

Ricoh Theta X 360-degree camera setup

This document outlines how to set up the 360-degree camera to view the livestream on an Ubuntu system. It has been tested and verified on Ubuntu 20.04 which is the operating system running on the ITX computer.

Theoretically it would be better to have the camera livestream to the PX2. However, this has not been verified to work as of now since the PX2 operates on Ubuntu 16.04.

<https://community.theta360.guide/t/live-stream-ricoh-theta-x-on-ubuntu-22-04/7992>

Prerequisites

- Ricoh Theta X 360-degree camera.
- Computer that runs Ubuntu 20.04 or newer version

Also, install the following packages:

- make
- libusb-1.0
- libjpeg-dev
- libgstreamer1.0-dev
- libgstreamer-plugins-base1.0-dev
- libgstreamer-plugins-bad1.0-dev
- gstreamer1.0-plugins-base
- gstreamer1.0-plugins-good
- gstreamer1.0-plugins-bad
- gstreamer1.0-plugins-ugly
- gstreamer1.0-libav
- gstreamer1.0-tools
- gstreamer1.0-x
- gstreamer1.0-alsa
- gstreamer1.0-gl
- gstreamer1.0-gtk3
- gstreamer1.0-qt5
- gstreamer1.0-pulseaudio

Steps

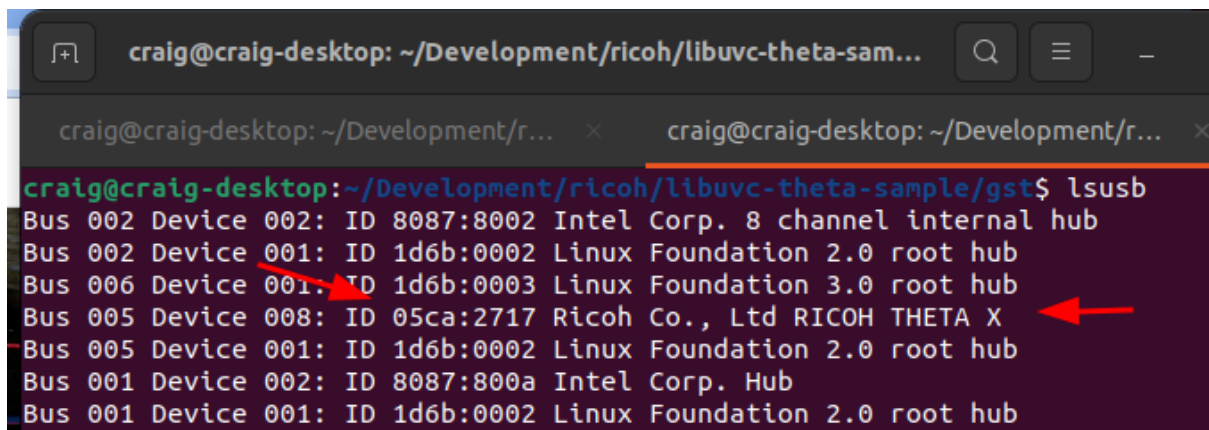
```
$ git clone https://github.com/ricohapi/libuvc-theta.git
$ git clone https://github.com/ricohapi/libuvc-theta-sample.git
$ cd libuvc-theta
$ mkdir build
$ cd build
$ cmake ..
$ sudo make install
$ cd ..
$ cd libuvc-theta-sample
$ cd gst
```

Now we need to change things in the file **thetavvc.c** to operate the camera. The original guide for these steps can be found [here](#).

Add definition for THETAX camera.

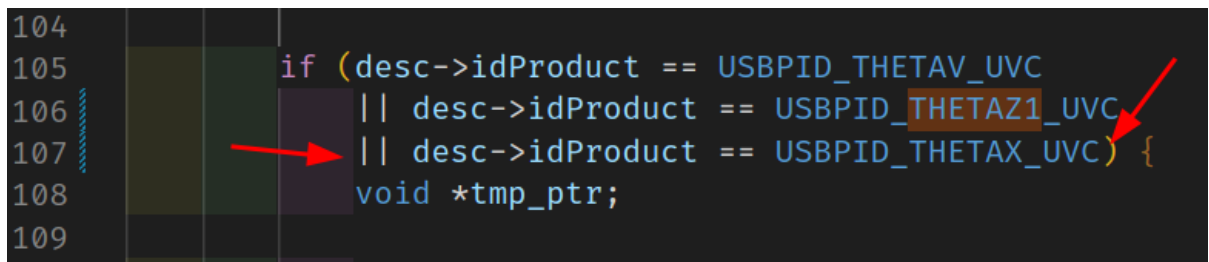
```
7
8  #include "libuvc/libuvc.h"
9  #include "thetavvc.h"
10
11  #define USBVID_RICOH 0x05ca
12  #define USBPID_THETA_V_UVC 0x2712
13  #define USBPID_THETA_Z1_UVC 0x2715
14  #define USBPID_THETA_X_UVC 0x2717
15
16
17  struct thetavvc_mode {
```

The hex-number is the number you receive when running the camera in live-mode and check USB connections with **lsusb** in Linux.



```
craig@craig-desktop: ~/Development/ricoh/libuvc-theta-sample/gst$ lsusb
Bus 002 Device 002: ID 8087:8002 Intel Corp. 8 channel internal hub
Bus 002 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
Bus 006 Device 001: ID 1d6b:0003 Linux Foundation 3.0 root hub
Bus 005 Device 008: ID 05ca:2717 Ricoh Co., Ltd RICOH THETA X
Bus 005 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
Bus 001 Device 002: ID 8087:800a Intel Corp. Hub
Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
```

After you add the definition, add an or check in the if statement that checks for the idProduct and have it accept the THETAX in addition to THETA_V and THETA_Z1.



```
104
105     if (desc->idProduct == USBPID_THETA_V_UVC
106         || desc->idProduct == USBPID_THETA_Z1_UVC
107         || desc->idProduct == USBPID_THETA_X_UVC) {
108         void *tmp_ptr;
109
```

Finally build and run the program

```
$ make  
$ ./gst_viewer
```

Enjoy the pretty viewport!