

main

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1 Randomness

1.1 Monte carlo

assume table with 50/50 red black

1.1.1 Gamblers fallacy

If the soccer team have won/lost 10 times in a row they have loose/win next match.

1.1.2 Regression to the mean - Francis Galton, 1885

If the parents are taller than the mean will the child be shorter than the mean. No biology, just analysing the data.

What it says: after an extreme event, you are likely to get a less extreme event. After spinning 10 reds. You are likely to get less than 10 reds on your next 10 spins, but the expected number is still 5.

Now if one is looking at the average of the 20 spins it will be closer to the mean, i.e. regression to the mean.

1.1.3 Summed up: why are these different?

1. The gambler fallacy says that we are expected to have

fewer than 5 reds on the 10 spins.

2. Regression to the mean says that we will probably have fewer than 10 reds on the next.

1. Below the mean.
2. closer to the mean.

1.2 Sample space

1.2.1 Girl boy paradox

My friend Nik has two kids, and he told you he has at least one a girl, hence what is the probability of the other kid is female?

First kid	Second Kid	$P()$
Boy	Boy	1/4
Boy	Girl	1/4
Girl	Girl	1/4
Girl	Boy	1/4

You saw my friend Nik was walking on the street with his daughter. And Nik told you he got another child at home, so, what is the probability of the other child was a female?

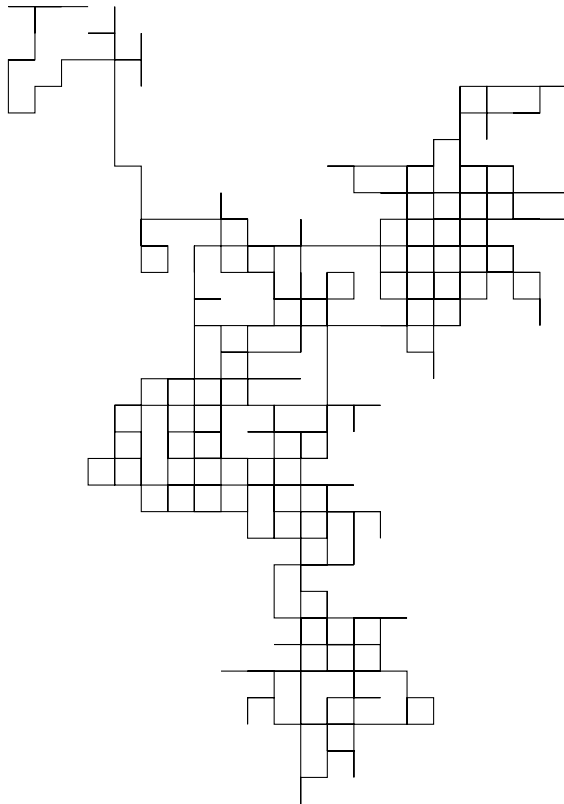
Behind door 1	Behind door 2	Behind door 3	P()
Goat	Goat	Car	1/3
Goat	Car	Goat	1/3
Car	Goat	Goat	1/3

1.2.2 Monty Hall problem

Still not convinced? Take a 100 doors, would you still switch?

1.3 Random processes

1.3.1 Random walk

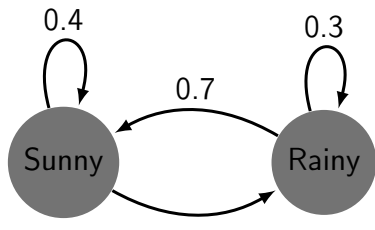


1.3.2 Markov chain

The Markov property/ assumption

$$\Pr(X_{n+1} = x \mid X_1 = x_1, X_2 = x_2, \dots, X_n = x_n) = \Pr(X_{n+1} = x \mid X_n = x_n)$$

$$\begin{aligned} p_{ij} &= \mathbf{P}(X_{n+1} = j \mid X_n = i) \\ &= \mathbf{P}(X_{n+1} = j \mid X_n = i, X_{n-1}, \dots, X_0) \end{aligned}$$

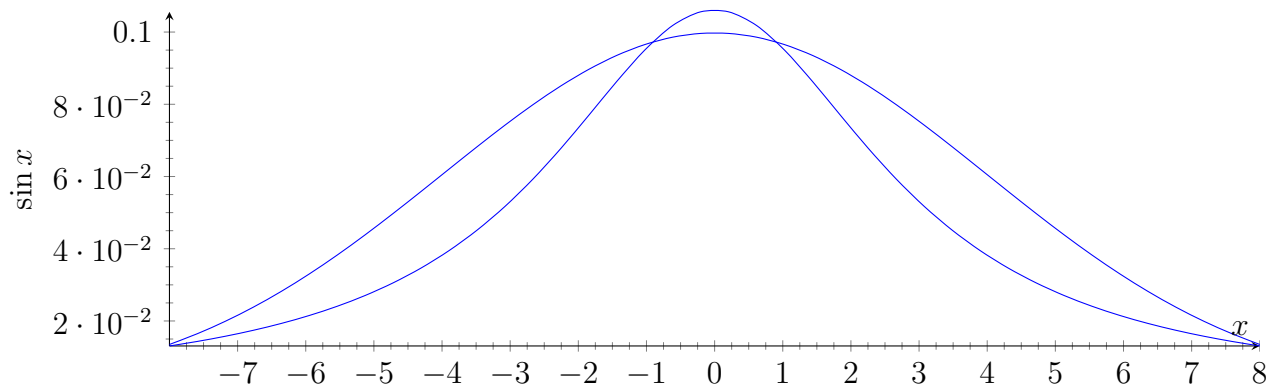


Random walk does not have a transition probability matrix since the state space are not finite. For Markov chain with finite state space matrices we just have a matrix describing all the probabilities.

2 PDF

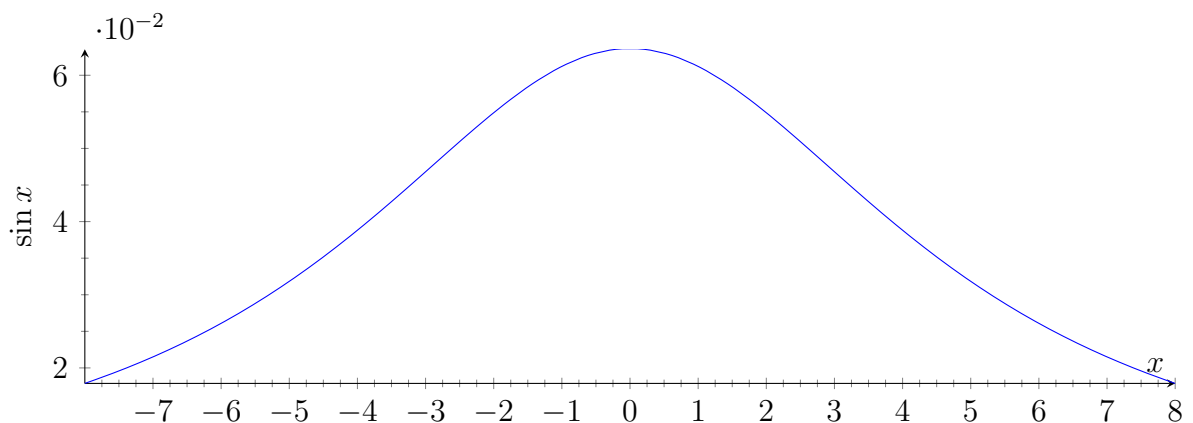
2.1 Normal distribution

$$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

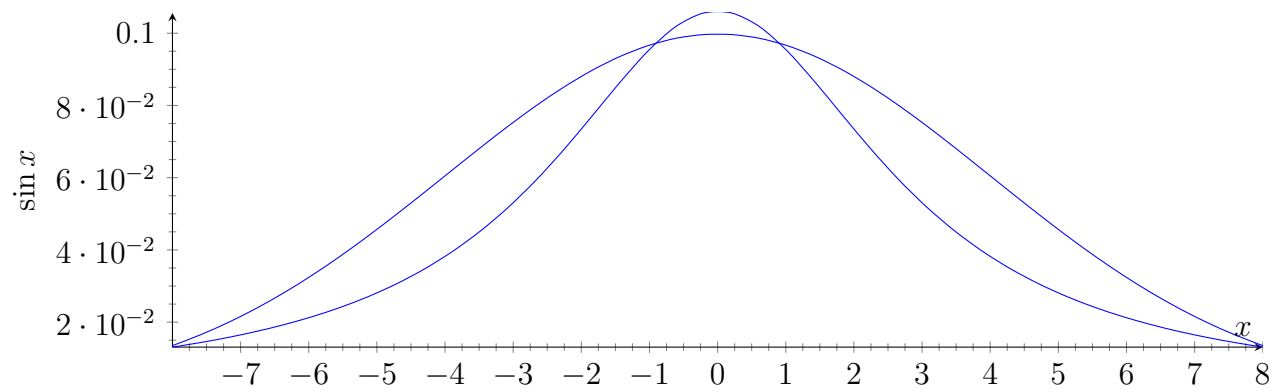


2.2 Cauchy distribution

$$\frac{1}{\pi\gamma \left[1 + \left(\frac{x-x_0}{\gamma} \right)^2 \right]}$$

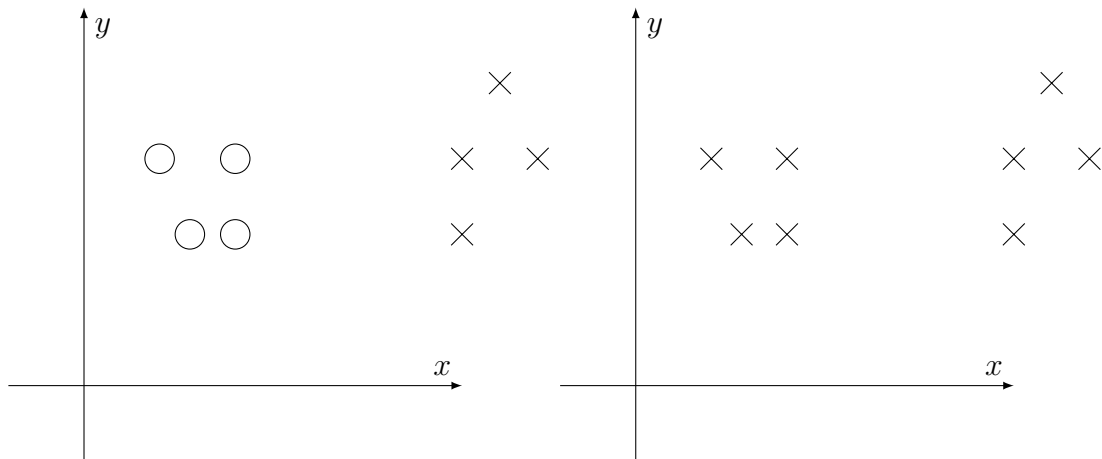


2.3 Together



3 Learning

3.1 supervised vs unsupervised learning



4 Ordbok

4.1 Vehicles

RPAS AUV ROV

5 Moving average / moving variance

Digital filter

$$\begin{aligned} y(k) &= \frac{1}{N+1} \sum_{n=0}^n b_N u(k-n) \\ y(k) &= b_0 u(k) + b_1 u(k-1) \dots b_N u(k-n) \end{aligned} \quad (1)$$

let n be the size of the filter, and y_k be the mesurments

$$\begin{aligned} y'_k &= y_k \frac{1}{n} + y_{k-1} \frac{1}{n} + y_{k-2} \frac{1}{n} + \dots + y_{k-n+1} \frac{1}{n} \\ &= \frac{1}{n} \sum_{i=0}^{n-1} y_{k-i} \end{aligned}$$

5.1 analyse of 6

$$\begin{aligned} y(k) &= \frac{1}{N+1} \sum_{n=0}^n u(k-n) \\ y(k) &= \frac{1}{6} \sum_{n=0}^n u(k-n) \end{aligned} \quad (2)$$

$$\begin{aligned} y(k) &= \frac{1}{6} [u(k-n) + u(k-1) + u(k-2) + u(k-3) + u(k-4) + u(k-5)] \\ \mathcal{Z}\{y(k)\} &= \frac{1}{6} [z + z^{-1} + z^{-2} + z^{-3} + z^{-4} + z^{-5}] \\ Y(z) &= \frac{1}{6} \cdot \frac{1 + z^1 + z^2 + z^3 + z^4 + z^5}{z^5} \end{aligned} \quad (3)$$

Frekvens respons (demping)

$$\begin{aligned} Y(jw) &= \frac{1}{6} (1 + e^{jwTs} \dots) \\ |Y(w)| &= \frac{1}{N} \left| \frac{\sin\left(\frac{wN}{2}\right)}{\sin\left(\frac{w}{2}\right)} \right| \end{aligned} \quad (4)$$

6 Chaos and Bifurcations

6.1 example

$$\begin{aligned}\ddot{x} + 0.1\dot{x} + x^5 &= 6 \sin t \\ x(0) &= 2, \quad \dot{x}(0) = 3 \\ x(0) &= 2.01, \quad \dot{x}(0) = 3.01\end{aligned}\tag{5}$$

from x 0 to 50

7 to be added

winer process markov process random walk