

sleep\_detector.ipynb

파일 수정 보기 삽입 런타임 도구 도움말 모든 변경사항이 저장됨

RAM 디스크

파일

..

.config

.ipynb\_checkpoints

drive

Trash-0

file-revisions-by-id

shortcut-targets-by-id

MyDrive

Colab Notebooks

dataset

sleep\_left

sleep\_right

wake

sample\_data

image\_classification\_model.h5

디스크 81.68 GB 사용 가능

+ 코드 + 텍스트

[1] import os  
import cv2  
import numpy as np  
import tensorflow as tf  
from tensorflow.keras import layers, models  
from sklearn.model\_selection import train\_test\_split  
from tensorflow.keras.preprocessing.image import ImageDataGenerator

[2] dataset\_path = "/content/drive/MyDrive/dataset"

[3] def load\_data(dataset\_path):  
 images = []  
 labels = []  
 classes = os.listdir(dataset\_path)  
 for i, class\_name in enumerate(classes):  
 class\_path = os.path.join(dataset\_path, class\_name)  
 for image\_name in os.listdir(class\_path):  
 image\_path = os.path.join(class\_path, image\_name)  
 image = cv2.imread(image\_path, cv2.IMREAD\_GRAYSCALE)  
 image = cv2.resize(image, (32, 32))  
 images.append(image)  
 labels.append(i)  
 images = np.array(images, dtype=np.float32) / 255.0  
 labels = np.array(labels)  
 return images, labels

images, labels = load\_data(dataset\_path)

[5] # 데이터 증강  
dataset = ImageDataGenerator(  
 rotation\_range=1,  
 width\_shift\_range=0.2,  
 height\_shift\_range=0.2,  
 horizontal\_flip=True  
)  
  
augmented\_images = []  
augmented\_labels = []  
  
for i in range(images.shape[0]):  
 image = images[i]  
 image = np.expand\_dims(image, axis=-1)  
 image = np.expand\_dims(image, axis=0)  
 label = labels[i]  
 for \_ in range(10): # 각 이미지에 10장의 추가 생성  
 for x\_augmented, y\_augmented in dataset.flow(image, [label], batch\_size=1):  
 augmented\_images.append(np.squeeze(x\_augmented))  
 augmented\_labels.append(y\_augmented[0])  
 break  
  
augmented\_images = np.array(augmented\_images)  
augmented\_labels = np.array(augmented\_labels)

[6] # 데이터 분할  
x\_train, x\_test, y\_train, y\_test = train\_test\_split(augmented\_images, augmented\_labels, test\_size=0.2, random\_state=42)

[7] model = models.Sequential([  
 layers.Conv2D(32, (3, 3), activation='relu', input\_shape=(32, 32, 1)),  
 layers.MaxPooling2D((2, 2)),  
 layers.Conv2D(64, (3, 3), activation='relu'),  
 layers.MaxPooling2D((2, 2)),  
 layers.Conv2D(64, (3, 3), activation='relu'),  
 layers.Flatten(),  
 layers.Dense(64, activation='relu'),  
 layers.Dense(3, activation='softmax') # 클래스 수만큼의 출력  
)

[8] model.summary()

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 30, 30, 32)	320
max_pooling2d (MaxPooling2D)	(None, 15, 15, 32)	0
conv2d_1 (Conv2D)	(None, 13, 13, 64)	18496
max_pooling2d_1 (MaxPooling2D)	(None, 6, 6, 64)	0
conv2d_2 (Conv2D)	(None, 4, 4, 64)	36928
flatten (Flatten)	(None, 1024)	0
dense (Dense)	(None, 64)	65600
dense_1 (Dense)	(None, 3)	195

Total params: 121539 (474.76 KB)  
Trainable params: 121539 (474.76 KB)  
Non-trainable params: 0 (0.00 Byte)

[9] # 모델 컴파일  
model.compile(optimizer='adam',  
 loss='sparse\_categorical\_crossentropy',  
 metrics=['accuracy'])

[10] # 모델 학습  
history = model.fit(x\_train, y\_train, epochs=200, batch\_size=32, validation\_data=(x\_test, y\_test))  
  
print(history.history)  
  
import matplotlib.pyplot as plt

Epoch 173/200  
2/2 [=====] - 0s 65ms/step - loss: 4.3915e-04 - accuracy: 1.0000 - val\_loss: 3.4386 - val\_accuracy: 0.4167  
Epoch 174/200  
2/2 [=====] - 0s 109ms/step - loss: 4.3453e-04 - accuracy: 1.0000 - val\_loss: 3.4472 - val\_accuracy: 0.4167  
Epoch 175/200  
2/2 [=====] - 0s 98ms/step - loss: 4.2900e-04 - accuracy: 1.0000 - val\_loss: 3.4532 - val\_accuracy: 0.4167  
Epoch 176/200  
2/2 [=====] - 0s 79ms/step - loss: 4.2297e-04 - accuracy: 1.0000 - val\_loss: 3.4590 - val\_accuracy: 0.4167  
Epoch 177/200  
2/2 [=====] - 0s 90ms/step - loss: 4.1533e-04 - accuracy: 1.0000 - val\_loss: 3.4634 - val\_accuracy: 0.4167  
Epoch 178/200  
2/2 [=====] - 0s 80ms/step - loss: 4.0919e-04 - accuracy: 1.0000 - val\_loss: 3.4675 - val\_accuracy: 0.4167  
Epoch 179/200  
2/2 [=====] - 0s 94ms/step - loss: 4.0443e-04 - accuracy: 1.0000 - val\_loss: 3.4759 - val\_accuracy: 0.4167  
Epoch 180/200

```

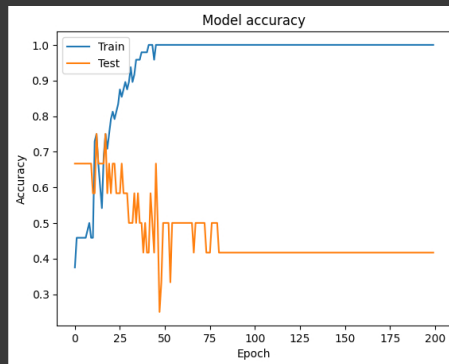
2/2 [=====] - 0s 90ms/step - loss: 3.9834e-04 - accuracy: 1.0000 - val_loss: 3.4839 - val_accuracy: 0.4167
Epoch 181/200
2/2 [=====] - 0s 96ms/step - loss: 3.9405e-04 - accuracy: 1.0000 - val_loss: 3.4929 - val_accuracy: 0.4167
Epoch 182/200
2/2 [=====] - 0s 97ms/step - loss: 3.9080e-04 - accuracy: 1.0000 - val_loss: 3.5023 - val_accuracy: 0.4167
Epoch 183/200
2/2 [=====] - 0s 103ms/step - loss: 3.8777e-04 - accuracy: 1.0000 - val_loss: 3.5085 - val_accuracy: 0.4167
Epoch 184/200
2/2 [=====] - 0s 96ms/step - loss: 3.8211e-04 - accuracy: 1.0000 - val_loss: 3.5136 - val_accuracy: 0.4167
Epoch 185/200
2/2 [=====] - 0s 102ms/step - loss: 3.7499e-04 - accuracy: 1.0000 - val_loss: 3.5196 - val_accuracy: 0.4167
Epoch 186/200
2/2 [=====] - 0s 89ms/step - loss: 3.6862e-04 - accuracy: 1.0000 - val_loss: 3.5235 - val_accuracy: 0.4167
Epoch 187/200
2/2 [=====] - 0s 96ms/step - loss: 3.6073e-04 - accuracy: 1.0000 - val_loss: 3.5264 - val_accuracy: 0.4167
Epoch 188/200
2/2 [=====] - 0s 96ms/step - loss: 3.5651e-04 - accuracy: 1.0000 - val_loss: 3.5306 - val_accuracy: 0.4167
Epoch 189/200
2/2 [=====] - 0s 89ms/step - loss: 3.5271e-04 - accuracy: 1.0000 - val_loss: 3.5341 - val_accuracy: 0.4167
Epoch 190/200
2/2 [=====] - 0s 100ms/step - loss: 3.5151e-04 - accuracy: 1.0000 - val_loss: 3.5378 - val_accuracy: 0.4167
Epoch 191/200
2/2 [=====] - 0s 92ms/step - loss: 3.5052e-04 - accuracy: 1.0000 - val_loss: 3.5428 - val_accuracy: 0.4167
Epoch 192/200
2/2 [=====] - 0s 88ms/step - loss: 3.4536e-04 - accuracy: 1.0000 - val_loss: 3.5509 - val_accuracy: 0.4167
Epoch 193/200
2/2 [=====] - 0s 86ms/step - loss: 3.3654e-04 - accuracy: 1.0000 - val_loss: 3.5622 - val_accuracy: 0.4167
Epoch 194/200
2/2 [=====] - 0s 101ms/step - loss: 3.2997e-04 - accuracy: 1.0000 - val_loss: 3.5730 - val_accuracy: 0.4167
Epoch 195/200
2/2 [=====] - 0s 91ms/step - loss: 3.2683e-04 - accuracy: 1.0000 - val_loss: 3.5834 - val_accuracy: 0.4167
Epoch 196/200
2/2 [=====] - 0s 90ms/step - loss: 3.2298e-04 - accuracy: 1.0000 - val_loss: 3.5903 - val_accuracy: 0.4167
Epoch 197/200
2/2 [=====] - 0s 97ms/step - loss: 3.2069e-04 - accuracy: 1.0000 - val_loss: 3.5959 - val_accuracy: 0.4167
Epoch 198/200
2/2 [=====] - 0s 89ms/step - loss: 3.1603e-04 - accuracy: 1.0000 - val_loss: 3.5988 - val_accuracy: 0.4167
Epoch 199/200
2/2 [=====] - 0s 69ms/step - loss: 3.1081e-04 - accuracy: 1.0000 - val_loss: 3.6003 - val_accuracy: 0.4167
Epoch 200/200
2/2 [=====] - 0s 64ms/step - loss: 3.0733e-04 - accuracy: 1.0000 - val_loss: 3.6016 - val_accuracy: 0.4167
{"loss": [1.0921732187271118, 1.0416163206100464, 1.0622382164001465, 1.0281723737718675, 1.0162220001220703, 1.00124776363728, 0.9947995543479919, 0.9840262532234192, 0.9564652442932129, 0.9566865397453308, 0.91

```

```

[11] plt.plot(history.history['accuracy'])
plt.plot(history.history['val_accuracy'])
plt.title('Model accuracy')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()

```



```

[12] # 모델 저장
model.save("image_classification_model.h5")

```

```

/usr/local/lib/python3.10/dist-packages/keras/src/engine/training.py:3103: UserWarning: You are saving your model as an HDF5 file via `model.save()`. This file format is considered legacy. We recommend using instead `saving_api.save_model`.

```