

(Math GATE)

• Matrices :- $(M \times n)$

*** TYPES OF MATRIX :-**

- ① Column Matrix:-
→ only one column.
- ② Row matrix:-
→ only one row.
- ③ Rectangular matrix:-
→ $M \neq n$
• $|A| \neq \text{not possible}$
• $|A - A'| = 0$ not possible.
- ④ Square Matrix:-
→ $M = n$.
- ⑤ Diagonal matrix:-
→ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ where $a_{ij}=0$.
↳ primary diagonal (or) principle dia. (may or) may not be zero).
- $\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \times \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$
- $\begin{bmatrix} 4 & 0 \\ 0 & 2 \end{bmatrix}^{-1} = \begin{bmatrix} \frac{1}{4} & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$
- * Concept of minm no. of zero:-
→ $2 \times 2 = 2$
 $3 \times 3 = 6$
 $4 \times 4 = 12$
 \vdots
 $n \times n = n(n-1)$.
- ⑥ Unit Matrix:-
→ $I = [1]$, $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
- $I^{-1} = I$ $I \cdot A = A$.
 $|I| = 1$
 $A \cdot I = A$
- ⑦ Upper Triangular Matrix:-
→ $A = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 2 & 6 \\ 0 & 0 & 7 \end{bmatrix}$
- Eigen values = $\lambda_1, \lambda_2, \lambda_3$
 $= 1, 2, 7$.
- $|A| = \text{Product of dia. elements}$
- ⑧ Lower Triangular Matrix:-
→ $A = \begin{bmatrix} 1 & 0 & 0 \\ 4 & 2 & 0 \\ 5 & 6 & 3 \end{bmatrix}$
- other same as UTM.

⑨ Scalar Matrix:-
→ $\begin{bmatrix} k & 0 \\ 0 & k \end{bmatrix} = kI$
↳ same

⑩ Symmetric Matrix:-
→ $A = A^T$
 $a_{ij} = a_{ji}$

⑪ Skew-Sym Matrix:-
→ $A = -A^T$
 $a_{ij} = -a_{ji}$
→ Diagonal elements are zero.

⑫ Hermitian Matrix:-
→ $a_{ij} = \bar{a}_{ji}$

⑬ Skew-Her. Matrix:-
→ $a_{ij} = -\bar{a}_{ji}$
→ $\bar{a}_{ii} = 0$ (or) it is purely imaginary.

⑭ Orthogonal Matrix:-
→ $A \cdot A^T = A^T \cdot A = I$
→ $A^{-1} = A^T$

⑮ Singular Matrix:-
→ $|A| = 0$ (Non-Invertible)
→ $|A| \neq 0$ (Invertible).
↳ Non-Singular.

⑯ Unitary Matrix:-
→ $A \cdot A^H = A^H \cdot A = I$
↳ Transpose of conjugate.

⑰ Special Matrix:-
• Involutory Matrix
 $A^2 = I$
• Idempotent Matrix
 $A^2 = A$
• Nilpotent Matrix.
 $A^K = 0$

*** Matrix Multiplication :-**
→ Associative $(AB)C = A(BC)$
Not commutative.
→ $A_{2 \times 2} \times B_{2 \times 3} = C_{2 \times 3}$
↳ equal
→ $A_{3 \times 3} \times B_{3 \times 4} \neq \text{not possible}$
→ $AB = BC \rightarrow B = C$
when 'A' is non-singular.

* If we have give $|A|$ and we perform operation R_i : $R_i \pm kR_j$ (or) $C_i \cdot C_i + kC_j$ then obtained $|B|$ remains unchanged.

* Trick:-

$A = \begin{vmatrix} 1+a & 1 & 1 & 1 \\ 1 & 1+b & 1 & 1 \\ 1 & 1 & 1+c & 1 \\ 1 & 1 & 1 & 1+d \end{vmatrix}$

$|A| = (abcd)(1 + \frac{1}{a} + \frac{1}{b} + \frac{1}{c} + \frac{1}{d})$

* $|A \text{ adj } A| = |A|^{n-1}$

* $|\text{adj}_i(\text{adj}(A))| = |A|^{(n-1)^2}$

* Inverse of Matrix:-
→ $A^{-1} = \frac{\text{adj}_i A}{|A|}$
→ $\text{adj}_i A = [\text{co-factor}]^T$

$A = \frac{1}{2} (A + A') + \frac{1}{2} (A - A')$
↳ Symmetric Skew-Sym

* If A is symmetric matrix (or) Real square matrix then $A \cdot A^T$ is Always summ matrix.

* $(P+Q)^2 = (P+Q)(P-Q)$
 $= P \cdot P + Q \cdot Q + PQ + Q \cdot P$

* 3x3 Matrix:-
Ex:- $A = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

* DETERMINANTS *

$\Delta = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$. $A^{-1} = ?$

* Minors and Co-factors:-
 $\rightarrow \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$

* Minor of $a_{21} = M_{21} = a_{12}a_{33} - a_{13}a_{32}$

* Co-factor = $A_{ij} = (-1)^{i+j} \cdot M_{ij}$

* The det of UTM, LTM & diagonal matrix is its multiplication of diagonal elements.

* Properties:-

- ① $|A^{-1}| = \frac{1}{|A|}$
- ② $|A^T| = |A|$

* RANK OF MATRIX *

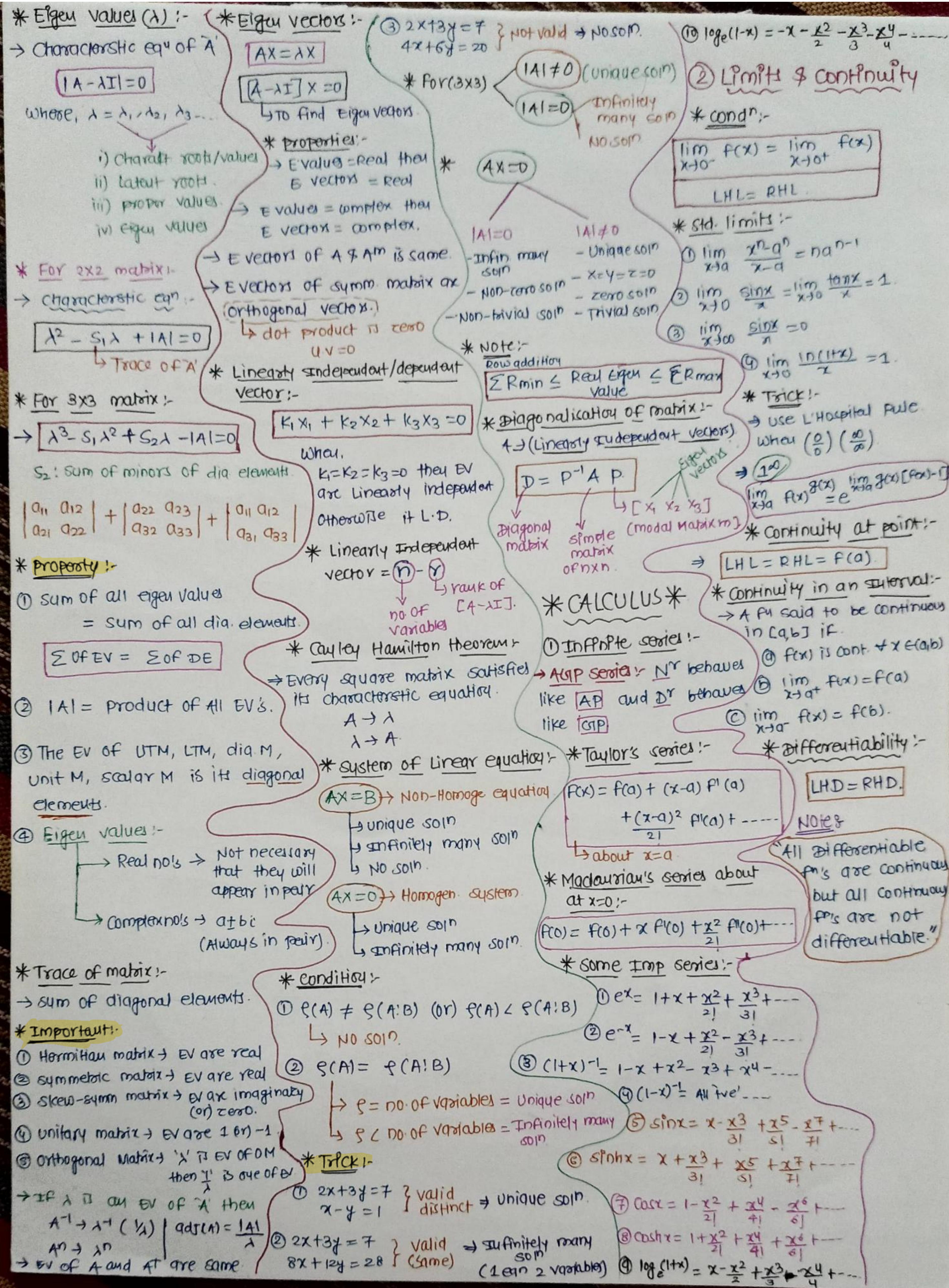
→ Rank of matrix = No. of non-zero rows + Echelon Matrix.

* Note:-

$A = \begin{bmatrix} 5 & 10 & 10 \\ 1 & 0 & 2 \\ 3 & 6 & 6 \end{bmatrix}$

Step-I] $|A|_{3 \times 3} = 0 \rightarrow r(A) \neq n$
 $\neq 0 \rightarrow r(A) = 0$

Step-II] $|A|_{2 \times 2} = 0 \rightarrow r(A) \neq (n-1)$
 $\neq 0 \rightarrow r(A) = (n-1)$



* Mean Value Theorems: $f_{xy} = \frac{\partial^2 F}{\partial x \cdot \partial y} \in S$.

- Rolle's Theorem :- $\rightarrow f(a) = f(b)$, $f'(c) = 0$
- Lagrange's MVT :- $\rightarrow f(a) \neq f(b)$, $f'(c) = \frac{f(b) - f(a)}{b - a}$
- Cauchy's MVT :- $\rightarrow \frac{f'(c)}{g'(c)} = \frac{f(b) - f(a)}{g(b) - g(a)}$

(1) Find P, Q, R, S, t (2) $\left(\frac{\partial F}{\partial x}\right) = 0, \left(\frac{\partial F}{\partial y}\right) = 0$ (3) at each stationary pt. find x, y, t . (4) $yt - s^2 > 0, s > 0$ \hookrightarrow minima at st. pt. (5) $yt - s^2 > 0, s < 0$ \hookrightarrow maxima at st. pt. (6) $yt - s^2 = 0$, saddle pt. (7) $yt - s^2 = 0$ undecided.

(18) $\int_a^b x \sin bx dx = \frac{e^{ax}}{a^2 + b^2} (a \sin bx - b \cos bx)$. $\int_a^b \frac{F(x)}{F(x) + F(a+b-x)} dx = \frac{b-a}{2}$

(19) $\int_a^b x \cos bx dx = \frac{e^{ax}}{a^2 + b^2} (a \cos bx + b \sin bx)$.

(20) $\int \frac{f'(x)}{f(x)} dx = \ln |f(x)| + C$

(21) $\int \frac{1}{(t^2 - x^2)^2} dx = \frac{1}{2a} \log \left(\frac{a+x}{a-x} \right) + C$

(22) $\int \frac{1}{x^2 - a^2} dx = \frac{1}{2a} \log \left(\frac{x-a}{x+a} \right) + C$

(23) $\int \frac{1}{\sqrt{x^2 + a^2}} dx = \sinh^{-1} \left(\frac{x}{a} \right) = \ln \left(x + \sqrt{x^2 + a^2} \right) + C$

(24) $\int \frac{1}{\sqrt{x^2 - a^2}} dx = \cosh^{-1} \left(\frac{x}{a} \right) = \ln \left(x + \sqrt{x^2 - a^2} \right) + C$

(25) $\int \sqrt{a^2 - x^2} dx = \frac{x}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \sin^{-1} \left(\frac{x}{a} \right) + C$

* Maxima and Minima :-

- When tangent makes acute angle with x -axis then graph is strictly increasing.
- Tangent make obtuse angle with x -axis then graph strictly decreasing.
- $f'(x) \geq 0 \Rightarrow$ Increasing graph.
- $f'(x) < 0 \Rightarrow$ Decreasing graph.

→ Steps to obtain maxima & minima :-

- $f'(x) = 0 \rightarrow x = a, b, c$.
- find $f''(x)$
- If $f''(a) < 0 \rightarrow$ maxima.
- If $f''(b) > 0 \rightarrow$ minima.
- If $f''(c) = 0 \rightarrow$ saddle pt.

* Partial differentiation :-

- Homogeneous function :- $f(\lambda x, \lambda y) = \lambda^n [f(x, y)]$.
- Euler's Homog. eqn :- $x \frac{\partial F}{\partial x} + y \frac{\partial F}{\partial y} = n \cdot F$
- Total derivative :- $\frac{du}{dt} = \frac{\partial u}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial u}{\partial y} \cdot \frac{dy}{dt}$

$x^2 \frac{\partial^2 F}{\partial x^2} + 2xy \frac{\partial^2 F}{\partial x \cdot \partial y} + y^2 \frac{\partial^2 F}{\partial y^2} = n(n-1)F$

* Integration by parts (ILATE) :-

$$I uv = u \int v - \int (u' \int v)$$

* Hindu's Method :-

$$\int x^n f(x) dx = x^n \int f(x) - \frac{d(x^n)}{dx} \int f(x) + \dots$$

→ Trigo/expo

* Definite Integral :-

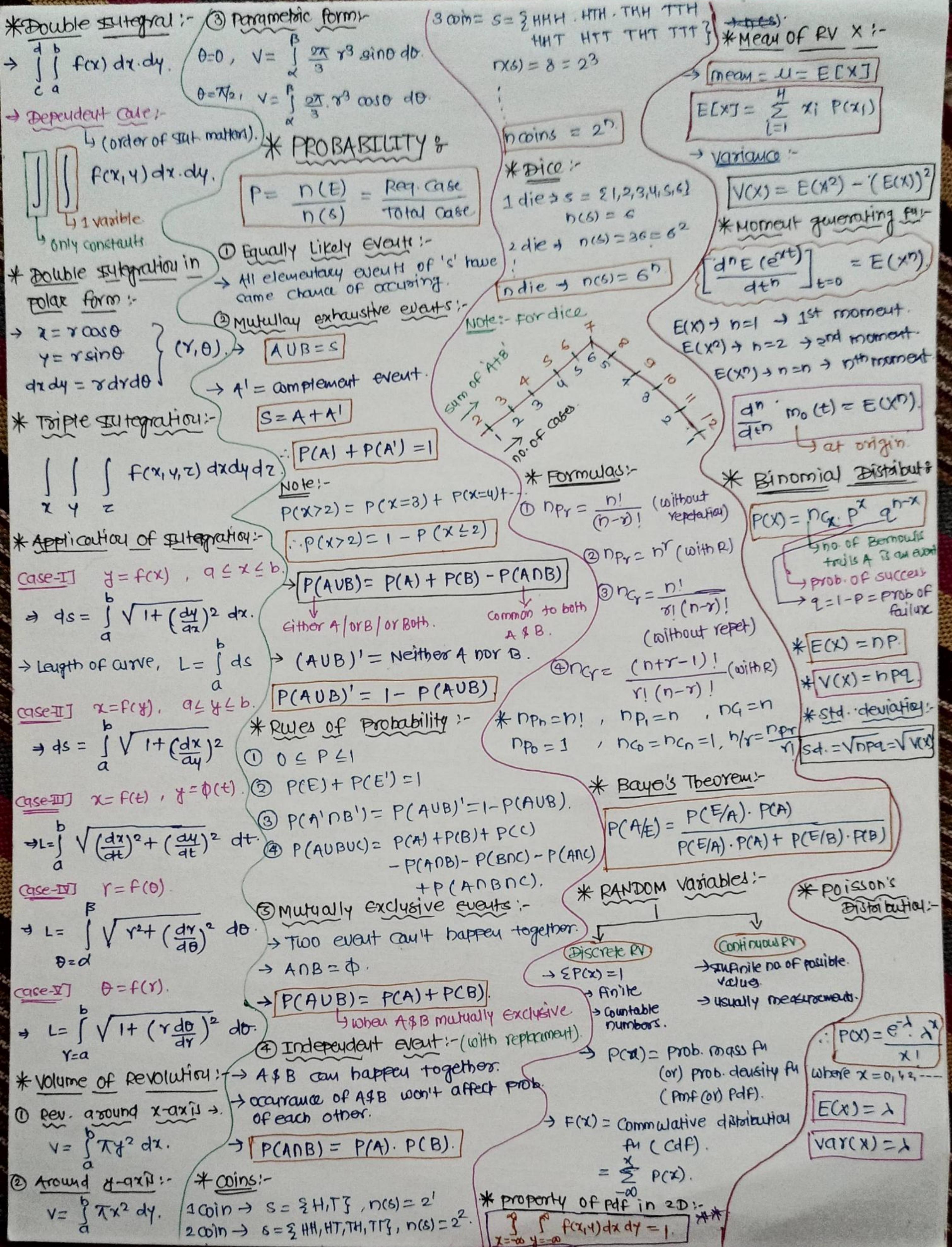
- $\int_a^b f(x) dx = [F(x)]_a^b = F(b) - F(a)$
- $\int_a^b f(x) dx = \int_a^b f(t) dt$
- $\int_a^b f(x) dx = - \int_b^a f(x) dx$.
- $\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$, where, $a < c < b$.
- $\int_a^b f(x) dx = \int_0^b f(a-x) dx$.
- $\int_a^b f(x) dx = \begin{cases} 2 \int_0^a f(x) dx, & \text{even fn. } [f(-x) = f(x)] \\ 0, & \text{odd fn. } [f(-x) = -f(x)] \end{cases}$
- $\int_0^{2a} f(x) dx = \begin{cases} 2 \int_0^a f(x) dx, & \text{even fn. } [f(2a-x) = f(x)] \\ 0, & \text{odd fn. } [f(2a-x) = -f(x)] \end{cases}$
- $\int_0^{na} f(x) dx = n \int_0^a f(x) dx$.
- $\int_a^b f(x) dx = \int_a^b f(a+b-x) dx$.
- $\int_0^{\pi/2} \sin^n x dx = \int_0^{\pi/2} \cos^n x dx = \left[\frac{(n-1)(n-3)\dots-2x_1}{n(n-2)(n-4)\dots-2x_1} \right] K$. Where, $K = \begin{cases} \pi/2, & n \text{ even} \\ 1, & n \text{ odd} \end{cases}$
- $\int_0^{\pi/2} \sin^m x \cos^n x dx = \left\{ \frac{[(m-1)(m-3)\dots-x_1][(n-1)(n-3)\dots-2x_1]}{[(m+n)(m+n-2)(m+n-4)\dots]} \right\} K$. Where, $K = \begin{cases} \pi/2, & m \& n \text{ even} \\ 1, & \text{otherwise} \end{cases}$

Ex :- $f(x) = 2x^2 - 9x - 1$, $[2, 5]$.
 $\rightarrow f(x) = 4x - 9 = 0$
 $x = 9/4$
 $\rightarrow f''(x) = 4 > 0$.
 $\rightarrow f(\frac{9}{4}) = -\frac{89}{8} \rightarrow$ min/m/least value.
 $\rightarrow f(2) = -11, f(5) = 4 \rightarrow$ greatest value.

→ Extremum value = optimum value
 \hookrightarrow either max/m/min.

* 2 variable max and minima :-

- $F_x = \frac{\partial F}{\partial x}$ (P), $F_{xx} = \frac{\partial^2 F}{\partial x^2}$ (R)
- $F_y = \frac{\partial F}{\partial y}$ (Q), $F_{yy} = \frac{\partial^2 F}{\partial y^2}$ (T)
- $\int \frac{dx}{a^2 + x^2} = \frac{1}{a} \tan^{-1} \left(\frac{x}{a} \right) + C$
- $\int \frac{dx}{\sqrt{a^2 - x^2}} = \sin^{-1} \left(\frac{x}{a} \right) + C$
- $\int \cos x \cdot \cot x \cdot dx = -\operatorname{cosec} x + C$
- $\int \frac{dx}{x^2 + a^2} = \frac{1}{a} \operatorname{tan}^{-1} \left(\frac{x}{a} \right) + C$
- $\int \sin^m x \cos^n x dx = \left\{ \frac{[(m-1)(m-3)\dots-x_1][(n-1)(n-3)\dots-2x_1]}{[(m+n)(m+n-2)(m+n-4)\dots]} \right\} K$. Where, $K = \begin{cases} \pi/2, & m \& n \text{ even} \\ 1, & \text{otherwise} \end{cases}$



⑤ * Uniform distribution:-
 → A cont. RV $X \rightarrow U(a, b)$
 $f(x) = \frac{1}{b-a}$, $a < x < b$.
 * Mean = $\frac{b+a}{2}$
 * Variance = $\frac{(b-a)^2}{12}$
 * Exponential distribution:-
 → A CRV $X - E(\lambda)$ is said to have exp. distribution.
 $f(x) = \lambda e^{-\lambda x}$, $x > 0$ & $\lambda > 0$.
 Mean = $\frac{1}{\lambda}$
 Var. = $\frac{1}{\lambda^2}$
 * Normal distribution:-
 $f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2}$
 → Mean = Median = Mode.
 * $P(z \leq 0) = P(z > 0) = \int_0^\infty f(z) dz = \int_{-\infty}^0 f(z) dz = \frac{1}{2}$
 * $\int_{-\infty}^\infty f(z) dz = 1$
 * $P(-1 < z < 1) = 0.6827$
 * $P(-2 < z < 2) = 0.9545$
 * $P(-3 < z < 3) = 0.9973$.

* Relationship :-
 $(\vec{a} \times \vec{b}) \times \vec{c} = (\vec{a} \cdot \vec{c}) \cdot \vec{b} - (\vec{b} \cdot \vec{c}) \cdot \vec{a}$
 $\text{div}(\vec{v}) = 0$
 ↳ solenoidal vector
 → It gives rate at which fluid flows out of unit volume.

* Std. deviation :-
 $\sigma = \sqrt{\frac{\sum (x - \bar{x})^2}{n}}$
 * Volume = $|\vec{a} \cdot (\vec{b} \times \vec{c})|$
 * Vector differential operator (∇) :-
 $\nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}$
 $\nabla^2 = \nabla \cdot \nabla = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$
 $\nabla^2 \phi = 0 \rightarrow \text{Laplace eqn.}$
 * curl of vector :-
 $\text{curl}(\vec{v}) = \nabla \times \vec{v}$
 $= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix}$
 $\rightarrow \text{curl}(\vec{v}) = \vec{0}$
 then $\vec{v} \rightarrow$ irrotational vector.
 → If \vec{v} is linear velocity then angular velocity
 $\vec{\omega} = \frac{1}{2} [\text{curl}(\vec{v})]$

* Vector Calculus:-
 * Scalar (or) DOT product:-
 $\vec{a} \cdot \vec{b} = |\vec{a}| \cdot |\vec{b}| \cos \theta$
 $\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$
 $\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0$
 * Cauchy's Schwartz inequality:-
 $|\vec{a} \cdot \vec{b}| \leq |\vec{a}| \cdot |\vec{b}|$
 * Cross product:-
 $|\vec{a} \times \vec{b}| = |\vec{a}| \cdot |\vec{b}| \sin \theta$
 $|\vec{a} \times \vec{b}| = |\vec{a}| \cdot |\vec{b}| \sin \theta$
 $\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$
 $\hat{i} \times \hat{j} = \hat{k}, \hat{j} \times \hat{k} = \hat{i}, \hat{k} \times \hat{i} = \hat{j}$
 $\hat{j} \times \hat{i} = -\hat{k}, \hat{k} \times \hat{j} = -\hat{i}, \hat{i} \times \hat{k} = -\hat{j}$
 $\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = 0$
 * Properties of Gradient:-
 ① $\nabla(f+g) = \nabla f + \nabla g$
 ② $\nabla(c_1 f + c_2 g) = c_1 \nabla f + c_2 \nabla g$
 ③ $\nabla(fg) = f \cdot \nabla g + g \cdot \nabla f$
 ④ $\nabla\left(\frac{f}{g}\right) = \frac{g \nabla f - f \nabla g}{g^2}, g \neq 0$.
 * Note:-
 ① $\text{Grad } r = \nabla r = \frac{\vec{r}}{r}$
 ② $\nabla(r^2) = 2\vec{r}$
 ③ $\nabla\left(\frac{1}{r}\right) = -\frac{\vec{r}}{r^3}$
 ④ $\nabla(\log r) = \frac{\vec{r}}{r^2}$
 ⑤ $\nabla(r^n) = n r^{n-2} \vec{r}$.
 ⑥ $\nabla(e^{r^2}) = 2e^{r^2} \vec{r}$.
 * Directional derivative (DD) :-
 $\rightarrow DD = \nabla \phi \cdot \hat{n}$
 where $\hat{n} = \frac{\vec{r}}{|r|}$
 $\rightarrow \text{Max}^m \text{ value of DD.} = |\nabla \phi|$.
 * Line integral :-
 $\int_C \vec{F} \cdot d\vec{r}$
 (Integration along curve)
 * Stokes theorem:-
 $\oint_C \vec{F} \cdot d\vec{r}$
 $= \iint_S \text{curl } \vec{F} \cdot \hat{n} ds$
 Relation between line & surface integration.

* Mean:-
 $\bar{x} = \frac{\sum x_i}{n} = \frac{\sum x_i f_i}{\sum f_i}$
 * Median:-
 ↳ middle no. → arrange nos' lowest to highest.
 ↳ No middle value → take '2' middle nos' and take Avg. of two.
 * Mode:-
 ↳ occurs most often.
 * When 'N' is even.
 $(\frac{N}{2})^{\text{th}}$ and $(\frac{N}{2}+1)^{\text{th}}$.
 → $\vec{a} \cdot (\vec{b} \times \vec{c}) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$
 $\rightarrow [\vec{a} \vec{b} \vec{c}] = [\vec{b} \vec{c} \vec{a}] = [\vec{c} \vec{a} \vec{b}]$
 $\rightarrow [\vec{a} \vec{b} \vec{c}] = -[\vec{b} \vec{c} \vec{a}]$.
 $\rightarrow [\vec{a} \vec{b} \vec{c}] = 0 \rightarrow$ coplanar vector.
 * Vector Triple Product:-
 $\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \vec{b} - (\vec{a} \cdot \vec{b}) \vec{c}$

* Green's Theorem :-

$$\oint_C M dx + N dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy.$$

↳ Relation b/w Line & double integration

$$(2) |z| = \sqrt{a^2 + b^2}$$

$$(3) |z| \cdot |\bar{z}| = |z|^2$$

$$(4) z^{-1} = \frac{\bar{z}}{|z|^2}$$

$$(5) |z_1 \cdot z_2| = |z_1| \cdot |z_2|$$

$$(6) \left| \frac{z_1}{z_2} \right| = \frac{|z_1|}{|z_2|}$$

$$(7) \left(\frac{\bar{z}_1}{\bar{z}_2} \right) = \frac{\bar{z}_1}{\bar{z}_2}$$

$$(8) z \bar{z} = \{ \operatorname{Re}(z) \}^2 + \{ \operatorname{Im}(z) \}^2$$

* Argument / Amplitude in the quadrant:-

① When $z = x+iy$, if $x>0, y>0$.

$$\operatorname{Arg} = \tan^{-1} \left| \frac{y}{x} \right|$$

(I)

$$\theta = \tan^{-1} \left| \frac{y}{x} \right|$$

② In 2nd quadrant if $x<0, y>0$.

$$\theta = \pi - \tan^{-1} \left| \frac{y}{x} \right|$$

(II)

③ When $z = x+iy$, if $x<0, y<0$

$$\theta = \pi + \tan^{-1} \left| \frac{y}{x} \right|$$

(or)

$$\theta = \tan^{-1} \left| \frac{y}{x} \right| - \pi$$

④ When $z = x+iy$, $x>0, y<0$.

$$\theta = 2\pi - \tan^{-1} \left| \frac{y}{x} \right|$$

(or)

$$\theta = -\tan^{-1} \left| \frac{y}{x} \right|$$

(IV)

* Polar form of complex no.:-

$$z = r (\cos \theta + i \sin \theta)$$

* Euler's Form of complex no.:-

$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$$

$$\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2}$$

$$z = r (\cos \theta + i \sin \theta)$$

$$z = r e^{i\theta}$$

* De-Movier's Theorem:-

$$(\cos \theta + i \sin \theta)^n = \cos n\theta + i \sin n\theta$$

$$= e^{in\theta}$$

$$(\cos \theta - i \sin \theta)^n = \cos n\theta - i \sin n\theta$$

$$= e^{-in\theta}$$

* Cube root of unity :-

$$z^3 = 1$$

roots $\rightarrow 1, \omega, \omega^2$

$$\omega = -\frac{1}{2} + i\frac{\sqrt{3}}{2}$$

$$\omega^2 = -\frac{1}{2} - i\frac{\sqrt{3}}{2}$$

$$1 + \omega^n + \omega^{3n} = \begin{cases} 0, & n \text{ is not multiple of } 3 \\ 3, & \text{multiple of } 3 \end{cases}$$

* Singularity:-

① Isolated singularity (not in that circle)

$$D \neq 0$$

② Non-isolated singularity (in given circle)

$$D = 0$$

③ Removable singularity:-

$$f(z) = \frac{z^2 - 3z + 2}{(z-1)(z+2)}$$

$z=1$ is removable sing

and $z=-2$ is simple pole

$$f(z) = \frac{(z-2)}{(z+2)}$$

④ Simple Pole:-

$$D \neq 0$$

$$f(z) = \frac{1}{(z-3)(z-7)}$$

Poles = 3, 7

⑤ Poles of order 'n'

$$f(z) = \frac{1}{(z+2)^2 (z-5)}$$

$z=-2$ is pole of order 2

$z=5$ is pole of order 1

⑥ Essential singularity:-

$$f(z) = \sin \left(\frac{1}{z-1} \right)$$

$$= \frac{1}{z-1} - \frac{1}{(z-1)^3} + \dots$$

$z=1$ is essential singularity.

* Residues:-

$$\int_C f(z) dz = 2\pi i \times$$

(sum of residues at the singular points within 'C').

* Calculation of Residue:-

① If $z=a$ is simple pole of $f(z)$ then,

$$[\operatorname{Res} f(z)]_{z=a} = \lim_{z \rightarrow a} (z-a) f(z)$$

② If $z=a$ is pole of order 'n' of $f(z)$ then

$$[\operatorname{Res} f(z)]_{z=a} = \lim_{z \rightarrow a} \frac{1}{(n-1)!} \frac{d^{n-1}}{dz^{n-1}}$$

$$\cdot (z-a)^n \cdot f(z)$$

* Modulus of z :-

$$z = |z| = \sqrt{a^2 + b^2}$$

$$z = |z| \cdot \bar{z}$$

$$z = |z| \cdot 1$$

$$z = |z| \cdot e^{i\theta}$$

$$z = |z| \cdot (\cos \theta + i \sin \theta)$$

$$z = |z| \cdot r e^{i\theta}$$

$$z = |z| \cdot r (\cos \theta + i \sin \theta)$$

$$z = |z| \cdot r e^{i\theta}$$

$$z = |z| \cdot r (\cos \theta + i \sin \theta)$$

$$z = |z| \cdot r e^{i\theta}$$

$$z = |z| \cdot r (\cos \theta + i \sin \theta)$$

$$z = |z| \cdot r e^{i\theta}$$

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$$z = |z| \cdot r e^{i\theta}$$

7 * Differential Eqn:-

* Order and Degree :-

$$\left(\frac{d^ny}{dx^n} \right) \quad \left(\frac{d^ny}{dx^n} \right)^P$$

↓
↑
 n is highest
power of highest order.

Note: FOR Transcendal eqn's degree is not defined.
(Trigo, expo., logr etc.)

* Linear & Non-Linear D.E. :-

$$P_0 \frac{d^ny}{dx^n} + P_1 \frac{d^{n-1}y}{dx^{n-1}} + P_2 \frac{d^{n-2}y}{dx^{n-2}} + \dots + P_n y = Q$$

where, $P_0, P_1, P_2, \dots, P_n$ & Q = constant/func.

$$= \frac{d^4y}{dx^4} + P \frac{d^2y}{dx^2} + Ky = 0 \quad (\text{LDE})$$

$$\frac{d^2y}{dx^2} + \frac{dy}{dx} + Siny = 0 \quad (\text{NLDE}).$$

* Formation & Soln of DE :-

$$y = f(x) \xrightarrow{\text{Formation}} y'' + Py = Q \quad \xrightarrow{\text{Soln of DE}}$$

* Leibnitz's Linear equation:-

$$\rightarrow \frac{dy}{dx} + Py = Q$$

where, $P \neq Q$ = constants/func.

$$\rightarrow \text{IF} = e^{\int P dx}$$

$$\rightarrow y(\text{IF}) = \int Q(\text{IF}) dx + C$$

* Bernoulli's equation:-

$$\rightarrow \frac{dy}{dx} + P.y = Q.y^n$$

→ Divide both side by y^n .

$$\rightarrow \text{Put } y^{1-n} = t$$

→ multiply both side by t^{n-1} .

$$\rightarrow \frac{dt}{dx} + P(n-1)t = Q(n-1)$$

$$\rightarrow \text{IF} = e^{\int (n-1)P dx}$$

$$\rightarrow y(\text{IF}) = \int (1-n)Q(\text{IF}) dx + C$$

* Exact D.E. :-

$$\text{Form:- } M dx + N dy = 0$$

$$\downarrow \quad \downarrow$$

$(x,y) \quad (x,y)$

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Solution:-

$$\int M dx + \int (\text{terms of } N \text{ not containing } x) dy = C$$

$y = \text{const}$

* Homogeneous D.E. :-

→ conversion of non exact D.E. to exact

$$\rightarrow \text{IF} = \frac{1}{MX + NY}$$

→ Then follow Exact D.E.

* Note:-

$$① x dy + y dx = d(xy)$$

$$② \frac{x dy - y dx}{x^2} = d\left(\frac{y}{x}\right)$$

$$③ \frac{x dy - y dx}{xy} = d\left(\ln\left(\frac{y}{x}\right)\right)$$

* Newton's Cooling law :-

$$\rightarrow \frac{d\theta}{dt} = -k(\theta - \theta_s)$$

$$\rightarrow \theta = \theta_s + C \cdot e^{-kt}$$

* Higher order linear D.E. :-

$$\rightarrow \frac{d^ny}{dx^n} + a_1 \frac{d^{n-1}y}{dx^{n-1}} + \dots + a_n y = Q$$

$$\rightarrow \text{put } \frac{d}{dx} = D$$

$$\rightarrow \text{when, } Q = f(x) = 0 \rightarrow \text{Homogeneous eqn.}$$

$$Q = f(x) \neq 0 \rightarrow \text{Non-Homo. eqn.}$$

→ Soln:-

$$y = C.F + P.F$$

→ Homogeneous eqn,

$$y = C.F$$

Roots of Auxiliary eqn (AE)

① Real & different roots.

$$m_1, m_2, m_3, \dots$$

② Real & equal roots.

$$i) m_1, m_1, m_3, \dots$$

$$ii) m_1, m_1, m_1, m_4, \dots$$

③ Complex roots.

$$\alpha + i\beta, \alpha - i\beta, m_3, \dots$$

$$\alpha \pm i\beta, \alpha \pm i\beta, m_3, \dots$$

$$\alpha \pm i\beta, \alpha \pm i\beta, m_3, \dots$$

* Wronskian : W
(For check Linearity dependent or independent)

$$W = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix}$$

$|W| = 0 \rightarrow \text{Linearity dependent}$

$|W| \neq 0 \rightarrow \text{Linearity independent}$

* FOR NON-HOMOGENEOUS D.E. :-

$$y = C.F + P.F \quad P.F \neq 0$$

→ To find P.I. &

$$i) \text{ when } x = e^{ax}$$

$$P.I. = \frac{1}{F(D)} e^{ax}$$

$$= \frac{1}{F(a)} e^{ax}, F(a) \neq 0$$

$$\rightarrow \text{if } F(a) = 0, \text{ then } P.I. = 0$$

$$P.I. = x \cdot \frac{1}{F'(a)} e^{ax}$$

$$ii) \text{ when } x = \sin(ax+b) \text{ (or)}$$

$$\cos(ax+b)$$

$$P.I. = \frac{1}{F(D^2)} \sin(ax+b)$$

$$\text{Replace } D^2 \text{ by } -a^2$$

$$iii) \text{ when } x = e^{xn}$$

$$P.I. = \frac{1}{F(D)} \cdot x^n$$

$$= [F(D)]^{-1} x^n$$

$$\text{by expand.}$$

$$iv) \text{ when } x = e^{ax} v, \text{ where } v$$

$$\text{is fn of } x$$

$$P.I. = \frac{1}{F(D)} e^{ax} v = e^{ax} \cdot \frac{1}{F(D+a)} v$$

$$\text{and then evaluate}$$

$$\frac{1}{F(D+a)} v$$

$$\text{in (i)(ii)(iii).}$$

$$\frac{1}{D-a} x = e^{ax} \int x e^{-ax} dx$$

$$\frac{1}{D-a} x = e^{ax} \int e^{ax} x dx$$
</

ii) when $f(x,y) = x^m y^n$. * Simpson's $\frac{3}{8}$ th rule :-
 $P.E = \frac{1}{F(DD)} x^m y^n$
 $P.I = [F(DD')]^{-1} x^m y^n$
 expand in according powers of $\frac{D}{D}$ & operate on $x^m y^n$.

* Classification of PDE:-
 A PDE of the form
 $A \frac{\partial^2 z}{\partial x^2} + B \frac{\partial^2 z}{\partial x \cdot \partial y} + C \frac{\partial^2 z}{\partial y^2} + f(x, y, z, p, q) = 0$
 is said to be,

- i) elliptic if $B^2 - 4AC < 0$
- ii) parabola if $B^2 - 4AC = 0$
- iii) hyperbola if $B^2 - 4AC > 0$

* Numerical Method *

- ① Newton-Raphson method:-
 $x_{i+1} = x_i - \frac{f(x_i)}{F'(x_i)}$
- ② Bisection method:-
 $c_1 = \frac{a_0 + b_0}{2}$
- ③ False Position / Regula Falsi method:-
 $c = a - \frac{(b-a)}{F(b)-F(a)} \cdot f(a)$

↓ use same process for next root successive iteration
- ④ Secant Method:-
 $x_{n+1} = x_n - \frac{(x_n - x_{n-1})}{F(x_n) - F(x_{n-1})} \cdot f(x_n)$

* Trapezoidal Rule:-
 $\int_a^b f(x) dx = \frac{h}{2} [(y_0 + y_n) + 2(y_1 + y_2 + \dots + y_{n-1})]$
 where, $h = \frac{b-a}{n}$

* Simpson's method:-
 $\int_a^b f(x) dx = \frac{h}{3} [(y_0 + y_n) + 2(y_2 + y_4 + \dots + y_{n-2}) + 4(y_1 + y_3 + \dots + y_{n-1})]$

* Simpson's $\frac{3}{8}$ th rule :-
 $\int_a^b f(x) dx = \frac{3h}{8} [(y_0 + y_n) + 2(y_1 + y_3 + \dots + y_{n-3}) + 3(y_2 + y_4 + \dots + y_{n-2})]$
 * shifting property :-
 (first shifting)
 $L\{e^{at} f(t)\} = F(s-a)$
 $L\{e^{at} f(t)\} = F(s+a)$

* Euler's forward method:-
 $y_{n+1} = y_n + h f(x_n, y_n)$

* Euler's backward method:-
 $y_{n+1} = y_n + h f(x_{n+1}, y_{n+1})$

* Runge-Kutta method:-
 $\frac{dy}{dx} = f(x, y)$
 calculate successively,
 $k_1 = h f(x_0, y_0)$
 $k_2 = h f(x_0 + \frac{h}{2}, y_0 + \frac{k_1}{2})$
 $k_3 = h f(x_0 + h, y_0 + \frac{k_2}{2})$
 $k_4 = h f(x_0 + h, y_0 + k_3)$
 \rightarrow order '2'
 $K = \frac{k_1 + k_2}{2}$
 \rightarrow order '3'
 $K = \frac{1}{6} [k_1 + 4k_2 + k_3]$
 \rightarrow order '4'
 $K = \frac{1}{6} [k_1 + 2k_2 + 2k_3 + k_4]$

* Multiplication by t^n :-
 $L\{t^n f(t)\} = (-1)^n \frac{d^n}{ds^n} (F(s))$

* Division by t^r :-
 $L\{F(t)\} = F(s)$ then $L\left\{\frac{1}{t^r} f(t)\right\} = \int_s^\infty f(u) du$

* LT. of periodic function:-
 Let $f(t)$ is periodic fn with period 'T'
 $L\{f(t)\} = \frac{1}{T} \int_0^T e^{-st} f(t) dt$

* LT. of differential equations:-
 $L\{f'(t)\} = s^1 F(s) - s^0 f(0)$
 $L\{f''(t)\} = s^2 - s^1 f(0) - s^0 f'(0)$
 $L\{f'''(t)\} = s^3 F(s) - s^2 f(0) - s f'(0) - s^0 f''(0)$

* $L\left\{\int_0^t f(u) du\right\} = \frac{1}{s} F(s)$
 $L\left\{\int_0^t \int_0^u f(u) du\right\} = \frac{1}{s^2} F(s)$

* Unit Step function:-
 $u(t-a) = \begin{cases} 1, & t > a \\ 0, & t \leq a. \end{cases}$

$L\{u(t-a)\} = \frac{e^{-as}}{s}$

* Unit Impulse function:-
 $L\{s(t)\} = 1$
 $L\{s(t-a)\} = e^{-as}$, $L\{s(t+a)\} = e^{as}$.

* Division by s^r :-
 $L^{-1}\left[\frac{F(s)}{s^r}\right] = \int_0^t L^{-1}[F(s)] dt = \int_0^t f(t) dt.$

* Convolution Theorem:-
 If $L\{f(t)\} = F(s)$ and
 $L\{g(t)\} = G(s)$ then
 $L\{f(t) * g(t)\} = L\left\{\int_0^t f(u) \cdot g(t-u) du\right\} = F(s) \cdot G(s).$

* Inverse Laplace Transform :-

$$\textcircled{1} \quad L^{-1}\left\{\frac{1}{s}\right\} = 1$$

$$\textcircled{2} \quad L^{-1}\left\{\frac{1}{s-a}\right\} = e^{at}$$

$$\textcircled{3} \quad L^{-1}\left\{\frac{1}{s^2+a^2}\right\} = \frac{1}{a} \sin at$$

$$\textcircled{4} \quad L^{-1}\left\{\frac{s}{s^2+a^2}\right\} = \cos at$$

$$\textcircled{5} \quad L^{-1}\left\{\frac{1}{s^2-a^2}\right\} = \frac{1}{a} \sinh at$$

$$\textcircled{6} \quad L^{-1}\left\{\frac{s}{s^2-a^2}\right\} = \cosh at$$

$$\textcircled{7} \quad L^{-1}\left\{\frac{1}{s^n}\right\} = \frac{1}{\Gamma n} t^{(n-1)}$$

$$\textcircled{8} \quad L^{-1}\left\{\frac{1}{s^n}\right\} = \frac{1}{(n-1)!} t^{(n-1)} \\ \hookrightarrow \text{tve' integer.}$$

$$\textcircled{9} \quad L^{-1}\left\{\frac{e^{-as}}{s-a}\right\} = u(t-a)$$

$$\textcircled{10} \quad L^{-1}\{e^{-as}\} = \delta(t-a).$$

$$\textcircled{11} \quad L^{-1}\left\{\frac{1}{(s-a)^n}\right\} = \frac{e^{at} \cdot t^{n-1}}{(n-1)!}$$

$$\textcircled{12} \quad L^{-1}\left\{\frac{1}{(s-a)^2+b^2}\right\} = \frac{1}{b} e^{at} \sin bt.$$

$$\textcircled{13} \quad L^{-1}\left\{\frac{s-a}{(s-a)^2+b^2}\right\} = \frac{1}{b} e^{at} \cos bt.$$

$$\textcircled{14} \quad L^{-1}\left\{\frac{s}{(s^2+a^2)^2}\right\} = \frac{1}{2a} t \sin at.$$

$$\textcircled{15} \quad L^{-1}\left\{\frac{1}{(s^2+a^2)^2}\right\} = \frac{1}{2a^2} (\sin at, \cos at)$$

* Scaling Property :-

$$L\{f(t)\} = F(s)$$

$$L\{f(at)\} = \frac{1}{a} F\left(\frac{s}{a}\right).$$