about 1 second, then continue blinking).
- Now you can continue with other CVs in the same manner.

- To exit the programming mode select CV 80 or switch off the track voltage for a moment (press „stop“ button followed by „go“ button on 6021). Please note that 6021 only permits entries from 01 to 80. There is no value „0“, instead always enter 80.

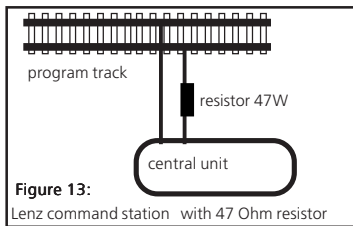


Figure 13:

Lenz command station with 47 Ohm resistor

6. Frequently asked questions (FAQ)

Usually there is no fault in the LokSound decoder if it does not work as desired but very likely some CVs are set incorrectly. Here are some examples of what may happen and how to solve the problem:

- Headlights and sound work, write CVs as well, but the engine does not move.

A short circuit on the motor terminals or a high current draw may trigger the overload protection. Perhaps the motor is not fully insulated against the chassis. To eliminate this as the cause of the malfunction, remove the motor and test-run it while outside the engine.

If load control is deactivated the starting voltage may be too low (CV 2).

- The engine jerks and runs very uneven at low speed with activated load control.

Deactivate load control and check if the problem remains (refer to Chapter 5.2.1). If the problem disappears then the parameters for load control have to be adjusted (as per 5.2.1).

- The engine runs perfectly, but there is no sound. Check the wires to the speaker.

With the Märklin® 6021 the new Motorola format has to be used, otherwise the F1 button does not work (refer to Chapter 4.2.1). If the format is set correctly, the speaker may be damaged.

- The engine runs perfectly, but the headlights do not work or switch on and off depending on the speed step.

If you have an engine with DCC socket, check if the plug has been inserted in the correct position (refer to Chapter 3.2).

- If you operate LokSound in DCC mode please refer to Chapter 4.2.2 where the solution to this problem is described.
- I would like to reset the LokSound decoder to the factory settings. What do I have to do?

With the aid of a PC and the LokProgrammer software a reset is easily achieved. If you only want to reset the CVs write value 8 in CV 8.

- I have read the instruction carefully but still have problems. What can I do?

If you have further questions regarding LokSound decoders please contact our Technical Customer Service.

Contact details are listed in Chapter 8 on page 50 of this Manual.

Should you have come to the conclusion you do not want to install decoders yourself we can offer you another solution:

ESU electronic solutions ulm GmbH & Co. KG offers an installation service in conjunction with experienced specialists.

Ask your dealer for the new ESU service pack: We arrange for installation of your decoder: comfortable and without risk for you!

7. List of all supported CVs

The following pages provide a list of all CVs of LokSound decoders. Please refer to the remarks regarding the concept of CVs in Chapter 5.1.

Change CVs only if you have a clear understanding of the implications. Incorrect settings may lead to malfunctioning decoders.

Function Mapping

Function Button	Description	Control CV A	Headlight	Back-Up Lights	AUX 1	AUX 2	AUX 3 only LokSoundXL	AUX 4 only LokSoundXL	AUX 5 only LokSoundXL	AUX 6 only LokSoundXL	
	value		1	2	4	8	16	32	64	128	
	stand forward	129									
	stand backward	132									
	drive forward	135									
	drive backward	138									
F0	light forward	141	1		4						
F0	light backward	144		2	4						
F1	key F1 forward	147									
F1	key F1 backward	150									
F2	key F2 forward	153									
F2	key F2 backward	156									
F3	key F3 forward	159									
F3	key F3 backward	162									
F4	key F4 forward	165									
F4	key F4 backward	168									
F5	key F5 forward	171									
F5	key F5 backward	174									
F6	key F6 forward	177									
F6	key F6 backward	180									
F7	key F7 forward	183									
F7	key F7 backward	186									
F8	key F8 forward	189									
F8	key F8 backward	192									
F9	key F9 forward	195									
F9	key F9 backward	198									
F10	key F10 forward	201									
F10	key F10 backward	204									
F11	key F11 forward	207									
F11	key F11 backward	210									
F12	key F12 forward	213									
F12	key F12 backward	216									
F13	key F13 forward	219									
F13	Key 13 backward	222									
F14	Key 14 forward	225									
F14	key 14 backward	228									
F15	Key 15 forward	231									
F15	Key 15 backward	234									
	sensor 1 forward	237									
	sensor 1 backward	240									
	sensor 2 forward	243									
	sensor 2 backward	246									

Function Mapping

	Control CV B	Acceleration On / Off	Shunting mode On / Off	Sound On / Off	Shift Mode	Blower	Doppler ON Sound Slot 1	Mute / Volume Control	Dynamic brake	Control CV	Sound Slot 1-16
	value	1	2	4	8	16	32	64	128	value	0, 1-16
	130									131	
	133									134	
	136									137	
	139									140	
	142									143	
	145									146	
	148			4						149	
	151			4						152	
	154						32			155	1
	157						32			158	1
	160									161	2
	163									164	2
	166									167	3
	169									170	3
	172									173	4
	175									176	4
	178	1	2							179	0
	181	1	2							182	0
	184									185	5
	187									188	5
	190							64		191	6
	193							64		194	6
	196									197	
	199									200	
	202									203	
	205									206	
	208									209	
	211									212	
	214									215	
	217									218	
	220									221	
	223									224	
	226									227	
	229									230	
	231									232	
	235									236	
	238									239	
	241									242	
	244									245	
	247									248	

List of all supported CVs

CV	Name	Description	Range	Default		
1	Engine address	Address of engine	1-127	3		
2	Start voltage	Sets the minimum speed of the engine	1-75	3		
3	Acceleration	This value multiplied by 0.869 is the time from stop to maximum speed	0-64	8		
4	Deceleration	This value multiplied by 0.869 is the time from maximum speed to stop	0-64	6		
5	Maximum speed	Maximum speed of engine	0-64	64		
6	Medium speed	Medium speed of engine	0-64	22		
7	Version number	Internal software version of LokSound decoder				
8	Manufacturer's ID	Manufacturer's ID - ESU – Writing value 8 in this CV triggers a reset to factory values		151		
13	Analogue mode F1-F8	Status of functions F1 to F8 in analogue mode	0-255	0		
		Bit			Description	value
		0			function F1	1
		1			function F2	2
		2			function F3	4
		3			function F4	8
		4			function F5	16
		5			function F6	32
		6			function F7	64
7	function F8	128				
14	Analogue mode FL, F9-F12	Status of functions FL, F9 to F12 in analogue mode	0-255	3		
		Bit			Description	value
		0			function FL (f)	1
		1			function FL (r)	2
		2			function F9 (f)	4
		3			function F10 (f)	8
		4			function F11	16
		5			function F12	32
		6			function F9 (r)	64
7	function F10 (r)	128				
17 18	Extended engine address	long address of engine CV17 contains byte with higher value (bit 6 and 9999, bit 6 and bit 7 must always be active), CV18 contains byte with lower value. Only active when function is switched on in CV 29 (see below).	128 9999	192		
19	Consist address	Additional address for consist value 0 or 128 means: consist address deactivated 1-127 consist address, normal direction 129-255 consist address, reverse direction	0-255	0		

List of all supported CVs

CV	Name	Description	Range	Default
21	Consist mode F1-F8	Status of functions F1 to F8 in consist mode	0-255	0
		Bit Description value		
		0 function F1		
		1 function F2		
		2 function F3		
		3 function F4		
		4 function F5		
		5 function F6		
		6 function F7		
		7 function F8		
22	Consist mode FL, F9-F12	Status of functions FL, F9 to F12 in consist mode	0-255	0
		Bit Description value		
		0 function FL (f)		
		1 function FL (r)		
		2 function F9 (f)		
		3 function F10 (f)		
		4 function F11		
		5 function F12		
		6 function F9 (r)		
		7 function F10 (r)		
29	Configuration register	The most complex CV within the DCC standards. This register contains important information, which is only relevant in DCC mode.		4
		Bit function value		
		0 Reverse direction of travel (forward becomes reverse) normal direction reversed direction		
		1 speed steps (only for DCC mode) 14 speed steps 28 or 128 speed steps		
		2 analogue operation analogue operation off analogue operation on		
		4 selection of speed curve speed curve through CV 2,5, 6 speed curve through CV 67 – 96		
		5 selection of engine address (only for DCC operation) short addresses (CV 1) in DCC mode long addresses (CV 17 + 18) in DCC mode		

List of all supported CVs

CV	Name	Description	Range	Default
49	Extended configuration	Activate support for brake sections or switch off Back EMF control	0-255	19
		Bit description		
		0 load control off load control activated		
		1 DC motor PWM frequency 15 kHz pulse frequency 30 kHz pulse frequency		
		2 Märklin® delta mode Delta mode off Delta mode on		
		3 Märklin® second address second address off second address on		
		4 Automatic speed step detection DCC speed step detection off DCC speed step detection on		
		5 LGB function button mode LGB mode off LGB mode on		
		6 Zimo manual function Zimo manual function off Zimo manual function on		
		7 Function key toggle mode Sound triggered by off2on only Sound triggered by off2on and on2off		
50	Analogue mode	Selection of desired analogue mode	0-3	3
		bit description		
		0 AC analogue mode AC analogue mode off AC analogue mode on		
		1 DC analogue mode DC analogue mode off DC analogue mode on		
51	Brake mode	Selection of desired brake mode		3
		Bit description		
		0 Märklin® brake mode Märklin® brake mode off Märklin® brake mode on		
		1 Zimo brake mode Zimo brake mode off Zimo brake mode on		
		2 not used		
		3 Lenz DC brake mode Lenz brake mode off Lenz brake mode on		

List of all supported CVs

CV	Name	Description	Range	Default
52	Helper mode	Select the helper mode setting whilst consist mode is active		0
		description		
		Helper mode off, use CV 21, 22 only		
		locomotive is head-of-consist		
53	Control reference	locomotive is mid-of-consist	0-80	56
		locomotive is end-of-consist		
		locomotive is standalone		
54	Load control parameter K	Defines the Back EMF voltage, which the motor should generate at maximum speed. The higher the efficiency of the motor, the higher this value may be set. If the engine does not reach maximum speed, reduce this parameter.	0-80	32
55	Load control parameter I	K-component of internal PI-controller Defines the effect of load control. The higher the value, the stronger the effect of Back EMF control	0-80	24
56	Operating range of load control	„I“-component of internal PI-controller Defines momentum (inertia) of motor. The higher the momentum of the motor (large flywheel or bigger diameter motor) the lower this value has to be set (see Chapter 5.2.1)	0-64	64
57	Sound mode 1	0 – 100% Defines up to which speed in % load control will be active. A value of 32 indicates that load control will be effective up to half speed.	0-127	20
58	Sound mode 2	Multiplied by 0,64 is the time in seconds between two chuff sounds at speed step 1. Value 0 indicates that period between exhaust chuffs is controlled by a wheel sensor	Steam: 0 Diesel: 0	50
59	Sound	Value defines the gradual decrease of intervals of exhaust chuffs with increasing speed. A higher value indicates a more rapid decrease, a lower value a slower decrease. If exhaust chuffs are triggered by a wheel sensor (if CV 57 = 0), this value specifies the number of trigger pulses required for one exhaust chuff.	Steam: 115 Diesel: 0 Electric: 0	95
60	Sound	Divided by 32 this will yield the factor for reproducing the sound at the slowest speed step. Values < 32 are slower, values > 32 are faster than original speed.	0-64	32
61	Sound	Divided by 32 this will yield the factor for reproducing the sound at the fastest speed step values < 32 are slower, values > 32 are faster than original speed.	0-64	48

List of all supported CVs

CV	Name	Description	Range	Default																														
61	Random sound min	Multiplied by 1 is the time in seconds for the shortest random sound interval. These values represent the interval between random sounds.	0-64	30																														
62	Random sound max	Multiplied by 1 is the time in seconds for the longest interval between random sounds. These values represent the interval between random sounds. Playing of random sounds is deactivated when CV 61 and CV 62 = 0	0-64	50																														
63	Sound volume	volume of running and additional sounds	0-64	64																														
64	Brake sound threshold	Specifies when the decoder starts the braking noises. The higher the value, the sooner it will start. If CV 64= 0, the braking sound is only played once the engine has stopped.	0-64	7																														
66	Forward trim	Divided by 128 is the factor used to multiply the motor voltage when driving forward. Value 0 deactivates the trim.	0-255	0																														
67-94	Speed table	Defines motor voltage for speed steps. The values „in between“ will be interpolated.	0-255	-																														
95	Reverse trim	Divided by 128 is the factor used to multiply the motor voltage when driving backwards. Value 0 deactivates the trim	0-255	0																														
112	Blinking light	Blinking frequency of Strobe effects. Always a multiple of 65.536 milliseconds	4-64	33																														
113	Headlight configuration	<table><tr><td colspan="2">configuration of headlights</td></tr><tr><td>description</td><td>value</td></tr><tr><td>continuous (dimmer)</td><td>Vol</td></tr><tr><td>blinking (phase 1)</td><td>Vol + 16</td></tr><tr><td>blinking (phase 2)</td><td>Vol + 32</td></tr><tr><td>Strobe light</td><td>Vol +48</td></tr><tr><td>Double Strobe light</td><td>Vol + 64</td></tr><tr><td>Fire box</td><td>Vol +80</td></tr><tr><td>Smoke generator</td><td>Vol +96</td></tr><tr><td>Headlight bright/dim</td><td>Vol +112</td></tr><tr><td>Mars light</td><td>Vol + 128</td></tr><tr><td>Gyra light</td><td>Vol + 144</td></tr><tr><td>Rule 17 for head light</td><td>Vol + 160</td></tr><tr><td>Rule 17 for rear light</td><td>Vol + 176</td></tr><tr><td colspan="2">Vol = brightness. Range 0 (dark) – 15 (maximum)</td></tr></table>	configuration of headlights		description	value	continuous (dimmer)	Vol	blinking (phase 1)	Vol + 16	blinking (phase 2)	Vol + 32	Strobe light	Vol +48	Double Strobe light	Vol + 64	Fire box	Vol +80	Smoke generator	Vol +96	Headlight bright/dim	Vol +112	Mars light	Vol + 128	Gyra light	Vol + 144	Rule 17 for head light	Vol + 160	Rule 17 for rear light	Vol + 176	Vol = brightness. Range 0 (dark) – 15 (maximum)		0-255	15
configuration of headlights																																		
description	value																																	
continuous (dimmer)	Vol																																	
blinking (phase 1)	Vol + 16																																	
blinking (phase 2)	Vol + 32																																	
Strobe light	Vol +48																																	
Double Strobe light	Vol + 64																																	
Fire box	Vol +80																																	
Smoke generator	Vol +96																																	
Headlight bright/dim	Vol +112																																	
Mars light	Vol + 128																																	
Gyra light	Vol + 144																																	
Rule 17 for head light	Vol + 160																																	
Rule 17 for rear light	Vol + 176																																	
Vol = brightness. Range 0 (dark) – 15 (maximum)																																		

List of all supported CVs

CV	Name	Description	Range	Default
114	Back-up light configuration	configuration of back-up lights	0-255	15
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Vol = brightness. Range 0 (dark) – 15 (maximum)		
115	AUX 1 configuration	configuration of output AUX 1	0-255	15
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Vol = brightness. Range 0 (dark) – 15 (maximum)		

List of all supported CVs

CV	Name	Description	Range	Default
116	AUX 2 configuration	configuration of output AUX 2	0-255	15
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Vol = brightness. Range 0 (dark) – 15 (maximum)		
117	AUX 3 configuration LokSoundXL only	configuration of output AUX 3	0-255	0
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Vol = brightness. Range 0 (dark) – 15 (maximum)		

List of all supported CVs

CV	Name	Description	Range	Default
118	AUX 4 configuration LokSoundXL only	configuration of output AUX 4	0-255	0
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Vol = brightness. Range 0 (dark) – 15 (maximum)		
119	AUX 5 configuration LokSoundXL only	configuration of output AUX 5	0-255	0
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Input REED-IN Sensor 1		
		Vol = brightness. 0 (dark) – 15 (maximum)		

List of all supported CVs

CV	Name	Description	Range	Default
120	AUX 6 configuration LokSoundXL only	configuration of output AUX 6	0-255	0
		description		
		continuous (dimmer)		
		blinking (phase 1)		
		blinking (phase 2)		
		Strobe light		
		Double Strobe light		
		Fire box		
		Smoke generator		
		Headlight bright/dim		
		Mars light		
		Gyra light		
		Rule 17 for head light		
		Rule 17 for rear light		
		Input REED-IN Sensor 1		
		240		
		Vol = brightness. Range 0 (dark) – 15 (maximum)		
121	Sound volume #1	volume of horn	0-64	64
122	Sound volume #2	volume of bell	0-64	64
123	Sound volume #3	volume of auxiliary sound effects	0-64	64
124	Auxiliary settings	controls auxiliary settings of the LokSound decoder		
		description		
		value		
		Store direction (for Märklin use only)		
		1		
		Store function state	2	
		Store current speed setting	4	
		Start again with acceleration ramp	8	
125	the value multiplied by	0.2 is the Voltage of engine in DC mode at speed value 1	0-127	110
126	the value multiplied by	0.2 is the voltage of engine in DC mode at speed value 127	0-127	127
127	the value multiplied by	0.2 is the voltage of engine in AC mode at speed value 1	0-127	50
128	the value multiplied by	0.2 is the voltage of engine in AC mode at speed value 127	0-127	127
129	Assignment of function button „stop“ forward A	Assignment of function outputs that are activated in status „stop – forward“	0-255	0
		bit description		
		value		
		0 headlights		
		1		
		back-up lights		
		2		
		function output AUX 1		
		4		
		function output AUX 2		
		8		
		function output AUX 3 (XL only)	16	
		function output AUX 4 (XL only)	32	
		function output AUX 5 (XL only)	64	
		function output AUX 6 (XL only)	128	

List of all supported CVs

CV	Name	Description	Range	Default
130	Assignment of function button „stop“ forward B	Assignment of function outputs that are activated in status „stop – forward“	0-255	0
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
131	Assignment of function button „stop“ forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
132	Assignment of function button „stop“ back-up A	Assignment of function outputs that are activated in status „stop – back-up“	0-255	0
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		
133	Assignment of function button „stop“ back-up B	Assignment of function outputs that are activated in status „stop – back-up“	0-255	0
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
134	Assignment of function button „stop“ back-up C	Defines, which sound will be activated with the given function button. 0= no sound, 1-16= No. of sound slot	0, 1-16	0

List of all supported CVs

CV	Name	Description	Range	Default
135	Assignment of function button „running“ forward A	Assignment of function outputs that are activated in status „running – forward“	0-255	0
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		
136	Assignment of function button „running“ forward B	Assignment of function outputs that are activated in status „running – forward“	0-255	0
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
137	Assignment of function button „running“ forward C	Defines, which sound will be activated with the given function button in status „running – forward“ 0= no sound, 1-16= No. of sound slot	0, 1-16	0
138	Assignment of function button „running“ back-up A	Assignment of function outputs that are activated in status „running – back-up“	0-255	0
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		

List of all supported CVs

CV	Name	Description	Range	Default
139	Assignment of function button „running“ back-up B	Assignment of function outputs that are activated in status „running – back-up“	0-255	0
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
140	Assignment of function button „running“ back-up C	Defines, which sound will be activated with the given function button in status „running – back-up“ 0= no sound, 1-16= No. of sound slot	0, 1-16	0
141	Assignment of function button headlight forward A	Assignment of function outputs that are activated in status „headlight – forward“	0-255	0
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		
142	Assignment of function button headlight forward B	Assignment of function outputs that are activated in status „headlight – forward“	0-255	0
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
143	Assignment of function button headlight forward C	Defines, which sound will be activated with the given function button in status „headlight – forward“ 0= no sound, 1-16= No. of sound slot	0, 1-16	0

List of all supported CVs

CV	Name	Description	Range	Default
144	Assignment of function button headlight reverse A	Assignment of function outputs that are activated in status „headlight – reverse“	0-255	2
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		
145	Assignment of function button headlight reverse B	Assignment of function outputs that are activated in status „headlight – reverse“	0-255	0
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
146	Assignment of function button headlight reverse C	Defines, which sound will be activated with the given function button in status „headlight – reverse“ 0= no sound, 1-16= No. of sound slot	0, 1-16	0
147	Assignment of function button F1 forward A	Assignment of function outputs that are activated with „F1 - forward“	0-255	0
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		

List of all supported CVs

CV	Name	Description	Range	Default
148	Assignment of function button F1 forward B	Assignment of function outputs that are activated with „F1 - forward“	0-255	4
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
149	Assignment of function button F1 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
150	Assignment of function button F1 reverse A	Assignment of function outputs that are activated with „F1 - reverse“	0-255	0
		bit description value		
		0 headlights 1		
		1 back-up lights 2		
		2 function output AUX 1 4		
		3 function output AUX 2 8		
		4 function output AUX 3 (XL only) 16		
		5 function output AUX 4 (XL only) 32		
		6 function output AUX 5 (XL only) 64		
		7 function output AUX 6 (XL only) 128		
151	Assignment of function button F1 reverse B	Assignment of function outputs that are activated with „F1 - reverse“	0-255	4
		bit description value		
		0 acceleration on / off 1		
		1 shunting mode on / off 2		
		2 sound on / off 4		
		3 shift mode 8		
		4 blower sound 16		
		5 Doppler On Sound Slot 1 32		
		6 Mute / Volume Control 64		
		7 Dynamic Brake 128		
152	Assignment of function button F1 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0

List of all supported CVs

CV	Name	Description	Range	Default
153	Assignment of function button F2 forward A	Assignment of function outputs that are activated with „F2 - forward“ description refer to CV 147	0-255	0
154	Assignment of function button F2 forward B	Assignment of function outputs that are activated with „F2 - forward“ description refer to CV 148	0-255	0
155	Assignment of function button F2 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	1
156	Assignment of function button F2 reverse A	Assignment of function outputs that are activated with „F2 - reverse“ description refer to CV 150	0-255	0
157	Assignment of function button F2 reverse B	Assignment of function outputs that are activated with „F2 - reverse“ description refer to CV 151	0-255	0
158	Assignment of function button F2 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	1
159	Assignment of function button F3 forward A	Assignment of function outputs that are activated with „F3 - forward“ description refer to CV 147	0-255	0
160	Assignment of function button F3 forward B	Assignment of function outputs that are activated with „F3 - forward“ description refer to CV 148	0-255	0
161	Assignment of function button F3 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	2
162	Assignment of function button F3 reverse A	Assignment of function outputs that are activated with „F3 - reverse“ description refer to CV 150	0-255	0
163	Assignment of function button F3 reverse B	Assignment of function outputs that are activated with „F3 - reverse“ description refer to CV 151	0-255	0
164	Assignment of function button F3 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	2
165	Assignment of function button F4 forward A	Assignment of function outputs that are activated with „F4 - forward“ description refer to CV 147	0-255	0

List of all supported CVs

CV	Name	Description	Range	Default
166	Assignment of function button F4 forward B	Assignment of function outputs that are activated with „F4 - forward“ description refer to CV 148	0-255	0
167	Assignment of function button F4 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	3
168	Assignment of function button F4 reverse A	Assignment of function outputs that are activated with „F4 - reverse“ description refer to CV 150	0-255	0
169	Assignment of function button F4 reverse B	Assignment of function outputs that are activated with „F4 - reverse“ description refer to CV 151	0-255	0
170	Assignment of function button F4 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	3
171	Assignment of function button F5 forward A	Assignment of function outputs that are activated with „F5 - forward“ description refer to CV 147	0-255	0
172	Assignment of function button F5 forward B	Assignment of function outputs that are activated with „F5 - forward“ description refer to CV 148	0-255	0
173	Assignment of function button F5 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	4
174	Assignment of function button F5 reverse A	Assignment of function outputs that are activated with „F5 - reverse“ description refer to CV 150	0-255	0
175	Assignment of function button F5 reverse B	Assignment of function outputs that are activated with „F5 - reverse“ description refer to CV 151	0-255	0
176	Assignment of function button F5 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	4
177	Assignment of function button F6 forward A	Assignment of function outputs that are activated with „F6 - forward“ description refer to CV 147	0-255	0
178	Assignment of function button F6 forward B	Assignment of function outputs that are activated with „F6 - forward“ description refer to CV 148	0-255	3

List of all supported CVs

CV	Name	Description	Range	Default
179	Assignment of function button F6 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
180	Assignment of function button F6 reverse A	Assignment of function outputs that are activated with „F6 - reverse“ description refer to CV 150	0-255	0
181	Assignment of function button F6 reverse B	Assignment of function outputs that are activated with „F6 - reverse“ description refer to CV 151	0-255	3
182	Assignment of function button F6 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
183	Assignment of function button F7 forward A	Assignment of function outputs that are activated with „F7 - forward“ description refer to CV 147	0-255	0
184	Assignment of function button F7 forward B	Assignment of function outputs that are activated with „F7 - forward“ description refer to CV 148	0-255	0
185	Assignment of function button F7 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	5
186	Assignment of function button F7 reverse A	Assignment of function outputs that are activated with „F7 - reverse“ description refer to CV 150	0-255	0
187	Assignment of function button F7 reverse B	Assignment of function outputs that are activated with „F7 - reverse“ description refer to CV 151	0-255	0
188	Assignment of function button F7 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	5
189	Assignment of function button F8 forward A	Assignment of function outputs that are activated with „F8 - forward“ description refer to CV 147	0-255	0
190	Assignment of function button F8 forward B	Assignment of function outputs that are activated with „F8 - forward“ description refer to CV 148	0-255	0
191	Assignment of function button F8 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	6
192	Assignment of function button F8 reverse A	Assignment of function outputs that are activated with „F8 - reverse“ description refer to CV 150	0-255	0

List of all supported CVs

CV	Name	Description	Range	Default
193	Assignment of function button F8 reverse B	Assignment of function outputs that are activated with „F8 - reverse“ description refer to CV 151	0-255	0
194	Assignment of function button F8 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	6
195	Assignment of function button F9 forward A	Assignment of function outputs that are activated with „F9 - forward“ description refer to CV 147	0-255	0
196	Assignment of function button F9 forward B	Assignment of function outputs that are activated with „F9 - forward“ description refer to CV 148	0-255	0
197	Assignment of function button F9 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
198	Assignment of function button F9 reverse A	Assignment of function outputs that are activated with „F9 - reverse“ description refer to CV 150	0-255	0
199	Assignment of function button F9 reverse B	Assignment of function outputs that are activated with „F9 - reverse“ description refer to CV 151	0-255	0
200	Assignment of function button F9 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
201	Assignment of function button F10 forward A	Assignment of function outputs that are activated with „F10 - forward“ description refer to CV 147	0-255	0
202	Assignment of function button F10 forward B	Assignment of function outputs that are activated with „F10 - forward“ description refer to CV 148	0-255	0
203	Assignment of function button F10 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
204	Assignment of function button F10 reverse A	Assignment of function outputs that are activated with „F10 - reverse“ description refer to CV 150	0-255	0
205	Assignment of function button F10 reverse B	Assignment of function outputs that are activated with „F10 - reverse“ description refer to CV 151	0-255	0
206	Assignment of function button F10 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0

List of all supported CVs

CV	Name	Description	Range	Default
207	Assignment of function button F11 forward A	Assignment of function outputs that are activated with „F11 - forward“ description refer to CV 147	0-255	0
208	Assignment of function button F11 forward B	Assignment of function outputs that are activated with „F11 - forward“ description refer to CV 148	0-255	0
209	Assignment of function button F11 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
210	Assignment of function button F11 reverse A	Assignment of function outputs that are activated with „F11 - reverse“ description refer to CV 150	0-255	0
211	Assignment of function button F11 reverse B	Assignment of function outputs that are activated with „F11 - reverse“ description refer to CV 151	0-255	0
212	Assignment of function button F11 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
213	Assignment of function button F12 forward A	Assignment of function outputs that are activated with „F12 - forward“ description refer to CV 147	0-255	0
214	Assignment of function button F12 forward B	Assignment of function outputs that are activated with „F12 - forward“ description refer to CV 148	0-255	0
215	Assignment of function button F12 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
216	Assignment of function button F12 reverse A	Assignment of function outputs that are activated with „F12 - reverse“ description refer to CV 150	0-255	0
217	Assignment of function button F12 reverse B	Assignment of function outputs that are activated with „F12 - reverse“ description refer to CV 151	0-255	0
218	Assignment of function button F12 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
219	Assignment of function button F13 forward A	Assignment of function outputs that are activated with „F13 - forward“ description refer to CV 147	0-255	0

List of all supported CVs

CV	Name	Description	Range	Default
220	Assignment of function button F13 forward B	Assignment of function outputs that are activated with „F13 - forward“ description refer to CV 148	0-255	0
221	Assignment of function button F13 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
222	Assignment of function button F13 reverse A	Assignment of function outputs that are activated with „F13 - reverse“ description refer to CV 147	0-255	0
223	Assignment of function button F13 reverse B	Assignment of function outputs that are activated with „F13 - reverse“ description refer to CV 148	0-255	0
224	Assignment of function button F13 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
225	Assignment of function button F14 forward A	Assignment of function outputs that are activated with „F14 - forward“ description refer to CV 147	0-255	0
226	Assignment of function button F14 forward B	Assignment of function outputs that are activated with „F14 - forward“ description refer to CV 148	0-255	0
227	Assignment of function button F14 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
228	Assignment of function button F14 reverse A	Assignment of function outputs that are activated with „F14 - reverse“ description refer to CV 150	0-255	0
229	Assignment of function button F14 reverse B	Assignment of function outputs that are activated with „F14 - reverse“ description refer to CV 151	0-255	0
230	Assignment of function button F14 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
231	Assignment of function button F15 forward A	Assignment of function outputs that are activated with „F15 - forward“ description refer to CV 147	0-255	0
232	Assignment of function button F15 forward B	Assignment of function outputs that are activated with „F15 - forward“ description refer to CV 148	0-255	0

List of all supported CVs

233	Assignment of function button F15 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
234	Assignment of function button F15 reverse A	Assignment of function outputs that are activated with „F15 - reverse“ description refer to CV 147	0-255	0
235	Assignment of function button F15 reverse B	Assignment of function outputs that are activated with „F15 - reverse“ description refer to CV 148	0-255	0
236	Assignment of function button F15 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
237	Assignment of function button sensor 1 forward A	Assignment of function outputs that are activated with „sensor 1 - forward“ description refer to CV 150	0-255	0
238	Assignment of function button sensor 1 forward B	Assignment of function outputs that are activated with „sensor 1 - forward“ description refer to CV 151	0-255	0
239	Assignment of function button sensor 1 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
240	Assignment of function button sensor 1 reverse A	Assignment of function outputs that are activated with „sensor 1 - reverse“ description refer to CV 147	0-255	0
241	Assignment of function button sensor 1 reverse B	Assignment of function outputs that are activated with „sensor 1 - reverse“ description refer to CV 148	0-255	0
242	Assignment of function button sensor 1 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
243	Assignment of function button sensor 2 forward A	Assignment of function outputs that are activated with „sensor 2 - forward“ description refer to CV 150	0-255	0
244	Assignment of function button sensor 2 forward B	Assignment of function outputs that are activated with „sensor 2 - forward“ description refer to CV 151	0-255	0
245	Assignment of function button sensor 2 forward C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0
246	Assignment of function button sensor 2 reverse A	Assignment of function outputs that are activated with „sensor 2 - reverse“ description refer to CV 147	0-255	0
247	Assignment of function button sensor 2 reverse B	Assignment of function outputs that are activated with „sensor 2 - reverse“ description refer to CV 148	0-255	0
248	Assignment of function button sensor 2 reverse C	Defines, which sound will be activated with the given function button 0= no sound, 1-16= No. of sound slot	0, 1-16	0

LokSound V3.0 / 3.5 Dimensions (mm) 31 x 15,5 x 6,5 Operating modes NMRA / DCC with 14, 28 and 128 speed steps 2-digit and 4-digit addresses Digital Märklin® / Motorola® (old and new) Conventional AC / DC operation Autodetection of operating mode Autodetection of DCC speed step setting Supports brake mode by Lenz® LG100, Märklin® & Roco® Supports direction correction bit Actual speed and function settings saved when in shutdown mode Special programming mode for Märklin® 6021	LokSound XL Dimensions (mm) 51 x 40 x 14 Operating modes NMRA / DCC with 14, 28 and 128 speed steps 2-digit and 4-digit addresses Digital Motorola® (old and new) Conventional AC / DC operation Autodetection of operating mode Autodetection of DCC speed step setting Supports brake mode by Lenz® LG100, Märklin® & Roco® Supports direction correction bit Actual speed and function settings saved when in shutdown mode Special programming mode for Märklin® 6021	LokSound micro Dimensions (mm) 28,5 x 10 x 5 Operating modes NMRA / DCC with 14, 28 and 128 speed steps 2-digit and 4-digit addresses Motorola® with 14 speed steps (No Conventional AC) Selectrix® System Conventional AC operation Autodetection of operating mode and DCC speed step setting Supports brake mode by Lenz® LG100, Märklin® & Roco® Supports direction correction bit Actual speed and function settings saved when in shutdown mode Special programming mode for Märklin® 6021
Motor control 1, 1 A continuous load Suitable for AC, DC and coreless motors (AC Motors with Hama conversion only) Silent motor control with 32 kHz PWM frequency Motor output protected against overload 4th generation load control (can be switched off)	Motor control 3,0 A continuous load Suitable for AC, DC and coreless motors (AC Motors with Hama conversion only) Silent motor control with 32 kHz PWM frequency Motor output protected against overload 4th generation load control (can be switched off)	Motor control 0,5 A continuous load Suitable for AC, DC and coreless motors (AC Motors with Hama conversion only) Silent motor control with 32 kHz PWM frequency Motor output protected against overload 4th generation load control (can be switched off)
Function outputs 4 outputs, 2 for head lights, 250 mA per output Total maximum current of all outputs is 500 mA Function mapping: F1 to F12 (V3.5 F1 - F20) Outputs are short circuit protected	Function outputs 8 outputs, 2 for head lights, 600 mA per output Total maximum current of all outputs is 2 A Function mapping: F1 to F12 (V3.5 F1 - F20) Outputs are short circuit protected	Function outputs 4 outputs, 2 for head lights, 180 mA per output Total maximum current of all outputs is 350 mA Function mapping: F1 - F20 Outputs are short circuit protected
Sound module 4(!) independent channels High performance output with 0,6 Watt Sound data flash memory may be modified Operating modes for steam-, dieselhydraulic-, diesel electric- and electric engines 8 MBit storage capacity (for up to 65 seconds)	Sound module 4(!) independent channels High performance output with 1,5 Watt Sound data flash memory may be modified Operating modes for steam-, dieselhydraulic-, diesel electric- and electric engines 8 MBit storage capacity (for up to 65 seconds)	Sound module 4(!) independent channels High performance output with 0,5 Watt Sound data flash memory may be modified Operating modes for steam-, dieselhydraulic-, diesel electric- and electric engines 8 MBit storage capacity (for up to 65 seconds)
Speaker Specially designed speaker 23mm speakers included	Speaker Speaker is not included	Speaker Specially designed speaker 16*25mm speakers included

9. Service-Support and assistance

Your model train or hobby shop is your competent partner for all questions regarding LokSound decoders.

You may also contact us directly. For enquiries please use either email or fax (don't forget to provide your own fax-no.) and we will reply within a few days.

Please call our hotline only in case of complex enquiries that can't be dealt with by email or fax. The hotline is often very busy and you may encounter delays.

Also check our website for more information. You will find many hints regarding FAQ and even feed back from other users.

Hotline +49 (0) 700 - 56576863 *
(0)700 - LOKSOUND
Tuesday and Wednesday
10AM - 12PM

Fax: +49 (0) 700- 37872537 *

Email: support@loksound.de

Post: ESU GmbH & Co. KG
Technical Support
Industriestrasse 5
D - 89081 Ulm

www.loksound.de

* 0,12 EUR / Minute



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Not suitable for children under 3 years of age. Inappropriate use may result in injury due to sharp points and edges.

Märklin® is a registered trademark of the company Gebr. Märklin® und Cie. GmbH, Göppingen, Germany.

Trouble Shooting Sheet

1. Personal Information

Name: _____

Address: _____

Address: _____

State: _____









Phone: _____

Email: _____

2. Product Details and System Environment

Order number	Description / Sound	Date of Purchase	Address (Märklin)
Operating Mode:	<input type="checkbox"/> DC <input type="checkbox"/> DCC	<input type="checkbox"/> DC Analog	<input type="checkbox"/> AC digital
Command Station Used:	<input type="checkbox"/> Märklin 6021	<input type="checkbox"/> Roco Digital	<input type="checkbox"/> LGB MZS
	<input type="checkbox"/> Intellibox	<input type="checkbox"/> Lenz Digital	<input type="checkbox"/> Digitrax
	<input type="checkbox"/> others _____		

3. Error Description

	Headlight Output	<input type="checkbox"/> Front <input type="checkbox"/> Rear
	Motor Putput	
	Short Circuit	
	Sound	<input type="checkbox"/> No Sound <input type="checkbox"/> Wrong Sound
	Programming	
	AUX-Outputs Fail	
	Change Direction Problems	
	Wire Harness	

4. Additional information

Installed by: _____

Comments: _____

5. Proof of Purchase

Please enclose with the claimed decoder!

6. Dealer Information

Company, Shop or Dealer Address _____