Search Efficiency in Sorted Arrays in Java

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Introduction

The time efficiency of different search operations will be measured in a sorted array with varying sizes. Two variants of the search operation will be tested and compared to the search time on an unsorted array.

The general behaviour of these operations are to be described as well as how they were created and implemented.

Method

We are already familiar with the search algorithm from a previous assignment. This report will expand on the search operation but include the same test methods that was used in the previous assignment.

The values that the operations will search for (keys) will be randomly generated and will not be sorted in any tests. The search methods will be looped where the time will be taken in intervals right before and after the loop. The difference of the time intervals will be the time to execute the search operation a loop amount of times. The time difference divided by loop will give the median execution time for one search operation. Only the minimal time values will be used for comparisons between operations due to consistency.

The search methods will be run for a sufficient time before the actual benchmark to enable the just-in-time compiler for time optimizations.

Unsorted search

The unsorted search time will be the time that I will compare the sorted search operations to.

The unsorted search method creates two arrays (array and keys) with randomly generated elements in a random order. The pool of values that the random number generator (RNG) takes from is double the size of the array, i.e. if the array size is 1000 then the pool size is 2000. The difference

between the two arrays is that the array array has the varying size n while the keys array will have the size loop.

The created arrays are then used in the for loop between the time intervals. The element that is to be searched for (key) is taken from the keys array for each loop iteration. The unsorted search operation is then used with the array and the key as arguments.

```
long t0 = System.nanoTime();
for(int i = 0; i < loop; i++){
   int key = keys[i];
   unsorted_srch(array, key);
}
long t1 = System.nanoTime();
return (t1 - t0);</pre>
```

The unsorted search operation is a simple for loop that compares an element at a certain array index to the key. The for loop stops when the same value is found, but will search through the whole array if no same value was found.

```
public static boolean unsorted_srch(int[] array, int key){
  for(int index = 0; index < array.length; index++){
    if(array[index] == key) return true;
  }
  return false;
}</pre>
```

The loop variable is set to 1,000 and the array sizes start from 1,000 and increases by doubling the size to 1,024,000 (n = {1000, 2000, ..., 512000, 1024000}). Running the code with these values yields the following graph:

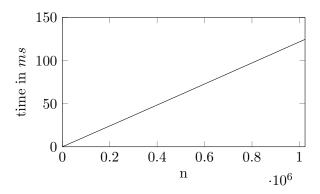


Figure 1: Unsorted search time

The search time for an unsorted array with a million elements takes about $125\mu s$.

Sorted search

The sorted search method is almost identical to the unsorted search method with the differences being:

- an added method to create a sorted array
- a change in the condition of the search operation
- an adjustment to the RNG pool

The elements of array were randomly generated in a random order in the unsorted search method. This time a method is created that still randomly generates the elements but every next element has a greater value than the previous.

The sort array method has a for loop that generates a random value from 0 to 10 and stores it in the nxt variable in each iteration. The nxt variable increases with the sum of the random value plus the value of the nxt variable from the previous iteration. This makes it so that the nxt variable has a greater value in every next iteration while maintaining the RNG. However, duplicates may still occur if the RNG generates the number 0. To solve this we add 1 to the sum which makes the nxt variable atleast 1 value greater in every next iteration.

```
public static int[] sort_array(int n, Random rnd){
  int[] array = new int[n];
  int nxt = 0;
  for(int i = 0; i < n; i++){
    nxt += rnd.nextInt(10) + 1;
    array[i] = nxt;
  }
  return array;
}</pre>
```

The sorted search operation is almost the same as the unsorted_srch operation from earlier. The sorted search operation is however optimized by one change in the condition of the if statement. The if statement will stop the search loop if the value of an element is the same or greater than the key. This is because the key wont be found when every next element is greater than the key now that the array is sorted.

The RNG pool is the same for both arrays in the unsorted search method which is double the size of \mathbf{n} . The sort array method complicates this in the sorted search method because it has an RNG pool of 10 times the size of \mathbf{n} -i.e. the maximum value is $10 \times n$ if the RNG always generates the greatest value which is highly unlikely. For consistency I chose the RNG pool for the keys to be 10 times the size of \mathbf{n} .

Running the code for the sorted search method with the same values as the unsorted search benchmark (loop = 1000 and n = $\{1000, 2000, ..., 512000, 1024000\}$) yields the following graph:

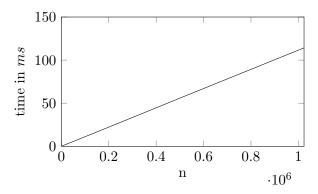


Figure 2: Sorted search time

The search time for a sorted array with a million elements takes about $114\mu s$.

Binary search

The binary search method is very similar to the sorted search method with the only difference being the usage of a whole different search algorithm.

The search algorithm in question is the binary search algorithm which checks the middle element and systematically divides the array in halves until the key is found. This is done by having a two variables (first and last) respectively pointing at the first and last index of the array. A while(true) loop is then made with four if statements and a middle variable that points to the element in the middle between the first and last index pointers.

The search loop stops if the value of the middle element is the same as the key. If the middle element is less than both the key and last pointer - i.e. if the key may be further to the last pointer - then the first pointer will point to where middle is pointing and middle will point to a new middle between first and last. Similarly, if middle is greater than key and first - i.e. if the key may be further to the first pointer - then last will point to the middle element. When the middle element is not the key, the first and last pointers will actually point to one index above and under middle respectively to not include that middle element that didn't have the key. The search loop is stopped if no key is found under the conditions of the if statements.

```
public static boolean binary_srch(int[] array, int key){
   int first = 0;
   int last = array.length - 1;
```

```
while(true){
    int middle = (first + last)/2;
    if(array[middle] == key) return true;
    if(array[middle] < key && middle < last){
        first = middle + 1;
        continue;
    }
    else if(array[middle] > key && middle > first){
        last = middle - 1;
        continue;
    }
    else return false;
}
```

Running the code for the binary search method with the same values from the two previous benchmarks yields the following graph:

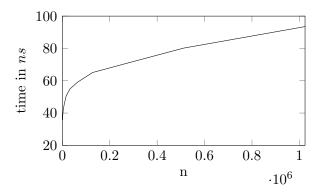


Figure 3: Binary search time

The binary search time for a sorted array with a million elements takes about 93ns. The binary search algorithm divides the array in half every time it checks for the key. This means that n is divided by 2^k where k is the number of checks until no more subarrays can be created. A function that roughly describes the execution time on an array of size n:

Looking at the graph, I estimated the time to search through an array with 64 million elements to take no more than 300ns. My optimistic guess was undeniably crushed by the output time I got from the test which was more than double my guessed time at roughly 650ns.

Conclusion

The time of the sorted search method compared to that of the unsorted search method shows a slight increase in performance. Decreasing the RNG pool for the keys array to the median max value of the last element in the array array improves the performance even more. However, those results may be skewed in a way that is inaccurate which is why they were not included to be compared.

The slight increase in performance of the sorted search method may likely prove useful in cases where an array is already sorted. The same can not be said if the array is unsorted for which the increased performance does not outweigh the cost of sorting the array.

The binary search method shows a significant increase in performance compared to both the sorted and unsorted search methods. The performance of the binary search method increases exponentially as the array size grows larger compared to the other two methods that has a linear performance. This makes the binary searh method a highly viable option for searching through arrays with huge sizes. The significantly increased performance overall likely outweighs the cost of sorting an unsorted array.

There is an overall increase in searching through data that is already sorted.