

Basics of Bayesian inferences and Bayesian deep learning

-Summary-

Review

- Difference between frequentist and Bayesian approaches for statistical inference:

Frequentist versus Bayesian Methods

- In frequentist inference, probabilities are interpreted as long run frequencies. The goal is to create procedures with long run frequency guarantees.
- In Bayesian inference, probabilities are interpreted as subjective degrees of belief. The goal is to state and analyze your beliefs.

- Bayesian inference procedure:

1. Choose prior distribution for $p(\theta)$: express our beliefs about a parameter θ before we see any data.
2. Choose statistical model $p(x|\theta)$: reflects our beliefs about x given θ .
3. After observing data $\mathcal{D}_n = \{X_1, \dots, X_n\}$, we update our beliefs and calculate the posterior distributions $p(\theta|\mathcal{D}_n)$.

Review

- Our goal is to find posterior distribution $p(\theta|\mathcal{D}_n)$ and estimate $E[g(\theta)|\mathcal{D}_n]$ by $\sum_{i=1}^n g(\theta^{(s)})$
 - **When $p(\theta|\mathcal{D}_n)$ can be computed explicitly** -> Use Monte Carlo (MC) method:

<MC algorithm> :

for $j = 1$ to s :

1. Sample $\theta^{(j)} \sim p(\theta|\mathcal{D}_n)$

This algorithm gives independent
Samples $\{\theta^{(1)}, \dots, \theta^{(s)}\}$

For example : $x_i|\mu, \tau \sim N(\mu, \frac{1}{\tau})$, $\mu|\tau, x \sim N(\mu_0, \frac{1}{\tau})$, $\tau \sim \text{Gamma}(\alpha, \beta)$:

$$p(\mu|x_1, \dots, x_n) \propto \left(2\beta + (\mu - \mu_0)^2 + \sum_{i=1}^n (x_i - \mu)^2 \right)^{-\alpha - \frac{(n+1)}{2}}$$

$$p(\tau|x_1, \dots, x_n) = d\text{Gamma} \left(\alpha + \frac{n}{2}, \beta + \frac{1}{2} \sum_{i=1}^n (x_i - \bar{x})^2 + \frac{n}{2(n+1)} (\bar{x} - \mu_0)^2 \right)$$

Review

- **When the posterior distribution $p(\theta|\mathcal{D}_n)$ is intractable** (or cannot given by implicit form):

(Let's denote $\theta = (\theta_1, \dots, \theta_k)$, $\theta_{-i} = (\theta_1, \dots, \theta_{i-1}, \theta_{i+1}, \dots, \theta_k)$)

If the full conditional distribution $p(\theta_i|\theta_{-i}, \mathcal{D}_n)$ is **known** -> Use Gibbs sampling:

<Gibbs sampling algorithm> :

Given the current state $\theta^{(s)} = (\theta_1^{(s)}, \dots, \theta_k^{(s)})$

(# $\theta^{(0)}$ can be chosen by appropriate estimator of θ)

1. Sample $\theta_1^{(s+1)} \sim p(\theta_1 | \theta_{-1}^{(s)}, x_1, \dots, x_n)$

...

K. Sample $\theta_k^{(s+1)} \sim p(\theta_k | \theta_{-k}^{(s)}, x_1, \dots, x_n)$

K+1. Set $\theta^{(s+1)} = (\theta_1^{(s+1)}, \dots, \theta_k^{(s+1)})$

This algorithm gives dependent
Samples $\{\theta^{(1)}, \dots, \theta^{(s)}\}$

Review

- **When the posterior distribution $p(\theta|\mathcal{D}_n)$ is intractable** (or cannot given by implicit form):
If the full conditional distribution $p(\theta_i|\theta_{-i}, \mathcal{D}_n)$ is **unknown**: -> Use Metropolis Algorithm

<Metropolis algorithm> :

Given the current state $\theta^{(s)} = (\theta_1^{(s)}, \dots, \theta_k^{(s)})$

This algorithm gives dependent
Samples $\{\theta^{(1)}, \dots, \theta^{(s)}\}$

1. Sample $\theta^* \sim J(\theta|\theta^{(s)})$
2. Compute the acceptance ratio:

$$r = \frac{p(\theta^*|x_1, \dots, x_n)}{p(\theta^{(s)}|x_1, \dots, x_n)} = \frac{p(x_1, \dots, x_n|\theta^*)p(\theta^*)}{p(x_1, \dots, x_n|\theta^{(s)})p(\theta^{(s)})}$$

3. Set $\theta^{(s+1)} = \begin{cases} \theta^* & \text{with probability } \min(r, 1) \\ \theta^{(s)} & \text{with probability } 1 - \min(r, 1) \end{cases}$

Note: $J(\theta|\theta^{(s)})$ is a symmetric proposal distribution

(ex: $J(\theta|\theta^{(s)}) = \text{uniform}(\theta^{(s)} - \delta, \theta^{(s)} + \delta)$ or $N(\theta^{(s)}, \delta^2)$, where δ is given)

Review

- Can we **generalize** the Gibbs sampling and Metropolis algorithm? -> Metropolis-Hasting

<Metropolis-Hasting algorithm> :

Given the current state $\theta^{(s)} = (\theta_1^{(s)}, \dots, \theta_k^{(s)})$:

for $i = 1$ to k :

1. Update θ_i :

a. Sample $\theta_i^* \sim J_i(\theta_i | \theta^{(s)})$

b. Compute the acceptance ratio :

$$r = \frac{p(\theta_i^*, \theta_{-i}^{(s)})}{p(\theta_i^{(s)}, \theta_{-i}^{(s)})} \times \frac{J_i(\theta_i^{(s)} | \theta_i^*, \theta_{-i}^{(s)})}{J_i(\theta_i^* | \theta_i^{(s)}, \theta_{-i}^{(s)})}$$

c. Set $\theta_i^{(s+1)} = \begin{cases} \theta_i^* & \text{with probability } \min(r, 1) \\ \theta_i^{(s)} & \text{with probability } 1 - \min(r, 1) \end{cases}$

Note:

1. This terms becomes 1 when J_i is symmetric.

(the algorithm regresses to Metropolis algorithm)

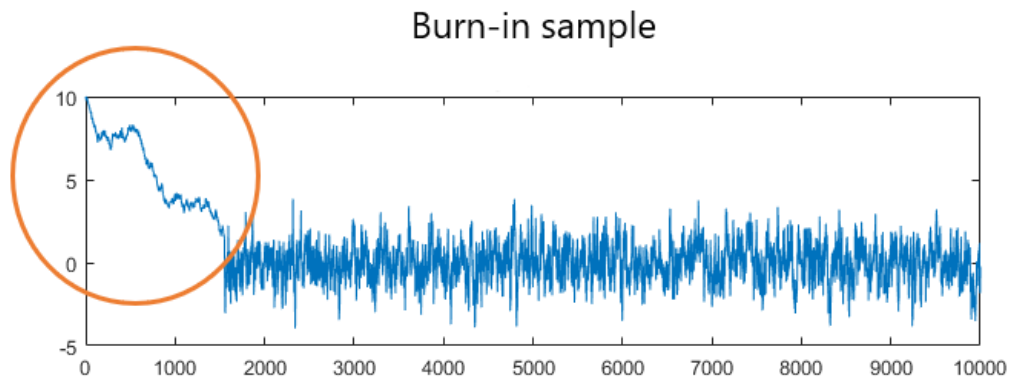
2. Acceptance ratio $r = 1$ when J_i is full conditional distribution of θ_i .

(the algorithm regresses to Gibbs Sampling)

- Here, $J_i(\theta_i | \theta^{(s)})$ does not need to be symmetric (i.e : $J_i(\theta_a | \theta_b) \neq J_i(\theta_b | \theta_a)$)

Review

- Recall that the Gibbs sampling / Metropolis (-Hasting) algorithms give '**dependent**' samples.
 - In other words, the samples will be autocorrelated within a Markov chain, and we want independent samples. (How to obtain nearly independent samples among them??)
- Q: Given s samples by MCMC, how many independent samples can be induced (or considered) from these samples? -> Check **Effective Sample Size (ESS)**
- Q: Under the MCMC process, Are all the samples important as samples? -> No (Use **burn-in**, for example: drop 1500 samples at the initial MCMC process)



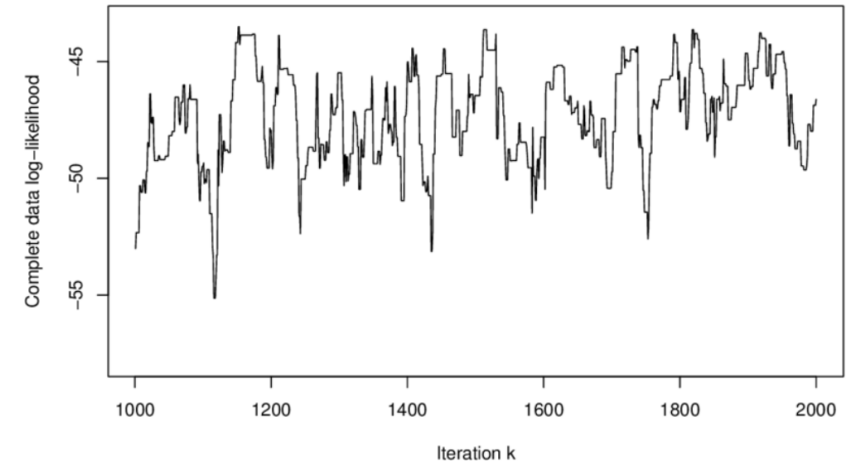
Review

- Recall that the Gibbs sampling / Metropolis (-Hasting) algorithms give '**dependent**' samples.

- How to select samples to make nearly independent sample set? -> Use **thinning**:

1. Check autocorrelation of MCMC chain
2. Pick lag number so that ACF is reasonably low. (here, lag = 40).
3. Among attained s samples by MCMC, pick every 40th samples to make a nearly independent sample set.

Trace plot for Metropolis random walk



Autocorrelation function for Metropolis random walk

