

$$\textcircled{1} f: \mathbb{R}^2 \rightarrow \mathbb{R}, (x_1, x_2) \mapsto x_1^2 + 0,5x_2^2 + x_1x_2$$

$$a) f'(x_1) = 2x_1 + x_2$$

$$f'(x_2) = x_2 + x_1$$

$$\hookrightarrow (2x_1 + x_2, x_2 + x_1) = \nabla f = C^1 \rightarrow \text{smooth}$$

$$b) \nabla f(1,1) = (2 \cdot 1 + 1, 1 + 1) = \underline{\underline{(3, 2)}}$$

$$c) -\nabla f(1,1) = -(3, 2) = (-3, 2)$$

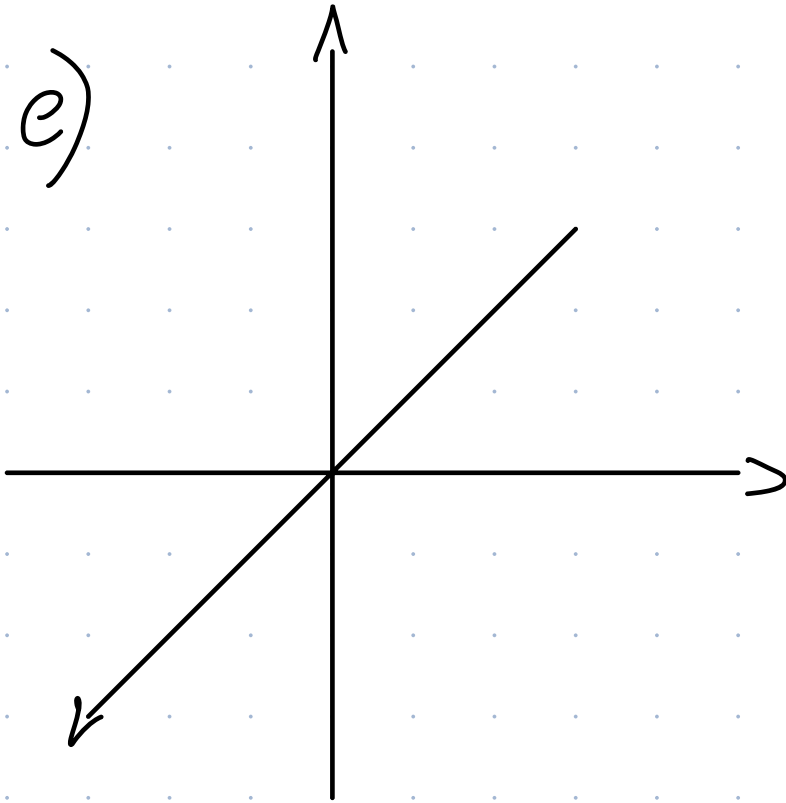
$$d) \nabla f(x) \cdot v = 0$$

$$\Rightarrow (3, 2) \cdot (v_1, v_2) = 0$$

$$\Rightarrow (3, 2) \cdot (-2, 3) = 0$$

$$\Rightarrow -6 + 6 = 0 \rightarrow v = \begin{pmatrix} -2 \\ 3 \end{pmatrix}$$

e)



$$f(\tilde{x}(t)) = f(1, 1)$$

$$\frac{\partial f(\tilde{x}(t))}{\partial t} = \frac{\partial f(x)}{\partial t} = 0$$

Chain-Rule:

$$\frac{\partial f}{\partial \tilde{x}} \cdot \frac{\partial \tilde{x}}{\partial t} = 0$$

$$\Rightarrow \nabla f(x)^T$$

↳

$$\textcircled{2} \quad A = \begin{pmatrix} 1 & 0 & 3 \\ 2 & 1 & 4 \\ 0 & 3 & 2 \end{pmatrix} \quad b = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

a)

$$Ab = \begin{pmatrix} 1 \cdot 3 + 2 \cdot 0 + 3 \cdot 1 \\ 2 \cdot 3 + 1 \cdot 2 + 1 \cdot 4 \\ 0 \cdot 3 + 2 \cdot 3 + 2 \cdot 1 \\ 1 \cdot 3 + 2 \cdot 1 + 0 \cdot 1 \end{pmatrix} \Rightarrow Ab = \begin{pmatrix} 6 \\ 12 \\ 8 \\ 5 \end{pmatrix}$$

b)

$A^T b$ hält nur wenn A von der form $n \times 3$ wäre

c) $A = \begin{pmatrix} 1 & 0 & 3 \\ 2 & 1 & 4 \\ 0 & 3 & 2 \end{pmatrix}$

$$\begin{array}{ccc|cc} 1 & 0 & 3 & 1 & 0 \\ 2 & 1 & 4 & 2 & 1 \\ 0 & 3 & 2 & 0 & 3 \end{array}$$

$$= 2 + 18 - 12 = 8 \neq 0$$

↳ Invertierbar ✓

$$d) A^{-1}$$

$$\begin{pmatrix} 1 & 0 & 3 \\ 2 & 1 & 4 \\ 0 & 3 & 2 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - 2 \cdot \text{I}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 3 & 2 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} - 3 \cdot \text{II}$$

$$= \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 8 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 6 & -3 & 1 \end{pmatrix} : 8$$

$$= \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ \frac{3}{4} & -\frac{3}{8} & \frac{1}{8} \end{pmatrix} \begin{array}{l} -3 \cdot \text{III} \\ +2 \cdot \text{III} \\ \end{array}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -\frac{5}{4} & \frac{3}{8} & -\frac{3}{8} \\ -\frac{1}{2} & \frac{1}{4} & \frac{2}{8} \\ \frac{3}{4} & -\frac{3}{8} & \frac{1}{8} \end{pmatrix}$$

③

$$a) \quad f(x + t(y-x))$$

$$g(x + t(y-x))$$

$$f(x + t(y-x)) + g(x + t(y-x))$$

$$\leq$$

$$\left(f(x) + t(f(y) - f(x))\right) + \left(g(x) + t(g(y) - g(x))\right)$$

$$\Rightarrow (f+g)(x+t(y-x)) \leq (f+g)(x) + t((f+g)(y) - (f+g)(x))$$

\rightarrow konvex

b) proof: $g \circ f \rightarrow$ konvex , $h = g \circ f$

$$\begin{aligned} \Rightarrow h(x+t(y-x)) &= g(f(x+t(y-x))) \\ &\leq g(f(x) + t(f(y) - f(x))) \\ &\leq g(f(x)) + t(g(f(y)) - g(f(x))) \end{aligned}$$

$$= h(x) + (h(y) - h(x))$$

$$(4) f: \mathbb{R}^2 \rightarrow \mathbb{R}, (x_1, x_2) \mapsto \exp(\tilde{\pi} \cdot x_1) - \sin(\tilde{\pi} \cdot x_2) + \tilde{\pi} \cdot x_1 \cdot x_2$$

a)

$$\frac{\partial f}{\partial x_1} = \tilde{\pi} \cdot \exp(\tilde{\pi} \cdot x_1) + \tilde{\pi} \cdot x_2 \Rightarrow \tilde{\pi} \cdot (\exp(\tilde{\pi} \cdot x_1) + x_2)$$

$$\frac{\partial f}{\partial x_2} = -\cos(\tilde{\pi} \cdot x_2) \cdot \tilde{\pi} + \tilde{\pi} \cdot x_1 = \tilde{\pi} \cdot (-\cos(\tilde{\pi} \cdot x_2) + x_1)$$

$$\nabla f = \tilde{\pi} \cdot (\exp(\tilde{\pi} \cdot x_1) + x_2, -\cos(\tilde{\pi} \cdot x_2) + x_1)$$

$$b) \frac{\partial^2 f}{\partial x_1} = \tilde{\pi} \cdot (\tilde{\pi} \cdot \exp(\tilde{\pi} \cdot x_1)) \Rightarrow \tilde{\pi}^2 \cdot \exp(\tilde{\pi} \cdot x_1)$$

$$\frac{\partial^2 f}{\partial x_2} = \tilde{\pi}^2 \cdot \sin(\tilde{\pi} \cdot x_2)$$

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = \tilde{\pi}$$

$$\frac{\partial^2 f}{\partial x_2 \partial x_1} = \tilde{\pi}$$

$$\nabla^2 f(x) = \begin{pmatrix} \tilde{\pi}^2 \cdot \exp(\tilde{\pi} \cdot x_1) & \tilde{\pi} \\ \tilde{\pi} & \tilde{\pi}^2 \cdot \sin(\tilde{\pi} \cdot x_2) \end{pmatrix}$$

$$\Rightarrow \tilde{\pi} \cdot \begin{pmatrix} \tilde{\pi} \cdot \exp(\tilde{\pi} \cdot x_1) & 1 \\ 1 & \tilde{\pi} \cdot \sin(\tilde{\pi} \cdot x_2) \end{pmatrix}$$

c) $T_{1,a}(x) \quad a = (0, 1)$

$$f(x) = f(a) + \nabla f(a)^T (x - a)$$

$$= 1 + (2\tilde{\pi}, \tilde{\pi}) \cdot (x_1, x_2 - 1)$$

$$= 1 + 2\tilde{\pi}x_1 + \tilde{\pi}x_2 - \tilde{\pi}$$

$$d) \quad \overline{T}_2(x, a)$$

$$= f(a) + \nabla f(a)^T (x-a) + \frac{1}{2} (x-a)^T H(a) (x-a)$$

$$\Rightarrow \frac{1}{2} (x_1, x_2 - 1) \cdot \tilde{\Pi} \begin{pmatrix} \tilde{\Pi} & 1 \\ 1 & 0 \end{pmatrix} (x_1, x_2 - 1)$$

$$= \left(\frac{1}{2} x_1, \frac{1}{2} x_2 - 0,5 \right) \cdot \underbrace{\begin{pmatrix} \tilde{\Pi}^2 & \tilde{\Pi} \\ \tilde{\Pi} & 0 \end{pmatrix}}_{\begin{pmatrix} \tilde{\Pi}^2 x_1 & \tilde{\Pi} x_2 - \tilde{\Pi} \\ \tilde{\Pi} x_1 & 0 \end{pmatrix}} (x_1, x_2 - 1)$$

$$\Rightarrow \left(\frac{1}{2} x_1, \frac{1}{2} x_2 - 0,5 \right) \cdot \begin{pmatrix} \tilde{\Pi}^2 x_1 & \tilde{\Pi} x_2 - \tilde{\Pi} \\ \tilde{\Pi} x_1 & 0 \end{pmatrix}$$

$$\Rightarrow \frac{1}{2}x_1 \cdot (\tilde{\pi}^2 x_1 + \tilde{\gamma} x_2 - \tilde{\pi}) + \left(\frac{1}{2}x_2 - 0,5\right) \cdot (\tilde{\pi} x_1)$$

$$\Rightarrow \frac{1}{2} \tilde{\pi}^2 x_1^2 + \frac{1}{2} x_1 \tilde{\pi} x_2 - \frac{1}{2} \tilde{\pi} x_1 + \frac{1}{2} \tilde{\gamma} x_1 x_2 - \frac{1}{2} \tilde{\pi} x_1$$

$$= \frac{1}{2} \tilde{\pi}^2 x_1^2 + \tilde{\pi} x_1 x_2 - \tilde{\pi} x_1$$

$$\Rightarrow 1 + 2\tilde{\pi} x_1 + \tilde{\gamma} x_2 - \tilde{\pi} + \frac{1}{2} \tilde{\pi}^2 x_1^2 + \tilde{\pi} x_1 x_2 - \tilde{\pi} x_1$$

$$= 1 + \tilde{\pi} x_1 + \tilde{\gamma} x_2 - \tilde{\pi} + \frac{1}{2} \tilde{\pi}^2 x_1^2 + \tilde{\pi} x_1 x_2$$