

Problem set 2, Task 3  
Synchronisation  
Computational Biology  
FFR110/FIM740

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a.)

From lecture note 9 (CompBioLecture9.pdf), we have the following formula on page 52,

$$\begin{aligned}\gamma &= K\gamma \int_{-\pi/2}^{\pi/2} \cos^2(\Theta)g(Kr\sin\Theta) d\Theta \\ 1 &= K \int_{-\pi/2}^{\pi/2} \cos^2(\Theta)g(Kr\sin\Theta) d\Theta\end{aligned}\tag{1}$$

we start with finding  $K_c$  by letting  $r$  go towards zero in equation 1,

$$K_c = \frac{1}{\int_{-\pi/2}^{\pi/2} \cos^2(\Theta)g(0) d\Theta}$$

as  $\int_{-\pi/2}^{\pi/2} \cos^2(\Theta) d\Theta = \pi/2$  and  $g(0)$  dont depend on  $\Theta$  we get the following,

$$\begin{aligned}K_c &= \frac{2}{\pi g(0)} \\ g(0) &= \frac{\gamma}{\pi(0^2 + \gamma^2)} = \frac{1}{\pi\gamma} \\ K_c &= \frac{2}{\pi \frac{1}{\pi\gamma}} = 2\gamma\end{aligned}$$

Now that we have  $K_c$  we want to solve the equation for  $r$ . We do this by using the following expansion (expansion in small  $r$ ) of the previous equation (also found in lecture note 9 (CompBioLecture9.pdf)).

$$1 = \frac{K}{K_c} + \frac{K(Kr)^2}{2}g''(0) \int_{-\pi/2}^{\pi/2} \cos^2(\Theta)\sin^2(\Theta) d\Theta\tag{2}$$

where  $\int_{-\pi/2}^{\pi/2} \cos^2(\Theta) \sin^2(\Theta) d\Theta$  is equal to  $\pi/8$ . Before solving it we need to find what  $g''(0)$  is,

$$\begin{aligned} g &= \frac{\gamma}{\pi(w^2 + \gamma^2)} = \frac{1}{\pi\gamma} \\ \frac{dg}{dw} &= -\frac{2w\gamma}{\pi(w^2 + \gamma^2)^2} \\ \frac{d^2g}{dw^2} &= -\frac{2\gamma(\gamma^2 - rw^2)}{\pi(w^2 + \gamma^2)^3} \\ g''(0) &= -\frac{2\gamma(\gamma^2 - r0^2)}{\pi(0^2 + \gamma^2)^3} = -\frac{2\gamma^3}{\pi\gamma^6} = -\frac{2}{\pi\gamma^3} \end{aligned}$$

we now get the following,

$$\begin{aligned} 1 &= \frac{K}{K_c} + \frac{K(Kr)^2}{2} \frac{-2}{\pi\gamma^3} \frac{\pi}{8} \\ 1 &= \frac{K}{K_c} - \frac{K^3 r^2}{8\gamma^3} \Rightarrow \left( \text{we set } \gamma \text{ to } \frac{K_c}{2} \right) \Rightarrow \frac{K}{K_c} - \frac{K^3 r^2}{8 \frac{K_c^3}{2^3}} \\ 1 &= \frac{K}{K_c} - \frac{K^3 r^2}{K_c^3} \\ \frac{K^3 r^2}{K_c^3} &= -1 + \frac{K}{K_c} \\ K^3 r^2 &= \frac{(K - K_c)K_c^3}{K_c} \\ r^2 &= \frac{(K - K_c)K_c^2}{K^3} \\ r &= \sqrt{\frac{(K - K_c)K_c^2}{K^3}} \end{aligned} \tag{3}$$

we now use equation 3 combined with the equations gain in the question,  $r = C\sqrt{\mu}$  and  $0 < \mu = (K - K_c)/K_c \ll 1$  and gain the following

$$\begin{aligned} C\sqrt{(K - K_c)/K_c} &= \sqrt{\frac{(K - K_c)K_c^2}{K^3}} \\ C &= \sqrt{\frac{K_c^3}{K^3}} \end{aligned} \tag{4}$$

we assume  $\gamma = 1$  and therefor  $K_c = 2\gamma = 2$ , and we gain the following answer for C,

$$C = 2\sqrt{\frac{2}{K^3}}$$

b.)

Three cases were chosen to be tested,  $K_1 = K_c/2 = 1$  (below  $K_c$ ),  $K_2 = K_c * 1.01 = 2.02$  (close to  $K_c$ ) and  $K_3 = K_c * 2 = 2$  (above  $K_c$ ). If we use the mean-field theory, we gain the 3 following estimates of  $r$ ,

$$\begin{aligned} r_1 &= \sqrt{\frac{(K_1 - K_c)K_c^2}{K_1^3}} = \sqrt{\frac{(1 - 2)2^2}{1^3}} = \sqrt{-4} \Rightarrow r_1 \text{ has no real part} \\ r_2 &= \sqrt{\frac{(K_2 - K_c)K_c^2}{K_2^3}} = \sqrt{\frac{(2.02 - 2)2^2}{2.02^3}} = \sqrt{\frac{0.02 * 4}{8.242408}} \approx 0.0097 \\ r_3 &= \sqrt{\frac{(K_3 - K_c)K_c^2}{K_3^3}} = \sqrt{\frac{(4 - 2)2^2}{4^3}} = \sqrt{\frac{8}{64}} = 0.125 \end{aligned}$$

When comparing it to the simulated version in Figure 1, it seems like the mean-field approximation is lower than the simulated value (for higher  $N$ ), where in the simulation  $K=2.02$ , the  $r$  hovers around 0.2 vs the approximations 0.0097, and for  $K=4$ , the simulation hovers around 0.7 vs the approximations 0.125.

It is a big difference in the noise for low values of  $N$  versus large values of  $N$ , where the larger  $N$  values give much more stable output. But it also generates more computational time needed.

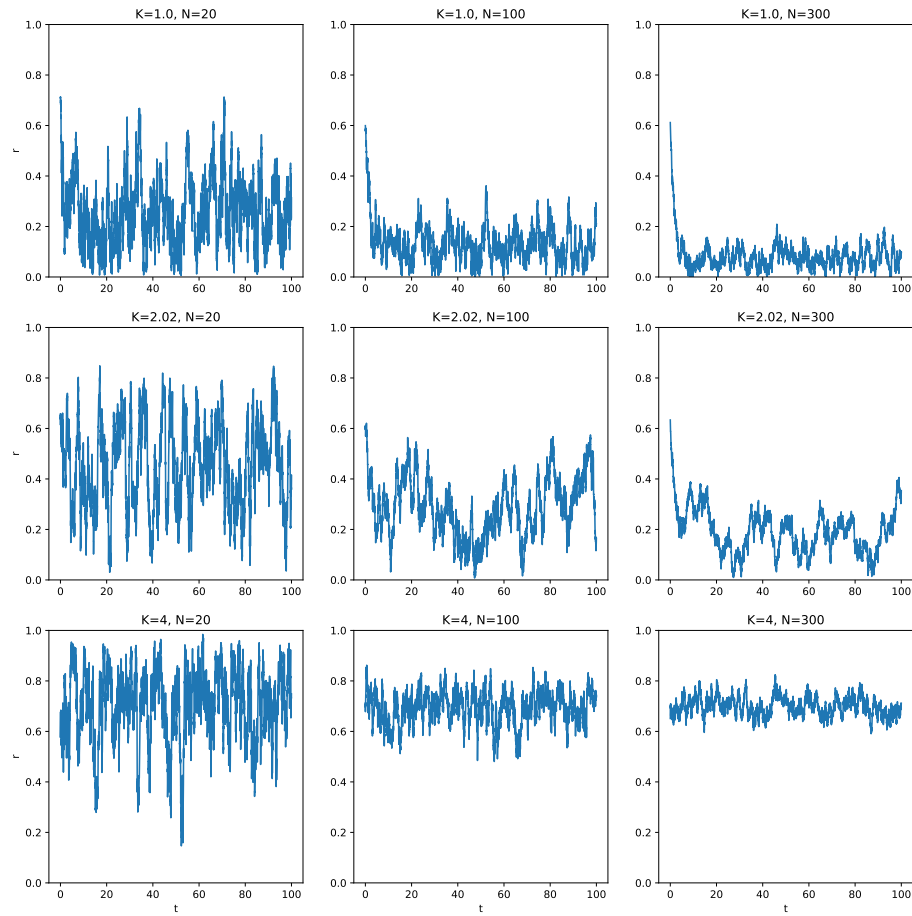


Figure 1: The plots shows all the different cases simulated. The time steps are set to 0.01 for all the simulations.

## Appendix

```

#Course : FFR110/FIM740 Computational Biology
#Problem : Problem set 2, Task 3. Synchronisation
#Code : Python 3.8.5

import numpy as np
import matplotlib.pyplot as plt
import math

def Calc_Kuramoto(K, N, Time, dTime):

    Theta_prev = (np.random.rand(N)*2-1)*np.pi/2
    Theta_current = np.zeros(N)

    r=np.zeros(int(Time/dTime))

    for t in range(int(Time/dTime)):

        w_i=np.random.standard_cauchy(N)

        for i in range(N):
            Theta_current[i]=np.sum(np.sin(Theta_prev-Theta_prev[i]))

        Theta_current[:]=Theta_prev[:]+dTime*(w_i[:]+Theta_current[:]*K/N)

        r[t]=1/N*np.sqrt((np.sum(np.cos(Theta_current))**2 + (np.sum(np.sin(Theta_current))**2)

        Theta_prev[:]=Theta_current

    return r

Kc=2
Time=100
dTime=0.01

KList=[Kc/2, Kc*1.01, Kc*2]
NList=[20, 100, 300]

t = np.arange(0, Time, dTime)

fig, axs = plt.subplots(3, 3, figsize=(15,15))

counter=0
for K in range(len(KList)):
    axs[K, 0].set_ylabel('r')
    for N in range(len(NList)):
        r = Calc_Kuramoto(KList[K], NList[N], Time, dTime)

        rMeanCalc=(KList[K]-Kc)*(Kc**2)/(KList[K]**3)
        if rMeanCalc > 0:
            rMean=np.sqrt(rMeanCalc)
        else:
            rMean=0
        axs[K, N].set_ylim([0, 1])
        titleString = "K=%s, N=%s" % (KList[K], NList[N])
        axs[K, N].title.set_text(titleString)
        axs[K, N].plot(t, r)

    if K==len(KList)-1:
        axs[K, N].set_xlabel('t')

plt.savefig("3_Synchronisation_output_test.pdf", bbox_inches = 'tight')
plt.show()

```