

Indian Institute of Technology, Guwahati



Department of Computer Science and Engineering

Project Report

On

“Speech Based Browser Automation”

Based on

Speech Recognition System

Course: CS566 Speech Processing

GROUP NO 19

Submitted to

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ABSTRACT

This document defines a set of evaluation criteria and test methods for speech recognition systems used in searching and retrieving contact details. This report is on the project which detects the contact name and show its details

.

INTRODUCTION

In this report, we concentrate on the speech recognition programs that are human-computer interactive. When software evaluators observe humans testing such software programs, they gain valuable insights into technological problems and barriers that they may never witness otherwise. . Testing speech recognition products for universal usability is an important step before considering the product to be a viable solution for its customers later. This document concerns Speech Recognition accuracy in contact searching and retrieving details, which is a critical factor in the development of hands-free human- machine interactive devices. There are two separate issues that we want to test: word recognition accuracy and software friendliness. Major factors that impede recognition accuracy in the environment noise sources and system noise.

However, what is speech recognition?

Speech recognition works like this. You speak into a microphone and the computer transforms the sound of your words into text to be used by your word processor or other applications available on your computer. The computer may repeat what you just said or it may give you a prompt for what you are expected to say next. This is the central promise of interactive speech recognition. You also had to correct any errors virtually as soon as they happened, which means that you had to concentrate so hard on the software that you often forgot what you were trying to say.

The new voice recognition systems are certainly much easier to use. You can speak at a normal pace without leaving distinct pauses between words. However, you cannot really use “*natural speech*” as claimed by the manufacturers. You must speak clearly, as you do when you speak to a Dictaphone or when you leave someone a telephone message. Remember, the computer is relying solely on your spoken words. It cannot interpret your tone or inflection, and it cannot interpret your gestures and facial expressions, which are part of everyday human communication. Some of the systems also look at whole phrases, not just the individual words you speak. They try to get information from the context of your speech, to help work out the correct interpretation.

The goal of this project is to define a set of evaluation criteria and test methods for the interactive voice recognition systems for searching contact and retrieving corresponding details for successful search.

PROPOSED METHODOLOGY

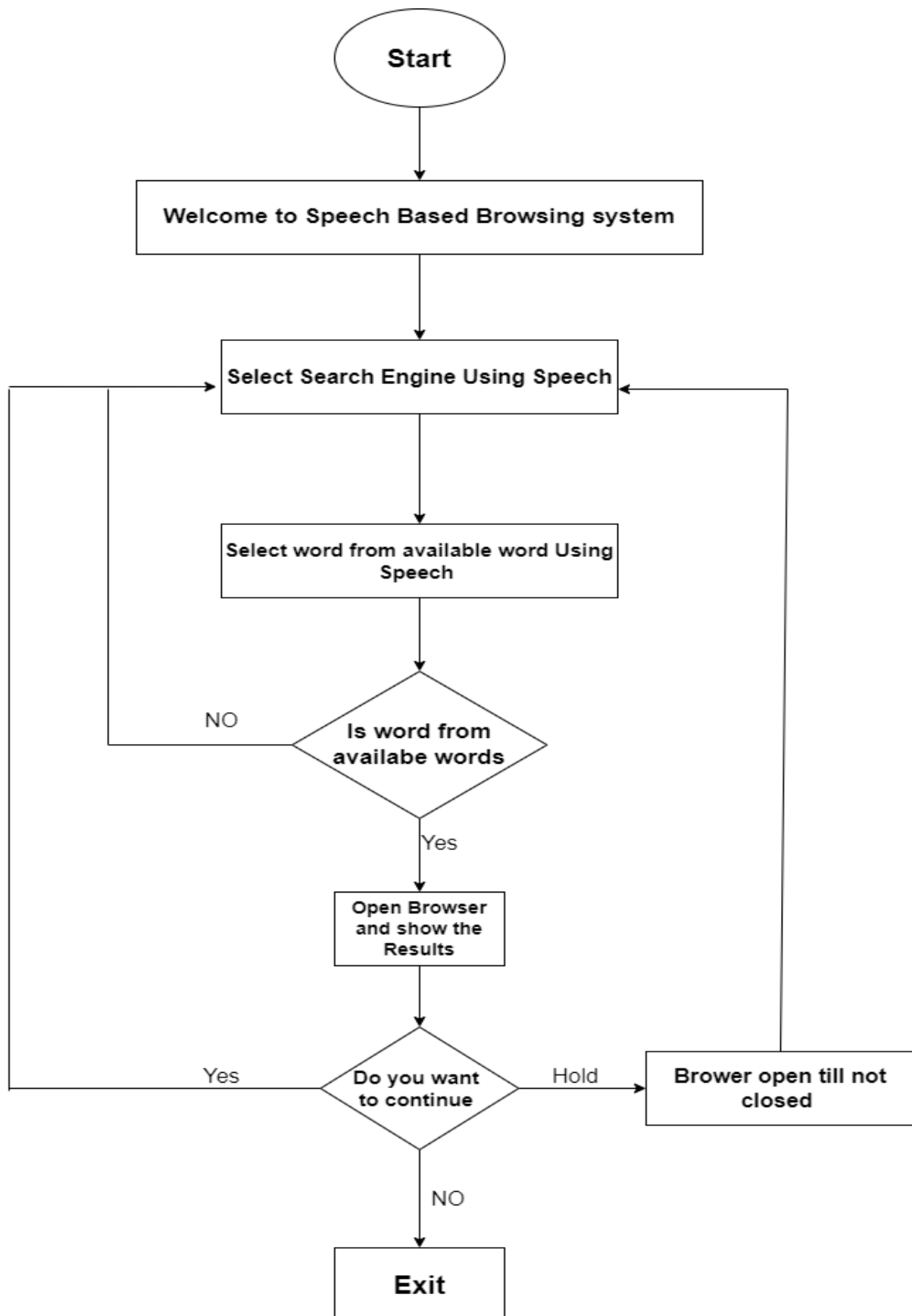
Basic requirements to develop this project are as follows:

- ✓ Windows OS
- ✓ Microsoft Visual Studio 2010
- ✓ C++ 11 integrated with VS2010
- ✓ Recording Module

With the availability of above software, we further proceed in modelling the logic. The prerequisites of this project are

- ✓ Basic i/o operations on file
- ✓ Pre-processing of speech data
- ✓ Feature extraction
- ✓ Modelling of extracted feature
- ✓ Enhancing model

With the availability of above tools, we further proceeded. Below is the flow chart for our project



EXPERIMENTAL SETUP

This project is divided into following modules:

- 1. Training Module**
- 2. Testing Module**

1. Training Module

The flow for training over data is as follows:

- i. Record the data as 30 utterance of each word
- ii. Extract frames for every utterance
- iii. Using local distance analysis (in vector quantization) calculate the observation sequence.
- iv. Pass this observation sequence to HMM for model designing.
- v. Now enhance the model using HMM re-estimation algorithm.

Now reference model is ready for our project. The training of data is not integrated with GUI application. This is different module, which will just evaluate reference model.

2. Testing Module

System will give instruction what is going on and user is required to follow it. The flow of testing is as follows:

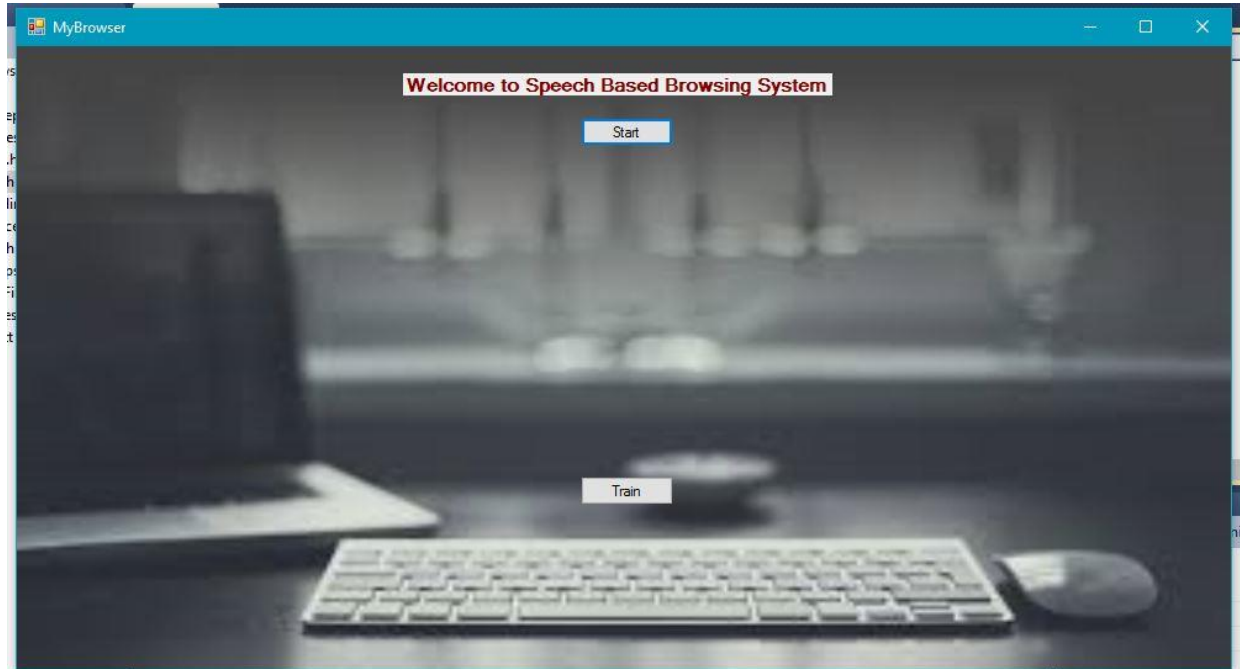
- i. Live recording of data is done when system instruct.
- ii. Testing the data with retrained models.
- iii. Detect the Search Engine
- iv. Detect the word which has to be search
- v. If word is correctly spoken then it opens browser.
- vi. If wrong word detected then ,record the input again.

3. WORDS USED

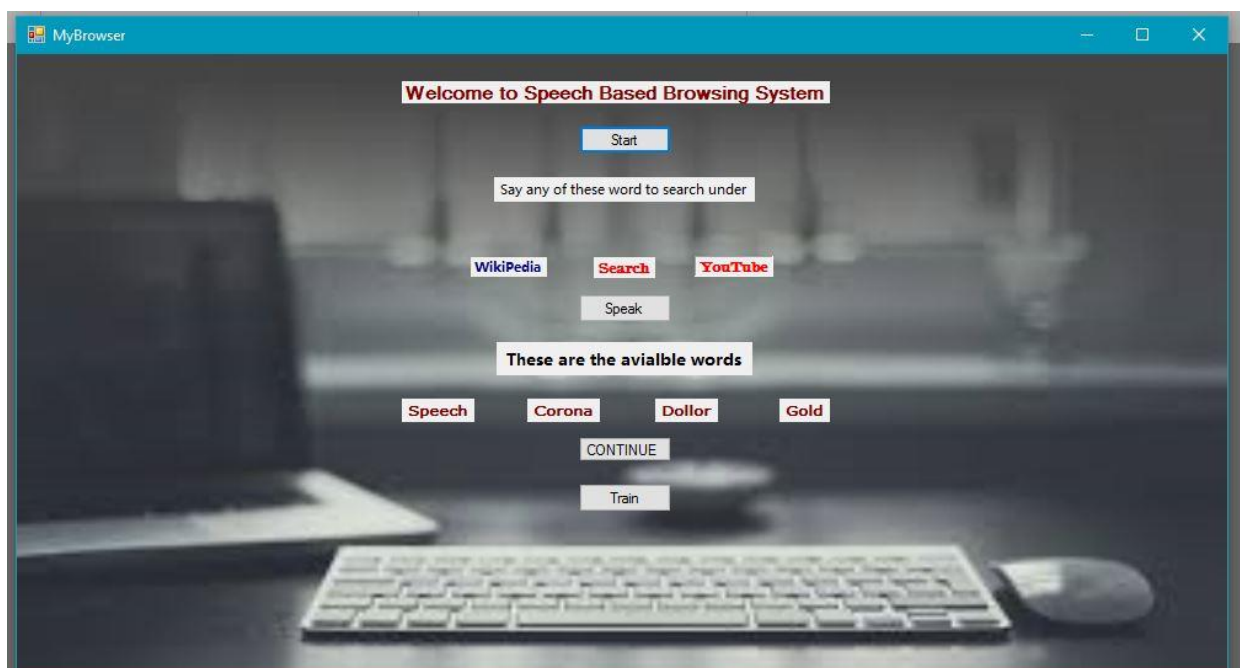
- 1. START**
- 2. STOP**
- 3. YES**
- 4. SEARCH**
- 5. WIKIPEDIA**
- 6. YOUTUBE**
- 7. SPEECH**
- 8. GOLD**
- 9. CORONA**
- 10. DOLLAR**

4. SCREEN SHORTS

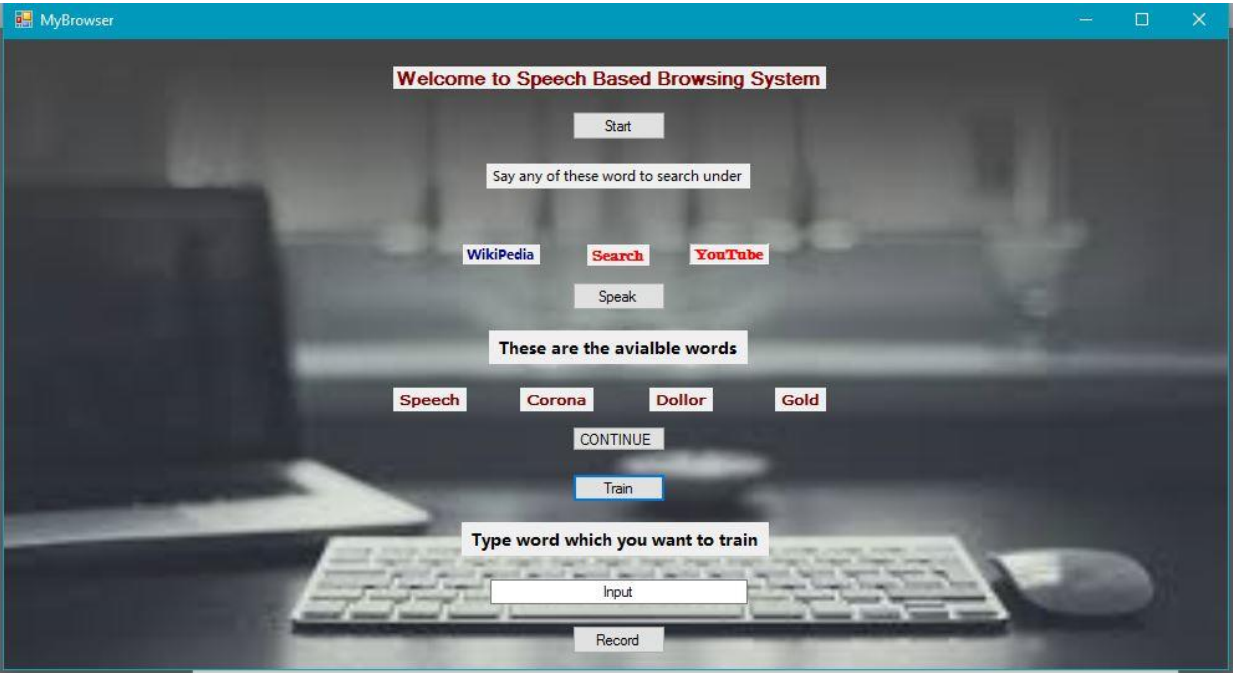
INITIAL WINDOW



WINDOW AFTER START



CLICK TARIN BUTTON



RESULT

For offline testing, we took 30 recordings of each word, with deterministic difference of maximum and second maximum $P(O/\lambda)$ we got 85% accuracy and without considering deterministic difference we got 95% accuracy.

The Spoken word will open in browser with selected Search engine i.e. YouTube , Google or Wikipedia , Then we search for the available words.

SOURCE CODE

```
#include "stdafx.h"
#include<iostream>
#include<iomanip>
#include<fstream>
#include<vector>
#include<string>
#include<ctype.h>
#include<string.h>
#include<cstring>

using namespace std;
typedef long double ld;

////////////////////////////////// VARIABLES USED FOR HMM ////////////////////////////////////
#define N 5 // number of states
#define M 32 // number of distinct observation symbols
#define T 40 // number of frames
#define p 12 // number of capstral coefficients per
frame // size of a frame (320 samples)
#define F 320 // codebook 32x12

vector<vector<long double>> cb;
vector<ld> data; // observation sequence
vector<ld> ob; // initial state distribution
vector<ld> pi(N,0); // state transition probability
vector<vector<ld>> a( N,vector<ld> (N,0)); // observation symbol probability in state
distribution
vector<vector<ld>> b( N,vector<ld> (M,0) );

vector<ld> pi_sum(N,0);
vector<vector<ld>> a_sum(N,vector<ld> (N,0));
vector<vector<ld>> b_sum(N,vector<ld> (M,0) );

vector<ld> pi_bar(N,0);
vector<vector<ld>> a_bar(N,vector<ld> (N,0));
vector<vector<ld>> b_bar(N,vector<ld> (M,0) );

vector<vector<ld>> alpha(T,vector<ld> (N,0)); // FORWARD VARIABLE - probab. of partial
onbserv. seq. o1,o2...ot // BACKWARD VARIABLE - joint probab. of
vector<vector<ld>> beta(T,vector<ld> (N,0)); // best score (heighest prob.) along a
ot+1,ot+2...oT at t ans state Si and model λ
vector<vector<ld>> delta(T,vector<ld> (N,0));
single path at time t
vector<vector<ld>> psi(T,vector<ld> (N,0));
vector<vector<ld>> gama(T,vector<ld> (N,0));
vector<vector<vector<ld>>> zeta(T,vector<vector<ld>> (N,vector<ld> (N,0))); // ξ

vector<ld> qstar(T);
ld P,
pstar;

//////////////////////////////////
////////////////////////////////// VARIABLES USED FOR CODEBOOK CALCULATION ////////////////////////////////////

string read_line ;//TO READ LINES FROM FILES

ld
sampleval_x1=0, // FOR
VALUES OF FILE
headerline_count=0, //
READING HEADER FILE FOR NUMBER OF SAMPLE
normalised_value=0,
//NORMALISED VALUES
// b=0,
no_of_frames=0, // NO OF
FRAMES
l=0,
```

```

        i=1,
        min=0,
//MINIMUM OF WHOLE DATA
        max_of_data=0,
//MAXIMUM OF WHOLE DATA
        steadyframes_xi[100][320]={0} , //STEADY
FRAME MATRIX CONTAINS VALUES OF 5 STEADY FRAMES

        feature_ref_matrix[41][13]={0}, //
FEATURE REFERENCE MATRIX CONTAINS VALUES OF RAISED SINE Ci VALUES

        E=0 , //USED IN DURBIB
ALGORITHM
        k[13]={0,0,0,0,0,0,0,0,0,0,0,0,0} , //USED
IN DURBIB ALGORITHM
        sum=0, //USED
IN DURBIB ALGORITHM
        alpha_durbin[13][13]={0}, //USED
IN DURBIB ALGORITHM
        ri[13]={0,0,0,0,0,0,0,0,0,0,0,0,0} ,//
        ai[13]={0,0,0,0,0,0,0,0,0,0,0,0,0} ,//
        ci[13]={0,0,0,0,0,0,0,0,0,0,0,0,0} ,//
        raisedci[13]={0,0,0,0,0,0,0,0,0,0,0,0,0} ,
//RAISED SINE Ci VALUES
        resultant_feat_ref_maxtrix[6][13]={0},
//RESULTANT FEATURE REFERENCE MATRIX CONTAINS VALUES OF RAISED SINE Ci VALUES
        tohkura=0.0,
//TOKHURA DISTANCE
        tokhura_w[12]={1.0 , 3.0, 7.0, 13.0 ,19.0, 22.0 , 25.0,33.0,42.0,50.0,56.0,61.0}, //GIVEN
TOKURA WEIGHTS
        dc_shift=0.0; //DC SHIFT VALUE

        int line_count=0 , // USE IN
COUNTING THE INDEX VALUES
        maxindex=0; //INDEX
OF MAXIMUM VALUE IN NORMALISED VALUES FOR SEARCHING THE 5 5 STEADY FRAMES

////////////////////////////////////

void dcshift(string &filename)
{
    fstream f;
    f.open(filename ,ios::in);
    if(!f)cout<<"ERROR FOR DC SHIFT ::"<<filename<<"\n";
    else
    {
        // cout<<"DC SHIFT ::"<<filename<<"\n";
        while(line_count<=5*F) // TAKING FIRST 5 FRAMES
        {
            //cout<<i<<"\n";i++;
            f>>read_line;
            sampleval_x1=stold(read_line);
            dc_shift=dc_shift+sampleval_x1;
            //cout<<i-10<<" )" <<dc_shift<<"\n";
            line_count++;
        }
        dc_shift=dc_shift/1600.0;
        // cout<<"DC_SHIFT= " <<dc_shift<<"\n";
        line_count=0;
        f.close();
    }
}

void findmax(string &filename)
{
    max_of_data=0;
    line_count=0;
    maxindex=0;
    fstream f;
    f.open(filename ,ios::in);
    if(!f)cout<<"ERROR FOR FIND MAX ::"<<filename<<"\n";
    else
    {
        // cout<<"FIND MAX ::"<<filename<<"\n";
        while(!f.eof())
        {
            f>>read_line;
            line_count++;
            sampleval_x1=stold(read_line);

            if((max_of_data >= sampleval_x1))
            {
                max_of_data=max_of_data;
            }
        }
    }
}

```

```

        else
        {
            max_of_data=sampleval_x1;
            maxindex=line_count;
        }
    }
    line_count=0;
    // cout<<"\nMAX= "<<" "<<max_of_data; // PRINTING MAX IN GIVEN FILE
    // cout<<"\nMAX INDEX = "<<" "<<maxindex;
}
f.close();
}
///////////////////////////////////////////////////////////////////FINDING STEADY FRAMES ///////////////////////////////////////////////////////////////////
void findsteadyframes(string &filename)
{
    fstream f;
    f.open(filename,ios::in);
    if(!f)cout<<"\nERROR FOR FIND STEADY FRAMES ::"<<filename<<"\n";
    else
    {
        // cout<<"\nFIND STEADY FRAMES ::"<<filename<<"\n";
        while(!f.eof())
        {
            f>>read_line;

            sampleval_x1=stold(read_line);
            line_count++;
            if(line_count == (maxindex- 20*F))// TAKING 30 FRAMES LEFT OF MAX VALUE AND 70
FRAMES RIGHT OF MAX VALUE
            {
                for (int b = 0; b < 40 ; b++)
                {
                    for(int d=0 ; d < 320 ; d++)
                    {
                        f>>read_line;
                        sampleval_x1=stold(read_line);
                        // cout<<sampleval_x1<<"\n";
                        steadyframes_xi[b][d]=sampleval_x1;// START SAVING
                        // cout<<steadyframes_xi[b][d]<<" ";
                    }
                    // cout<<"-----\n";
                }
                break;
            }

            // if(sampleval_x1 >= (50/100)*max_of_data || sampleval_x1 <= -(50/100)*max_of_data )
            // {
            //     f1<<read_line<<"\n";
            // }

        }//while ends.....
    }
    f.close();
    //NORMALISE/////////////////////////////////////////////////////////////////
    for (int b = 0; b < 40 ; b++)
    {
        for(int d=0 ; d < 320 ; d++)
        {
            steadyframes_xi[b][d]= ((steadyframes_xi[b][d] - dc_shift ))*(5000/ (max_of_data));
        }
    }
    ///////////////////////////////////////////////////////////////////
    /////////////////////////////////////////////////////////////////// checking the cut.....
    fstream f1;
    f1.open("log.txt",ios::out);
    if(!f1)cout<<"\nerror...log"<<"\n";
    else
    {
        f1.clear();
        // cout<<"\nsuces...log";
        for (int b = 0; b < 40 ; b++)
        {
            for(int d=0 ; d < 320 ; d++)
            {
                f1<<steadyframes_xi[b][d]<<"\n";
                // sampleval_x1=stold(read_line);
                // cout<<sampleval_x1<<"\n";
                // steadyframes_xi[b][d]=sampleval_x1;// START SAVING
                // cout<<steadyframes_xi[b][d]<<" ";
            }
        }
    }
    STEADY FRAMES VALUES IN A MATRIX OF 5 x 12

```

```

    }
    // cout<<"-----\n";

}

// cout<<"\nFRAME -->"<b+1;

// cout<<"\nCALCULATING R(i)....\n";

ld sum=0;

for (int i = 0; i <= 12; i++)
{
    // if(i==1)break;
    sum=0;
    for (int j = 0; j <= 320 -1 -i ; j++)
    {
        sum = sum + steadyframes_xi[b][j] *

        // cout<<j+1<<" "<<test[j]*test[i+j]<<"\n";
        // cout<<i<<" "<<i+j<<"\n";

    } //cout<<"-----\n\n";
    feature_ref_matrix[b][i] = sum;
    // cout<<a<<"\n";

}

// for (int i = 0; i <= 12; i++)
// {
//     cout<<b<<" "<<i<<"
//     cout<<b<<" "<<i<<"

"<<fixed<<setprecision(4)<<feature_ref_matrix[b][i]<<"\n";
//     cout<<"\n";

// }

// cout<<"\n";

// //////////////////////////////////////// ai
// ////////////////////////////////////////

// cout<<"\nCALCULATING A(i)....\n";
E=feature_ref_matrix[b][0];
// cout<<fixed<<setprecision(8);
// cout<<E;

sum=0;

for (int i = 1; i <= 12 ; i++)
{
    sum = 0.0;
    // cout<<"\n\ni="<<i;
    // cout<<"\nki -----\n";

    for (int j = 1; j <= i - 1; j++)
    {
        sum = sum + alpha_durbin[i - 1][j] *

        // cout<<"sum= "<<sum<<"\n";

    }

    // k[i] calculation
    k[i] = (feature_ref_matrix[b][i] - sum) / E;
    // cout<<"ki ="<<k[i]<<"\n";

    // cout<<"alpha i i-----\n";

    alpha_durbin[i][i] = k[i];
    // cout<<alpha[i][i]<<"\n";

    // cout<<"alpha i j-----\n";

    //alpha calculation

```

```

alpha_durbin[i - 1][i - j] );

for (int j = 1; j <= i - 1; j++)
{
    alpha_durbin[i][j] = alpha_durbin[i - 1][j] - ( k[i] *

        // cout<<alpha_durbin[i][j]<<"\n";

    }

    // cout<<"E ----- \n";

    //Energy calculation
    E = (1 - k[i] * k[i]) * E;
    // cout<<E<<"\n";

    // cout<<"----- \n";

}

}

//ppppp

for (int i = 1; i <= 12; i++)
{
    feature_ref_matrix[b][i-1]=alpha_durbin[12][i];
    // cout<<feature_ref_matrix[b][i]<<"\n";
    // cout<<alpha[12][i]<<"\n";

}

// cout<<"----- \n";

// for (int i = 1; i <= 12; i++)
// {
//     // cout<<feature_ref_matrix[b][i]<<"\n";
//     cout<<b<<" "<<i<<"

"<<fixed<<setprecision(4)<<feature_ref_matrix[b][i]<<"\n";
// }

//

////////////////////////////////////

// ////////////////////////////////// ci
////////////////////////////////////
// cout<<"\nCALCULATING C(i)....\n";
// long double ci[13] ,ai[13] ;
// ci[0]=log(feature_ref_matrix[b][0] *

feature_ref_matrix[b][0]);

ci[0] = feature_ref_matrix[b][1];
// cout<<ci[0];

// long double a=0.0;

sum=0;

for (int m = 1; m <= 12; m++)
{
    sum=0;
    for (int k = 1; k <= m-1 ; k++)
    {
        // cout<<k<<" "<< (double)k/ (double)m <<" "<<ci[k]<<"

        sum= sum + ((double)k/ (double)m) * ci[k] *

        // cout<<(k/m) * ci[k] * ai[m-k]<<"\n";
        // cout<<a<<"\n";
    }/cout<<"----- \n";

    ci[m] = feature_ref_matrix[b][m-1] + sum;
    // cout<<ci[m]<<"\n";

}

for (int i = 1; i <= 12; i++)
{
    feature_ref_matrix[b][i]=ci[i];
    // cout<<ci[i]<<"\n";
    // cout<<feature_ref_matrix[b][i]<<" ";

}

// cout<<"----- \n";

////////////////////////////////////

// ////////////////////////////////// RAISED SINE
////////////////////////////////////
// cout<<"\nRAISED SINE RC(i)....\n";

for (int i = 1; i <= 12; i++)
{

```

```

3.1415926535 * i )/12 ) ) ;

raisedci[i] = feature_ref_matrix[b][i] * (1 + 6 * sin( (
}

for (int i = 1; i <= 12; i++)
{
    feature_ref_matrix[b][i]=raisedci[i];
    // cout<<raisedci[i]<<"\n";
    // cout<<feature_ref_matrix[b][i]<<" ";
}
// cout<<"-----\n";

//
////////////////////////////////////

    /// adding in myuniverse.txt

    // fstream u;
    // u.open("projectuniverse.txt" , ios::app);
    // if(!u)cout<<"\nERROR OPENING myuniverse.txt\n";
    // else
    // {
    //     for (int i = 1; i <= 12; i++)
    //     {
    //         // feature_ref_matrix[b][i]=raisedci[i];
    //         // cout<<raisedci[i]<<"\n";
    //         // u<<feature_ref_matrix[b][i]<<" ";
    //     }

    //     u<<"\n";
    //     // cout<<"\nsucess...universe";
    // }

    }//LOOP ENDS FOR ALL FRAMES.....

}

void findobservationseq()
{
    int min_tok=INT_MAX;
    int ob_index=0;

    // cout<<"sucess...codebook\n";

    // for (int frame = st; frame < st+1; frame++)
    for (int frame = 0; frame < 40; frame++)
    {
        min_tok=INT_MAX;
        // tohkurad=INT_MAX;
        fstream f;
        f.open("projectcodebook2.txt" ,ios::in|ios::out);
        if(!f)cout<<"\nERROR IN OPENING CODEBOOK \n";
        else
        {
            for (int row = 0; row < 32; row++)
            {

                for (int c = 1; c <= 12; c++)
                {
                    f>>read_line;
                    // cout<<read_line<<" ";
                    // cout<<feature_ref_matrix[frame][c]<<" ";
                    tohkurad = tohkurad + tokhura_w[c-1] * ( (feature_ref_matrix[frame][c] -
stold(read_line))*(feature_ref_matrix[frame][c] - stold(read_line)) );
                }
                // cout<<tohkurad<<"\n";

                if(tohkurad < min_tok)
                {
                    min_tok=tohkurad;
                    ob_index=row;
                    // cout<<row<<"\n";
                }
                tohkurad=0.0;
            }

            ob.push_back(ob_index);
            // cout<<"\n-----\n";

        }

    }

    // for (int i = 0; i < ob.size(); i++)
    // {
    //     // cout<<i<<"--"<<ob[i]<<"\n";
    //     cout<<ob[i]<<" ";

```



```

        // }
        // cout<<"\n-----\n";

} // findobservationseq() ends.....

////////// INITIALISING WITH BAYKIS-MODEL //////////
void baykis_model()
{
    pi[0]=1.0;
    for(int i=0;i<N;i++)
    {
        for(int j=0;j<N;j++)
        {
            if(i==j&&i!=N-1)
            {
                a[i][j]=0.8;
            }
            else if(i==j&&i==N-1)
            {
                a[i][j]=1;
            }
            else if(j==i+1)
            {
                a[i][j]=0.2;
            }
            else
                a[i][j]=0;
        }
    }

    for(int i=0;i<N;i++)
    {
        for(int j=0;j<M;j++)
        {
            b[i][j]=1.0/M;
        }
    }
}

//////////

void display_A_B_matrix()
{
    cout<<"Pi is \n";
    cout<<"-----\n\n";
    for (int i = 0; i < N; i++)
    {
        cout<<pi[i]<<" ";
    }cout<<"\n";
    cout<<"-----\n\n";

    cout<<"A matrix is \n";
    cout<<"-----\n\n";
    for(int i=0;i<N;i++)
    {
        for(int j=0;j<N;j++)
        {
            cout<<setprecision(12)<<a[i][j]<<"\t";
            cout<<"\n";
        }
    }
    cout<<"\n-----";
    cout<<"\n\n";
    cout<<"\n\nB matrix is \n";
    cout<<"\n-----";
    cout<<"\n";
    for(int i=0;i<N;i++)
    {
        for(int j=0;j<M;j++)
        {
            cout<<setprecision(12)<<b[i][j]<<"\t";
            cout<<"\n";
        }
    }
    cout<<"\n-----";
    cout<<"\n";
}

////////// SOLUTIONS TO 3 PROBLEMS //////////

//SOLUTION TO 1 PROBLEM
ld forward() // O(N^2 T)
{
    //initialisation
    for(int i=0;i<N;i++)
    {
        // cout<<pi[i]<<"x"<<b[i][ob[0]-1]<<"\n";
    }
}

```

```

        alpha[0][i]=pi[i]*b[i][ob[0]];
    }

    // cout<<"\n aftr intialization\n";
    // for(int i=0;i<N;i++)
    //     cout<<alpha[0][i]<<" ";
    // cout<<"\n";

    //induction
    for(int t=0;t<T-1;t++)
    {
        // cout<<t<<"--> ";
        for(int j=0;j<N;j++)
        {
            ld sum=0;
            for(int i=0;i<N;i++)
            {
                sum+=alpha[t][i] * a[i][j];
            }
            // cout<<sum<<" ";
            //cout<<t<<" "<<j<<"\n";
            alpha[t+1][j]=sum * b[j][ob[t+1]];
            // cout<<alpha[t+1][j]<<" ";
        }
        // cout<<"\n";
    }

    //termination
    P=0;
    for(int i=0;i<N;i++)
    {
        P+=alpha[T-1][i];
        //cout << alpha[T-1][i] << "\n";
    }
    return P;
}

ld backward() // O(N^2 T)
{
    // initialisation
    for(int i=0;i<N;i++)
        beta[T-1][i]=1;

    // cout<<"\n after intialization\n";
    // for(int i=0;i<N;i++)
    //     cout<<alpha[0][i]<<" ";
    // cout<<"\n";

    //induction
    for(int t=T-2;t>=0;t--)
    {
        for(int i=0;i<N;i++)
        {
            ld sum=0;
            for(int j=0;j<N;j++)
            {
                sum+= a[i][j] * b[j][ob[t+1]] * beta[t+1][j];
            }
            beta[t][i]=sum;
            // cout<<beta[t][i]<<" ";
            // cout<<sum<<" ";
        }
        // cout<<"\n";
    }
    P=0;
    //termination
    for(int i=0;i<N;i++)
    {
        P+=beta[0][i];
        //cout << beta[0][i] << "\n";
    }
    return P;
}

//SOLUTION TO 2 PROBLEM
ld viterbi_algorithm()
{
    int arg_max=0;
    //step 1 initialisation
    for(int i=0;i<N;i++)
    {
        delta[0][i]=pi[i]*b[i][ob[0]];
    }

```

```

        //cout << delta[0][i] << "\n";
        psi[0][i]=-1;
    }

    //step 2 induction
    for(int t=1;t<T;t++)
    {
        for(int j=0;j<N;j++)
        {
            arg_max=0;
            for(int i=1;i<N;i++)
            {
                if(delta[t-1][i]*a[i][j] > delta[t-1][arg_max]* a[arg_max][j])
                    arg_max=i;
            }
            // cout<<"here"<<j<<" "<<i<<"\n";
            delta[t][j]=delta[t-1][arg_max]*a[arg_max][j]* b[j][ob[t]];
            psi[t][j]=arg_max;
        }
    }

    arg_max=0;
    for(int i=1;i<N;i++)
    {
        if(delta[T-1][i] > delta[T-1][arg_max])
            arg_max=i;
    }

    // step 3 termination
    pstar=delta[T-1][arg_max];

    //backtrack_qstar(argmax);
    //step 4 back tracking
    qstar[T-1]=arg_max;
    // cout<<"\n";

    for(int t=T-2;t>=0;t--)
    {
        qstar[t]=psi[t+1][(long int)qstar[t+1]];
        // cout<<qstar[t]<<" ";
    }
    for (int i = 0; i < T; i++)
    {
        // cout<<qstar[i]<<" ";
    }

    return pstar;
}

void gamma()
{
    int argmax=0;
    ld devider=0;
    for(int t=0;t<T;t++)
    {
        for(int i=0;i<N;i++)
        {
            devider+=alpha[t][i]*beta[t][i];
        }
        argmax=0;
        for(int i=0;i<N;i++)
        {
            gama[t][i]=alpha[t][i]*beta[t][i]/devider;
            if(gama[t][argmax]<gama[t][i])
                argmax=i;
        }
        devider=0;
    }
}

void zeta_calculation()
{
    ld devider=0;
    for(int t=0;t<T-1;t++)
    {
        devider=0;
        for(int i=0;i<N;i++)
        {
            for(int j=0;j<N;j++)
                devider+=alpha[t][i]*a[i][j]*b[j][ob[t+1]]*beta[t+1][j];
        }
        for(int i=0;i<N;i++)
        {
            for(int j=0;j<N;j++)

```

```

        zeta[t][i][j]=alpha[t][i]*a[i][j]*b[j][ob[t+1]]*beta[t+1][j]/devider;
    }
}

// SOLUTION TO 3 PROBLEM
void re_estimation()
{
    ld numerator=0, denominator=0;

    //calculating pi bar
    for(int i=0;i<N;i++)
        pi_bar[i]=gama[0][i];

    //calculating a bar
    for(int i=0;i<N;i++)
    {
        for(int j=0;j<N;j++)
        {
            numerator=0;
            denominator=0;
            for(int t=0;t<T-2;t++)
            {
                numerator+=zeta[t][i][j];
                denominator+=gama[t][i];
            }
            a_bar[i][j]=numerator/denominator;
        }
    }

    //calculating b bar
    for(int j=0;j<N;j++)
    {
        for(int k=0;k<M;k++)
        {
            numerator=0;
            denominator=0;
            for(int t=0;t<T;t++)
            {
                if(ob[t] ==k)
                    numerator+=gama[t][j];
            }
            for(int t=0;t<T-1;t++)
            {
                denominator+=gama[t][j];
            }
            b_bar[j][k]=max(numerator/denominator , (ld)1e-30 );
        }
    }
}

void update() // upadting λ
{
    for(int i=0;i < N;i++) pi[i]=pi_bar[i]; // updating PI

    for(int i=0;i < N;i++) // updating A matrix
    {
        for(int j=0;j < N;j++)
        {
            a[i][j]=a_bar[i][j];
        }
    }

    for(int i=0;i < N;i++) // upadting B matrix
    {
        for(int j=0;j < M;j++)
        {
            b[i][j]=b_bar[i][j];
        }
    }
}

////////////////////////////////////

void recognise()
{
    string word[11]={ "yes", "no", "start", "stop", "wikipedia",
                     "youtube", "search", "speech", "dollar", "corona",
                     "gold"
    };

    string s1="", s2="";
    int i=1;
    string filename="WORD";
    //LIVE TESTING.....
    while(i<=2)

```

```

{

    data.clear(); //clear data[]
    ob.clear(); //clearing for new file

    string path= "RM\\\\"Recording_Module.exe 3 ";
    string filename="WORD";
    path.append(filename);
    path.append(to_string((ld)i));
    path.append(".wav ");
    filename="WORD";
    filename.append(to_string((ld)i));
    filename.append(".txt");
    path.append(filename);

        int n=path.size()+1;

    char ar[100];

        strcpy(ar,path.c_str());

/* for (int i = 0; i < path.size(); i++)
{
    ar[i]=path[i];
    // cout<<a[i];
}*/
// system("RM\\Recording_Module.exe 3 LIVETEST.wav LIVETEST.txt");
system(ar);
// system("taskkill/im Recording_Module.exe");
string test =filename;
cout<<filename<<"\n";

dcshift(test);
findmax(test);
findsteadyframes(test);
ci_cal();
// adding to universe
findobservationseq();
fstream lamda;
lamda.open("projectlamdas.txt",ios::in|ios::out);
if(!lamda)cout<<"\nERROR OPENING lamdamodels.txt\n";
else
{
    ld maxp=-1,modelno=-1;
    for (int model = 0; model <= 10; model++)
    {
        string val;
        for(int m=0;m<N;m++)
        {
            lamda>>val; pi[m]=stold(val);
        }

        for(int m=0;m<N;m++)
        {
            for(int n=0;n<N;n++)
            {
                lamda>>val; a[m][n]=stold(val);
            }
        }

        for(int m=0;m<N;m++)
        {
            for(int n=0;n<N;n++)
            {
                lamda>>val; b[m][n]=stold(val);
            }
        }

        ld temp=forward();
        // cout<<"--"<<max(temp,(ld)maxp)<<"\n";
        cout<<"\n FOR "<<model<<" P ="<<temp;
        if(temp > maxp)
        {
            maxp=temp;
            modelno=model;
            // cout<<modelno<<"\n";
        }

        // cout<<endl;
        // for(int m=0;m<N;m++)
        // { cout<<pi[m]<<" ";}
        // cout<<"\n";
        // for(int m=0;m<N;m++)
        // {for(int n=0;n<N;n++)
        // {cout<<a[m][n]<<" ";}

```

```

        //      cout<<endl;
        //    }
        // for(int m=0;m<N;m++)
        //   {for(int n=0;n<M;n++)
        //     {cout<<b[m][n]<<" ";}
        //   }
        //   cout<<endl;
        // }
    }
    cout<<"\nRECOGNISED WORD --> "<<word[(int)modelno]<<"\n";
    if(i==1)s1=word[(int)modelno];
    if(i==2)s2=word[(int)modelno];
    // if(td==modelno)r++;
    cout<<"\n-----\n";
}
lamda.close();

i++;
}

cout<<s1<<"\n"<<s2<<"\n";

////BROWSER OPENING //////////////////////////////////////
if(s1=="search")
{
    string q="start https://google.com/search?q=";
    q.append(s2);
    char ar[100];
    for (int i = 0; i < 100; i++)
    {
        ar[i]=' ';
    }

    for (int i = 0; i < q.size(); i++)
    {
        ar[i]= q[i];
        // cout<<a[i];
    }

    if(s2=="corona")
    {
        system("start https://www.mohfw.gov.in");
    }
    else
    {
        if(s2=="gold")system("start https://www.goodreturns.in/gold-
rates/");

        else system(ar);
    }
}

if(s1=="wikipedia")
{
    string q="start https://en.wikipedia.org/wiki/";
    q.append(s2);
    char ar[100];
    for (int i = 0; i < 100; i++)
    {
        ar[i]=' ';
    }
    for (int i = 0; i < q.size(); i++)
    {
        ar[i]= q[i];
        // cout<<a[i];
    }
    system(ar);
}

if(s1=="youtube")
{
    string q="start https://www.youtube.com/results?search_query=";
    q.append(s2);
    char ar[100];
    for (int i = 0; i < 100; i++)
    {
        ar[i]=' ';
    }
    for (int i = 0; i < q.size(); i++)
    {
        ar[i]= q[i];
        // cout<<a[i];
    }
    system(ar);
}

}
////////////////////////////////////
}

```

