

Control Systems

G V V Sharma*

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Abstract—This manual is an introduction to control systems in feedback circuits. Links to sample Python codes are available in the text.

Download python codes using

```
svn co https://github.com/gadepall/school/trunk/
control/feedback/codes
```

1	FEEDBACK VOLTAGE AMPLIFIER: SERIES-SHUNT
2	FEEDBACK CURRENT AMPLIFIER: SHUNT-SERIES
2.1	Ideal Case
2.2	Practical Case
3	FEEDBACK CURRENT AMPLIFIER: EXAMPLE
4	FEEDBACK TRANSCONDUCTANCE AMPLIFIER: SERIES-SERIES
5	OP-AMP RC OSCILLATOR CIRCUIT

- 5.1. For the circuit in Fig. 5.1.1 (ignore the amplitude stabilization circuitry), find the loop gain GH by breaking the circuit at node X.
- 5.2. **Solution:** The equivalent control system representation of Oscillator circuit is shown in

*The author is with the Department of Electrical Engineering, Indian Institute of Technology, Hyderabad 502285 India e-mail: gadepall@iith.ac.in. All content in this manual is released under GNU GPL. Free and open source.

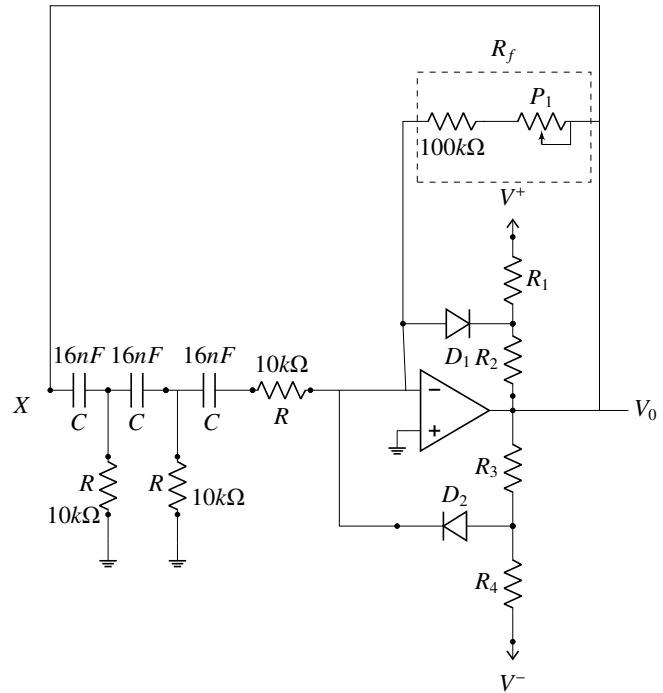


Fig. 5.1.1

Fig. 5.2.2. Note that oscillator circuits do not have a input. After removing the amplitude

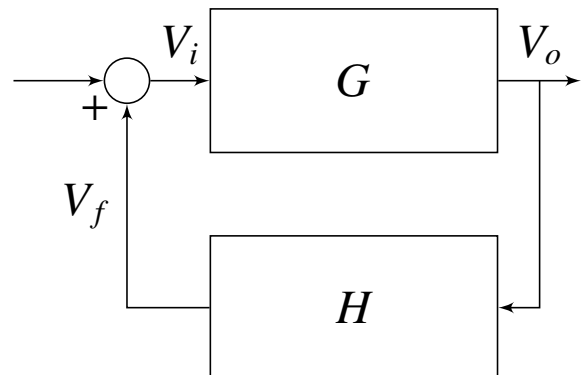


Fig. 5.2.2

stabilization circuitry, when we break the loop at X, the value of gain

$$GH = \frac{v_o(j\omega)}{v_x(j\omega)} \quad (5.2.1)$$

from Fig. 5.2.3

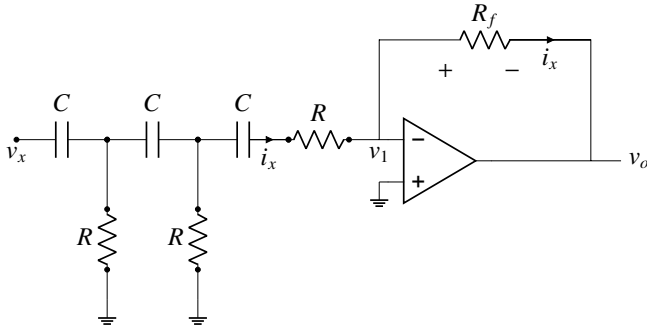


Fig. 5.2.3

$$v_1 = 0 \quad (5.2.2)$$

$$\Rightarrow v_o = -i_x R_f \quad (5.2.3)$$

Considering the circuit between node X and inverting terminal of op-amp,

$$\frac{v_x}{i_x} = \left(R + \frac{6}{sC} + \frac{5}{s^2 C^2 R} + \frac{1}{s^3 C^3 R^2} \right) \quad (5.2.4)$$

From (5.2.3)

$$\frac{v_x}{v_o} = -\frac{R}{R_f} \left(1 + \frac{6}{sCR} + \frac{5}{s^2 C^2 R^2} + \frac{1}{s^3 C^3 R^3} \right) \quad (5.2.5)$$

$$\Rightarrow \frac{v_o}{v_x} = -\frac{R_f s^3 C^3 R^3}{R(s^3 C^3 R^3 + 6s^2 C^2 R^2 + 5sCR + 1)} \quad (5.2.6)$$

Substituting $s = j\omega$ gives us the transfer function

$$\frac{v_o}{v_x} = GH = \frac{\omega^2 C^2 R_f R}{(5 - \omega^2 C^2 R^2) + j(6\omega CR - \frac{1}{\omega CR})} \quad (5.2.7)$$

5.3. Find frequency of oscillation f_0 .

5.4. **Solution:** For system to oscillate at a frequency f_0 ,

$$GH = 1 \quad (5.4.1)$$

$$\Rightarrow \angle(GH) = 0 \quad (5.4.2)$$

$$\Rightarrow 6\omega_0 CR = \frac{1}{\omega_0 CR} \quad (5.4.3)$$

$$\Rightarrow \omega_0 = \frac{1}{\sqrt{6}CR} \quad (5.4.4)$$

$$\Rightarrow f_0 = 406.1 \text{ Hz} \quad (5.4.5)$$

5.5. Find R_f for oscillation to begin.

5.6. **Solution:** From (5.4.1)

$$Re(GH) = 1 \quad (5.6.1)$$

$$\Rightarrow \frac{R_f \omega_0^2 C^2 R^2}{5 - \omega_0^2 C^2 R^2} = 1 \quad (5.6.2)$$

$$\Rightarrow R_f = 290 \text{ k}\Omega \quad (5.6.3)$$

Thus, for the oscillations to begin, R_f should be slightly greater than $290 \text{ k}\Omega$.

5.7. Tabulate your results.

5.8. **Solution:** See table 5.8

Parameter	Value
ω_0	2551.55 rad/s
f_0	406.1 Hz
R_f	290 k Ω

TABLE 5.8: calculated parameters