

Numpy vs Pytorch vs Cupy

linalg.pinv Library Comparison:

CuPy and PyTorch offer significant speedups (4.5x and 4.24x respectively) for pinv with only a modest reduction in accuracy.

Batched Computation:

PyTorch enables parallel batched computation of the inverse, delivering a substantial speed advantage(6.73x) over CuPy, suitable for scenarios requiring multiple independent inversions.

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Method	Time (s)	Speedup v	s M1 Error	Status
Method 1 (NumPy pinv)	1.3569	1.00	8.87e-16	PASSED
Method 2 (NumPy solve)	0.1393	9.74	2.24e-15	PASSED
Method 3 (PyTorch pinv)	0.3203	4.24	6.95e-05	PASSED
Method 4 (PyTorch solve)	0.0340	39.90	6.81e-05	PASSED
Method 5 (PT batch pinv)	0.2018	6.73	6.95e-05	PASSED
Method 6 (PT batch solve)	0.0016	866.97	6.82e-05	PASSED
Method 7 (CuPy pinv)	0.3015	4.50	8.24e-07	PASSED
Method 8 (CuPy solve)	0.0073	185.20	4.83e-07	PASSED



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linalg.solve formulation:

New formulation explaining why the `linalg.solve` method is appropriate for solving the system in equation

Method 8 (CuPy solve)

Original formulation for A^{\dagger} :

$$\begin{split} X &= A^{\dagger} \hat{Y}, \\ X \hat{Y}^T &= A^{\dagger} \hat{Y} \hat{Y}^T, \\ X \hat{Y}^T \left(\hat{Y} \hat{Y}^T \right)^{-1} &= A^{\dagger} \left(\hat{Y} \hat{Y}^T \right) \left(\hat{Y} \hat{Y}^T \right)^{-1}, \\ A^{\dagger} &= X \hat{Y}^T \left(\hat{Y} \hat{Y}^T \right)^{-1} = X \hat{Y}^{\dagger} \end{split}$$

Formulation for using linalg.solve:

$$\begin{split} X &= A^{\dagger} \hat{Y}, \\ X \hat{Y}^T &= A^{\dagger} \hat{Y} \hat{Y}^T, \\ X \hat{Y}^T \left(\hat{Y} \hat{Y}^T \right)^{-1} &= A^{\dagger} \left(\hat{Y} \hat{Y}^T \right) \left(\hat{Y} \hat{Y}^T \right)^{-1}, \\ A^{\dagger} &= X \hat{Y}^T \left(\hat{Y} \hat{Y}^T \right)^{-1} \\ \left(A^{\dagger} \right)^T &= \left(\left(\hat{Y} \hat{Y}^T \right)^{-1} \right)^T \left(X \hat{Y}^T \right)^T \\ \left(A^{\dagger} \right)^T &= \left(\hat{Y} \hat{Y}^T \right)^{-1} \hat{Y} X^T \end{split}$$

COMPREHENSIVE PERFORMANCE AND ACCURACY COMPARISON					
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185.20

4.83e-07

PASSED

0.0073

Formulation with zero-order Tikhonov regularization of regularization parameter $\varepsilon :$

$$(A^{\dagger})^T = \left(\widehat{Y}\widehat{Y}^T + \varepsilon I\right)^{-1}\widehat{Y}X^T$$



Numpy vs Pytorch vs Cupy

• linalg.solve Library Comparison:

Numpy.linalg.solve offer 9.74 speedup with small accuracy reduction

CuPy and PyTorch offer significant speedups (185.2x and 39.9x respectively) for solve with only a modest reduction in accuracy.

Batch Pytorch offer even larger speedup(867x) and similar reduction in accuracy to Pytorch

COMPREHENSIVE PERFORMANCE AND ACCURACY COMPARISON				
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Cupynumeric vs Cupy

Cupynumeric Library Comparison :

Regarding parallel computation of the pseudoinverse, the cupynumeric library currently does not support this functionality. However, `linalg.solve` is supported and can leverage multiple GPUs for processing a single matrix. You can find an example in the attached file "cpn_solve_example.py." To test multi-GPU performance, please run:

. . .

legate --gpus 2 cpn_solve_example.py --size 50000 --skip-cupy

This configuration enables parallel computation for matrices as large as 50,000 x 50,000; in contrast, CuPy encounters out-of-memory errors at this scale.

50000x50000	1 gpu (RTX 5880	2 gpu (RTX 5880	Cupy
matrix	ada)	ada)	
Time (ms)	16479.9410 ms	12114.6650 ms	ООМ



