ASSIGNMENT-3

1. Problem Statement

Given an undirected, connected graph, we want to traverse the graph randomly, ensuring that all nodes are eventually visited. Instead of following a predefined order, we select the next node randomly from the current node's neighbors.

Objective: Implement a randomized depth-first search (DFS) to traverse the graph and compare the performance with DFS and BFS.

CODE:

```
% Randomized DFS algorithm
function gpath = dfs(graph, start, target, visited, path)
% If target is found, return the path
if (start == target)
    gpath = [path, start];
    return;
end

% If already visited, return empty
if visited(start)
    gpath = [];
    return;
end
```

```
visited(start) = true;
  path = [path, start];
  neighbours = find(graph(start, :));
  % Shuffle the neighbours randomly
  neighbours = neighbours(randperm(length(neighbours)));
  % Perform DFS on each neighbor
  for i = 1:length(neighbours)
    node = neighbours(i);
    if ~visited(node)
      result = dfs(graph, node, target, visited, path);
      if ~isempty(result)
         gpath = result;
         return;
      end
    end
  end
  gpath = [];
end
% Traditional DFS Algorithm
function gpath = standard_dfs(graph, start, target, visited, path)
  % If target is found, return the path
  if (start == target)
    gpath = [path, start];
    return;
  end
```

```
% If already visited, return empty
  if visited(start)
    gpath = [];
    return;
  end
  visited(start) = true;
  path = [path, start];
  neighbours = find(graph(start, :));
  neighbours = neighbours(randperm(length(neighbours)));
  % Perform DFS on each neighbor
  for i = 1:length(neighbours)
    node = neighbours(i);
    if ~visited(node)
      result = standard_dfs(graph, node, target, visited, path);
      if ~isempty(result)
         gpath = result;
         return;
      end
    end
  end
  gpath = [];
end
```

```
% Creating a sample graph to check the performance of the algorithm
numNodes = 10;
s = [112345634];
t = [234572413];
G = digraph(s, t);
A = adjacency(G);
visited = false(numNodes, 1);
path = [];
% Call Randomized DFS function
newpath = dfs(A, 1, 7, visited, path);
disp('Randomized DFS Path:');
disp(newpath);
time_randomized = toc;
visited = false(numNodes, 1);
path = [];
% Call Standard DFS function
disp('Standard DFS Path: ');
standard_path = standard_dfs(A, 1, 7, visited, path);
disp(standard_path);
time_standard = toc;
% Comparing the performances
disp('Permance Comaprison: ');
fprintf('Randomized DFS: Time = %.6f seconds, Path Length = %d\n', time_randomized,
length(newpath));
```

fprintf('Standard DFS Path: Time = %.6f seconds, Path Length = %d\n', time_standard, length(standard path));

SIMULATION OUPUT:

Randomized DFS Path:

1 3 5 2 4 7

Standard DFS Path:

1 3 5 2 4 7

Performance Comparison:

Randomized DFS: Time = 3272.038840

seconds, Path Length = 6

Standard DFS Path: Time = 3272.041995

seconds, Path Length = 6

OBSERVATIONS:

From the results of the simulation, we can infer that although both randomized DFS and the traditional DFS algorithm work on similar principles, the randomized DFS algorithm can avoid worst-case scenarios with the help of randomness while the same cannot be said for the traditional DFS algorithm.

2. Problem Statement

Given a large dataset (millions of records), sorting needs to be performed efficiently while avoiding worst-case scenarios. Challenges:

- 1. Deterministic QuickSort suffers from O(n2) worst-case complexity if the pivot selection is poor.
- 2. Large datasets may cause performance bottlenecks in memory usage and computation time.
- 3. Parallel execution requires adaptable sorting algorithms.

Objective: Implement Randomized QuickSort, analyze its performance, and compare it with traditional sorting algorithms (Quick Sort & Merge Sort).

CODE:

```
% Randomized Algorithm
max_size = 1000;
x_axis = 1:max_size;
y_axis = zeros(1, max_size);
% Functions to highlight the implementation of traditional QuickSort
% algorithm
function [arr, pidx, num] = partition(arr, low, high)
    num = 0;
    pivot = arr(high);
    i = low-1;

for j=low:high-1
```

```
num = num+1;
    if arr(j) > pivot
      i=i+1;
      temp =arr(i);
      arr(i) = arr(j);
      arr(j) = temp;
    end
  end
  i = i+1;
  temp = arr(i);
  arr(i) = arr(high);
  arr(high) = temp;
  pidx=i;
end
function [arr, totalcomp] = quicksort(arr, low, high)
  totalcomp = 0;
  if low < high
    [arr, pidx, num] = partition(arr, low, high);
    totalcomp = totalcomp + num;
    [arr, leftcomp] = quicksort(arr, low, pidx-1);
    totalcomp = totalcomp + leftcomp;
    [arr, rightcomp] = quicksort(arr, pidx+1, high);
    totalcomp = totalcomp + rightcomp;
  end
end
% Implementation of Randomized QuickSort algorithm on different arrays
for n=1:max_size
  arr = round(rand(1, n)*100);
```

```
arr1 = zeros(1, n);
  num=0;
  for i=1:n-1
    j = randi(1, n);
    if arr(j) \approx 0
      break;
    end
    arr1(j) = arr(i);
    num=num+1;
  end
  for a=1:n-2
    if arr1(a+1) < arr1(a)
      break;
    end
    num=num+1;
  end
  y_axis(n) = num;
end
y_axis2 = zeros(1, max_size);
for t=1:max_size
  arr2 = round(rand(1, t)*100);
  [~, num1] = quicksort(arr2, 1, t);
  y_axis2(t) = num1;
end
figure;
plot(x_axis, y_axis, LineWidth=2, Color='r');
```

```
title("Randomized Algorithm");

xlabel('Data Size Input');

ylabel("Number of Comparisons");

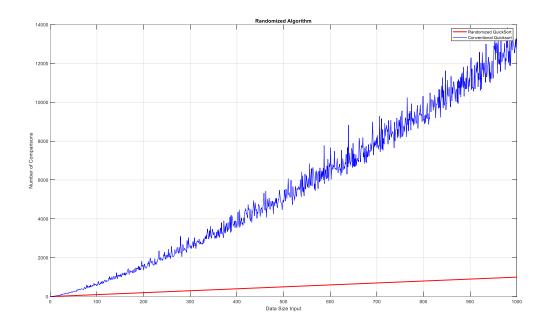
grid on;

hold on;

plot(x_axis, y_axis2, LineStyle="-", Color='b');

legend("Randomized QuickSort", "Conventional Quicksort");
```

SIMULATION:



OBSERVATIONS:

Most of the traditional algorithms like Quick sort, Merge sort etc, tend to perform much worse compared to Randomized Quick sort as they tend to go into worst-case scenarios. In terms of time complexity, traditional sorting algorithms go upto O(N^2) and O(N) for randomized sorting algorithms.