POLITECHNIKA WROCŁAWSKA
WYDZIAŁ ELEKTRONIKI

KIERUNEK: Informatyka (INF)
SPECJALNOŚĆ: Internet Engineering (INE)

PRACA DYPLOMOWA MAGISTERSKA

Smartfon z systemem Android
jako wysokopoziomowy sterownik robota

Android smartphone
as a high-level controller of a robot

AUTOR:
Michał Kowalski

PROWADZĄCY PRACĘ:
dr inż. Marek Woda

OCENA PRACY:

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Contents

Chapter 1

Introduction

1.1 Description of problem

1.2 Goal of a project

1.3 State of art

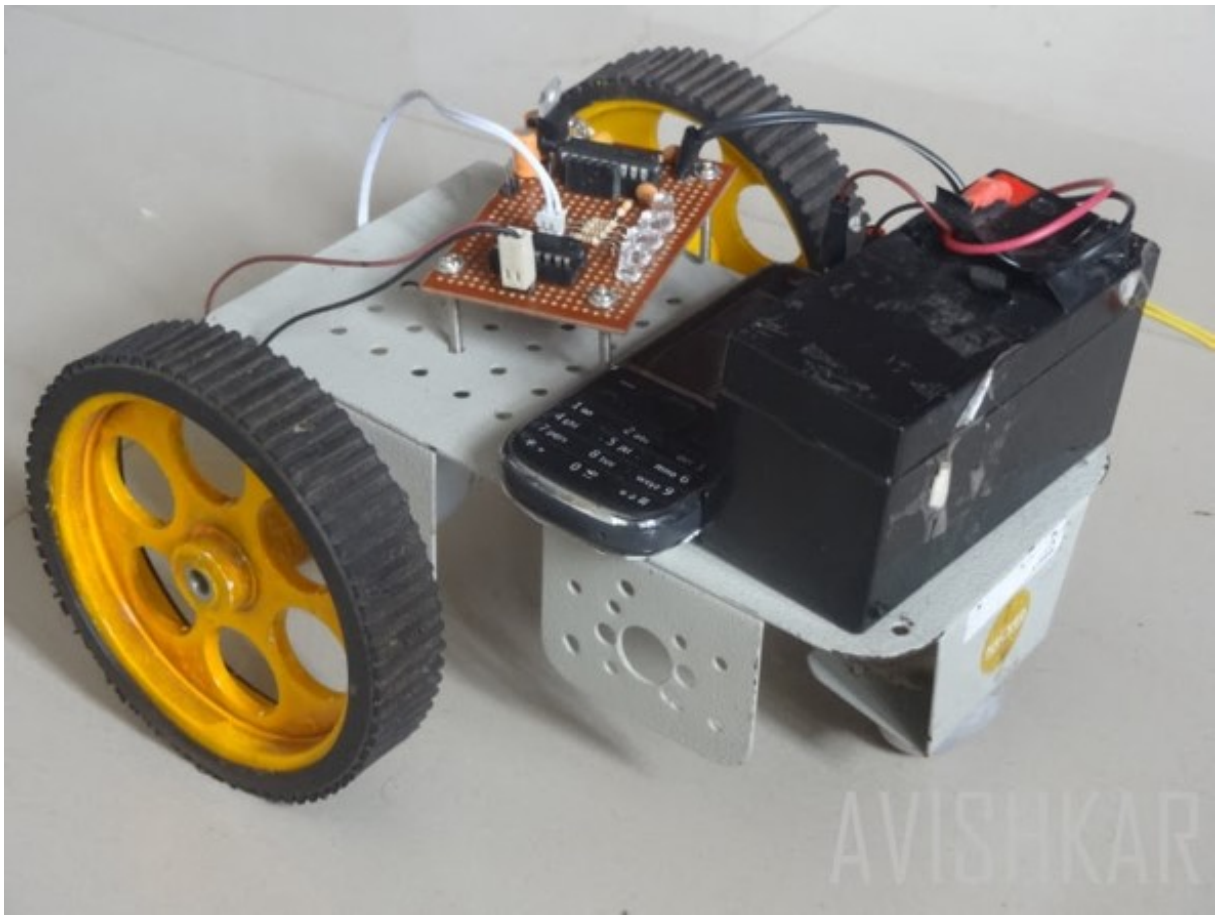

Figure 1.1 robot1, [1] fdfsdfsdf dgfdgdf gfhgfh

Figure 1.2 robot2, [2]

Figure 1.3 robot3, [3]

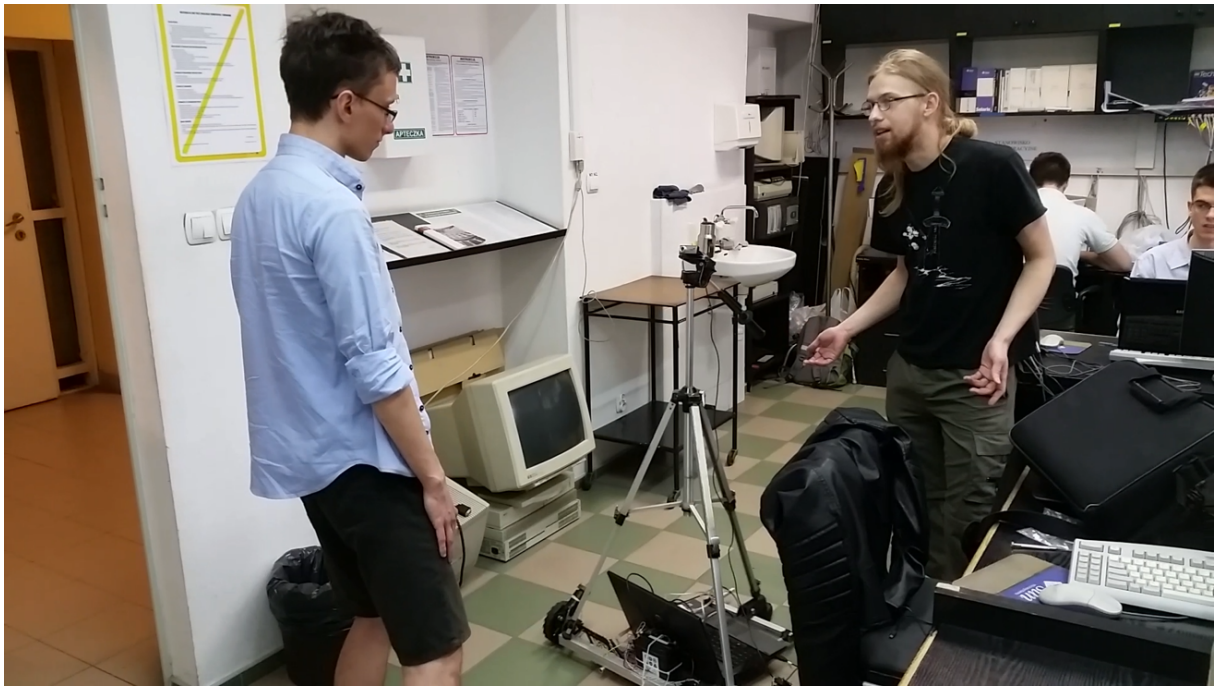

Figure 1.4 own robot

Chapter 2

Platforms

2.1 Android

2.2 MCU

Chapter 3

Communication

3.1 Introduction

3.2 Communication through USB cable - MCU

3.2.1 UART

3.2.2 CDC

3.3 Communication through USB cable - Android

3.3.1 USB Host API

3.3.2 mik3y

3.3.3 felHR85

3.4 Summary

Chapter 4

Sensors

4.1 Introduction

Modern smartphones has many sensors, and most of them can extend robot's functionality. Sensors differ between phones, and new (or more advanced) ones can be connected using possible connections (mostly USB and Bluetooth). Most popular ones are:

- touch screen,
- accelerometer,
- gyroscope,
- microphone(s),
- front and rear camera(s),
- position sensors:
  - GPS,
  - based on GSM and WiFi,
- magnetometer,
- light sensor,
- proximity sensor.

Some (mostly high-end, or specialized ones) have also sensors like electronic compass, humidity/temperature sensors, fingerprint scanner, or even thermal camera.

4.2 Face detection

Available implementations of face detection includes:

- FaceDetector API,
- Camera API,
- openCV for Android,
- openCV NDK.

4.2.1 FaceDetector API

4.2.2 Camera API

4.2.3 openCV for Android

4.2.4 openCV NDK

4.3 Summary

Chapter 5

Summary

Bibliography

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[8] mik3y's GitHub

[9] felHR85's GitHub