Supplementary Material for Reconstruct Private Data via Public Knowledge in Distillation-based Federated Learning

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A Proofs

- 2 **Prop. 1**
- 3 *Proof.* Since h is differentiable, we have the following equations;

$$\frac{\partial L}{\partial b_i} = \frac{\partial L}{\partial y_i} \frac{\partial y_i}{\partial b_i} = \frac{\partial L}{\partial y_i} h^{(1)} (Az + b)_i, \quad \frac{\partial y_i}{\partial A_i} = h^{(1)} (Az + b)_i z^T$$
 (S-1)

, where i is the index of A's row. From the above equations, we can analytically determine z from $\frac{\partial L}{\partial b_i}$ and $\frac{\partial L}{\partial A_i}$ as follows;

$$z^{T} = \frac{1}{h^{(1)}(Az+b)} \frac{\partial y_{i}}{\partial A_{i}} = \frac{1}{h^{(1)}(Az+b)} \frac{\partial y_{i}}{\partial L} \frac{\partial L}{\partial A_{i}} = \frac{\partial L}{\partial A_{i}} / \frac{\partial L}{\partial b_{i}}$$
(S-2)

- 6 Then, if we think the neural network as a Markov chain $x \to z \to y$, the data processing inequality [1]
- 7 leads to Inequal. 4;

$$I(x; \frac{\partial L}{\partial A}, \frac{\partial L}{\partial b}) \ge I(x; z) \ge I(x; y)$$
 (S-3)

9 Lemma. 1

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10 *Proof.* We optimize Eq. 5 independently for p_{c_i} and p_s . Given the range of probability, the optimal p_{c_i} is obviously as follows;

$$\hat{p}'_{c_i,k} = \begin{cases} 1 & (k=j) \\ 0 & (k \neq j) \end{cases}$$

Next, we use Lagrange multipliers to find the optimal p_s under the constraint of its sum equal to one.

$$\max_{p'_{s}} p'_{s,j} + \alpha H(p'_{s}) \tag{S-4}$$

$$s.t. \sum_{k=1}^{J} p'_{s,k} = 1 \tag{S-5}$$

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13 We require that

$$\frac{\partial}{\partial p_s'} \{ p_{s,j}' + \alpha H(p_s') + \lambda (\sum_{k=1}^J p_{s,k}' - 1) \} |_{p_s' = \hat{p}_s'} = 0$$
 (S-6)

, which gives a system of J equations, k = 1, ..., J, such that,

$$\frac{\partial}{\partial p'_{s,k}} \{ p'_{s,j} + \alpha (\sum_{k=1}^{J} - p'_{s,k} \log p'_{s,k}) + \lambda (\sum_{k=1}^{J} p'_{s,k} - 1) \} |_{p'_{s} = \hat{p}'_{s,k}} = 0$$
 (S-7)

15 Eq. S-7 yields

$$\begin{cases} 1 - \alpha(\log \hat{p'}_{s,k} + 1) + \lambda = 0 & (k = j) \\ -\alpha(\log \hat{p'}_{s,k} + 1) + \lambda) = 0 & (k \neq j) \end{cases}$$
 (S-8)

16 Then, we have that

$$\lambda = \alpha(\log \hat{p}'_{s,k} + 1) \tag{S-9}$$

$$\hat{p}'_{s,k} = \begin{cases} \exp(\frac{1+\lambda-\alpha}{\alpha}) & (k=j) \\ \exp(\frac{\lambda-\alpha}{\alpha}) & (k\neq j) \end{cases}$$
 (S-10)

17 Eq. S-5 and Eq. S-10 indicate

$$\{J - 1 + \exp(\frac{1}{\alpha})\} \exp(\frac{\lambda - \alpha}{\alpha}) = 1$$

$$\therefore \lambda = \alpha \log\{\frac{1}{J - 1 + \exp(\frac{1}{\alpha})}\} + \alpha$$
 (S-11)

18 Combining Eq. S-10 and Eq. S-11, we finally have

$$\hat{p}_{s,k}^{'} = \begin{cases} \frac{\sqrt[\infty]{e}}{J-1+\sqrt[\infty]{e}} & (k=j)\\ \frac{1}{J-1+\sqrt[\infty]{e}} & (k\neq j) \end{cases}$$

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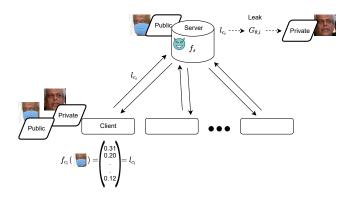


Figure S-1: The overview of our scenario

B Protocols and architectures

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```
Algorithm S-1 FedMD
                                                  Algorithm S-2 FedGEMS
                                                                                                    Algorithm S-3 DSFL
Input: Private dataset D_{pri} = Input: Private dataset D_{pri} = Input: Private dataset D_{pri} = 
      \{m{X}_{pri}, m{y}_{pri}\}, public dataset D_{pub} = \{m{X}_{pub}, m{y}_{pub}\}, lo-
                                                                                                          \{ \boldsymbol{X}_{pri}, \boldsymbol{y}_{pri} \}, public dataset D_{pub} = \{ \boldsymbol{X}_{pub}, \boldsymbol{y}_{pub} \}, lo-
                                                         \{oldsymbol{X}_{pri},oldsymbol{y}_{pri}\}, public dataset
                                                         \hat{D}_{pub} = \{\hat{\boldsymbol{X}}_{pub}, \boldsymbol{y}_{pub}\}, \text{ lo-}
      cal model f_{c_i,i=1...C}, global
                                                        cal model f_{c_i,i=1...C}, global
                                                                                                          cal model f_{c_i,i=1...C}, global
                                                                                                          model f_s, number of commu-
      model f_s, number of commu-
                                                        model f_s, number of com-
      nications T.
                                                        munications T.
                                                                                                          nications T.
                                                    1: Train f_{c_i} on D_{public}
                                                                                                      1: Train f_{c_i} on D_{public}
  1: Train f_{c_i} on D_{public}
 2: Train f_{c_i} on D_{pri}
                                                    2: Train f_{c_i} on D_{pri}
                                                                                                      2: Train f_{c_i} on D_{pri}
                                                    3: for t = 1 \leftarrow T do
 3: for t = 1 \leftarrow T do
                                                                                                      3: for t = 1 \leftarrow T do
           c_i sends l_{c_i} = f_{c_i}(\boldsymbol{X}_{pub})
                                                                                                                Train f_{c_i} on \{D_{pri}\}
 4:
                                                              Selectively train f_s on 4:
                                                                                                               c_i \text{ sends } l_{c_i} = f_{c_i}(\boldsymbol{X}_{pub})

\tilde{l} = \text{ERA}(\sum_{i=1}^{C} \frac{l_{c_i}}{C}) \quad \triangleright
           \tilde{l} = \frac{1}{C} \sum_{i=1}^{C} l_{c_i}  > The
                                                         \{D_{pub}, l, l_{c_i}\}, where l_{c_i} =
                                                         f_{c_i}(\boldsymbol{X}_{pub})
      server computes the consen-
      sus logits.
                                                    5:
                                                              \hat{l} = f_s(X_{pub})
                                                                                                          The server computes the con-
                                                                                                          sensus logits.
           Train f_{c_i} on \{X_{pub}, l\}
 6:
                                                              Train f_{c_i} on \{D_{pub}, l\}
                                                    6:
           Train f_{c_i} on D_{pri}
 7:
                                                              Train f_{c_i} on \{D_{pri}\}
                                                                                                      7:
                                                                                                                Train f_{c_i} on \{\boldsymbol{X}_{pub}, l\}
                                                    7:
           Train f_s on D_{public}
 8:
                                                    8: end for
                                                                                                                Train f_s on \{X_{pub}, \tilde{l}\}
                                                                                                      8:
 9: end for
                                                                                                      9: end for
```

Fig. S-1 shows the overview of our scenario, where the malicious server tries to reconstruct the private data via the output logits of the public data with the inversion model. Alg. S-1, S-2, and S-3 are the pseudo-codes of each protocol, where we additionally train the server-side model on the public dataset at line 9 in FedMD. Code. 1 and 2 are the implementation of server-side, client-side, and inversion models.

Listing 1: server and local models

```
nn. Sequential (
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        nn.Conv2d(3, 32, kernel\_size = (3, 3), stride = 1, padding = 0),
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29
        nn . ReLU(),
        nn.MaxPool2d(kernel_size=(3, 3), stride=None, padding=0),
30
31
        nn. Flatten(),
        nn.Linear(12800, output_dim),
32
33
   )
                               Listing 2: inversion model
   nn. Sequential (
        nn. ConvTranspose2d (input dim, 1024, (4, 4), stride = (1, 1)),
```

```
nn.BatchNorm2d(1024),
36
        nn. Tanh().
37
        nn.ConvTranspose2d(1024, 512, (4, 4),
38
                              stride = (2, 2), padding = (1, 1),
39
        nn.BatchNorm2d(512),
40
        nn. Tanh(),
41
        nn. ConvTranspose2d (512, 256, (4, 4),
42
                              stride = (2, 2), padding = (1, 1),
43
        nn. BatchNorm2d(256),
44
        nn. Tanh(),
45
        nn. ConvTranspose2d(256, 128, (4, 4),
46
                              stride = (2, 2), padding = (1, 1),
        nn.BatchNorm2d(128),
48
        nn. Tanh(),
49
        nn. ConvTranspose2d(128, channel, (4, 4),
50
                              stride = (2, 2), padding = (1, 1),
51
52
        nn. Tanh()
53
```

₅₄ C Gradient inversion

Algorithm S-4 Gradient inversion

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Input: The number of communication T, the target model F, the number of clients C, the number of classes J, the number of classes of each private dataset $\{J_i\}_{i=1...C}$, the dimension of input d.

```
Output: Reconstructed data \{X_i' \in \mathbb{R}^{d \times J_i}\}_{i=1...C} for t=1 \leftarrow T do for i=1 \leftarrow C do Receive \nabla W_i from client c_i. if t=1 then Infer Y_i, the unique labels of c_i's private dataset. X_i' \in \mathbb{R}^{d \times J_i} \leftarrow \mathcal{N}(0,1) end if for m=1 \leftarrow M do \nabla W_i' \leftarrow \frac{\partial \ell(f(X_i',W_i),Y_i)}{\partial W_i} X_i' \leftarrow X_i' - \eta \nabla_{X_i'} L_{GB}(X_i') end for end for end for return \{X_i'\}_{i=1...C}
```

Although the existing gradient inversion methods focus on reconstructing the exact batch data and labels, our interest is in recovering the class representation of the private training dataset. Then, we view that the received gradient ∇W_i is calculated with $X_i \in \mathbb{R}^{J_i \times d}$, where X_i represents the class representations of client c_i 's private dataset, J_i is the number of unique classes of the dataset, and d is the dimension of the input data. The attacker can infer the labels used to train the local model from the received gradient with the batch label restoration method proposed in [2]. Then, we optimize dummy class representations $X_i' \in \mathbb{R}^{J_i \times d}$ with the following cost function;

$$L_{GB}(X_i') = 1 - \frac{\langle \nabla W_i', \nabla W_i \rangle}{||\nabla W_i'|| ||\nabla W_i||} + \gamma \text{TV}(X_i')$$
 (S-12)

, where TV denotes the total variation and γ is its coefficient. This cost function is the same as the one used in [3]. Note that unlike our proposed attack against FedKD, the attacker must know the number of unique labels in each local dataset in advance.

Result details

Result of 4.2

Tab. S-1, S-2, and S-3 shows the specific numerical results for 4.2. Fig. S-2 represents the loss 67 of PTBI and TBI in each epoch, which indicates that the relationship between inversion loss and temperature is consistent with attack success rate and temperature. Note that we train the inversion model 3 epochs per communication in a total of 5 communications. Fig. S-3 shows the percentage of reconstructed images whose closest image is public data belonging to the target label, which indicates 71 that PTBI tends not to reconstruct public data compared to TBI. Fig. S-4 and S-5 are the examples of 72 reconstructed images with PTBI and TBI. Fig. S-6 and Fig. S-7 also shows some images that PTBI reconstructs with different τ .

Table S-1: Attack success rate ($\tau = 3.0$)

		DSFL		FedMD		FedGEMS	
C	dataset attack	LFW	LAG	LFW	LAG	LFW	LAG
1	TBI	91.0%	90.5%	21.5%	19.0%	0.0%	1.0%
	PTBI	89.5%	92.0%	59.5%	51.0%	9.0%	10.5%
10	TBI	22.0%	36.5%	8.5%	10.5%	9.0%	4.0%
	PTBI	2.5%	8.0%	45.0%	41.5%	26.0%	18.5%

Table S-2: Attack success rate ($\tau = 1.0$)

		DSFL		FedMD		FedGEMS	
C	dataset attack	LFW	LAG	LFW	LAG	LFW	LAG
1	TBI	59.0%	92.5%	9.0%	5.0%	0.0%	0.0%
	PTBI	68.5%	94.5%	38.5%	20.0%	0.0%	0.0%
10	TBI	67.0%	38.5%	13.0%	5.0%	0.0%	0.0%
	PTBI	70.0%	54.5%	21.0%	9.0%	0.0%	0.0%

Table S-3: Attack success rate ($\tau = 0.3$)

		DSFL		FedMD		FedGEMS	
C	dataset attack	LFW	LAG	LFW	LAG	LFW	LAG
1	TBI	16.0%	73.5%	5.0%	5.0%	0.0%	0.0%
	PTBI	12.0%	83.0%	14.0%	6.5%	0.0%	0.0%
10	TBI	84.5%	63.0%	2.0%	2.0%	0.0%	0.0%
	PTBI	88.5%	59.0%	2.5%	4.5%	0.0%	0.0%

D.2 Ablation studies

- We do ablation studies with the same setting as 4.2 of C=10, where we remove each term of Q. Tab. S-4 shows the optimal $p_{c_i,k}^{'}$ and $p_{s,k}^{'}$ in each ablations. In the case of $Q=p_{s,j}^{'}+\alpha H(p_s^{'})$, we do not need the client-side model, so we train an inversion model only with the global logits, where
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- the architecture of the inversion model is the same as that of TBI.

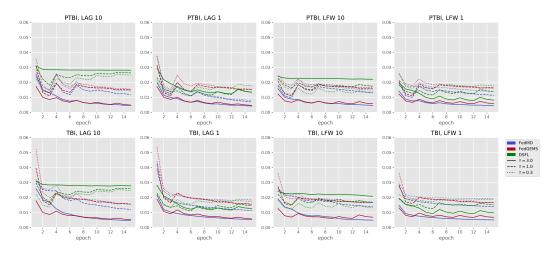


Figure S-2: Inversion loss

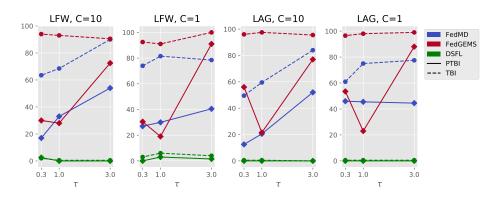


Figure S-3: Percentage of reconstructed images whose closest image is public data

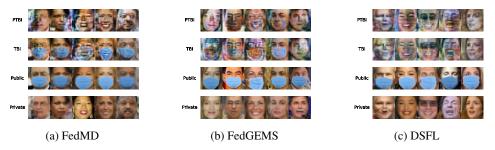


Figure S-4: LFW: example of reconstructed images

80 D.3 Impact of public dataset size

Fig. S-8 shows the results of the experiments with the smaller public dataset, which consists of 400 celebrities.

References

[1] Thomas M Cover. Elements of information theory. John Wiley & Sons, 1999.

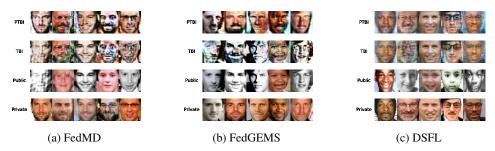


Figure S-5: LAG: example of reconstructed images

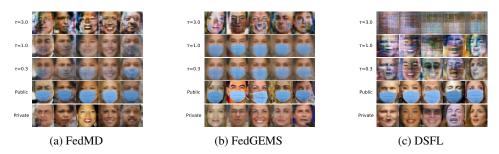


Figure S-6: LFW: example of reconstructed images with different τ

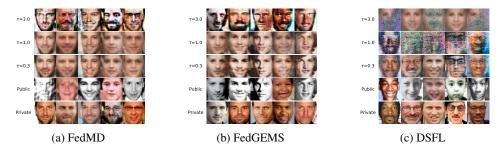


Figure S-7: LAG: example of reconstructed images with different τ

Table S-4: Optimal Q in each ablation study

Q	$\hat{p}_{c_i,k}^{'}$	$\hat{p}_{s,k}^{'}$
$p_{c_i,j}^{'} + p_{s,j}^{'}$ $p_{c_i,j}^{'} + \alpha H(p_s^{'})$	$ \begin{cases} 1 & (k=j) \\ 0 & (k \neq j) \\ 1 & (k=j) \\ 0 & (k \neq j) \end{cases} $	$\begin{cases} 1 & (k=j) \\ 0 & (k \neq j) \end{cases}$
$p_{s,j}^{'} + \alpha H(p_{s}^{'})$	-	$\begin{cases} \frac{\sqrt[\infty]{e}}{J-1+\sqrt[\infty]{e}} & (k=j)\\ \frac{1}{J-1+\sqrt[\infty]{e}} & (k\neq j) \end{cases}$

^[2] Hongxu Yin, Arun Mallya, Arash Vahdat, Jose M Alvarez, Jan Kautz, and Pavlo Molchanov. See through gradients: Image batch recovery via gradinversion. In Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition, pages 16337–16346, 2021.

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^[3] Jonas Geiping, Hartmut Bauermeister, Hannah Dröge, and Michael Moeller. Inverting gradients-how easy is it to break privacy in federated learning? Advances in Neural Information Processing Systems,

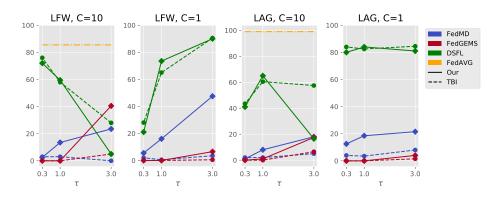


Figure S-8: Attack success rate with small public dataset

33:16937-16947, 2020.

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