

# A Solution Manual to Eric Poisson's A Relativist's Toolkit

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My units are such that  $c = 4\pi G = 1$ ; this may lead to some discrepancies with the book.

## Chapter 1

## Chapter 2

## Chapter 3

### 1

Let's work in the units with  $r_S = 2GM/c^2 = 1$ .

a) The gradient is

$$dx^\mu \partial_\mu T = dt + \frac{\sqrt{r} dr}{r-1}$$

Interestingly, this is normal and timelike

$$n_\alpha = \left(1, \frac{\sqrt{r}}{r-1}, 0, 0\right)$$

The parametric equations are

$$t = T - 2 \left[ \sqrt{R} + \frac{1}{2} \log \left( \frac{\sqrt{R}-1}{\sqrt{R}+1} \right) \right] \quad ; \quad r = R \quad ; \quad \theta = \Theta \quad ; \quad \phi = \Phi$$

where  $(R, \Theta, \Phi)$  are the tangent coordinates.

b) The induced metric is flat

$$ds^2 = dR^2 + R^2 d\Omega^2$$

c) Let's start with the covariant derivative  $\nabla_\mu n_\nu$ :

$$\nabla_t n_t = \frac{-1}{2r^{5/2}}$$

$$\nabla_t n_r = \nabla_r n_t = \frac{-1}{2r(r-1)}$$

$$\nabla_r n_r = \frac{-\sqrt{r}}{2(r-1)^2}$$

$$\nabla_\theta n_\theta = \sqrt{r}$$

$$\nabla_\varphi n_\varphi = \sqrt{r} \sin^2 \theta$$

Then the nonzero components of the extrinsic curvature follow

$$\boxed{K_{RR} = \frac{-1}{2R^{3/2}} \quad ; \quad K_{\Theta\Theta} = \sqrt{R} \quad ; \quad K_{\Phi\Phi} = \sqrt{R} \sin^2 \Theta}$$

This is clearly in accordance (in fact, it's the same calculation) with the results described in section 3.6.6. The trace is

$$K = h^{ab} K_{ab} = \frac{3}{2R^{3/2}}$$

Since the metric is  $T$  independent, and  $n_\mu = \partial_\mu T$ , the normal vector is a Killing vector. Since it has constant length, it is also tangent to a geodesic bundle; the divergence of which is given by

$$\theta = \nabla_\alpha n^\alpha = K$$

This agrees with the result in section 2.3.7 of the book as well.

d) Let's use the results from part (a) directly

$$\begin{aligned} ds^2 &= -(1 - 1/r)dt^2 + dr^2/(1 - 1/r) + r^2 d\Omega^2 = -\frac{R-1}{R} \left( dT - \frac{\sqrt{R}dR}{R-1} \right)^2 + \frac{RdR^2}{R-1} + R^2 d\Omega^2 \\ &= \boxed{-dT^2 + (dR + dT/\sqrt{R})^2 + R^2 d\Omega^2} \end{aligned}$$

## 2

a) The normal is best found given the constraint description of the hypersurface. It is

$$a^2 = \eta_{AB} z^A z^B = \text{const.}$$

The normal is then found as

$$\boxed{n_A = \frac{1}{a} \eta_{AB} z^B}$$

b)

$$\begin{aligned} ds^2 &= \eta_{AB} dz^A dz^B = -\cosh(t/a)dt^2 + \sum_{A>0} (dz^A)^2 \\ &= -\cosh^2(t/a)dt^2 + \sinh^2(t/a)dt^2 + a^2 \cosh^2(t/a)d\Omega_3^2 \\ &= \boxed{-dt^2 + a^2 \cosh^2(t/a)d\Omega_3^2} \end{aligned}$$

This is of course, the de Sitter space time. It's conformally flat and is a solution to the Einstein field equations in vacuum with positive cosmological constant.

c)

$$\begin{aligned} K_{\alpha\beta} &= e_\alpha^A e_\beta^B \nabla_A n_B = e_\alpha^A e_\beta^B \partial_A n_B \\ &= e_\alpha^A e_\beta^B \left( \frac{1}{a} \eta_{AB} - \frac{1}{a^2} z_B \partial_A a \right) = \frac{1}{a} e_\alpha^A e_\beta^B \eta_{AB} = \boxed{\frac{1}{a} g_{\alpha\beta}} \end{aligned}$$

The other terms vanish because on the hypersurface,  $a$  is constant. Now let's use the fully tangential component of the Gauss-Codazzi relations; (equation 3.39). It reads

$$0 = R_{\alpha\beta\mu\nu} + K_{\alpha\nu} K_{\beta\mu} - K_{\alpha\mu} K_{\beta\nu}$$

or

$$\boxed{R_{\alpha\beta\mu\nu} = \frac{1}{a^2} (g_{\alpha\mu} g_{\beta\nu} - g_{\alpha\nu} g_{\beta\mu})}$$

### 3

a) The mass function is defined in the metric form

$$ds^2 = [1 - m(r)/2\pi r]^{-1} dr^2 + r^2 d\Omega^2$$

Comparison leads to

$$\boxed{m = 2\pi r \left[ 1 - \left( \frac{dr}{dl} \right)^2 \right]}$$

b) The constraint equation reads

$${}^3R = 4T(n, n)$$

Or, in terms of the mass function

$$\frac{dm}{dr} = 4\pi r^2 \rho$$

The regularity at the origin imposes

$$m(0) = 0$$

Therefore

$$\boxed{m(r) = \frac{4}{3} \pi r^3 \rho}$$

Putting this back to the differential equation connecting  $r$  and  $l$ , we find

$$\boxed{r(l) = \sqrt{\frac{3}{2\rho}} \sin\left(\sqrt{\frac{2\rho}{3}} l\right)}$$

c, d) This is clear from the expression for  $r(l)$  that it can not go beyond

$$\boxed{r_{\max} = \sqrt{\frac{3}{2\rho}}}$$

Then, since  $dm/dr > 0$ , the maximum mass is also achieved at maximum aerial radius, when the mass function attains the value

$$m(r) = 2\pi r_{\max}.$$

e) The metric is

$$ds^2 = dl^2 + r_{\max}^2 \sin^2(l/r_{\max}) d\Omega_2^2$$

This space-time is symmetric under the discrete transformation

$$l \rightarrow \pi r_{\max} - l$$

Therefore, the  $l = \pi r_{\max}$  is also a center of the polar coordinates where the area of the sphere vanishes and all the  $\Omega_2$  variables become irrelevant. This is exactly the description of a 3 sphere,  $\mathbb{S}^3$ . One just needs to define  $\psi \equiv l/r_{\max}$  to find

$$ds^2 = r_{\max}^2 d\Omega_3^2$$

## 4

The condition  $[K_{ab}] = 0$  is clearly necessary for regularity of the Riemann tensor because of how the Gauss-Codazzi equations relate some components of the Riemann tensor to the extrinsic curvature. It remains to show that  $R(e_a, n, e_b, n)$  is also consistent if the extrinsic curvature is the same from both sides. Let  $y^a$  be the local normal coordinate system on the hypersurface and  $l$  be the orthogonal geodesic direction. Then, the only non-vanishing metric derivative is

$$\partial_l g_{ab} = 2K_{ab}$$

The Riemann component that we are after, then simplifies into

$$\begin{aligned} R_{alb}^l &= \partial_l \Gamma_{ab}^l - \Gamma_{bc}^l \Gamma_{la}^c \\ &= -\varepsilon(\partial_l K_{ab} - K_{ac} K_b^c) \end{aligned}$$

Clearly, this shows that if  $[K_{ab}] = 0$  is satisfied, the Riemann tensor will at most have a jump discontinuity and not a delta function singularity.

## 5

Now that we have all of the components of the Riemann tensor, we may as well find the stress energy tensor completely by following the standard procedure.

$$T_{\alpha\beta} = \frac{1}{2} R_{\alpha\mu\beta}^{\mu} - \frac{1}{4} R^{\mu\nu}_{\mu\nu} g_{\alpha\beta}$$

The answer will be

$$\begin{aligned} T_{ll} &= \frac{1}{4} (-\varepsilon^3 R + K^2 - K_{ab} K^{ab}) \\ T_{la} &= \frac{1}{2} (D^b K_{ab} - D_a K) \\ T_{ab} &= {}^3T_{ab} + \frac{\varepsilon}{4} [2(2K_{ac} K_b^c - \partial_l K_{ab} - K K_{ab}) - h_{ab}(3K_{ab} K^{ab} - 2\partial_l K - K^2)] \end{aligned}$$

Now we can explicitly write

$$-\varepsilon[j^a] = -\varepsilon h^{ab}[T_{lb}] = \frac{1}{2}(D_b[K^{ab}] - D^a[K]) = D_b S^{ab} \blacksquare$$

Let's consider a timelike shell like  $z = 0$ . The  $t$ -component formula above asserts that the discontinuity in  $T^{tz}$ , or the mass flow across the shell is equal to the rate with which mass accumulates on the shell. The other components of the formula are interpreted similarly.

## 6

I will work in the units where  $l_0 = 1$ . Also, the tangent coordinates are  $(t, \theta, \varphi)$ . Topologically speaking, this is the same as a stationary space with  $\mathbb{S}^3$  topology. The space has two flattened hemispheres connected together via the hypersurface.

a) Let's start with finding the extrinsic curvature on both sides. The normal vector is

$$n = \partial_t$$

The nonzero Christoffel symbols are

$$\begin{aligned} \pm \Gamma_{\theta\theta}^l &= \pm r \quad ; \quad \pm \Gamma_{\varphi\varphi}^l = \pm r \sin^2 \theta \\ \pm \Gamma_{l\theta}^\theta &= \pm \Gamma_{\theta l}^\theta = \pm \Gamma_{l\varphi}^\varphi = \pm \Gamma_{\varphi l}^\varphi = \frac{\mp 1}{r} \\ \Gamma_{\varphi\varphi}^\theta &= -\sin \theta \cos \theta \quad ; \quad \Gamma_{\theta\varphi}^\varphi = \Gamma_{\varphi\theta}^\varphi = \cot \theta \end{aligned}$$

From these, it follows that  $K_{ab}$  is only nonzero for angular components.

$$\pm K_{\theta\theta} = \mp 1 \quad ; \quad \pm K_{\varphi\varphi} = \mp \sin^2 \theta$$

Then follows  $S_{ab}$ :

$$\boxed{S_{tt} = 2 \quad ; \quad S_{\theta\theta} = -1 \quad ; \quad S_{\varphi\varphi} = -\sin^2 \theta}$$

This corresponds to a surface density  $\sigma$ , surface pressure  $p$ , and 4 velocity  $V$  as below

$$\boxed{V = \partial_t \quad ; \quad \sigma = 2 \quad ; \quad p = -1}$$

b) The null tangent vector is  $k = \partial_t + \partial_l$ . The expansion is

$$\pm \theta = \nabla_\alpha k^\alpha = \partial_\alpha k^\alpha + \pm \Gamma_{\mu\alpha}^\alpha k^\mu = \pm \Gamma_{l\alpha}^\alpha = \boxed{\frac{\mp 2}{r}}$$

This clearly changes sign from positive to negative as the geodesic crosses from the negative region to the positive region.

c) Raychaudhuri's equation is

$$\frac{d\theta}{d\lambda} = -B_{\alpha\beta} B^{\beta\alpha} - R_{\mu\nu} k^\mu k^\nu$$

Integrating this across the shell, it follows that

$${}^+\theta - {}^-\theta = - \int_{1-\varepsilon}^{1+\varepsilon} dl R(\partial_t + \partial_l, \partial_t + \partial_l) = -2S_{ab} k^a k^b = -2S_{tt} = -4$$

Which is in accordance with the explicit result we found.

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a) The first junction condition, implies that the hypersurface is described by functions

$$r^- = r^+ = R(\tau) \quad ; \quad t^- = t^-(\tau) \quad ; \quad t^+ = t^+(\tau)$$

Where  $t^\pm$  are defined via

$$\frac{dt^\pm}{d\tau} = \frac{1}{1 - r_S^\pm/R} \sqrt{1 - \frac{r_S^\pm}{R} + (dR/d\tau)^2}$$

The induced metric and coordinates are as below

$$ds_\Sigma^2 = -d\tau^2 + R^2(\tau)d\Omega_2^2$$

The normal form on each side is

$$n_\mu^\pm = (-\frac{dR}{d\tau}, \frac{dt^\pm}{d\tau}, 0, 0)$$

And the tangent vectors are

$$e_\tau^\mu = (\frac{dt^\pm}{d\tau}, \frac{dR}{d\tau}, 0, 0) \quad ; \quad e_\theta^\mu = (0, 0, 1, 0) \quad ; \quad e_\varphi^\mu = (0, 0, 0, 1)$$

Finding the angular components of the extrinsic curvature is not difficult

$$^\pm K_{\theta\theta} = \nabla_\theta n_\theta = R \sqrt{1 + (dR/d\tau)^2 - r_S^\pm/R}$$

$$^\pm K_{\varphi\varphi} = ^\pm K_{\theta\theta} \sin^2 \theta$$

The  $\tau\tau$  component is way more cumbersome

$$K_{\tau\tau} = e_\tau^\mu e_\tau^\nu \nabla_\mu n_\nu = e_\tau^\mu \partial_\tau n_\mu - \Gamma_{\mu\nu}^\alpha e_\tau^\mu e_\tau^\nu n_\alpha = \frac{dR}{d\tau} \frac{d^2 t}{d\tau^2} - \frac{d^2 R}{d\tau^2} \frac{dt}{d\tau} + \frac{3r_S}{2R(R-r_S)} \left(\frac{dR}{d\tau}\right)^2 \frac{dt}{d\tau} - \frac{r_S(R-r_S)}{2R^3} \left(\frac{dt}{d\tau}\right)^3$$

In any case, the density and pressure are given by

$$\sigma = \frac{-1}{R^2} [K_{\theta\theta}] \quad ; \quad p = \frac{1}{2} \left( \frac{1}{R^2} [K_{\theta\theta}] - [K_{\tau\tau}] \right)$$

And that means we need to prove

$$\frac{d[K_{\theta\theta}]/d\tau}{[K_{\theta\theta}]} - \frac{dR}{Rd\tau} = -R \frac{dR}{d\tau} \frac{[K_{\tau\tau}]}{[K_{\theta\theta}]}$$

b) Let

$$\alpha_\pm \equiv \arcsin \frac{r_S^\pm}{R}$$

Then

$$\sigma = \frac{1}{R} (\cos \theta_- - \cos \theta_+) > 0$$

$$p = \frac{1}{4R} (2 \cos \theta_+ + \tan \theta_+ - 2 \cos \theta_- - \tan \theta_-) > 0$$

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## Chapter 4

1

a) The EL equations are

$$\frac{\partial \mathcal{L}}{\partial A_\alpha} = \nabla_\beta \frac{\partial \mathcal{L}}{\partial \nabla_\beta A_\alpha}$$

Or

$$0 = -\frac{1}{2} \nabla_\beta \left( F^{\mu\nu} \frac{\partial F_{\mu\nu}}{\partial \nabla_\beta A_\alpha} \right) = -\frac{1}{2} \nabla_\alpha F^{\mu\nu} (\delta_\mu^\beta \delta_\nu^\alpha - \delta_\nu^\beta \delta_\mu^\alpha) = \nabla_\beta F^{\alpha\beta} \blacksquare$$

b)

$$T_{\alpha\beta} = g_{\alpha\beta} \mathcal{L} - 2 \frac{\partial \mathcal{L}}{\partial g^{\alpha\beta}} = \boxed{F_{\alpha\mu} F_\beta{}^\mu - \frac{1}{4} g_{\alpha\beta} F^{\mu\nu} F_{\mu\nu}}$$

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a) The action is

$$S = -m \int d\lambda \sqrt{-g_{\alpha\beta} \dot{z}^\alpha \dot{z}^\beta}$$

Then, the stress-energy tensor is

$$T_{\mu\nu}(x) = \frac{-2}{\sqrt{-g(x)}} \frac{\delta S}{\delta g^{\mu\nu}(x)} = \frac{m}{\sqrt{-g(x)}} \int d\lambda \frac{1}{\sqrt{-\dot{z}_\alpha \dot{z}^\alpha}} \dot{z}_\mu \dot{z}_\nu \delta(z^\gamma - x^\gamma)$$

This is best re-written in terms of the 4 velocity of the particle as

$$\boxed{T^{\mu\nu} = m \int d\tau V^\mu V^\nu \delta(z, x)}$$

b) The conservation is equivalent to

$$\int dx \sqrt{-g} A_\beta \nabla_\alpha T^{\alpha\beta} = 0$$

where  $A_\beta$  is any localized vector field. For a single particle, this is

$$\begin{aligned} 0 &= \int dx \sqrt{-g} A_\beta \nabla_\alpha T^{\alpha\beta} = m \int dx \sqrt{-g} d\tau A_\beta(x) V^\beta(\tau) V^\alpha(\tau) \nabla_\alpha \delta(z, x) \\ &= -m \int d\tau V^\alpha V^\beta \int dx \sqrt{-g} \delta(z, x) \nabla_\alpha A_\beta = -m \int d\tau V^\alpha V^\beta \nabla_\alpha A_\beta \\ &= -m \int d\tau V^\alpha \nabla_\alpha (V^\beta A_\beta) + m \int d\tau A_\beta V^\alpha \nabla_\alpha V^\beta \\ &= -m \langle V, A \rangle \Big|_{\tau=-\infty}^{\tau=+\infty} + m \int d\tau A_\beta V^\alpha \nabla_\alpha V^\beta \end{aligned}$$

$$= m \int d\tau A_\beta V^\alpha \nabla_\alpha V^\beta$$

Which is equivalent to the geodesic equation.

c)

### 3

Let's use the units in which  $r_S = 1$ . The bulk action is zero since this is a vacuum solution. The extrinsic curvature on the  $\Sigma_{t_i}$  are zero since the normals are killing fields. The non dynamical terms also cancel on the  $\Sigma_{t_i}$  by virtue of symmetry. Therefore the action is

$$S = 2\pi(t_2 - t_1)r^2(K_r - K_0)\Big|_\rho^R$$

Where

$$K_r - K_0 = \frac{1}{2r^2\sqrt{1-1/r}} + \frac{2\sqrt{1-1/r}}{r} - \frac{2}{r}$$

This then gives

$$S(R, \rho, t_1, t_2) = \pi(t_2 - t_1) \left[ \frac{1}{\sqrt{1-1/r}} - 4r(1 - \sqrt{1-1/r}) \right] \Big|_\rho^R$$

and

$$\lim_{R \rightarrow \infty} S(R, \rho, t_1, t_2) = \pi(t_2 - t_1) \left[ -1 - \frac{1}{\sqrt{1-1/\rho}} + 4\rho(1 - \sqrt{1-1/\rho}) \right]$$

## Chapter 5