Here's the Github Link of the Codes of Publisher and Subscriber:

1) **Talker File:**

   https://github.com/KraKEn-bit/ALTAIR_RECruiT/blob/main/Week-3/ROS_Tasks/src/my_robot_controller/my_robot_controller/talker.py
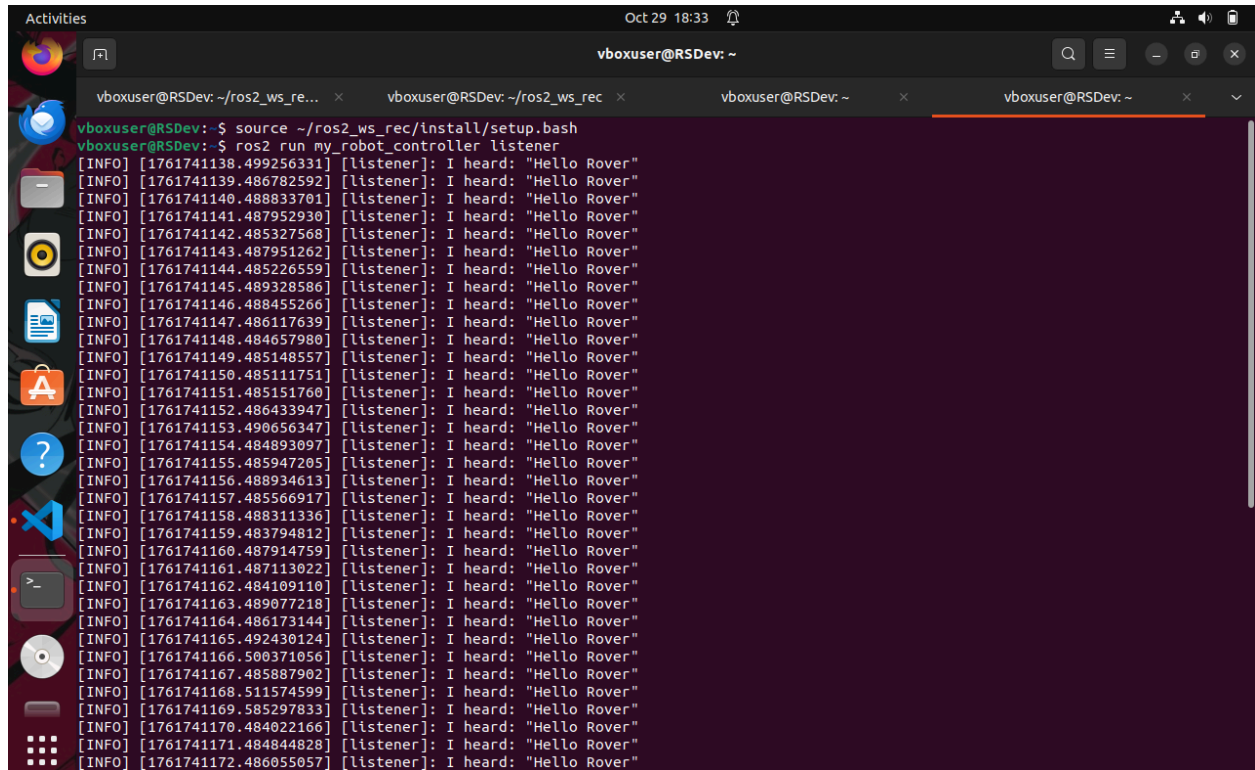
2) **Subscriber File:**

   https://github.com/KraKEn-bit/ALTAIR_RECruiT/blob/main/Week-3/ROS_Tasks/src/my_robot_controller/my_robot_controller/listener.py
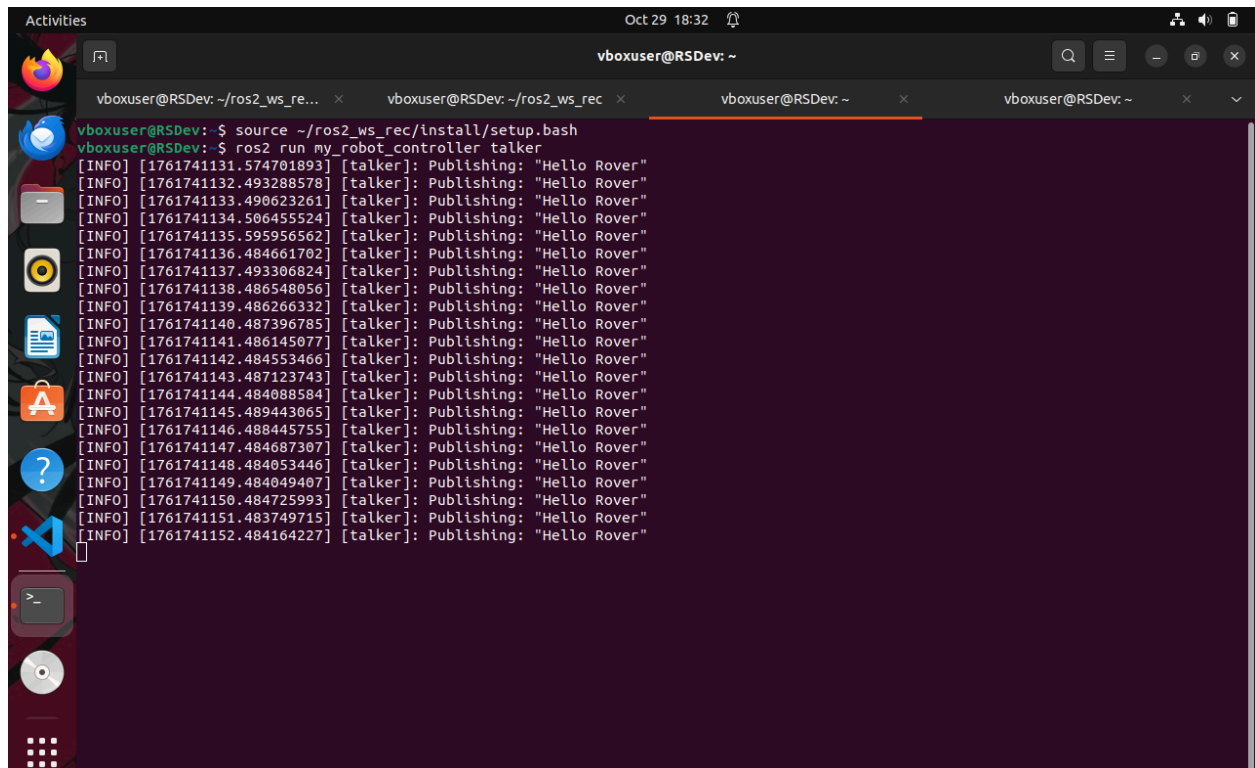
What's happening is that:

In Terminal-1 I ran the publisher and it sends **"Hello Rover"** every second on a ROS2 topic named `chatter`. In Terminal-2 I ran the subscriber and it listens to that topic and prints the message it receives.

Here's an Image of the Subscriber listening to the Publisher and prints the msg that it receives:

Here's an Image of the Talker sending "Hello Rover" Every second: