```
else if (c == '.') d = true;
else n = c - '0':
    General
    Algorithms
                                                              while ((c=inchar())!=' '&&c!='\n') {
                                                               if (c == '.') d = true;
lelse if (d) { m=m*10+c-'0'; o*=0.1; }
lelse n = n * 10 + c - '0';
    Data Structures
    String
    Math
                                                              n = s * (n + m * o):
    Graph
                                                             void read(double& n) {
    2D Geometry
                                                              ld m; read(m); n = m;
    3D Geometry
                                                             void read(float& n) {
9 Optimization
                                                              ld m: read(m): n = m:
10 Additional
                                                             void read(string& s) {
                                                              char c; s = "
     General
                                                              while((c=inchar())!=' '\&\&c!=' \n')
run.sh
g++ -g -02 -std=gnu++17 -static prog.cpp
                                                             bool readline(string& s) {
./a.exe
                                                              char c; s = '
                                                              while(c=inchar()) {
test.sh
                                                               if (c == '\n') return true;
if (c == EOF) return false;
# compile and test all *.in and *.ans
g++ -g -02 -std=gnu++17 -static prog.cpp
                                                               s += c;
for i in *.in; do
f=${i%.in}
../a.exe < $i > "$f.out"
                                                              return false:
 diff -b -q "$f.ans" "$f.out"
                                                             void print(unsigned int n) {
                                                             if (n / 10) print(n / 10);
outchar(n % 10 + '0');
Header
// use better compiler options
                                                             void print(int n) {
#pragma GCC optimize("Ofast", "unroll-loops")
                                                             if (n < 0) { outchar('-'); n*=-1; }
print((unsigned int)n);
#pragma GCC target("avx2, fma")
// include everything
#include <bits/stdc++.h>
#include <bits/extc++.h>
                                                             Common Structs
#include <sus/resource.h>
                                                             // n-dimension vectors
// Vec<2, int> v(n, m) = arr[n][m]
// Vec<2, int> v(n, m, -1) default init -1
// namespaces
using namespace std;
                                                             template < int D, typename T>
using namespace __gnu_cxx; // rope
using namespace __gnu_pbds; // tree/trie
                                                             struct Vec : public vector < Vec < D-1, T >> {
// common defines
                                                               template<typename... Args>
                                                               Vec(int n=0, Args... args) : vector<Vec<D-1,</pre>
#define fastio
\rightarrow ios_base::sync_with_stdio(0);cin.tie(0); #define_nostacklim_rlimit
                                                              \rightarrow T>>(n, Vec<D-1, T>(args...)) {}
                                                             |};
|template<typen<u>a</u>me T>
     RZ; getrlimit(3,&RZ); RZ.rlim_cur=-
                                                            struct Vec<1, T> : public vector<T> {
   Vec(int n=0, T val=T()) : vector<T>(n, val)
    1; setrlimit(3, &RZ);
#define DEBUG(v) cout<<"DEBUG: "<<#v<<" =
                                                            | → {} ·
⇒ "<<v<'\n';
#define ll long long
#define ull unsigned ll
                                                             2 Algorithms
#define i128 __int128
#define u128 unsigned i128
                                                             Min/Max Subarray
#define ld long double
// global variables
                                                             // max - compare = a < b, reset = a < 0
                                                             // min - compare = a > b. reset = a > 0
mt19937 rng((uint32_t)chrono::steady
                                                            // returns {sum, {start, end}}
pair<int, pair<int, int>>

    _clock::now().time_since_epoch().count());
                                                                  ContiguousSubarrav(int* a. int size.
Fast IO
// _unlocked is faster, but not universally
                                                                 bool(*compare)(int, int).
                                                             bool(*reset)(int), int defbest = 0) {
int best = defbest, cur = 0, start = 0, end =

→ supported (windows, codeforces)

#define inchar() getchar/*_unlocked*/()
                                                              \rightarrow 0, s = 0;
#define outchar(x) putchar/*_unlocked*/(x)
                                                             for (int i = 0; i < size; i++) {
  cur += a[i];</pre>
void read(unsigned int& n) {
 char c; n = 0;
while ((c=inchar())!=' '&&c!='\n')
n = n * 10 + c - '0';
                                                               if ((*compare)(best, cur)) { best = cur;
                                                                start = s; end = i; }
                                                               if ((*reset)(cur)) { cur = 0; s = i + 1; }
void read(int& n) {
  char c; n = 0; int s = 1;
  if ((c=inchar())=='-') s = -1;
                                                              return {best, {start, end}};
| else n = c - '0';
| while ((c=inchar())!=' '&&c!='\n')
| n = n * 10 + c - '0';
| n *= s'
                                                             Quickselect
                                                             #define QSNE -999999
                                                             int partition(int arr[], int 1, int r)
void read(ld& n) {
                                                              int x = arr[r], i = 1;
 char c; n = 0;

ld m = 0, o = 1; bool d = false; int s = 1;

if ((c=inchar())=='-') s = -1;
                                                             for (int j = 1; j <= r - 1; j++)
...if (arr[j] <= x)
```

```
. swap(arr[i++], arr[j]);
 swap(arr[i], arr[r]);
 return i;
// find k'th smallest element in unsorted
→ array, only if all distinct
int qselect(int arr[], int l, int r, int k)
 if (!(k > 0 && k <= r - 1 + 1)) return QSNE;
swap(arr[1 + rng() % (r-1+1)], arr[r]);
 int pos = partition(arr, 1, r);
 if (pos-l==k-1) return arr[pos]:
 if (pos-1>k-1) return qselect(arr,1,pos-1,k);
 return qselect(arr, pos+1, r, k-pos+1-1);
// TODO: compare against std::nth element()
Saddleback Search
// search for v in 2d array arr[x][v]. sorted

→ on both axis

pair<int, int> saddleback_search(int** arr,
 \stackrel{\cdot}{\hookrightarrow} int x, int y, int v) {
 int i = x-1, j = 0;
 while (i >= 0 && j < y) {
  if (arr[i][j] == v) return {i, j};
  (arr[i][j] > v)? i--: j++;
 return \{-1, -1\};
Ternary Search
// < max, > min, or any other unimodal func
#define TERNCOMP(a,b) (a)<(b)
int ternsearch(int a, int b, int (*f)(int)) {
 while (b-a > 4)
int m = (a+b)/2
  if (TERNCOMP((*f)(m), (*f)(m+1))) a = m;
  else b = m+1;
 for (int i = a+1; i <= b; i++)
if (TERNCOMP((*f)(a), (*f)(i)))
 . a = i;
return a:
#define TERNPREC 0.000001
double ternsearch(double a, double b, double

    (*f)(double)) {
    while (b-a > TERNPREC * 4) {
        double m = (a+b)/2;
    }
}

  if (TERNCOMP((*f)(m), (*f)(m + TERNPREC))) a
  = m;
else b = m + TERNPREC;
 for (double i = a + TERNPREC; i <= b; i +=
    TERNPREC)
     if (TERNCOMP((*f)(a), (*f)(i)))
 return á;
3 Data Structures
Fenwick Tree
// Fenwick tree, array of cumulative sums -
 \rightarrow O(\log n) updates, O(\log n) gets
struct Fenwick {
int n; ll* tree;
 void update(int i, int val) {
  .++i:
  while (i <= n) {
   tree[i] += val:
  i += i & (-i);
 Fenwick(int size) {
  n = size;
  tree = new ll[n+1];
  for (int i = 1; i \le n; i++)
  tree[i] = 0;
 Fenwick(int* arr, int size) : Fenwick(size) {
  for (int i = 0; i < n; i++)</pre>
```

```
update(i, arr[i]);
  ~Fenwick() { delete[] tree; }
 11 operator[](int i) {
  if (i < 0 || i > n) return 0;
  while (i>0)
   sum += tree[i]:
   i -= i & (-i);
  return sum;
 11 getRange(int a, int b) { return
    operator[](b) - operator[](a-1); }
Hashtable
// similar to unordered map, but faster
struct chash {
  const uint64 t C = (11)(2e18 * M_PI) + 71;
  ll operator()(11 x) const { return
    __builtin_bswap64(x*C); }
int main() {
  gp_hash_table<11,int,chash>
    hashtable({},{},{},{},{1<<16});
for (int i = 0; i < 100; i++)
  hashtable[i] = 200+i;
  if (hashtable.find(10) != hashtable.end())
  cout << hashtable[i];</pre>
Ordered Set
typedef tree<int,null_type,less<int>,rb_tree
     _tag,tree_order_statistics_node update>
⇒ ordered int main()
    ordered set;
 lordered_set o_set;
o_set.insert(5); o_set.insert(1);
 \rightarrow o_set.insert(3);
 // get second smallest element
 cout << *(o_set.find_by_order(1)) << '\n';
 // number of elements less than k=4
 cout << o_set.order_of_key(4) << '\n';
Rope
// O(\log n) insert, delete, concatenate
int main() {
 // generate rope
 rope<int> v;
 for (int i = 0: i < 100: i++)
  v.push_back(i);
 // move range to front
 rope<int> copy = v.substr(10, 10);
 v.erase(10, 10):
 v.insert(copy.mutable_begin(), copy);
 // print elements of rope
 for (auto it : v) cout << it << " ";
Segment Tree
//max(a,b), min(a,b), a+b, a*b, gcd(a,b), a*b
struct SegmentTree {
 typedef int T:
 static constexpr T UNIT = INT MIN;
 T f(Ta, Tb) {
  if (a == UNIT) return b;
if (b == UNIT) return a;
  return max(a,b);
 int n; vector<T> s;
SegmentTree(int n, T def=UNIT) : s(2*n, def),
 SegmentTree(vector<T> arr) :

    SegmentTree(arr.size()) {
    for (int i=0;i<arr.size();i++)
}
</pre>

    update(i,arr[i]);
```

```
void update(int pos, T val) {
 for (s[pos += n] = val; pos /= 2;)
                                                           sq.push(s[e].go[c]);
   s[pos] = f(s[pos * 2], s[pos*2+1]);
 T query(int b, int e) { // query [b, e)
 Tra = UNIT, rb = UNIT; query [15].
for (b+=n, e+=n; b<e; b/=2, e/=2) {
    if (b % 2) ra = f(ra, s[b++]);
    if (e % 2) rb = f(s[--e], rb);
  return f(ra. rb):
                                                        int cur = 0;
 T get(int p) { return query(p, p+1); }
                                                          cur = s[cur].fail;
Trie
                                                         if (s[cur].out.size())
typedef trie<string, null_type,

→ trie_string_access_traits<>,

 .pat_trie_tag,
                                                          end.second});

→ trie_prefix_search_node_update> trie type;

int main() {
                                                        return toret:
 // generate trie
 trie_type trie;
 for (int i = 0; i < 20; i++)
 trie.insert(to_string(i)); // true if new,
                                                      Bover Moore
struct defint { int i = -1; };
 // print things with prefix "1"
 auto range = trie.prefix_range("1");
 for (auto it = range.first; it !=

    range.second; it++)

                                                       → defint> badchar:
  cout << *it << "
                                                         = i:
   String
                                                       int s = 0:
                                                       while (s <= n - m) {
  int j = m - 1;
Aho Corasick
// range of alphabet for automata to consider
// MAXC = 26. OFFC = 'a' if only lowercase
                                                        if (j < 0) {
const int MAXC = 256;
const int OFFC = 0;
                                                         .toret.push_back(s);
struct aho_corasick {
   struct state
                                                       \rightarrow m]].\dot{i}: 1;
  set<pair<<u>int</u>, <u>int</u>>> out;
 int fail; vector<int> go;
                                                       return toret;
  state(): fail(-1), go(MAXC, -1) {}
 vector<state> s;
                                                      English Conversion
 int id = 0;
```

aho_corasick(string* arr, int size) : s(1) { for (int i = 0; i < size; i++) { int cur = 0: for (int c : arr[i]) { if (s[cur].go[c-OFFC] == -1) { ...s[cur].go[c-OFFC] = s.size();s.push_back(state()); cur = s[cur].go[c-OFFC];s[cur].out.insert({arr[i].size(), id++}); for (int c = 0; c < MAXC; c++) if (s[0].go[c] == -1) $..s[0].go[\tilde{c}] = 0;$ aueue<int> sq; for (int c = 0; c < MAXC; c++) { if (s[0].go[c] != 0) { s[s[0].go[c]].fail = 0; sq.push(s[0].go[c]); while (sq.size()) { int e = sq.front(); sq.pop(); for (int c = 0; c < MAXC; c++) { if (s[e].go[c] != -1) {</pre> int failure = s[e].fail; while (s[failure].go[c] == -1) ... failure = s[failure].fail; failure = s[failure].go[c];

s[s[e].go[c]].fail = failure;

```
....for (auto length : s[failure].out)
 s[s[e].go[c]].out.insert(length);
 // list of {start pos, pattern id}
 vector<pair<int, int>> search(string text)
  vector<pair<int, int>> toret;
  for (int i = 0; i < text.size(); i++) {
  while (s[cur].go[text[i]-OFFC] == -1)</pre>
   cur = s[cur].go[text[i]-OFFC];
    for (auto end : s[cur].out)
. toret.push_back({i - end.first + 1,
vector<int> boyermoore(string txt, string pat)
 vector<int> toret; unordered_map<char,
 int m = pat.size(), n = txt.size();
 for (int i = 0; i < m; i++) badchar[pat[i]].i
  while (j \ge 0 \&\& pat[j] == txt[s + j]) j--;
   s += (s + m < n) ? m - badchar[txt[s +
   s += \max(1, i - badchar[txt[s + i]].i):
const string ones[] = {"", "one", "two",
   "three", "four", "five", "six", "seven", "eight", "nine"];
const string teens[] ={"ten", "eleven",
    "twelve", "thirteen", "fourteen",
"fifteen", "sixteen", "seventeen",
"eighteen", "nineteen"};
const string tens[] = {"twenty", "thirty",
    "forty", "fifty", "sixty", "seventy", "eighty", "ninety";
const string mags[] = {"thousand", "million",
     "billion", "trillion", "quadrillion",
     "quintillion", "sextillion",
    "septillion"};
string convert(int num, int carry) {
 if (num < 0) return "negative " +
    convert(-num, 0);
if (num < 10) return ones[num];
if (num < 20) return teens[num % 10];
 if (\text{num} < 100) return tens (\text{num} / 10) - 2 + 100
     (num%10==0?"":" ") + ones[num % 10];
     (num < 1000) return ones[num / 100]
    (num/100==0?"":" ") + "hundred" + (num%100==0?"":" ") + convert(num % 100,
    0);
 return convert(num / 1000, carry + 1) + " " +
    mags[carry] + " " + convert(num % 1000,
    0);
```

```
|string convert(int num) {
 return (num == 0) ? "zero" : convert(num, 0);
Knuth Morris Pratt
vector<int> kmp(string txt, string pat) {
     vector<int> toret;
 int m = txt.length(), n = pat.length();
 int next[n + 1]:
 for (int i = 0; i < n + 1; i++)
.next[i] = 0;
.for (int i = 1; i < n; i++) {
.int j = next[i + 1];
  .while (j > 0 && pat[j] != pat[i])
   .j = next[j];
  .if (j > 0 || pat[j] == pat[i])
   next[i + 1] = j + 1;
 for (int i = 0, j = 0; i < m; i++) {
  if (txt[i] == pat[j]) {
  if (++j == n)
    toret.push_back(i - j + 1);
  } else if (j > 0) {
...j = next[j];
 return toret;
Longest Common Prefix
string lcp(string* arr, int n) {
 if (n == 0) return ""
 sort(arr, arr + n);
string r = ""; int v = 0;
 while (v < arr[0].length() && arr[0][v] ==
 → arr[n-1][v])
∴r += arr[0][v++];
 return r;
Longest Common Subsequence
string lcs(string a, string b) {
 int m = a.length(), n = b.length();
 int L[m+1][n+1];
 for (int i = 0; i <= m; i++) {
    for (int j = 0; j <= n; j++) {
        if (i == 0 || j == 0) L[i][j] = 0;
    else if (a[i-1] == b[j-1]) L[i][j] =
  L[i-1][j-1]+1; 

...else L[i][j] = max(L[i-1][j], L[i][j-1]); 
 // return L[m][n]; // length of lcs
 string out = "";

int i = m - 1, j = n - 1;

while (i >= 0 && j >= 0) {

if (a[i] == b[j]) {
  .out = a[i--] + out;
  else if (L[i][j+1] > L[i+1][j]) i--;
  else j--;
 return out;
Longest Common Substring
 // l is array of palindrome length at that
 \hookrightarrow index
int manacher(string s, int* 1) {
 int n = s.length() * 2;
 for (int i = 0, j = 0, k; i < n; i += k, j =
 \rightarrow max(j-k, 0)) {
 while (i \ge j \&\& i + j + 1 < n \&\& s[(i-j)/2]]
 \Rightarrow == s[(i+j+1)/2]) j++;
  .1[i] = j;
  for (k = 1; i >= k && j >= k && l[i-k] !=
```

```
1[i+k] = min(1[i-k], j-k);
return *max element(1, 1 + n):
Subsequence Count
// "banana", "ban" >> 3 (ban, ba..n, b..an)
ull subsequences(string body, string subs) {
 int m = subs.length(), n = body.length();
 if (m > n) return 0;
 ull** arr = new ull*[m+1];
for (int i = 0; i <= m; i++) arr[i] = new
 \rightarrow ull[n+1];
 for (int i = 1; i <= m; i++) arr[i][0] = 0;
for (int i = 0; i <= n; i++) arr[0][i] = 1;
for (int i = 1; i <= m; i++)

for (int j = 1; j <= n; j++)

arr[i][j] = arr[i][j-1] + ((body[j-1] ==
\rightarrow subs[i-1])? arr[i-1][i-1] : 0):
return arr[m][n]:
5 Math
Catalan Numbers
ull* catalan = new ull[1000000];
void genCatalan(int n, int mod) {
  catalan[0] = catalan[1] = 1;
  for (int i = 2; i <= n; i++) {
    catalan[i] = 0;</pre>
  for (int j = i - 1; j >= 0; j--) {
    catalan[i] += (catalan[j] * catalan[i-j-1])
   if (catalan[i] >= mod)
    .catalan[i] -= mod;
// TODO: consider binomial coefficient method
Combinatorics (nCr, nPr)
// can optimize by precomputing factorials, and
\rightarrow fact[n]/fact[n-r]
ull nPr(ull n, ull r) {
 ull v = 1
 for (ull i = n-r+1; i \le n; i++)
.v *= i;
return v:
ull nPr(ull n, ull r, ull m) {
 for (ull i = n-r+1; i <= n; i++)
. v = (v * i) % m;
 return v;
ull nCr(ull n, ull r) {
 long double v = 1;
 for (ull i = 1; i <= r; i++)
 v = v * (n-r+i) /i;
return (ull)(v + 0.001);
// requires modulo math
// can optimize by precomputing mfac and
ull nCr(ull n, ull r, ull m) {
return mfac(n, m) * minv(mfac(k, m), m) % m *
\downarrow \rightarrow \min_{k} \min_{k} (mfac(n-k, m), m) \% m;
Chinese Remainder Theorem
bool ecrt(ll* r, ll* m, int n, ll& re, ll& mo)
 11 x, y, d; mo = m[0]; re = r[0];
 for (int i = 1; i < n; i++) {
  d = egcd(mo, m[i], x, y);
 if ((r[i] - re) % d != 0) return false;

x = (r[i] - re) / d * x % (m[i] / d);

re += x * mo;
  mo = mo / d * m[i];
  re %= mo;
 re = (re + mo) % mo;
return true;
```

```
Count Digit Occurences
 /*count(n,d) counts the number of occurences of
 \hookrightarrow a digit d in the range [0,n]*/
ll digit_count(ll n, ll d) {
 ll result = 0;
 while (n != 0) {
result += ((n%10) == d ? 1 : 0);
  n /= 10:
 return result:
11 count(11 n, 11 d) {
   if (n < 10) return (d > 0 && n >= d);
   if ((n % 10) != 9) return digit_count(n, d) +
 \rightarrow count(n-1, d);
return 10*count(n/10, d) + (n/10) + (d > 0);
Discrete Logarithm
unordered_map<int, int> dlogc;
int discretelog(int a, int b, int m) {
 dlogc.clear();
ll n = sqrt(m)+1, an = 1;
 for (int i = 0; i < n; i++)
an = (an * a) % m;
  11 c = an;
 for (int i = 1; i \le n; i++)
  if (!dlogc.count(c)) dlogc[c] = i;
  c = (c * an) \% m;
 for (int i = 0; i <= n; i++) {
  if (dlogc.count(c)) return (dlogc[c] * n - i
 \rightarrow + m - 1) % (m-1);
c = (c * a) % m;
return -1;
Euler Phi / Totient
int phi(int n) {
 int^r = n;
 for (int i = 2; i * i <= n; i++) {
    if (n % i == 0) r -= r / i;
    while (n % i == 0) n /= i;
 if (n > 1) r -= r / n;
return r;
}
#define n 100000
ll phi[n+1];
void computeTotient() {
 for (int i=1; i<=n; i++) phi[i] = i;
for (int p=2; p<=n; p++) {
  if (phi[p] == p) {
  ...phi[p] = p-1;
  for (int i = 2*p; i<=n; i += p) phi[i] =
 \hookrightarrow (phi[i]/p) * (\bar{p}-1);
Factorials
 // digits in factorial
 #define kamenetsky(n) (floor((n * log10(n /
 \rightarrow ME)) + (loq10(2 * MPI * n) / 2.0)) + 1)
// approximation of factorial
#define stirling(n) ((n == 1) ? 1 : sqrt(2 *
 \rightarrow M PI * n) * pow(n / M E, n))
// natural log of factorial
#define lfactorial(n) (lgamma(n+1))
Prime Factorization
 // do not call directly
ll pollard rho(ll n. ll s) {
 x = y = rand() \% (n - 1) + 1;
 int head = 1, tail = 2;
while (true) {
```

x = mult(x, x, n);

```
x = (x + s) \% n;
if (x == y) return n;
  11 d = _{gcd(max(x - y, y - x), n);}
  if (1 < \overline{d} \&\& d < n) return d:
  if (++head == tail) y = x, tail <<= 1;
// call for prime factors
void factorize(ll n, vector<ll> &divisor) {
  if (n == 1) return;
 if (isPrime(n)) divisor.push_back(n);
 else {
...ll d = n:
  while (d'>= n) d = pollard_rho(n, rand() %
factorize(n / d, divisor);
factorize(d, divisor);
Farey Fractions
// generate 0 \le a/b \le 1 ordered, b \le n
   farey(4) = 0/1 1/4 1/3 1/2 2/3 3/4 1/1
// length is sum of phi(i) for i = 1 to n
vector<pair<int, int>> farev(int n) {
 int h = 0, k = 1, x = 1, y = 0, r;
 vector<pair<int, int>> v;
  v.push_back({h, k});
  r = (n-y)/k;
  y += r*k; x' += r*h;
swap(x,h); swap(y,k);
x = -x; y = -y;
while (k > 1);
 v.push_back({1, 1});
 return v;
Fast Fourier Transform
const double PI = acos(-1);
void fft(vector<cd>& a, bool invert) {
 int n = a.size();
 for (int i = 1, j = 0; i < n; i++) {
  int bit = n >> 1;
 for (; j & bit; bit >>= 1) j ^= bit;
j ^= bit;
  if (i < j) swap(a[i], a[j]);
 for (int len = 2; len <= n; len <<= 1) {
    double ang = 2 * PI / len * (invert ? -1 :
  cd wien(cos(ang), sin(ang));
for (int i = 0; i < n; i += len) {
   .cd w(1);
  for (int j = 0; j < len / 2; j++) {
.cd u = a[i+j], v = a[i+j+len/2] * w;
    a[i+j] = u + v;
a[i+j+len/2] = u - v;
    .w *= wlen;
 if (invert)
  for (auto& x : a)
  x /= n;
vector<int> fftmult(vector<int> const& a,

  vector<int> const& b) {
  vector<cd> fa(a.begin(), a.end()),

    fb(b.begin(), b.end());

int n = 1 << (32 - _builtin_clz(a.size() +

→ b.size() - 1));
fa.resize(n); fb.resize(n);
fft(fa, false); fft(fb, false);
for (int i = 0; i < n; i++) fa[i] *= fb[i];</pre>
 fft(fa, true);
 vector<int> toret(n);
 for (int i = 0; i < n; i++) toret[i] =
→ round(fa[i].real());
return toret;
```

```
Greatest Common Denominator
                                                                Sieve of Eratosthenes
11 egcd(11 a, 11 b, 11& x, 11& y) {
  if (b == 0) { x = 1; y = 0; return a; }
                                                               bitset<100000001> sieve:
 11 gcd = egcd(b, a % b, x, y);
 x = a / b * y;
 swap(x, y);
 return gcd;
Josephus Problem
// 0-indexed, arbitrary k
int josephus(int n, int k) {
  if (n == 1) return 0;
  if (k == 1) return n-1;
 if (k > n) return (josephus(n-1,k)+k)%n;
 int res = josephus(n-n/k,k)-n\%k;
 return res + ((res<0)?n:res/(k-1));
// fast case if k=2, traditional josephus
int josephus(int n) {
 return 2*(n-(1<<(32-\_builtin_clz(n)-1)));
Least Common Multiple
#define lcm(a,b) ((a*b)/__gcd(a,b))
Modulo Operations
#define MOD 1000000007
#define madd(a,b,m) (a+b-((a+b-m>=0)?m:0)) #define mult(a,b,m) ((ull)a*b\%m) #define msub(a,b,m) (a-b+((a<b)?m:0))
11 mpow(ll b, ll e, ll m) {
 \overline{11} \times = 1;
 while (e > 0) {
    if (e % 2) x = (x * b) % m;
    b = (b * b) % m;
  e /= 2:
 return x % m:
ull mfac(ull n, ull m) {
  ull f = 1;
 for (int i = n; i > 1; i--)
 return f;
// if m is not guaranteed to be prime
11 minv(11 b, 11 m) {
 11 x = 0, y = 0;

if (egcd(b, m, x, y) != 1) return -1;
 return (x \% m + m) \% m:
11 mdiv_compmod(int a, int b, int m) {
  if (_gcd(b, m) != 1) return -1;
 return mult(a, minv(b, m), m);
// if m is prime (like 10^9+7)
11 mdiv_primemod (int a, int b, int m) {
 return mult(a, mpow(b, m-2, m), m);
Miller-Rabin Primality Test
// Miller-Rabin primality test - O(10 log^3 n)
bool isPrime(ull n) {
  if (n < 2) return false;</pre>
 if (n < 2) return false;
if (n = 2) return true;
if (n % 2 == 0) return false;
ull s = n - 1;
while (s % 2 == 0) s /= 2;
for (int i = 0; i < 10; i++) {</pre>
  ull temp = s:
  ull a = rand() % (n - 1) + 1;
ull mod = mpow(a, temp, n);
   while (temp!=n-1\&\&mod!=1\&\&mod!=n-1) {
   mod = mult(mod, mod, n);
    temp *= 2;
  if (mod!=n-1&&temp%2==0) return false;
 return true:
```

```
// generate sieve - O(n log n)
void genSieve(int n) {
void gensieve(int i) {
    sieve[0] = sieve[1] = 1;
    for (ull i = 3; i * i < n; i += 2)
        if (!sieve[i])</pre>
   for (ull j = i * 3; j <= n; j += i * 2)
...sieve[j] = 1;</pre>
// query sieve after it's generated - O(1)
bool querySieve(int n) {
 return n == 2 || (n % 2 != 0 && !sieve[n]);
Simpson's / Approximate Integrals
// integrate f from a to b, k iterations 

// error <= (b-a)/18.0 * M * ((b-a)/2k)^4
// where M = max(abs(f´``(x))) for x in [a,b]
// "f" is a function "double func(double x)"
double Simpsons (double a, double b, int k,
 \begin{array}{ll} \rightarrow & \text{double (*f)(double)) } \{\\ & \text{double dx = (b-a)/(2.0*k), t = 0;} \end{array}
 for (int i = 0; i < k; i++)

t += ((i==0)?1:2)*(*f)(a+2*i*dx) + 4 *
\leftrightarrow (*f)(a+(2*i+1)*dx);
return (t + (*f)(b)) * (b-a) / 6.0 / k;
Common Equations Solvers
// ax^2 + bx + c = 0, find x
vector<double> solveEq(double a, double b.
double c) {
.vector<double> r;
.double z = b * b - 4 * a * c;
 if (z == 0)
  r.push_back(-b/(2*a));
 else if (z > 0) {
   r.push_back((sqrt(z)-b)/(2*a));
  r.push\_back((sqrt(z)+b)/(2*a));
 .}
return r:
\frac{1}{2} / ax^3 + bx^2 + cx + d = 0, find x
vector < double > solve Eq (double a, double b,

    double c, double d) {
    vector < double > res;
}

 long double a1 = b/a, a2 = c/a, a3 = d/a:
 long double q = (a1*a1 - 3*a2)/9.0, sq =
\rightarrow -2*sqrt(q);
 long double r = (2*a1*a1*a1 - 9*a1*a2 +
 \rightarrow 27*a3)/54.0;
long double z = r*r-q*q*q, theta;
 if (z <= 0) {
  theta = acos(r/sqrt(q*q*q));
  res.push_back(sq*cos(theta/3.0) - a1/3.0);
  res.push_back(sq*cos((theta+2.0*PI)/3.0)
 \rightarrow a1/3.0):
  res.push_back(sq*cos((theta+4.0*PI)/3.0) -
 \rightarrow a1/3.0);
  res.push_back(pow(sqrt(z)+fabs(r), 1/3.0));
  res[0] = (res[0] + q / res[0]) *
((r<0)?1:-1) - a1 / 3.0;
 return res;
\frac{1}{2} linear diophantine equation ax + by = c,
\hookrightarrow find x and y
// infinite solutions of form x+k*b/g, y-k*a/g bool solveEq(11 a, 11 b, 11 c, 11 &x, 11 &y,
 g = egcd(abs(a), abs(b), x, y);
 if (c % g) return false;
 x *= c / g * ((a < 0) ? -1 : 1);
```

```
y *= c / g * ((b < 0) ? -1 : 1);
                                                          .int s = (a[0]!=-1 \&\& a[1]!=-1 ? a[0] :
 return true:
                                                          \rightarrow (a[0]==-1 && a[1]==-1 ? edges[0].u : -1));
                                                          if(s==-1) return false;
// m = # equations, n = # variables, a[m][n+1]
                                                           while(!st.empty() || !graph[s].empty()) {
\rightarrow = coefficient matrix
                                                           if (graph[s].empty()) {
// a[i][0]x + a[i][1]y + ... + a[i][n]z =
                                                             circuit.push_back(s); s = st.top();
\stackrel{\hookrightarrow}{\sim} a[i][n+1] const double eps = 1e-7;
                                                            st.pop(); }
                                                            else {
bool zero(double a) { return (a < eps) && (a >
                                                             int w = edges[*graph[s].begin()].v;
                                                             graph[s].erase(graph[s].begin());
vector < double > solveEq(double **a, int m, int
                                                             st.push(s); s = w;
\underset{int}{\hookrightarrow} n) { int cur = 0:
 for (int i = 0; i < n; i++) {
                                                           circuit.push back(s):
for (int j = cur; j < m; j++) {
    if (!zero(a[j][i])) {
                                                          return circuit.size()-1==edges.size();
 ...if (j != cur) swap(a[j], a[cur]);
  for (int sat = 0; sat < m; sat++) {
   if (sat == cur) continue;
   double num = a[sat][i] / a[cur][i];
                                                        Minimum Spanning Tree
                                                         // returns vector of edges in the mst
  for (int sot = 0; sot <= n; sot++)
a[sat][sot] -= a[cur][sot] * num;
                                                         // graph[i] = vector of edges incident to
    cur++:
                                                            places total weight of the mst in Stotal
                                                         // if returned vector has size != n-1, there is
    break:
                                                        vector<edge> mst(vector<vector<edge>> graph,
                                                         → 11 &total) {
 for (int j = cur; j < m; j++)
   if (!zero(a[j][n])) return vector<double>();
                                                         priority_queue<edge, vector<edge>,
 vector<double> ans(n,0);
                                                            greater<edge>> pq;
for (int i = 0, sat = 0; i < n; i++)
    if (sat < m && !zero(a[sat][i]))
    ans[i] = a[sat][n] / a[sat++][i];
                                                         vector<edge> MST;
                                                         bitset<20001> marked; // change size as

\begin{array}{c}
\rightarrow & needed \\
narked[0] = 1;
\end{array}

                                                         for (edge ep : graph[0]) pq.push(ep);
while(MST.size()!=graph.size()-1 &&
    Graph
                                                            pq.size()!=0) {
struct edge {
                                                           edge e = pq.top(); pq.pop();
int u,v,w;
edge (int u,int v,int w) : u(u),v(v),w(w) {}
                                                          int u = e.u, v = e.v, w = e.w;
if(marked[u] && marked[v]) continue;
 edge (): u(0), v(0), w(0) {}
                                                           else if(marked[u]) swap(u, v);
                                                           for(edge ep : graph[u]) pq.push(ep);
bool operator < (const edge &e1, const edge
                                                           marked[u] = 1:
\rightarrow &e2) { return e1.w < e2.w: }
                                                           MST.push_back(e);
bool operator > (const edge &e1, const edge
                                                          total += e.w:
return MST;
struct subset { int p, rank; };
Eulerian Path
                                                         Union Find
#define edge_list vector<edge>
#define adj sets vector<set<int>>>
                                                        int uf_find(subset* s, int i) {
  if (s[i].p!= i) s[i].p = uf_find(s, s[i].p);
struct EulerPathGraph {
                                                         return s[i].p;
adj_sets graph; // actually indexes incident

→ edges

                                                        void uf_union(subset* s, int x, int y) {
 edge_list edges; int n; vector<int> indeg;
                                                         int xp = uf_find(s, x), yp = uf_find(s, y);
 EulerPathGraph(int n): n(n) {
                                                         if (s[xp].rank > s[yp].rank) s[yp].p = xp;
 indeg = *(new vector<int>(n,0));
                                                         else if (s[xp].rank < s[yp].rank) s[xp].p =
 graph = *(new adj_sets(n, set<int>()));

    yp;
else { s[yp].p = xp; s[xp].rank++; }

 void add_edge(int u, int v) 
  graph[u].insert(edges.size());
                                                             2D Geometry
  indeg[v]++;
  edges.push_back(edge(u,v,0));
                                                        #define point complex<double>
                                                        #define EPS 0.0000001
 bool eulerian_path(vector<int> &circuit) {
                                                        #define sq(a) ((a)*(a))
  if(edges.size()==0) return false;
                                                        #define c\bar{b}(a) ((a)*(a)*(a))
  stack<int> st;
                                                        double dot(point a, point b) { return
  int a[] = {-1, -1};

→ real(conj(a)*b); }

  for(int v=0;v<n;v++) {
  if(indeg[v]!=graph[v].size()) {
                                                        double cross (point a, point b) { return

    imag(conj(a)*b); }

 bool b = indeg[v] > graph[v].size();
                                                        struct line { point a, b; };
struct circle { point c; double r; };
struct segment { point a, point b; };
...if (abs(((int)indeg[v])-((int)graph[v]
     .size())) > 1) return
    false;
(a[b]
a[b] = v;
                                                        struct triangle { point a, b, c; };
....if (a[b] != -1) return false;
                                                        struct rectangle { point tl, br; };
                                                        struct convex_polygon {
                                                        vector<point points;
```

```
convex_polygon(vector<point> points) :
 → points(points) {}
 convex_polygon(triangle a) {
 points.push_back(a.a); points.push_back(a.b);
    points.push back(a.c);
 convex_polygon(rectangle a) {
 points.push_back(a.tl);
    points.push back({real(a.tl).
    imag(a.br)});
  points.push_back(a.br);
    points.push_back({real(a.br),
    imag(a.tl)}):
struct polygon {
 vector<point> points;
 polygon(vector<point> points) :
 → points(points) {}
 polygon(triangle a) {
 points.push_back(a.a); points.push_back(a.b); Intersection
    points.push back(a.c);
 polygon(rectangle a) {
 points.push_back(a.tl);
    points.push_back({real(a.tl),
    imag(a.br)});
  points.push_back(a.br);
    points.push back({real(a.br).
    imag(a.tl)}):
 polygon(convex_polygon a) {
  for (point v : a.points)
   points.push_back(v);
// triangle methods
double area heron(double a, double b, double c)
 \overrightarrow{i}f (a < b) swap(a, b);
 if (a < c) swap(a, c):
 if (b < c) swap(b, c);
 if (a > b + c) return -1;
return sqrt((a+b+c)*(c-a+b)*(c+a-b)*(a+b-c)
   /16.0):
// segment methods
double lengthsq(segment a) { return
    sq(real(a.a) - real(a.b)) + sq(imag(a.a) -
    imag(a.b)); }
double length(segment a) { return
    sqrt(lengthsq(a)); }
   circle methods
double circumference(circle a) { return 2 *
\rightarrow a.r * M_PI; }
double area(circle a) { return sq(a.r) * M PI:
| \rightarrow \rangle rectangle methods
double width(rectangle a) { return
\rightarrow abs(real(a.br) - real(a.tl)); }
double height (rectangle a) { return

→ abs(imag(a.br) - real(a.tl)); }

double diagonal (rectangle a) { return

    sqrt(sq(width(a)) + sq(height(a)));
]
double area (rectangle a) { return width(a) *
→ height(a); }
double perimeter(rectangle a) { return 2 *
\hookrightarrow (width(a) + height(a)); }
// check if `a` fit's inside `b
// swap equalities to exclude tight fits
bool doesfitInside(rectangle a, rectangle b) {
 int x = width(a), w = width(b), y = height(a),
\rightarrow h = height(b);
if (x > y) swap(x, y);
```

```
if (w > h) swap(w, h);
 if (w < x) return false;
 if (y <= h) return true;
double a=sq(y)-sq(x), b=x*h-y*w, c=x*w-y*h;
return sq(a) \le sq(b) + sq(c);
// polygon methods
// get both area and centroid
pair<double, point> area(polygon a) {
 int n = a.points.size();
 double area = 0;
point c(0, 0);
for 9int i = n - 1, j = 0; j < n; i = j++) {
 double a = cross(a.points[i], a.points[j])
 area += a;
 c += (a.points[i] + a.points[j]) * (a / 3);
c /= area;
return {c, area};
// -1 coincide, 0 parallel, 1 intersection
int intersection(line a, line b, point& p)
if (abs(cross(a.b - a.a, b.b - b.a)) > EPS) {
 p = cross(b.a - a.a, b.b - a.b) / cross(a.b)
\Rightarrow a.a, b.b - b.a) * (b - a) + a;
 return 1:
if (abs(cross(a.b - a.a, a.b - b.a)) > EPS)

    return 0;

return -1;
// area of intersection
double intersection(circle a, circle b) {
  double d = abs(a.c - b.c);
  if (d <= b.r - a.r) return area(a);
  if (d <= a.r - b.r) return area(b);</pre>
 if (d \ge a.r + b.r) return 0;
double alpha = acos((sq(a.r) + sq(d) -
\Rightarrow sq(b.r)) / (2 * a.r * d));
double beta = acos((sq(b.r) + sq(d) -
\rightarrow sq(a.r)) / (2 * b.r * d));
return sq(a.r) * (alpha - 0.5 * sin(2 *
    alpha)) + sq(b.r) * (beta - 0.5 * sin(2 *
   beta)):
// -1 outside, 0 inside, 1 tangent, 2
intersection circle a. circle b.
→ vector<point>& inter) {
double d2 = norm(b.c - a.c), rS = a.r + b.r
\rightarrow rD = a.r - b.r;
if (d2 > sq(rS)) return -1;
if (d2 < sq(rD)) return 0;
 double ca = 0.5 * (1 + rS * rD / d2);
 point z = point(ca, sqrt(sq(a.r) / d2 -
\rightarrow sq(ca));
 inter.push back(a.c + (b.c - a.c) * z);
 if (abs(imag(z)) > EPS) inter.push_back(a.c +
\rightarrow (b.c - a.c) * conj(z));
return inter.size():
// points of intersection
vector<point> intersection(line a, circle c) {
vector<point> inter;
.c.c -= a.a;
.a.b -= a.a;
 point m = a.b * real(c.c / a.b);
 double d2 = norm(m - c.c);
if (d2 > sq(c.r)) return 0;
 double l = sqrt((sq(c.r) - d2) / norm(a.b));
 inter.push_back(a.a + m + 1 * a.b);
if (abs(1) > EPS) inter.push_back(a.a + m - 1
return inter;
// area of intersection
```

```
double intersection(rectangle a, rectangle b)
                                                      // SameNumberOfOneBits, next permutation
                                                      int snoob(int a) {
  int b = a & -a, c = a + b;
 double x1 = max(real(a.tl), real(b.tl)), y1 =
                                                       return c | ((a^ c) >> 2) / b;

→ max(imag(a.tl), imag(b.tl));
double x2 = min(real(a.br), real(b.br)), y2 =
                                                       // example usage
                                                      int main() {
  char l1[] = {'1', '2', '3', '4', '5'};
  char l2[] = {'a', 'b', 'c', 'd'};
  int d1 = 5, d2 = 4;

→ min(imag(a.br), imag(b.br));
return (x2 \le x1 \mid | y2 \le y1)?
    (x2-x1)*(y2-y1);
                                                        // prints 12345abcd, 1234a5bcd,
                                                       int min = (1 << d1) -1, max = min << d2;
Convex Hull
                                                       for (int i = min; i <= max; i = snoob(i)) {
  int p1 = 0, p2 = 0, v = i;
bool cmp(point a, point b) {
if (abs(real(a) - real(b)) > EPS) return
                                                        while (p1 < d1 || p2 < d2) {
    cout << ((v & 1) ? 11[p1++] : 12[p2++]);
    real(a) < real(b);
if (abs(imag(a) - imag(b)) > EPS) return
                                                         .v /= 2;

    imag(a) < imag(b);
</pre>
return false;
                                                         cout << '\n';
convex_polygon convexhull(polygon a) {
 sort(a.points.begin(), a.points.end(), cmp);
 vector<point> lower, upper;
 for (int i = 0; i < a.points.size(); i++) {
                                                      Powers
 while (lower.size() >= 2 &&
                                                      bool isPowerOf2(11 a) {
    cross(lower.back() - lower[lower.size()
                                                       return a > 0 \&\& !(a \& a-1);
   2], a.points[i] - lower.back()) < EPS)
  lower.pop_back();
                                                      bool isPowerOf3(11 a) {
   return a>0&&!(12157665459056928801ull%a);
  while (upper.size() >= 2 &&
    cross(upper.back() - upper[upper.size()
                                                      bool isPower(ll a, ll b) {
double x = log(a) / log(b);
   2], a.points[i] - upper.back()) > -EPS)
   upper.pop_back();
                                                       return abs(x-round(x)) < 0.00000000001;
  lower.push_back(a.points[i]);
  upper.push_back(a.points[i]);
 lower.insert(lower.end(), upper.rbegin() + 1,
                                                      10 Additional

    upper.rend());

return convex_polygon(lower);
                                                      Judge Speed
                                                        / kattis: 0.50s
                                                       // codeforces: 0.421s
    3D Geometry
                                                      #include <bits/stdc++.h>
struct point3d {
                                                      using namespace std;
double x, y, z;
                                                      int \vec{v} = 1e9/2, p = 1;
.point3d operator+(point3d a) const { return
                                                      int main() {
                                                           for (int i = 1; i <= v; i++) p *= i;
\rightarrow {x+a.x, y+a.y, z+a.z}; }
                                                           cout << p;
point3d operator*(double a) const { return
\rightarrow {x*a, v*a, z*a}; }
point3d operator-() const { return {-x, -y,
\hookrightarrow -z}; }
                                                       Judge Error Codes
point3d operator-(point3d a) const { return
                                                       // each case tests a different fail condition
\leftrightarrow *this + -a; }
                                                       // try them before contests to see error codes
point3d operator/(double a) const { return
double norm() { return x*x + y*y + z*z; }
double abs() { return sqrt(norm()); }
                                                      struct g { int arr[1000000]; g(){}};
                                                      vector<ğ> a;
                                                      // O=WA 1=TLE 2=MLE 3=OLE 4=SIGABRT 5=SIGFPE
                                                           6=SIGSEGV 7=recursive MLE judge(int n) {
 point3d normalize() { return *this /
   this->abs(); }
                                                           (n == 0) exit(0);
(n == 1) while(1);
double dot(point3d a, point3d b) { return
                                                       if (n == 2) while (1) a.push_back(g());
\rightarrow a.x*b.x + a.y*b.y + a.z*b.z;
                                                       if (n == 3) while(1) putchar_unlocked('a');
point3d cross(point3d a, point3d b) { return
                                                       if (n == 4) assert(0);
    {a.y*b.z - a.z*b.y, a.z*b.x - a.x*b.z,
                                                           (n == 5) 0 / 0;
                                                       if
                                                       if (n == 6) * (int*)(0) = 0;
\stackrel{\Longrightarrow}{\rightarrow} a.x*b.y - a.y*b.x}; }
                                                       return n + judge(n + 1);
struct line3d { point3d a, b; };
struct plane { double a, b, c, d; } // a*x +
\rightarrow b*y + c*z + d = 0
struct sphere { point3d c; double r; };
                                                      Limits
#define sq(a) ((a)*(a))
                                                                                           \pm 2^{31} - 1|10^9
#define c\bar{b}(a) ((a)*(a)*(a))
                                                                          \pm 2147483647
                                                      int
                                                                                             \bar{2}^{32} - \bar{1}|\bar{1}^{9}|
double surface(circle a) { return 4 * sq(a.r)
                                                                            4294967295
                                                       uint
                                                                                           \pm 2^{63} - 1|10^{18}
                                                              \pm 9223372036854775807
double volume(circle a) { return 4.0/3.0 *
                                                                                             \overline{2}^{64} - \overline{1}|10^{19}
                                                      ull
                                                              18446744073709551615
\hookrightarrow cb(a.r) * M_PI; }
                                                                                          |+2^{127} - 1|10^{38}
                                                            |\pm 170141183460469231...
                                                      i128
     Optimization
                                                                                            2^{128} - 1 | 10^{38}
                                                      |u128| 340282366920938463..
```

Complexity classes input size (per second):

Snoob

```
\begin{array}{cccc} O(n^n) \text{ or } O(n!) & & n \leq 10 \\ O(2^n) & & n \leq 30 \\ O(n^3) & & n \leq 1000 \\ O(n^2) & & n \leq 30000 \\ O(n\sqrt{n}) & & n \leq 10^6 \\ O(n \log n) & & n \leq 10^7 \\ O(n) & & n < 10^9 \\ \end{array}
```