Dynamical Systems TIF155/FIM770

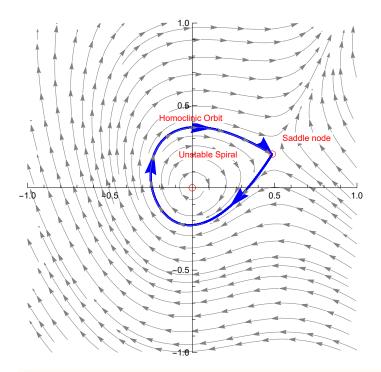
Konstantinos Zakkas

Problem set 2

2.4 Homoclinic bifurcation

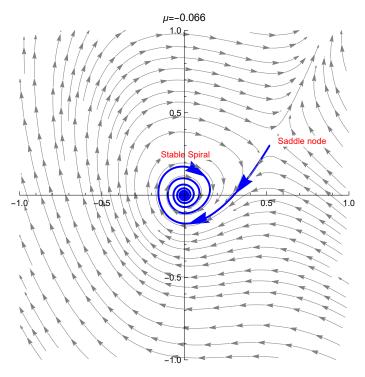
```
ln[*]:= xDot[x_, y_, \mu_] := \mu x + y - x^2;
      yDot[x_, y_, \mu_] := -x + \mu y + 2 x^2;
      FPs = Solve[\{xDot[x, y, \mu] = 0, yDot[x, y, \mu] = 0\}, \{x, y\}]
Out[*]= \left\{ \{ \mathbf{X} \to \mathbf{0}, \ \mathbf{y} \to \mathbf{0} \}, \ \left\{ \mathbf{X} \to \frac{\mathbf{1} + \mu^2}{\mathbf{2} + \mu}, \ \mathbf{y} \to \frac{\mathbf{1} - \mathbf{2} \mu + \mu^2 - \mathbf{2} \mu^3}{(\mathbf{2} + \mu)^2} \right\} \right\}
       (*Using different values for mu we check the stability and
         the value of mu which gives a homoclinic bifurcation is \mu=0.066*)
      \mu = 0.066;
      t0 = 0;
      tmax = 300;
      x0 = (x /. FPs[2]) - 0.005;
      y0 = (y /. FPs[2]);
      sol = NDSolve[\{x'[t] = xDot[x[t], y[t], \mu],
            y'[t] = yDot[x[t], y[t], \mu], x[0] = x0, y[0] = y0\}, \{x[t], y[t]\}, \{t, t0, tmax\}];
      p0 = ParametricPlot[{x[t], y[t]} /. sol, {t, t0, tmax}, PlotRange <math>\rightarrow {\{-1, 1\}, \{-1, 1\}\}},
            PlotLabel \rightarrow StringForm["\mu=``", \mu] , PlotStyle \rightarrow {Thick, Blue}] /.
           Line[x_] \Rightarrow {Arrowheads[{0.05, {0.05, 0.4}, {0.05, 0.2}, {0.05, 0.1}}], Arrow[x]};
      p1 = StreamPlot[{xDot[x, y, \mu], yDot[x, y, \mu]}, {x, -1, 1}, {y, -1, 1},
           StreamStyle → Gray, StreamColorFunction → None];
      p3 = Graphics[{Red, Circle[Evaluate[{x, y}] /. FPs[1], 0.02]}];
      p4 = Graphics[{Red, Circle[Evaluate[{x, y}] /. FPs[2], 0.02]}];
      Show[p0, p1, p3, p4]
```

 $\mu = 0.066$

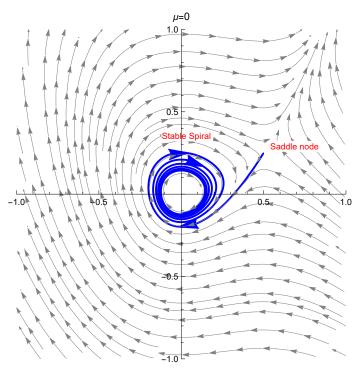


b)

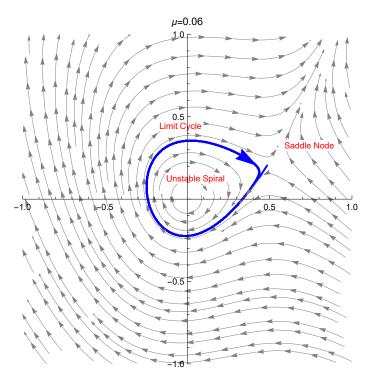
```
ln[-] = \mu = -0.066;
                        t0 = 0;
                        tmax = 300;
                        x0 = (x /. FPs[2]) - 0.005;
                        y0 = (y /. FPs[2]);
                        sol = NDSolve[{x'[t] = xDot[x[t], y[t], \mu],}
                                                y'[t] = yDot[x[t], y[t], \mu], x[0] = x0, y[0] = y0\}, \{x[t], y[t]\}, \{t, t0, tmax\}];
                        p0 = ParametricPlot[\{x[t], y[t]\} /. sol, \{t, t0, tmax\}, PlotRange \rightarrow \{\{-1, 1\}, \{-1, 1\}\}, \{-1, 1\}\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-
                                                {\tt PlotLabel \to StringForm["$\mu$=``", $\mu$], PlotStyle \to {\tt Thick, Blue}] /.}
                                           Line[x_] \Rightarrow {Arrowheads[{{0.05, 0.4}, {0.05, 0.2}, {0.05, 0.1}}], Arrow[x]};
                        p1 = StreamPlot[\{xDot[x, y, \mu], yDot[x, y, \mu]\}, \{x, -1, 1\}, \{y, -1, 1\},
                                    StreamStyle → Gray, StreamColorFunction → None];
                        Show[p0, p1]
```



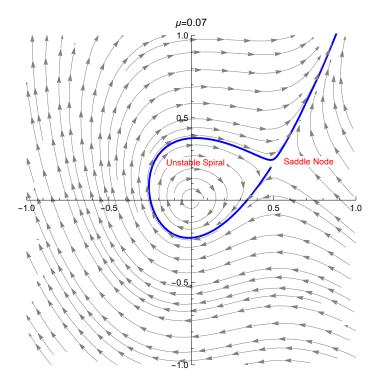
```
ln[-]:= \mu = 0;
                         t0 = 0;
                         tmax = 50;
                         x0 = (x /. FPs[2]) - 0.005;
                         y0 = (y /. FPs[2]);
                         sol = NDSolve[\{x'[t] = xDot[x[t], y[t], \mu],
                                                 y'[t] = yDot[x[t], y[t], \mu], x[0] = x0, y[0] = y0\}, \{x[t], y[t]\}, \{t, t0, tmax\}];
                         p0 = ParametricPlot[\{x[t], y[t]\} /. sol, \{t, t0, tmax\}, PlotRange \rightarrow \{\{-1, 1\}, \{-1, 1\}\}, \{-1, 1\}\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-
                                                  PlotLabel \rightarrow StringForm["\mu=``", \mu], PlotStyle \rightarrow {Thick, Blue}] /.
                                            Line[x_{-}] \Rightarrow \{Arrowheads[\{\{0.05, 0.4\}, \{0.05, 0.2\}, \{0.05, 0.1\}\}], Arrow[x]\};
                         p1 = StreamPlot[{xDot[x, y, \mu], yDot[x, y, \mu]}, {x, -1, 1}, {y, -1, 1},
                                     StreamStyle \rightarrow Gray, StreamColorFunction \rightarrow None];
                         Show[p0, p1]
```



```
 \begin{split} & \text{Im}[*] = \mu = 0.06; \\ & \text{t0} = 0; \\ & \text{tmax} = 300; \\ & \text{x0} = (\text{x} / \text{.FPs}[2]) - 0.005; \\ & \text{y0} = (\text{y} / \text{.FPs}[2]); \\ & \text{sol} = \text{NDSolve}[\{\text{x}'[t] = \text{xDot}[\text{x}[t], \text{y}[t], \mu], \\ & \text{y}'[t] = \text{yDot}[\text{x}[t], \text{y}[t], \mu], \text{x}[0] = \text{x0}, \text{y}[0] = \text{y0}\}, \{\text{x}[t], \text{y}[t]\}, \{\text{t}, \text{t0}, \text{tmax}\}]; \\ & \text{p0} = \text{ParametricPlot}[\{\text{x}[t], \text{y}[t]\} / . \text{sol}, \{\text{t}, \text{t0}, \text{tmax}\}, \text{PlotRange} \rightarrow \{\{-1, 1\}, \{-1, 1\}\}, \\ & \text{PlotLabel} \rightarrow \text{StringForm}["\mu = \hat{\ } ", \mu], \text{PlotStyle} \rightarrow \{\text{Thick}, \text{Blue}\}] / . \\ & \text{Line}[\text{x}_] \Rightarrow \{\text{Arrowheads}[\{\{0.05, 0.3\}, \{0.05, 0.2\}, \{0.05, 0.1\}\}], \text{Arrow}[\text{x}]\}; \\ & \text{p1} = \text{StreamPlot}[\{\text{xDot}[\text{x}, \text{y}, \mu], \text{yDot}[\text{x}, \text{y}, \mu]\}, \{\text{x}, -1, 1\}, \{\text{y}, -1, 1\}, \\ & \text{StreamStyle} \rightarrow \text{Gray}, \text{StreamColorFunction} \rightarrow \text{None}]; \\ & \text{Show}[\text{p0}, \text{p1}] \end{split}
```



```
ln[@]:= \mu = 0.07;
                          t0 = 0;
                          tmax = 300;
                          x0 = (x /. FPs[2]) - 0.005;
                          y0 = (y /. FPs[2]);
                          sol = NDSolve[\{x'[t] = xDot[x[t], y[t], \mu],
                                                   y'[t] = yDot[x[t], y[t], \mu], x[0] = x0, y[0] = y0\}, \{x[t], y[t]\}, \{t, t0, tmax\}];
                          p0 = ParametricPlot[\{x[t], y[t]\} /. sol, \{t, t0, tmax\}, PlotRange \rightarrow \{\{-1, 1\}, \{-1, 1\}\}, \{-1, 1\}\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-1, 1\}, \{-
                                                    PlotLabel \rightarrow StringForm["\mu=``", \mu], PlotStyle \rightarrow {Thick, Blue}] /.
                                             Line[x_] \Rightarrow {Arrowheads[{{0.05}}}], Arrow[x]};
                          p1 = StreamPlot[{xDot[x, y, \mu], yDot[x, y, \mu]}, {x, -1, 1}, {y, -1, 1},
                                      StreamStyle \rightarrow Gray, StreamColorFunction \rightarrow None];
                          Show[p0, p1]
```



c)

 $ln[*] = sols = DSolve[{x'[t] == u x[t], y'[t] == s y[t], x[0] == \gamma, y[0] == 1}, {x[t], y[t]}, t]$ Solve[(x[t] /. Part[sols, 1, 1]) = 1, t]

$$\textit{Out[*]=} \ \left\{ \left\{ t \to \boxed{ \begin{array}{c} 2 \ \dot{\mathbb{1}} \ \pi \ \mathbb{c}_1 + Log \left[\frac{1}{\gamma} \, \right] \\ \\ u \end{array} \right. \ \text{if} \ \mathbb{c}_1 \in \mathbb{Z} \ \right\} \right\}$$

d)

 $ln[\circ]:= \mu = .$

saddlex = x /. Part[FPs, 2, 1]

$$Out[\circ] = \frac{1 + \mu^2}{2 + \mu}$$

 $ln[\cdot]:=$ jacobianMatrix = {{ $\mu - 2$ saddlex, 1}, {-1 + 4 saddlex, μ }}; eigenValues = Eigenvalues[jacobianMatrix]

Out[*]=
$$\left\{ \frac{-1 + 2 \mu - \sqrt{5 + 9 \mu^2 + 4 \mu^3 + \mu^4}}{2 + \mu} \right\}$$
, $\frac{-1 + 2 \mu + \sqrt{5 + 9 \mu^2 + 4 \mu^3 + \mu^4}}{2 + \mu} \right\}$

In[@]:= Part[eigenValues, 2] // Simplify

Out[*]=
$$\frac{-1 + 2 \mu + \sqrt{5 + 9 \mu^2 + 4 \mu^3 + \mu^4}}{2 + \mu}$$