

Dynamical Systems TIF155/FIM770
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Problem set 2

2.3 Hopf bifurcation

c)

```
In[ ]:= f1[x_, y_] = -x^3;  
        g1[x_, y_] = 2 y^3;  
        f2[x_, y_] = -x^2;  
        g2[x_, y_] = 2 x^2;
```

```
In[ ]:= ω1 = 3;  
        ω2 = -1;
```

For system (1)

```
In[ ]:= fxxx = D[f1[x, y], {x, 3}]
```

```
Out[ ]:= -6
```

```
In[ ]:= fxyy = D[f1[x, y], {x, 1}, {y, 2}]
```

```
Out[ ]:= 0
```

```
In[ ]:= gxyy = D[g1[x, y], {x, 2}, {y, 1}]
```

```
Out[ ]:= 0
```

```
In[ ]:= gyyy = D[g1[x, y], {y, 3}]
```

```
Out[ ]:= 12
```

```
In[ ]:= fxy = D[D[f1[x, y], {x}], {y}]
```

```
Out[ ]:= 0
```

```
In[ ]:= fxx = D[f1[x, y], {x, 2}]
```

```
Out[ ]:= -6 x
```

```
In[ ]:= fyy = D[f1[x, y], {y, 2}]
```

```
Out[ ]:= 0
```

```
In[ ]:= gxy = D[D[g1[x, y], {x}], {y}]
```

```
Out[ ]:= 0
```

```
In[ ]:= gxx = D[g1[x, y], {x, 2}]
```

```
Out[ ]:= 0
```

In[]:= **gyy = D[g1[x, y], {y, 2}]**

Out[]:= 12 y

In[]:= **$\alpha 1 = f_{xxx} + f_{xyy} + g_{xxy} + g_{yyy} +$
 $1 / \omega 1 (f_{xy} (f_{xx} + f_{yy}) - g_{xy} (g_{xx} + g_{yy}) - f_{xx} * g_{xx} + f_{yy} * g_{yy}) - 16 \alpha$**

Out[]:= 6 - 16 α

In[]:= **Solve[$\alpha 1 == 0$]**

Out[]:= $\left\{ \left\{ \alpha \rightarrow \frac{3}{8} \right\} \right\}$

$\alpha > 0$ so the bifurcation is subcritical

For system (2)

In[]:=

fxxx = D[f2[x, y], {x, 3}]

Out[]:= 0

In[]:= **fxyy = D[f2[x, y], {x}, {y, 3}]**

Out[]:= 0

In[]:= **gxxxy = D[g2[x, y], {x, 2}, {y}]**

Out[]:= 0

In[]:= **gyyyy = D[g2[x, y], {y, 3}]**

Out[]:= 0

In[]:= **fxy = D[f2[x, y], {x}, {y}]**

Out[]:= 0

In[]:= **fxx = D[f2[x, y], {x, 2}]**

Out[]:= -2

In[]:= **fyy = D[f2[x, y], {y, 2}]**

Out[]:= 0

In[]:= **gxy = D[g2[x, y], {x}, {y}]**

Out[]:= 0

In[]:= **gxx = D[g2[x, y], {x, 2}]**

Out[]:= 4

In[]:= **gyy = D[g2[x, y], {y, 2}]**

Out[]:= 0

```
In[ ]:=  $\alpha 2 = f_{xxx} + f_{xyy} + g_{xxy} + g_{yyy} +$   

 $1 / \omega 2 (f_{xy} (f_{xx} + f_{yy}) - g_{xy} (g_{xx} + g_{yy}) - f_{xx} * g_{xx} + f_{yy} * g_{yy}) - 16 \alpha$ 
```

```
Out[ ]:=  $-8 - 16 \alpha$ 
```

```
In[ ]:= Solve[ $\alpha 2 == 0$ ]
```

```
 $\left\{ \left\{ \alpha \rightarrow -\frac{1}{2} \right\} \right\}$ 
```

$\alpha < 0$ so the bifurcations is supercritical

d)

(*System 1*)

```
In[1]:= xDot[x_, y_,  $\mu$ _] :=  $\mu x - 3 y - x^3$ ;  

yDot[x_, y_,  $\mu$ _] :=  $3 x + \mu y + 2 y^3$ ;
```

```
In[ ]:=  $\mu = -0.2$ ;  

t0 = 0;  

tMax = -10;
```

```
sol = Table[NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ],  

y'[t] == yDot[x[t], y[t],  $\mu$ ], x[0] == x0, y[0] == y0}, {x[t], y[t]}, {t, t0, tMax}], {x0,  

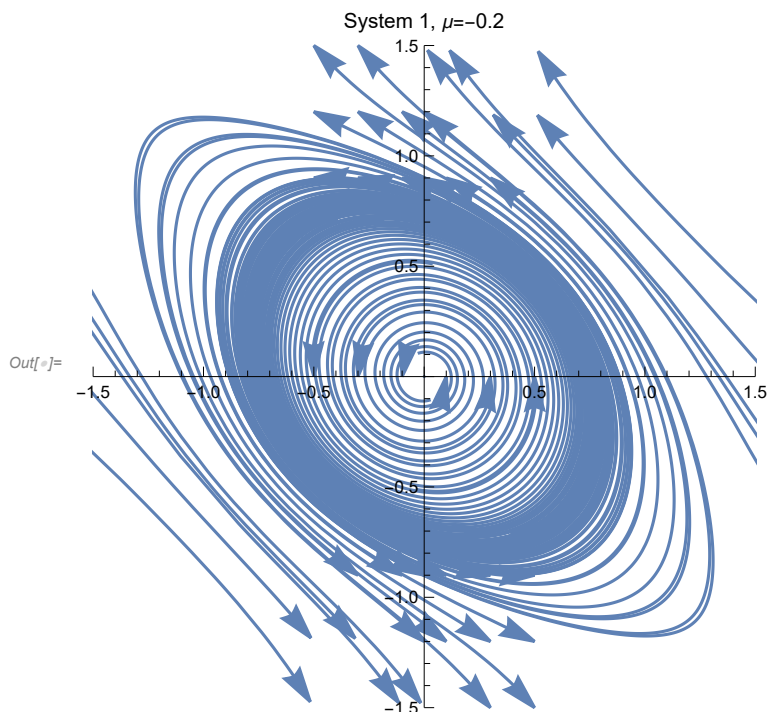
{-0.5, -0.3, -0.1, 0, 0.1, 0.3, 0.5}}, {y0, {-1.5, -1.2, -0.9, 0, 0.9, 1.2, 1.5}}];  

Length[sol]  

p1 = ParametricPlot[{x[t], y[t]} /. sol, {t, t0, tMax},  

PlotRange -> {{-1.5, 1.5}, {-1.5, 1.5}}, PlotLabel -> StringForm["System 1,  $\mu=-`"$ ",  $\mu$ ] /.  

Line[x_] -> {Arrowheads[{0.05}], Arrow[x]}]
```



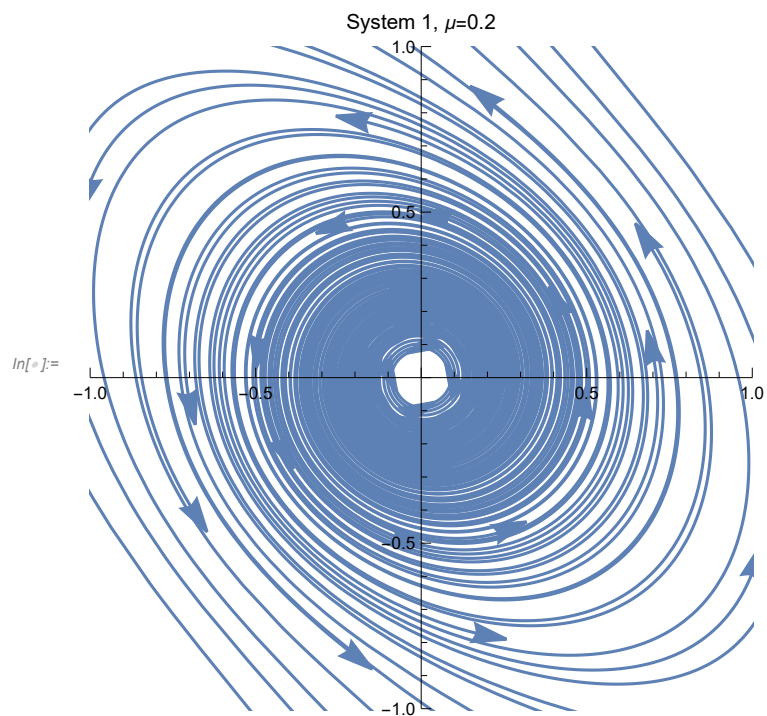
```

 $\mu$  = 0.2;
t0 = 0;
tMax = 7.7;

sol = Table[NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ],
  y'[t] == yDot[x[t], y[t],  $\mu$ ], x[0] == x0, y[0] == y0}, {x[t], y[t]}, {t, t0, tMax}],
  {x0, {-0.12, -0.08, -0.04, 0.04, 0.08, 0.12}},
  {y0, {-0.12, -0.08, -0.04, 0.04, 0.08, 0.12}}];

p2 = ParametricPlot[{x[t], y[t]} /. sol, {t, t0, tMax},
  PlotRange -> {{-1, 1}, {-1, 1}}, PlotLabel -> StringForm["System 1,  $\mu$ =`",  $\mu$ ] /.
  Line[x_] -> {Arrowheads[{0.05}], Arrow[x]}

```



```

In[3]:= (*System 2*)
 $\mu$  = .
xDot[x_, y_,  $\mu$ ] :=  $\mu$  x + y - x^2;
yDot[x_, y_,  $\mu$ ] := -x +  $\mu$  y + 2 x^2;

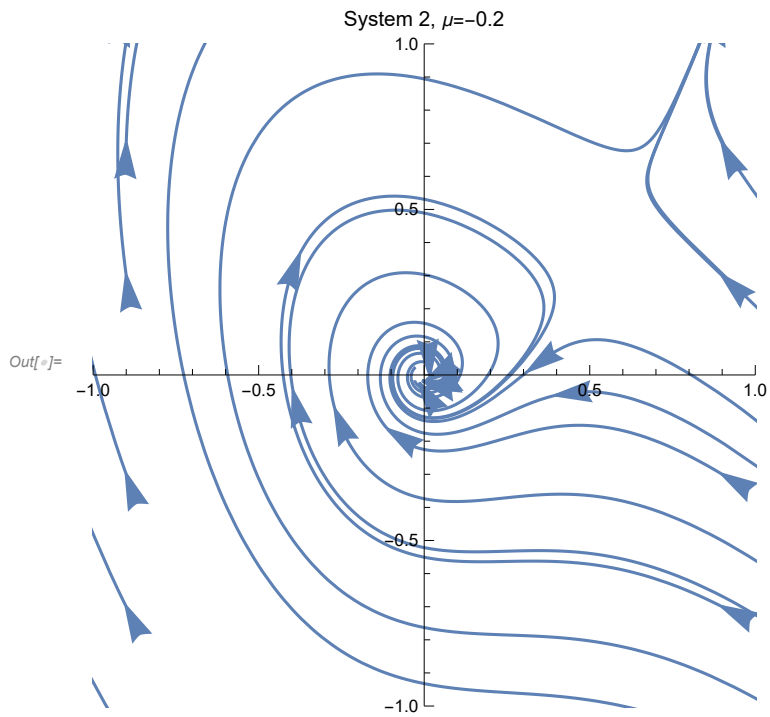
```

```

In[ ]:=  $\mu$  = -0.2;
t0 = 0;
tMax = 15;

sol = Table[NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ],
  y'[t] == yDot[x[t], y[t],  $\mu$ ], x[0] == x0, y[0] == y0}, {x[t], y[t]}, {t, t0, tMax}],
  {x0, {-1.5, -1.2, -0.9, 0.9, 1.2, 1.5}}, {y0, {-1.1, -0.7, -0.3, 0.3, 0.7, 1.1}}];
p3 = ParametricPlot[{x[t], y[t]} /. sol, {t, t0, tMax},
  PlotRange -> {{-1, 1}, {-1, 1}}, PlotLabel -> StringForm["System 2,  $\mu$ =",  $\mu$ ] /.
  Line[x_] -> {Arrowheads[{{0.05}, {0.05, 0.5}, {0.05}}], Arrow[x]}

```



```

In[6]:=  $\mu$  = 0.2;
t0 = -15;
tMax = 15;

sol = Table[NDSolve[{x'[t] == xDot[x[t], y[t],  $\mu$ ],
  y'[t] == yDot[x[t], y[t],  $\mu$ ], x[0] == x0, y[0] == y0}, {x[t], y[t]}, {t, t0, tMax}],
  {x0, {-0.9, -0.5, -0.1, 0.1, 0.5, 0.9}}, {y0, {-0.9, -0.5, -0.1, 0.1, 0.5, 0.9}}];
p4 = ParametricPlot[{x[t], y[t]} /. sol, {t, t0, tMax}, PlotRange -> {{-1, 1}, {-1, 1}},
  PlotStyle -> {Red, Thick}, PlotLabel -> StringForm["System 2,  $\mu$ =`",  $\mu$ ] /.
  Line[x_] -> {Arrowheads[{{0.05}}], Arrow[x]};
stream4 = StreamPlot[{xDot[x, y,  $\mu$ ], yDot[x, y,  $\mu$ ]}, {x, -1, 1},
  {y, -1, 1}, StreamStyle -> Blue, StreamColorFunction -> None];
Show[{p4, stream4}]

```

